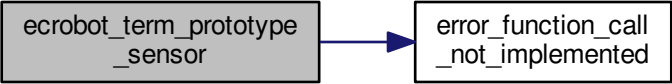


ecrobot_term_prototype
_sensor



```
graph LR; A[ecrobot_term_prototype_sensor] --> B[error_function_call_not_implemented]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'ecrobot_term_prototype' on the top line and '_sensor' on the bottom line. The right box is white and contains the text 'error_function_call' on the top line and '_not_implemented' on the bottom line. A dark blue arrow points from the right side of the gray box to the left side of the white box.

error_function_call
_not_implemented