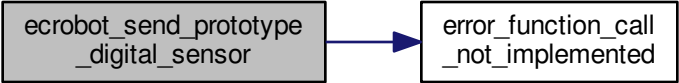


ecrobot\_send\_prototype  
\_digital\_sensor



```
graph LR; A["ecrobot_send_prototype  
_digital_sensor"] --> B["error_function_call  
_not_implemented"]
```

error\_function\_call  
\_not\_implemented