

ecrobot_adc_data_monitor



```
graph LR; A[ecrobot_adc_data_monitor] --> B[error_function_call  
_not_implemented]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is light gray with a black border and contains the text 'ecrobot_adc_data_monitor'. The right box is white with a black border and contains the text 'error_function_call' on the top line and '_not_implemented' on the bottom line. A dark blue arrow points from the right side of the left box to the left side of the right box.

error_function_call
_not_implemented