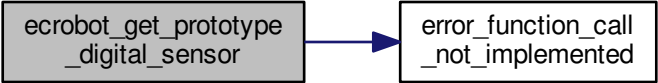


ecrobot\_get\_prototype  
\_digital\_sensor



```
graph LR; A["ecrobot_get_prototype  
_digital_sensor"] --> B["error_function_call  
_not_implemented"]
```

A diagram consisting of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'ecrobot\_get\_prototype' followed by '\_digital\_sensor' on a new line. The right box is white and contains the text 'error\_function\_call' followed by '\_not\_implemented' on a new line. A dark blue arrow points from the right side of the gray box to the left side of the white box.

error\_function\_call  
\_not\_implemented