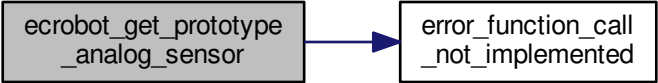


ecrobot_get_prototype
_analog_sensor



```
graph LR; A["ecrobot_get_prototype  
_analog_sensor"] --> B["error_function_call  
_not_implemented"]
```

error_function_call
_not_implemented