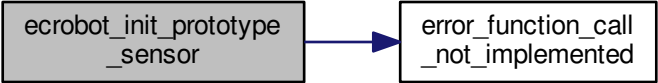


ecrobot_init_prototype
_sensor



```
graph LR; A[ecrobot_init_prototype_sensor] --> B[error_function_call_not_implemented]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a light gray fill and a black border, containing the text 'ecrobot_init_prototype' on the top line and '_sensor' on the bottom line. A dark blue arrow points from the right side of this box to the left side of the right box. The right box has a white fill and a black border, containing the text 'error_function_call' on the top line and '_not_implemented' on the bottom line.

error_function_call
_not_implemented