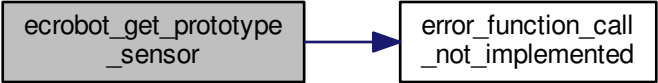


ecrobot\_get\_prototype  
\_sensor



```
graph LR; A[ecrobot_get_prototype_sensor] --> B[error_function_call_not_implemented]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'ecrobot\_get\_prototype\_sensor'. The right box is white and contains the text 'error\_function\_call\_not\_implemented'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

error\_function\_call  
\_not\_implemented