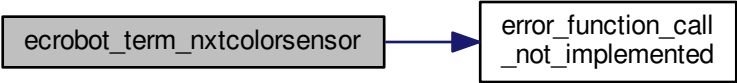


ecrobot\_term\_nxtcolorsensor



```
graph LR; A[ecrobot_term_nxtcolorsensor] --> B[error_function_call_not_implemented]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is light gray with a black border and contains the text 'ecrobot\_term\_nxtcolorsensor'. The right box is white with a black border and contains the text 'error\_function\_call' on the top line and '\_not\_implemented' on the bottom line. A dark blue arrow points from the right side of the left box to the left side of the right box.

error\_function\_call  
\_not\_implemented