

ecrobot_get_nxtcolorsensor_rgb



```
graph LR; A[ecrobot_get_nxtcolorsensor_rgb] --> B[error_function_call_not_implemented]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is light gray with a black border and contains the text 'ecrobot_get_nxtcolorsensor_rgb'. A dark blue arrow points from the right side of this box to the left side of the right box. The right box is white with a black border and contains the text 'error_function_call' on the top line and '_not_implemented' on the bottom line.

error_function_call
_not_implemented