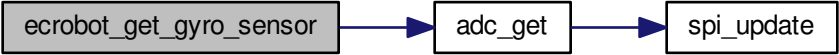


ecrobot_get_gyro_sensor



```
graph LR; A[ecrobot_get_gyro_sensor] --> B[adc_get]; B --> C[spi_update];
```

A flowchart illustrating a sequence of three operations. The first operation, 'ecrobot_get_gyro_sensor', is highlighted with a gray background. It is connected by a dark blue arrow to the second operation, 'adc_get', which has a white background. This second operation is then connected by another dark blue arrow to the third operation, 'spi_update', also with a white background. All three operations are contained within rectangular boxes with black borders.

adc_get

spi_update