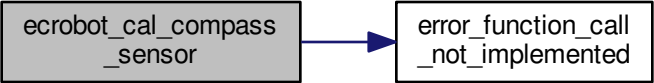


ecrobot_cal_compass
_sensor



```
graph LR; A[ecrobot_cal_compass_sensor] --> B[error_function_call_not_implemented]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'ecrobot_cal_compass' followed by '_sensor' on a new line. The right box is white and contains the text 'error_function_call' followed by '_not_implemented' on a new line. A blue arrow points from the right side of the gray box to the left side of the white box.

error_function_call
_not_implemented