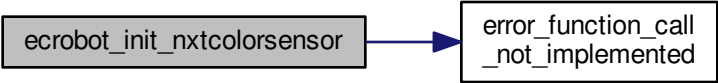


ecrobot_init_nxtcolorsensor



```
graph LR; A[ecrobot_init_nxtcolorsensor] --> B[error_function_call _not_implemented]
```

error_function_call
_not_implemented