

leJOS_EV3/src/ev3/adc
_sensors.h

```
graph BT; A[ECRobot/ecrobot_interface.c] --> B[ECRobot/ecrobot_interface.h]; B --> C[leJOS_EV3/src/ev3/adc_sensors.h];
```

ECRobot/ecrobot_interface.h

ECRobot/ecrobot_interface.c