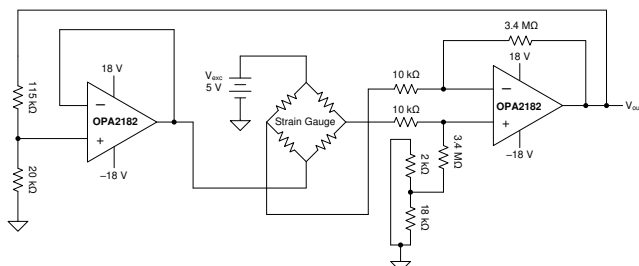# OPA2182 36-V, 5-MHz, Low-Noise, Zero-Drift, MUX-Friendly, Precision Op Amp

## 1 Features

- Ultra-high precision:
  - Zero-drift: 0.003 µV/°C
  - Ultra-low offset voltage: 4 µV (maximum)
- Excellent dc precision:
  - CMRR: 168 dB
  - Open-loop gain: 170 dB
- Low noise:
  - $e_n$ at 1 kHz: 5.7 nV/√Hz
  - 0.1-Hz to 10-Hz noise: 0.12 µV$_{PP}$
- Excellent dynamic performance:
  - Gain bandwidth: 5 MHz
  - Slew rate: 10 V/µs
  - Fast settling: 10-V step, 0.01% in 1.7 µs
- Robust design:
  - MUX-friendly inputs
  - RFI/EMI filtered inputs
- Wide supply: : ±2.25 V to ±18 V, 4.5 V to 36 V
- Quiescent current: 0.85 mA
- Rail-to-rail output
- Input includes negative rail

## 2 Applications

- Battery test
- DC power supply, ac source, electronic load
- Data acquisition (DAQ)
- Semiconductor test
- Weigh scale
- Analog input module
- Flow transmitter

## 3 Description

The OPA2182 high-precision operational amplifier is an ultra-low noise, fast-settling, zero-drift device that provides rail-to-rail output operation and features a unique MUX-friendly architecture and controlled start-up system. These features and excellent ac performance, combined with only 0.45 µV of offset voltage and 0.003 µV/°C of drift over temperature, makes the OPA2182 a great choice for data acquisition, battery test, analog input modules, weigh scales, and any other systems requiring high dc precision and low noise.
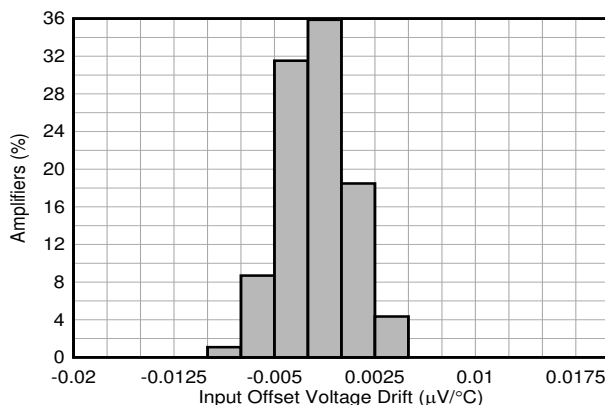
The MUX-friendly input architecture prevents inrush current when applying large input differential voltages that improves settling performance in multichannel systems. Moreover, the controlled start-up system rejects any inrush current upon ramping up the supply rails, all while providing robust ESD protection during shipment, handling, and assembly.

The device is specified from –40°C to +125°C.

**Device Information**

| PART NUMBER | PACKAGE[1] | BODY SIZE (NOM) |
|---|---|---|
| OPA2182 | SOIC (8) | 4.90 mm x 3.90 mm |
| | VSSOP (8) | 3.00 mm x 3.00 mm |

(1) For all available packages, see the package option addendum at the end of the data sheet.



**OPA2182 Bridge Sensor Application**



**OPA2182 Offset Drift**

# Table of Contents

# 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

## 5 Device Comparison Table

| PRODUCT | FEATURES |
|---|---|
| OPA2189 | 0.4-µV offset, 0.005-µV/°C drift, 5.2-nV/√Hz, rail-to-rail output, 36-V, zero-drift, MUX-friendly CMOS |
| OPA2188 | 6-µV offset, 0.03-µV/°C drift, 8.8-nV/√Hz, rail-to-rail output, 36-V, zero-drift, MUX-friendly CMOS |
| OPA2187 | 1-µV offset, 0.001-µV/°C drift, 100-µA quiescent current, rail-to-rail output, 36-V, zero-drift CMOS |
| OPA2388 | 0.25-µV offset, 0.005-µV/°C drift, 7-nV/√Hz, 10-MHz, *true* rail-to-rail input/output, 5.5-V, zero-drift, zero-crossover CMOS |
| OPA2180 | 120-µV, 10-MHz, 5.1-nV/√Hz, 36-V JFET input industrial op amp |

## 6 Pin Configuration and Functions



OUT A — 1    8 — V+
−IN A — 2    7 — OUT B
+IN A — 3    6 — −IN B
V− — 4    5 — +IN B

Not to scale
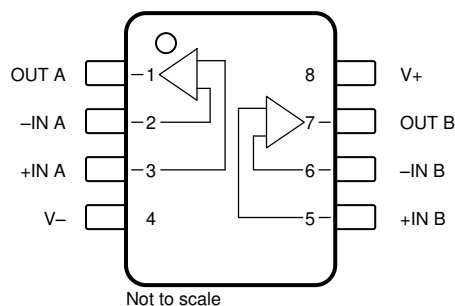
**Figure 6-1. D (8-Pin SOIC) and DGK (8-Pin VSSOP) Packages, Top View**

**Table 6-1. Pin Functions**

| PIN NAME | PIN NO. | I/O | DESCRIPTION |
|---|---|---|---|
| −IN A | 2 | I | Inverting input channel A |
| +IN A | 3 | I | Noninverting input channel A |
| −IN B | 6 | I | Inverting input channel B |
| +IN B | 5 | I | Noninverting input channel B |
| OUT A | 1 | O | Output channel A |
| OUT B | 7 | O | Output channel B |
| V− | 4 | — | Negative supply |
| V+ | 8 | — | Positive supply |

# 7 Specifications

## 7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)[1]

| | | | MIN | MAX | UNIT |
|---|---|---|---|---|---|
| $V_S$ | Supply voltage | Single-supply, $V_S$ = (V+) | | 40 | V |
| | | Dual-supply, $V_S$ = (V+) – (V–) | | ±20 | |
| | Signal input voltage | Common-mode | (V–) – 0.5 | (V+) + 0.5 | V |
| | | Differential | | (V+) – (V–) + 0.2 | |
| | Current | | | ±10 | mA |
| | Output short circuit[2] | | Continuous | Continuous | |
| $T_A$ | Operating temperature | | –55 | 150 | °C |
| $T_J$ | Junction temperature | | | 150 | °C |
| $T_{stg}$ | Storage temperature | | –65 | 150 | °C |

(1)   Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. Theseare stress ratings only, which do not imply functional operation of the device at these or anyother conditions beyond those indicated under *Recommended OperatingConditions*. Exposure to absolute-maximum-rated conditions for extended periods mayaffect device reliability.

(2)   Short-circuit to ground, one amplifier per package.

## 7.2 ESD Ratings

| | | | VALUE | UNIT |
|---|---|---|---|---|
| $V_{(ESD)}$ | Electrostatic discharge | Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001[1] | ±4000 | V |
| | | Charged-device model (CDM), per JEDEC specification JESD22-C101[2] | ±1000 | |

(1)   JEDEC document JEP155 states that 500-V HBM allows safemanufacturing with a standard ESD control process.

(2)   JEDEC document JEP157 states that 250-V CDM allows safemanufacturing with a standard ESD control process.

## 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

| | | | MIN | NOM | MAX | UNIT |
|---|---|---|---|---|---|---|
| $V_S$ | Supply voltage | Single-supply, $V_S$ = (V+) | 4.5 | | 36 | V |
| | | Dual-supply, $V_S$ = (V+) – (V–) | ±2.25 | | ±18 | |
| $T_A$ | Operating temperature | | –40 | | 125 | °C |

## 7.4 Thermal Information: OPA2182

| | | OPA2182 | | UNIT |
|---|---|---|---|---|
| THERMAL METRIC[1] | | D (SOIC) | DGK (VSSOP) | |
| | | 8 PINS | 8 PINS | |
| $R_{\theta JA}$ | Junction-to-ambient thermal resistance | 108.1 | 150.2 | °C/W |
| $R_{\theta JC(top)}$ | Junction-to-case (top) thermal resistance | 45.8 | 43.9 | °C/W |
| $R_{\theta JB}$ | Junction-to-board thermal resistance | 51.3 | 71.4 | °C/W |
| $\Psi_{JT}$ | Junction-to-top characterization parameter | 7.2 | 2.9 | °C/W |
| $\Psi_{JB}$ | Junction-to-board characterization parameter | 50.6 | 70.0 | °C/W |
| $R_{\theta JC(bot)}$ | Junction-to-case (bottom) thermal resistance | N/A | N/A | °C/W |

(1)   For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report.

## 7.5 Electrical Characteristics

at $T_A$ = 25°C, $V_{CM}$ = $V_{OUT}$ = $V_S$ / 2, and $R_{LOAD}$ = 10 kΩ connected to $V_S$ / 2 (unless otherwise noted)

| PARAMETER | | TEST CONDITIONS | | MIN | TYP | MAX | UNIT |
|---|---|---|---|---|---|---|---|
| **OFFSET VOLTAGE** | | | | | | | |
| $V_{OS}$ | Input offset voltage | | | | ±0.45 | ±4 | µV |
| | | $T_A$ = 0°C to 85°C | | | | ±4 | µV |
| | | $T_A$ = –40°C to 125°C | | | | ±4 | µV |
| $dV_{OS}/dT$ | Input offset voltage drift | $T_A$ = 0°C to 85°C | | | ±0.003 | ±0.012 | µV/°C |
| | | $T_A$ = –40°C to 125°C | | | ±0.003 | ±0.012 | |
| PSRR | Power-supply rejection ratio | $T_A$ = –40°C to +125°C | | | ±0.005 | ±0.05 | µV/V |
| **INPUT BIAS CURRENT** | | | | | | | |
| $I_B$ | Input bias current | $Z_{IN}$ = 100 kΩ ǁ 500 pF | | | ±50 | ±350 | pA |
| | | | $T_A$ = 0°C to 85°C | | | ±1 | nA |
| | | | $T_A$ = –40°C to +125°C | | | ±7 | |
| $I_{OS}$ | Input offset current | $Z_{IN}$ = 100 kΩ ǁ 500 pF | | | ±140 | ±700 | pA |
| | | | $T_A$ = 0°C to 85°C | | | ±2 | nA |
| | | | $T_A$ = –40°C to +125°C | | | ±3 | |
| **NOISE** | | | | | | | |
| $E_n$ | Input voltage noise | f = 0.1 Hz to 10 Hz | | | 18 | | $nV_{RMS}$ |
| | | | | | 0.119 | | $µV_{PP}$ |
| $e_n$ | Input voltage noise density | f = 10 Hz | | | 5.7 | | nV/√Hz |
| | | f = 100 Hz | | | 5.7 | | |
| | | f = 1 kHz | | | 5.7 | | |
| | | f = 10 kHz | | | 5.7 | | |
| $i_n$ | Input current noise density | f = 1 kHz | | | 165 | | fA/√Hz |
| **INPUT VOLTAGE** | | | | | | | |
| $V_{CM}$ | Common-mode voltage range | | | (V–) – 0.1 | | (V+) – 2.5 | V |
| CMRR | Common-mode rejection ratio | (V–) – 0.1 V ≤ $V_{CM}$ ≤ (V+) – 2.5 V | $V_S$ = ±2.25 V | 120 | 140 | | dB |
| | | | $V_S$ = ±18 V | 143 | 168 | | |
| | | (V–) – 0.1 V ≤ $V_{CM}$ ≤ (V+) – 2.5 V, $T_A$ = –40°C to +125°C | $V_S$ = ±2.25 V | 120 | | | |
| | | | $V_S$ = ±18 V | 140 | | | |
| **INPUT IMPEDANCE** | | | | | | | |
| $z_{id}$ | Differential input impedance | | | | 0.1 ǁ 3.7 | | GΩ ǁ pF |
| $z_{ic}$ | Common-mode input impedance | | | | 60 ǁ 2.3 | | TΩ ǁ pF |

## 7.5 Electrical Characteristics (continued)

at $T_A$ = 25°C, $V_{CM}$ = $V_{OUT}$ = $V_S$ / 2, and $R_{LOAD}$ = 10 kΩ connected to $V_S$ / 2 (unless otherwise noted)

| PARAMETER | | TEST CONDITIONS | | MIN | TYP | MAX | UNIT |
|---|---|---|---|---|---|---|---|
| **OPEN-LOOP GAIN** | | | | | | | |
| $A_{OL}$ | Open-loop voltage gain | $V_S$ = ±18 V | (V−) + 0.3 V < $V_O$ < (V+) − 0.3 V, $R_{LOAD}$ = 10 kΩ | 150 | 170 | | dB |
| | | | (V−) + 0.3 V < $V_O$ < (V+) − 0.3 V, $R_{LOAD}$ = 10 kΩ, $T_A$ = −40°C to +125°C | 146 | | | |
| | | | (V−) + 0.6 V < $V_O$ < (V+) − 0.6 V, $R_{LOAD}$ = 2 kΩ | 150 | 170 | | |
| | | | (V−) + 0.6 V < $V_O$ < (V+) − 0.6 V, $R_{LOAD}$ = 2 kΩ, $T_A$ = −40°C to +125°C | 140 | | | |
| **FREQUENCY RESPONSE** | | | | | | | |
| UGB | Unity-gain Bandwith | $A_V$ = 1 | | | 3.6 | | MHz |
| GBW | Gain-bandwith Product | $A_V$ = 1000 | | | 5 | | |
| SR | Slew rate | Gain = 1, 10-V step | | | 10 | | V/µs |
| THD+N | Total harmonic distortion + noise | Gain = 1, f = 1 kHz, $V_O$ = 3.5 $V_{RMS}$ | | | 0.00008% | | |
| | Crosstalk | OPA2182, at dc | | | 150 | | dB |
| | | OPA2182, f = 10 kHz | | | 120 | | |
| $t_S$ | Settling time | To 0.1% | $V_S$ = ±18 V, gain = 1, 10-V step | | 1.3 | | µs |
| | | To 0.01% | $V_S$ = ±18 V, gain = 1, 10-V step, falling | | 1.7 | | |
| | | | $V_S$ = ±18 V, gain = 1, 10-V step, rising | | 3.4 | | |
| $t_{OR}$ | Overload recovery time | $V_{IN}$ × gain = $V_S$ = ±18V | | | 220 | | ns |
| **OUTPUT** | | | | | | | |
| $V_O$ | Voltage output swing from rail | Positive rail | No load | | 5 | 15 | mV |
| | | | $R_{LOAD}$ = 10 kΩ | | 20 | 110 | |
| | | | $R_{LOAD}$ = 2 kΩ | | 80 | 500 | |
| | | Negative rail | No load | | 5 | 15 | |
| | | | $R_{LOAD}$ = 10 kΩ | | 20 | 110 | |
| | | | $R_{LOAD}$ = 2 kΩ | | 80 | 500 | |
| | | $T_A$ = −40°C to +125°C, both rails, $R_{LOAD}$ = 10 kΩ | | | 20 | 120 | |
| $I_{SC}$ | Short-circuit current | | | | ±65 | | mA |
| $C_{LOAD}$ | Capacitive load drive | | | | See Typical Characteristics | | pF |
| $Z_O$ | Open-loop output impedance | f = 1 MHz | | | 320 | | Ω |
| **POWER SUPPLY** | | | | | | | |
| $I_Q$ | Quiescent current per amplifier | $V_S$ = ±2.25 V to ±18 V | $T_A$ = 25°C | | 0.85 | 1 | mA |
| | | | $T_A$ = −40°C to +125°C | | | 1.1 | |

## 7.6 Typical Characteristics

at $T_A$ = 25°C, $V_S$ = ±18 V, $V_{CM}$ = $V_S$ / 2, $R_{LOAD}$ = 10 kΩ connected to $V_S$ / 2, and $C_L$ = 100 pF (unless otherwise noted)

### Table 7-1. Typical Characteristic Graphs

| DESCRIPTION | FIGURE |
|---|---|
| Offset Voltage Production Distribution | Figure 7-1 |
| Offset Voltage Drift Distribution From –40°C to 125°C | Figure 7-2 |
| Input Bias Current Production Distribution | Figure 7-3 |
| Input Offset Current Production Distribution | Figure 7-4 |
| Offset Voltage vs Temperature | Figure 7-5 |
| Offset Voltage vs Common-Mode Voltage | Figure 7-6 |
| Offset Voltage vs Supply Voltage | Figure 7-7 |
| Open-Loop Gain and Phase vs Frequency | Figure 7-8 |
| Closed-Loop Gain vs Frequency | Figure 7-9 |
| Input Bias Current vs Common-Mode Voltage | Figure 7-10 |
| Input Bias Current and Offset vs Temperature | Figure 7-11 |
| Output Voltage Swing vs Output Current (Sourcing) | Figure 7-12 |
| Output Voltage Swing vs Output Current (Sinking) | Figure 7-13 |
| CMRR and PSRR vs Frequency | Figure 7-14 |
| CMRR vs Temperature | Figure 7-15 |
| PSRR vs Temperature | Figure 7-16 |
| 0.1-Hz to 10-Hz Voltage Noise | Figure 7-17 |
| Input Voltage Noise Spectral Density vs Frequency | Figure 7-18 |
| THD+N Ratio vs Frequency | Figure 7-19 |
| THD+N vs Output Amplitude | Figure 7-20 |
| Quiescent Current vs Supply Voltage | Figure 7-21 |
| Quiescent Current vs Temperature | Figure 7-22 |
| Open-Loop Gain vs Temperature (10-kΩ) | Figure 7-23 |
| Open-Loop Output Impedance vs Frequency | Figure 7-24 |
| Small-Signal Overshoot vs Capacitive Load (10-mV Step) | Figure 7-25, Figure 7-26 |
| No Phase Reversal | Figure 7-27 |
| Positive Overload Recovery | Figure 7-28 |
| Negative Overload Recovery | Figure 7-29 |
| Small-Signal Step Response (10-mV Step) | Figure 7-30, Figure 7-31 |
| Large-Signal Step Response (10-V Step) | Figure 7-32, Figure 7-33 |
| Settling Time | Figure 7-34 |
| Short Circuit Current vs Temperature | Figure 7-35 |
| Maximum Output Voltage vs Frequency | Figure 7-36 |
| EMIRR vs Frequency | Figure 7-37 |
| Channel Separation | Figure 7-38 |

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## 7.6 Typical Characteristics (continued)

at $T_A$ = 25°C, $V_S$ = ±18 V, $V_{CM}$ = $V_S$ / 2, $R_{LOAD}$ = 10 kΩ connected to $V_S$ / 2, and $C_L$ = 100 pF (unless otherwise noted)
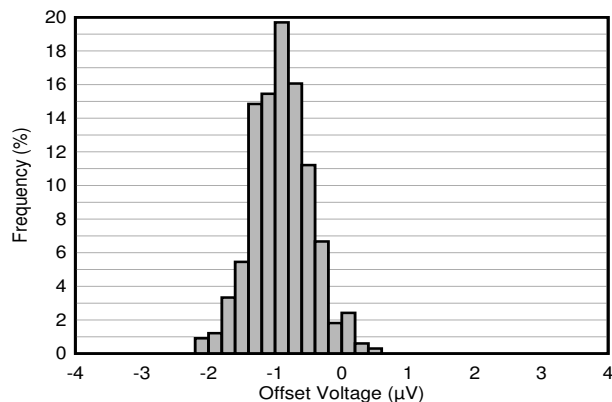
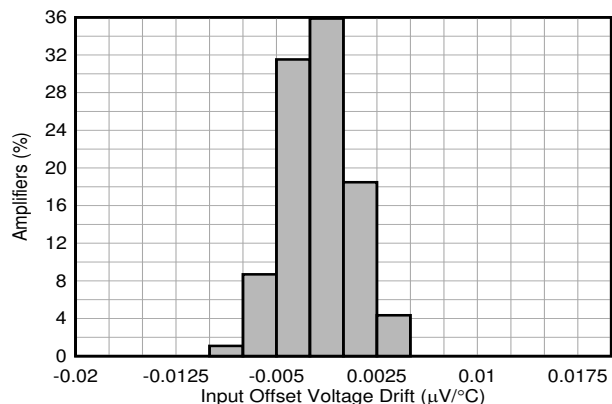**Figure 7-1. Offset Voltage Production Distribution**
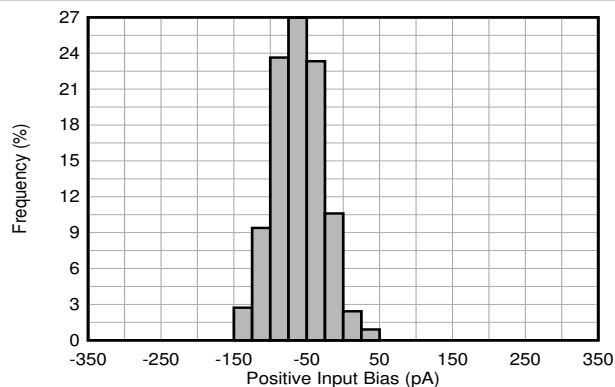
**Figure 7-2. Offset Voltage Drift Distribution**

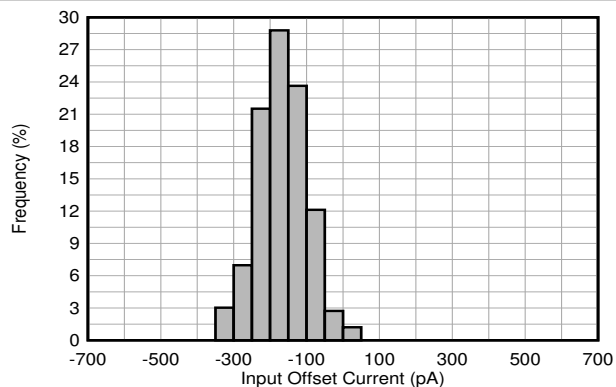**Figure 7-3. Input Bias Current Production Distribution**

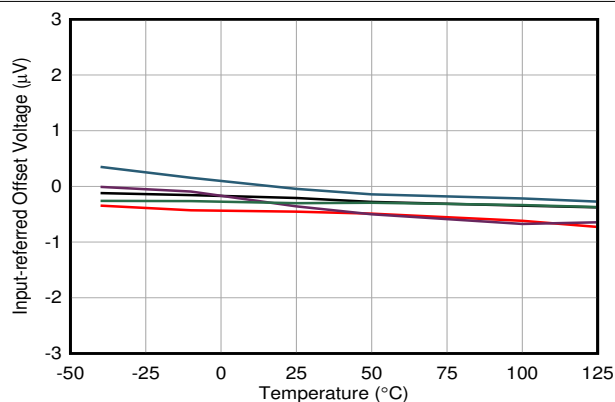**Figure 7-4. Input Offset Current Production Distribution**

**Figure 7-5. Offset Voltage vs Temperature**
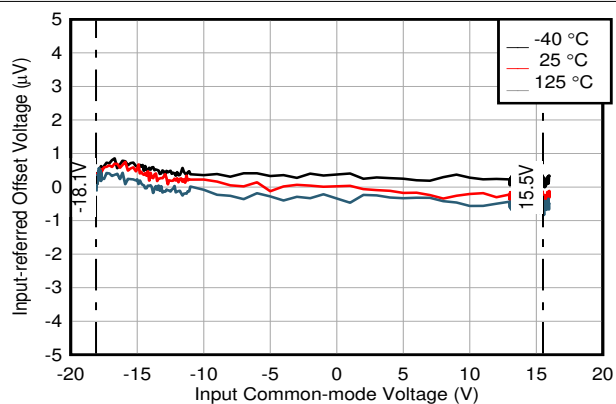
**Figure 7-6. Offset Voltage vs Common-Mode Voltage**

Product Folder Links: *OPA2182*

## 7.6 Typical Characteristics (continued)

at $T_A$ = 25°C, $V_S$ = ±18 V, $V_{CM}$ = $V_S$ / 2, $R_{LOAD}$ = 10 kΩ connected to $V_S$ / 2, and $C_L$ = 100 pF (unless otherwise noted)
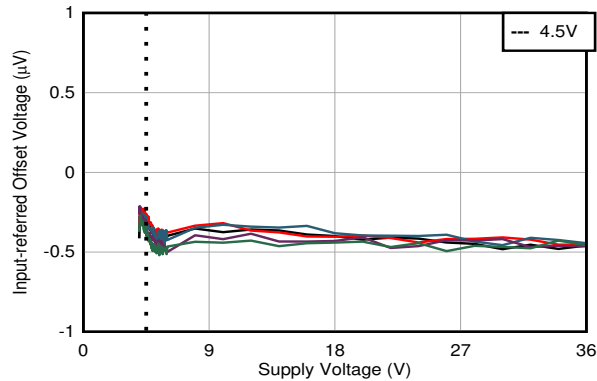
**Figure 7-7. Offset Voltage vs Supply Voltage**
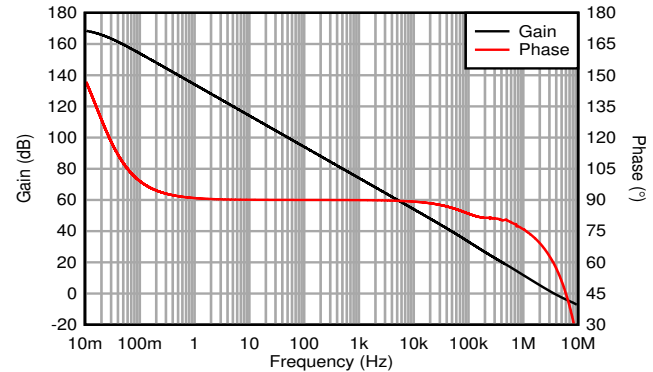
**Figure 7-8. Open-Loop Gain and Phase vs Frequency**
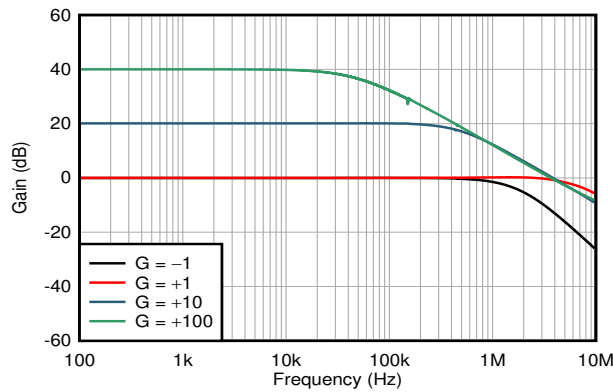
**Figure 7-9. Closed-Loop Gain vs Frequency**
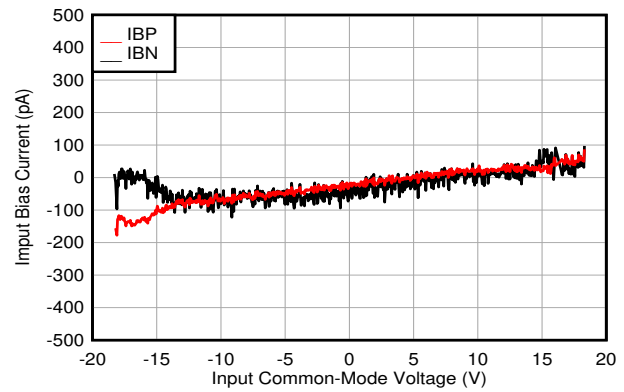
**Figure 7-10. Input Bias Current vs Common-Mode Voltage**
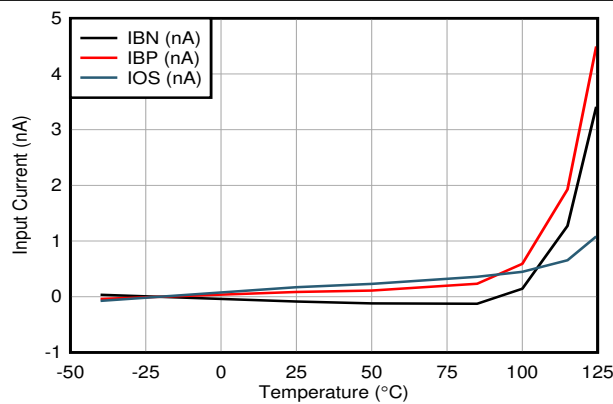
**Figure 7-11. Input Bias Current and Offset vs Temperature**
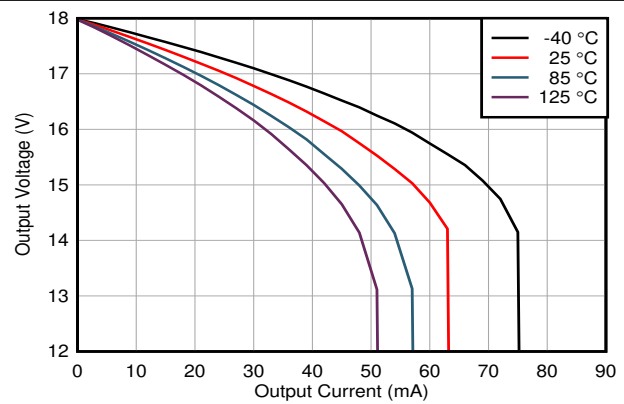
**Figure 7-12. Output Voltage Swing vs Output Current (Sourcing)**

## 7.6 Typical Characteristics (continued)

at $T_A$ = 25°C, $V_S$ = ±18 V, $V_{CM}$ = $V_S$ / 2, $R_{LOAD}$ = 10 kΩ connected to $V_S$ / 2, and $C_L$ = 100 pF (unless otherwise noted)
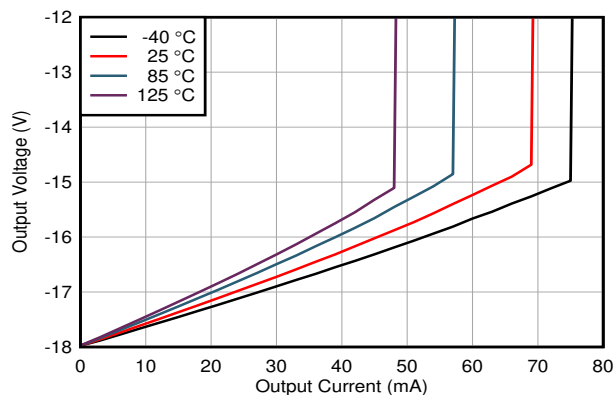
**Figure 7-13. Output Voltage Swing vs Output Current (Sinking)**
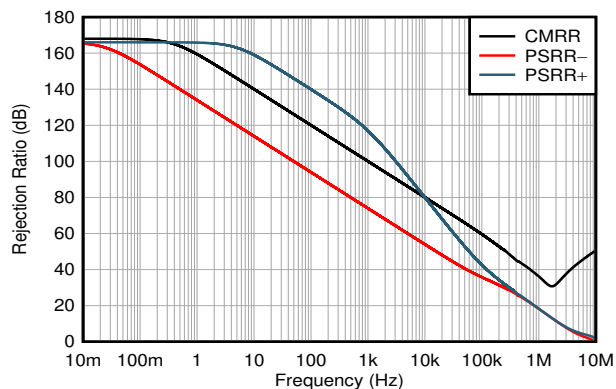
**Figure 7-14. CMRR and PSRR vs Frequency**
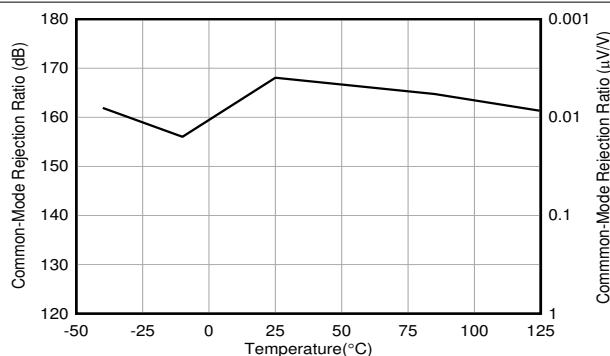
**Figure 7-15. CMRR vs Temperature**
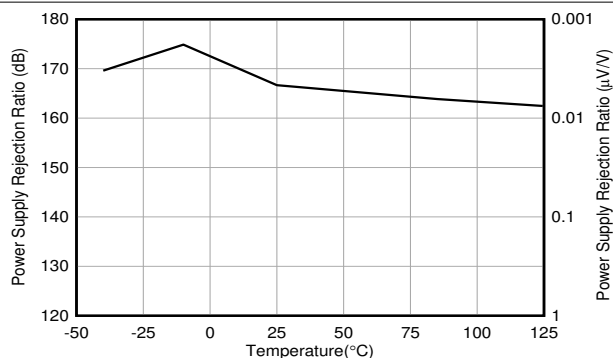
**Figure 7-16. PSRR vs Temperature**
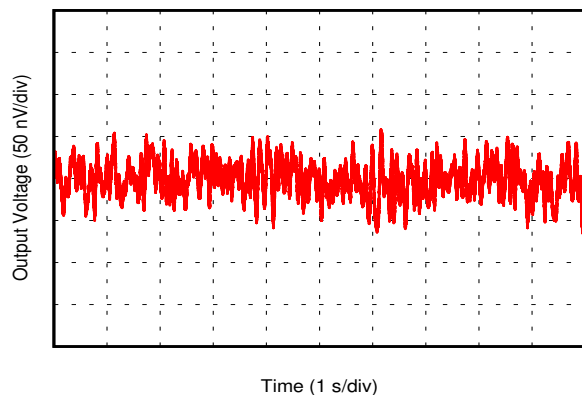
**Figure 7-17. 0.1-Hz to 10-Hz Voltage Noise**
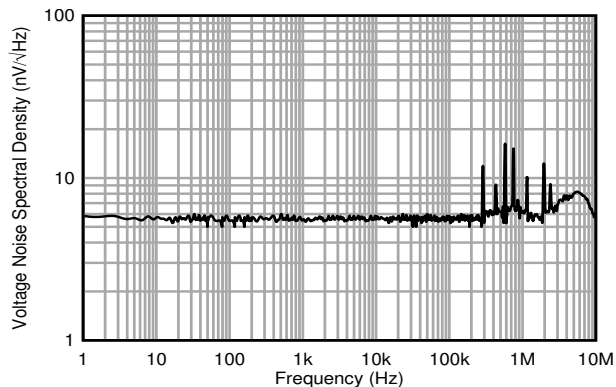
**Figure 7-18. Input Voltage Noise Spectral Density vs Frequency**

Product Folder Links: *OPA2182*

## 7.6 Typical Characteristics (continued)

at $T_A$ = 25°C, $V_S$ = ±18 V, $V_{CM}$ = $V_S$ / 2, $R_{LOAD}$ = 10 kΩ connected to $V_S$ / 2, and $C_L$ = 100 pF (unless otherwise noted)



**Figure 7-19. THD+N Ratio vs Frequency**
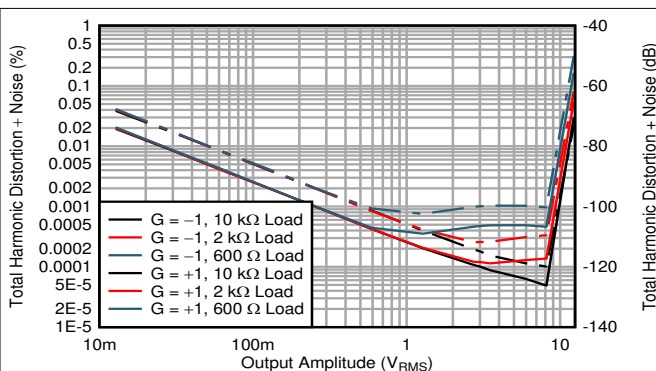


**Figure 7-20. THD+N vs Output Amplitude**
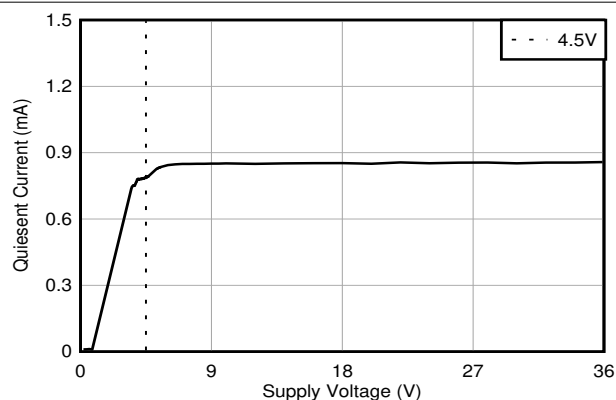


**Figure 7-21. Quiescent Current vs Supply Voltage**
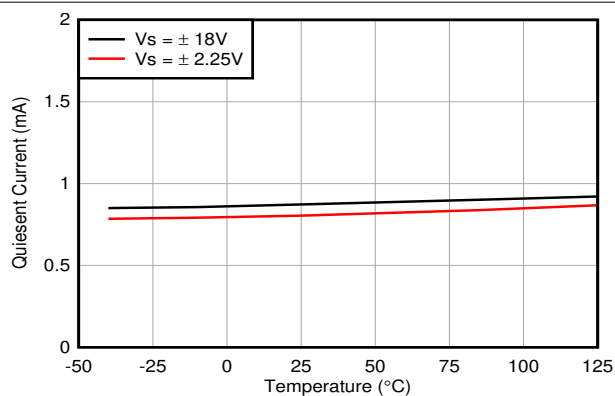


**Figure 7-22. Quiescent Current vs Temperature**
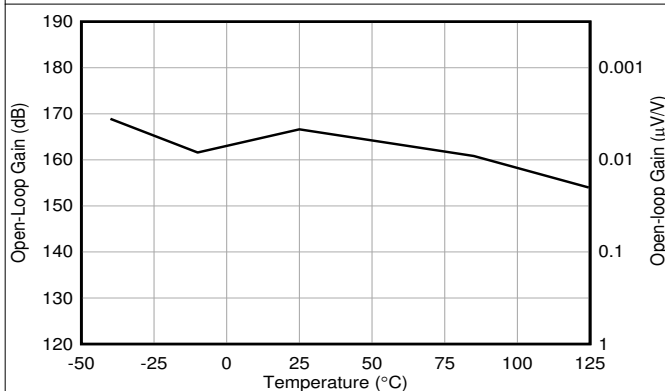


**Figure 7-23. Open-Loop Gain vs Temperature (10-kΩ)**
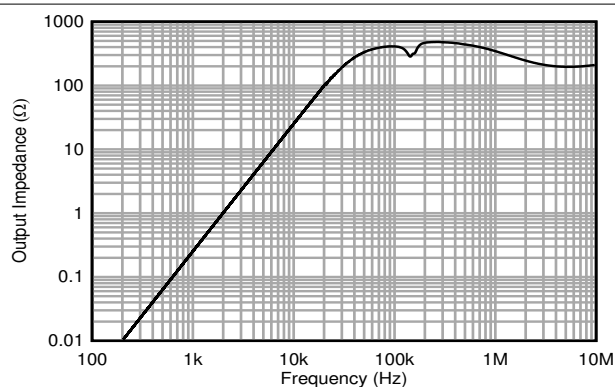


**Figure 7-24. Open-Loop Output Impedance vs Frequency**

## 7.6 Typical Characteristics (continued)

at $T_A$ = 25°C, $V_S$ = ±18 V, $V_{CM}$ = $V_S$ / 2, $R_{LOAD}$ = 10 kΩ connected to $V_S$ / 2, and $C_L$ = 100 pF (unless otherwise noted)



Inverting Configuration
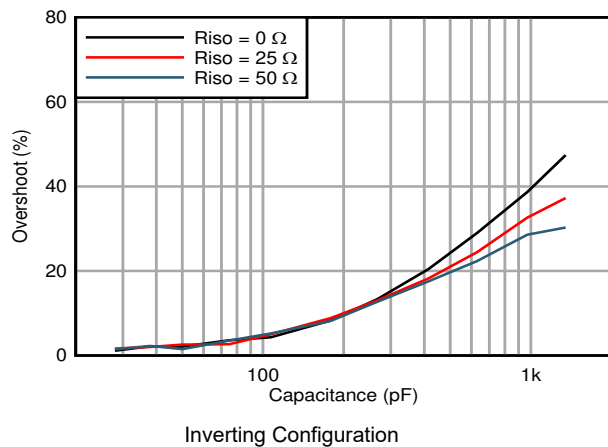
**Figure 7-25. Small-Signal Overshoot vs Capacitive Load**



Noninverting Configuration
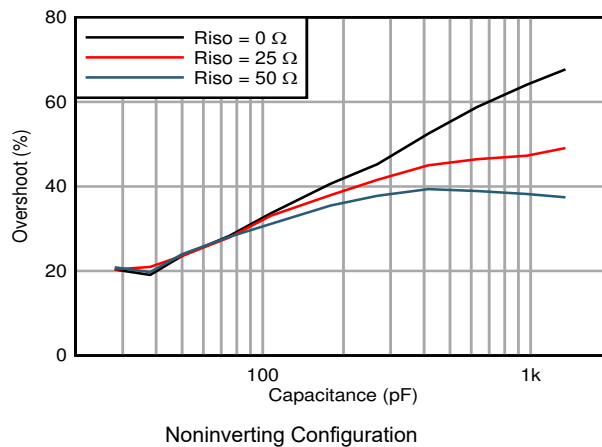
**Figure 7-26. Small-Signal Overshoot vs Capacitive Load**
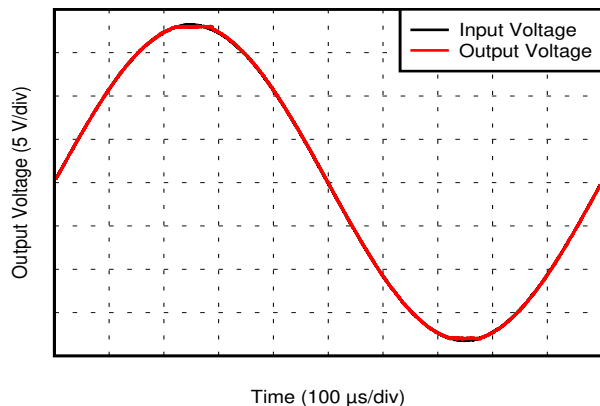


**Figure 7-27. No Phase Reversal**
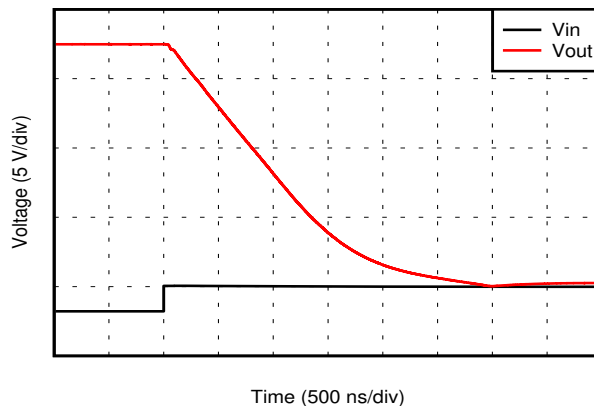


**Figure 7-28. Positive Overload Recovery**
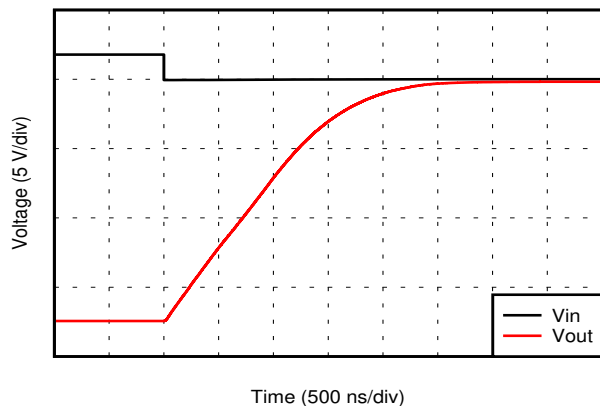


**Figure 7-29. Negative Overload Recovery**



Inverting Configuration
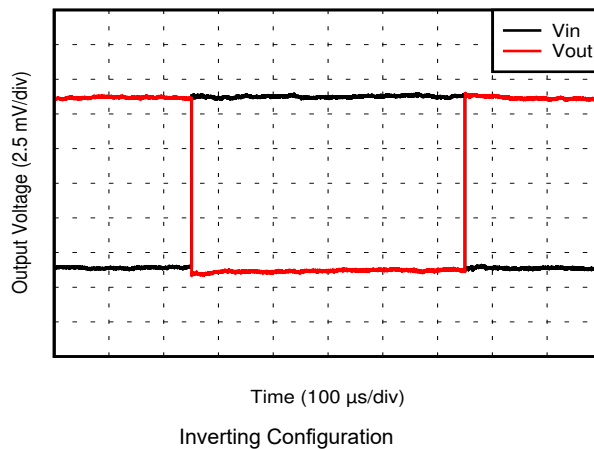
**Figure 7-30. Small-Signal Step Response**

Product Folder Links: *OPA2182*

## 7.6 Typical Characteristics (continued)

at $T_A$ = 25°C, $V_S$ = ±18 V, $V_{CM}$ = $V_S$ / 2, $R_{LOAD}$ = 10 kΩ connected to $V_S$ / 2, and $C_L$ = 100 pF (unless otherwise noted)



Noninverting Configuration
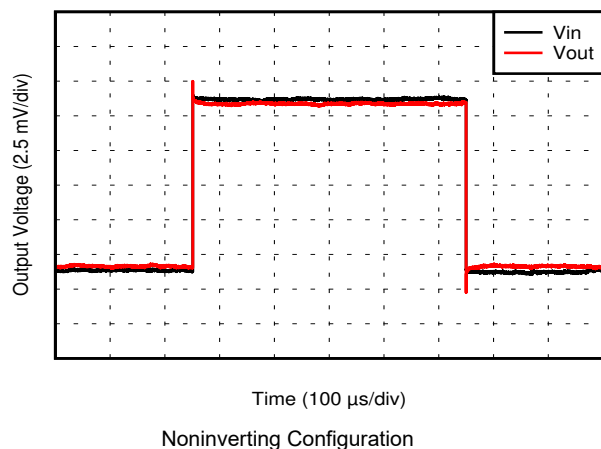
**Figure 7-31. Small-Signal Step Response**



Inverting Configuration
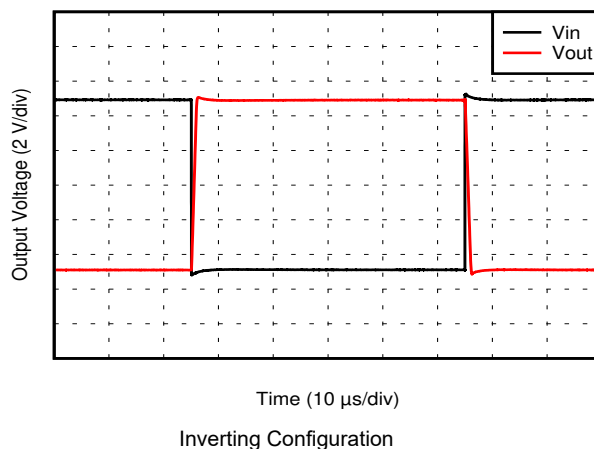
**Figure 7-32. Large-Signal Step Response**



Noninverting Configuration
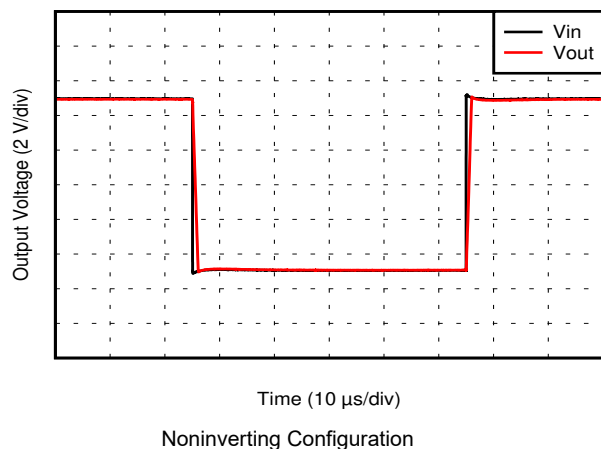
**Figure 7-33. Large-Signal Step Response**
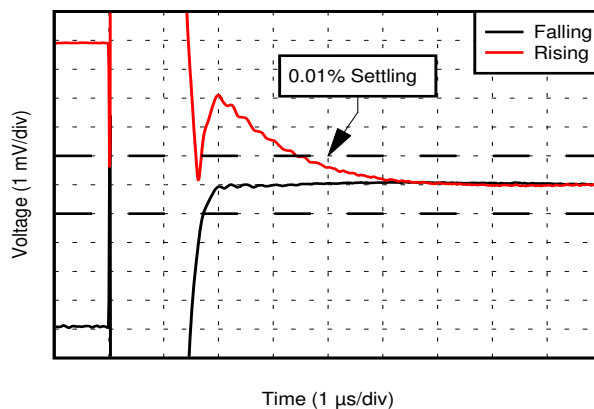


**Figure 7-34. Settling Time**
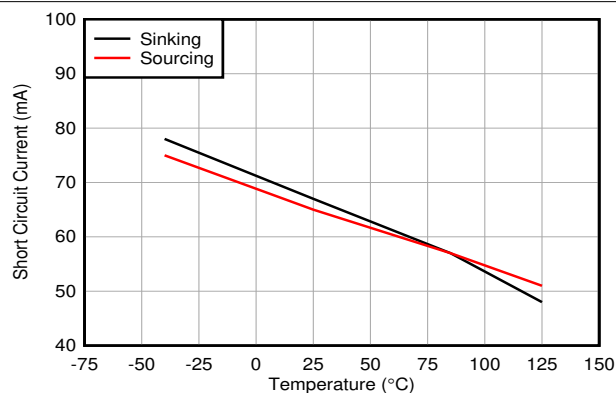


**Figure 7-35. Short-Circuit Current vs Temperature**
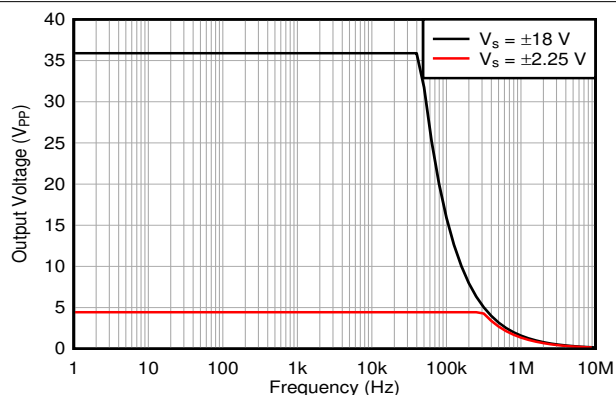


**Figure 7-36. Maximum Output Voltage vs Frequency**

Product Folder Links: OPA2182

## 7.6 Typical Characteristics (continued)

at $T_A$ = 25°C, $V_S$ = ±18 V, $V_{CM}$ = $V_S$ / 2, $R_{LOAD}$ = 10 kΩ connected to $V_S$ / 2, and $C_L$ = 100 pF (unless otherwise noted)

**Figure 7-37. EMIRR vs Frequency**
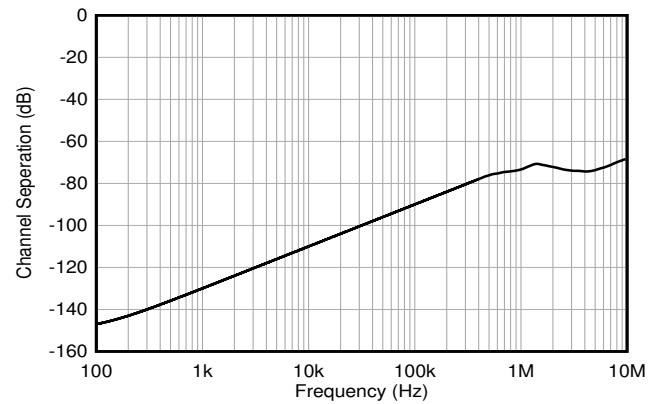
**Figure 7-38. Channel Separation**

Product Folder Links: *OPA2182*

# 8 Detailed Description

## 8.1 Overview

The OPA2182 operational amplifier combines precision offset and drift with excellent overall performance, making the device a great choice for many precision applications. The precision offset drift of only 0.005 µV/°C provides stability over the entire temperature range. In addition, this device offers excellent linear performance with high CMRR, PSRR, and $A_{OL}$. As with all amplifiers, applications with noisy or high-impedance power supplies require decoupling capacitors close to the device pins. In most cases, 0.1-µF capacitors are adequate. See the *Layout Guidelines* section for details and a layout example.

The OPA2182 is a zero-drift, MUX-friendly, rail-to-rail output operational amplifier. The device operates from 4.5 V to 36 V, is unity-gain stable, and a great choice for a wide range of general-purpose and precision applications. The zero-drift architecture provides ultra-low input offset voltage and near-zero input offset voltage drift over temperature and time. This choice of architecture also offers outstanding ac performance, such as ultra-low broadband noise, zero flicker noise, and outstanding distortion performance when operating below the chopper frequency.

## 8.2 Functional Block Diagram

The functional block diagram shows a representation of the proprietary OPA2182 architecture.
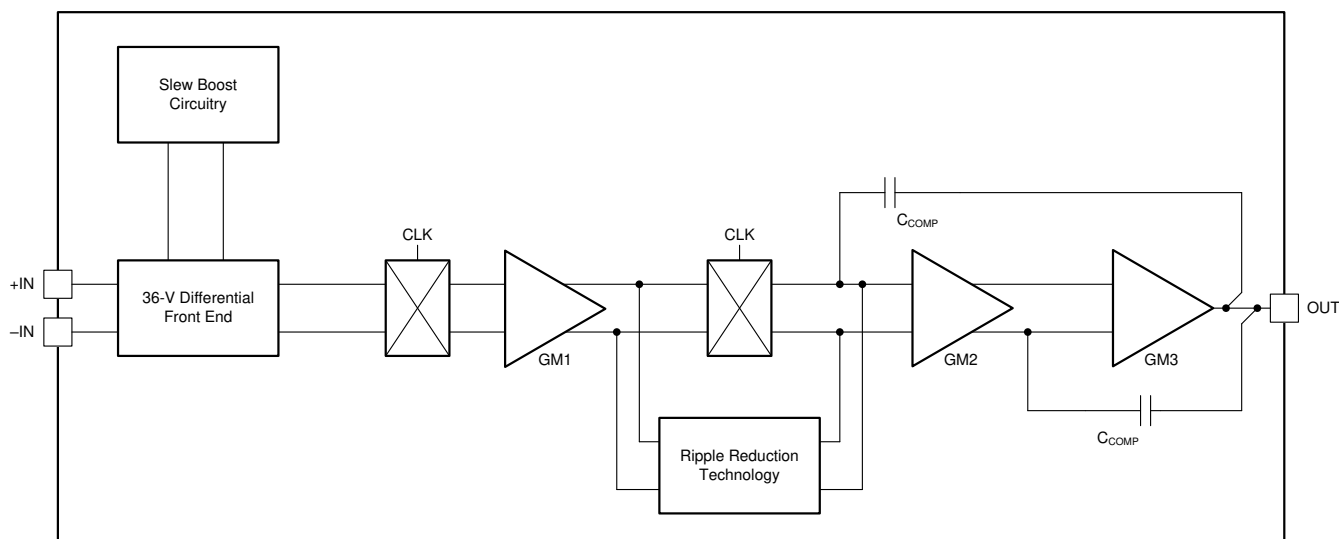
## 8.3 Feature Description

The OPA2182 operational amplifier has several integrated features that help maintain a high level of precision throughout all operating conditions. These features include phase-reveral protection, input bias current clock feedthrough and MUX-friendly inputs.

### 8.3.1 Phase-Reversal Protection

The OPA2182 has an internal phase-reversal protection. Many op amps exhibit a phase reversal when the input is driven beyond the linear common-mode range. This condition is most often encountered in noninverting circuits when the input is driven beyond the specified common-mode voltage range, causing the output to reverse into the opposite rail. The OPA2182 input prevents phase reversal with excessive common-mode voltage. Instead, the output limits into the appropriate rail. This performance is shown in Figure 8-1.
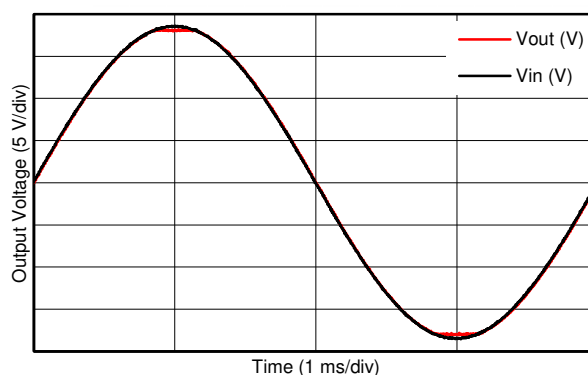


**Figure 8-1. No Phase Reversal**

### 8.3.2 Input Bias Current Clock Feedthrough

Zero-drift amplifiers such as the OPA2182 use switching on the inputs to correct for the intrinsic offset and drift of the amplifier. Charge injection from the integrated switches on the inputs can introduce short transients in the input bias current of the amplifier. The extremely short duration of these pulses prevents the pulses from amplifying; however, the pulses may be coupled to the output of the amplifier through the feedback network. The most effective method to prevent transients in the input bias current from producing additional noise at the amplifier output is to use a low-pass filter such as an RC network.

### 8.3.3 EMI Rejection

The OPA2182 uses integrated electromagnetic interference (EMI) filtering to reduce the effects of EMI interference from sources such as wireless communications and densely-populated boards with a mix of analog signal chain and digital components. EMI immunity can be improved with circuit design techniques; the OPA2182 benefits from these design improvements. Texas Instruments has developed the ability to accurately measure and quantify the immunity of an operational amplifier over a broad frequency spectrum extending from 10 MHz to 6 GHz. Figure 8-2 shows the results of this testing on the OPA2182. Table 8-1 lists the EMIRR +IN values for the OPA2182 at particular frequencies commonly encountered in real-world applications. Applications listed in Table 8-1 may be centered on or operated near the particular frequency shown. Detailed information can also be found in *EMI Rejection Ratio of Operational Amplifiers* (SBOA128), available for download from www.ti.com.

The electromagnetic interference (EMI) rejection ratio, or EMIRR, describes the EMI immunity of operational amplifiers. An adverse effect that is common to many op amps is a change in the offset voltage as a result of RF signal rectification. An op amp that is more efficient at rejecting this change in offset as a result of EMI has a higher EMIRR and is quantified by a decibel value. Measuring EMIRR can be performed in many ways, but this section provides the EMIRR +IN, which specifically describes the EMIRR performance when the RF signal is applied to the noninverting input pin of the op amp. In general, only the noninverting input is tested for EMIRR for the following three reasons:

- Op amp input pins are known to be the most sensitive to EMI, and typically rectify RF signals better than the supply or output pins.
- The noninverting and inverting op amp inputs have symmetrical physical layouts and exhibit nearly matching EMIRR performance
- EMIRR is more simple to measure on noninverting pins than on other pins because the noninverting input terminal can be isolated on a PCB. This isolation allows the RF signal to be applied directly to the noninverting input terminal with no complex interactions from other components or connecting PCB traces.

High-frequency signals conducted or radiated to any pin of the operational amplifier may result in adverse effects, as the amplifier would not have sufficient loop gain to correct for signals with spectral content outside the bandwidth. Conducted or radiated EMI on inputs, power supply, or output may result in unexpected DC offsets, transient voltages, or other unknown behavior. Take care to properly shield and isolate sensitive analog nodes from noisy radio signals and digital clocks and interfaces.

The EMIRR +IN of the OPA2182 is plotted versus frequency as shown in Figure 8-2. If available, any dual and quad op amp device versions have nearly similar EMIRR +IN performance. The OPA2182unity-gain bandwidth is 14 MHz. EMIRR performance below this frequency denotes interfering signals that fall within the op amp bandwidth.
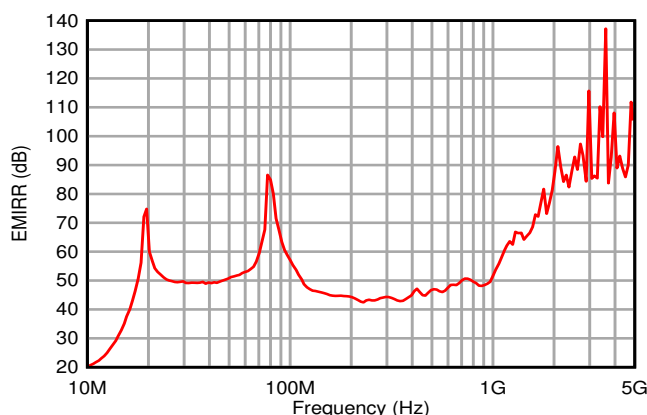


**Figure 8-2. EMIRR Testing**

**Table 8-1. OPA2182 EMIRR IN+ for Frequencies of Interest**

| FREQUENCY | APPLICATION AND ALLOCATION | EMIRR IN+ |
|---|---|---|
| 400 MHz | Mobile radio, mobile satellite, space operation, weather, radar, ultra-high frequency (UHF) applications | 44.9 dB |
| 900 MHz | Global system for mobile communications (GSM) applications, radio communication, navigation, GPS (to 1.6 GHz), GSM, aeronautical mobile, UHF applications | 48.4 dB |
| 1.8 GHz | GSM applications, mobile personal communications, broadband, satellite, L-band (1 GHz to 2 GHz) | 81.7 dB |
| 2.4 GHz | 802.11b, 802.11g, 802.11n, Bluetooth®, mobile personal communications, industrial, scientific and medical (ISM) radio band, amateur radio and satellite, S-band (2 GHz to 4 GHz) | 87.9 dB |
| 3.6 GHz | Radiolocation, aero communication and navigation, satellite, mobile, S-band | 137.2 dB |
| 5 GHz | 802.11a, 802.11n, aero communication and navigation, mobile communication, space and satellite operation, C-band (4 GHz to 8 GHz) | 99.2 dB |

Product Folder Links: OPA2182

### 8.3.4 Electrical Overstress

Designers often ask questions about the capability of an operational amplifier to withstand electrical overstress. These questions tend to focus on the device inputs, but may involve the supply voltage pins or even the output pin. Each of these different pin functions have electrical stress limits determined by the voltage breakdown characteristics of the particular semiconductor fabrication process and specific circuits connected to the pin. Additionally, internal electrostatic discharge (ESD) protection is built into these circuits to protect from accidental ESD events both before and during product assembly.

Having a good understanding of this basic ESD circuitry and the relevance to an electrical overstress event is helpful. See Figure 8-3 for an illustration of the ESD circuits contained in the OPA2182 (indicated by the dashed line area). The ESD protection circuitry involves several current-steering diodes connected from the input and output pins and routed back to the internal power-supply lines, where the diodes meet at an absorption device internal to the operational amplifier. This protection circuitry is intended to remain inactive during normal circuit operation.

An ESD event produces a short-duration, high-voltage pulse that is transformed into a short-duration, high-current pulse while discharging through a semiconductor device. The ESD protection circuits are designed to provide a current path around the operational amplifier core to prevent damage. The energy absorbed by the protection circuitry is then dissipated as heat.

When an ESD voltage develops across two or more amplifier device pins, current flows through one or more steering diodes. Depending on the path that the current takes, the absorption device may activate. The absorption device has a trigger or threshold voltage that is above the normal operating voltage of the OPA2182 but below the device breakdown voltage level. When this threshold is exceeded, the absorption device quickly activates and clamps the voltage across the supply rails to a safe level.

When the operational amplifier connects into a circuit (as shown in Figure 8-3), the ESD protection components are intended to remain inactive and do not become involved in the application circuit operation. However, circumstances may arise where an applied voltage exceeds the operating voltage range of a given pin. Should this condition occur, there is a risk that some internal ESD protection circuits may be biased on, and conduct current. Any such current flow occurs through steering-diode paths and rarely involves the absorption device.

Figure 8-3 shows a specific example where the input voltage ($V_{IN}$) exceeds the positive supply voltage (V+) by 500 mV or more. Much of what happens in the circuit depends on the supply characteristics. If V+ can sink the current, one of the upper input steering diodes conducts and directs current to $+V_S$. Excessively high current levels can flow with increasingly higher $V_{IN}$. As a result, the data sheet specifications recommend that applications limit the input current to 10 mA.

If the supply is not capable of sinking the current, $V_{IN}$ may begin sourcing current to the operational amplifier, and then take over as the source of positive supply voltage. The danger in this case is that the voltage can rise to levels that exceed the operational amplifier absolute maximum ratings.

Another common question involves what happens to the amplifier if an input signal is applied to the input while the power supplies V+ or V– are at 0 V. Again, this question depends on the supply characteristic while at 0 V, or at a level below the input signal amplitude. If the supplies appear as high impedance, then the operational amplifier supply current may be supplied by the input source through the current-steering diodes. This state is not a normal bias condition; the amplifier most likely does not operate normally. If the supplies are low impedance, then the current through the steering diodes can become quite high. The current level depends on the ability of the input source to deliver current, and any resistance in the input path.

If there is any uncertainty about the ability of the supply to absorb this current, external zener diodes must be added to the supply pins, as shown in Figure 8-3. The zener voltage must be selected such that the diode does not turn on during normal operation. However, the zener voltage must be low enough so that the zener diode conducts if the supply pin begins to rise above the safe operating supply voltage level.
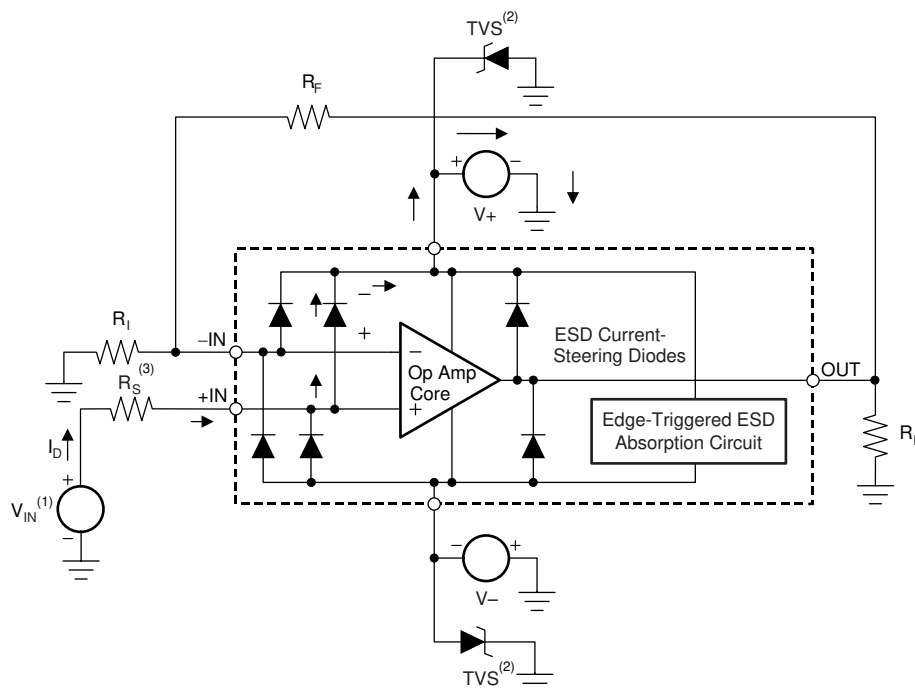
$V_{IN}$ = V+ + 500 mV

TVS: 40 V > $V_{TVSBR\ (min)}$ > V+ ; where $V_{TVSBR\ (min)}$ is the minimum specified value for the transient voltage suppressor breakdown voltage

Suggested value is approximately 5 kΩ in overvoltage conditions.

**Figure 8-3. Equivalent Internal ESD Circuitry Relative to a Typical Circuit Application**

### 8.3.5 MUX-Friendly Inputs

The OPA2182 features a proprietary input stage design that allows an input differential voltage to be applied while maintaining high input impedance. Typically, high-voltage CMOS or bipolar-junction input amplifiers feature antiparallel diodes that protect input transistors from large $V_{GS}$ voltages that may exceed the semiconductor process maximum and permanently damage the device. Large $V_{GS}$ voltages can be forced when applying a large input step, switching between channels, or attempting to use the amplifier as a comparator. For more information, see the *MUX-Friendly Precision Operational Amplifiers* tech note.

The OPA2182 solves these problems with a switched-input technique that prevents large input bias currents when large differential voltages are applied. This input architecture solves many issues seen in switched or multiplexed applications, where large disruptions to RC filtering networks are caused by fast switching between large potentials. The OPA2182 offers outstanding settling performance because of these design innovations, along with built-in slew rate boost and wide bandwidth. The OPA2182 can also be used as a comparator. Differential and common-mode *Absolute Maximum Ratings* still apply relative to the power supplies.

## 8.4 Device Functional Modes

The OPA2182 has a single functional mode, and is operational when the power-supply voltage is greater than 4.5 V (±2.25 V). The maximum power supply voltage for the OPA2182 is 36 V (±18 V).

# 9 Application and Implementation

> **Note**
>
> Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

## 9.1 Application Information

The OPA2182 operational amplifier combines precision offset and drift with excellent overall performance, making the series a great choice for many precision applications. The precision offset drift of only 0.005 µV/°C provides stability over the entire temperature range. In addition, the device pairs excellent CMRR, PSRR, and $A_{OL}$ dc performance with outstanding low-noise operation. As with all amplifiers, applications with noisy or high-impedance power supplies require decoupling capacitors close to the device pins. In most cases, 0.1-µF capacitors are adequate.

The following application examples highlight only a few of the circuits where the OPA2182 can be used.

## 9.2 Typical Applications

### 9.2.1 Strain Gauge Analog Linearization
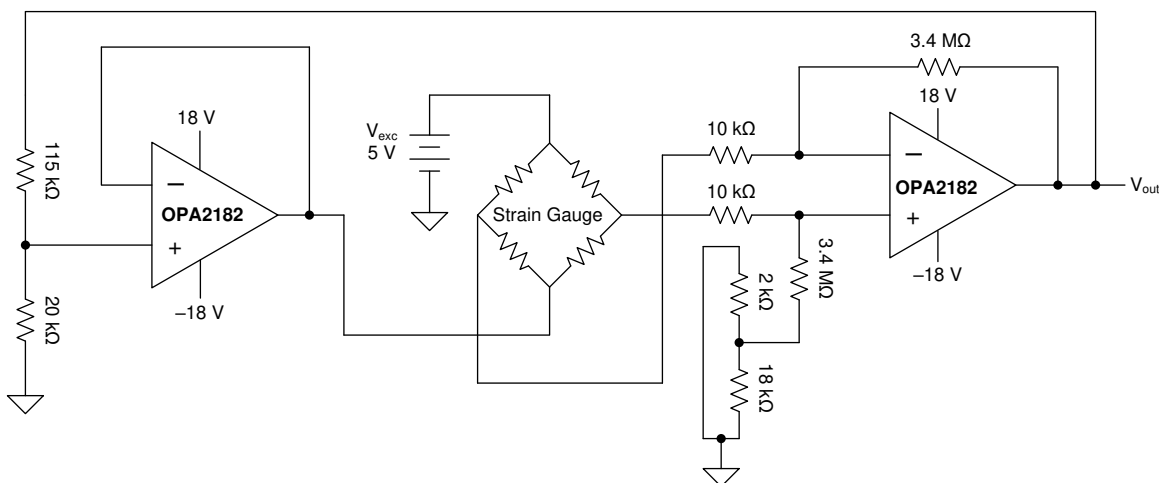


**Figure 9-1. Bridge Sensor Analog Linearization With the OPA2182**

#### 9.2.1.1 Design Requirements

A strain gauge is used to measure an alteration due to external force through the use of electrical resistance in a Wheatstone-bridge configuration. The Wheatstone bridge is used to measure very low values of resistances down in the mΩ range, with precision. An excitation voltage is applied to the bridge, and the output voltage across the middle of the bridge is measured. The total change in output voltage is relatively small, typically in the mV range. Therefore, an op amp is used to amplify the signal. The OPA2182 is designed to construct high-precision amplification.

Use the following parameters for this design example:
- Use the op amp linear output operating range, which is usually specified under the AOL test conditions. The common-mode voltage is equal to the input signal.
- Use an op amp that does not add significant noise to the system or else the small output voltage from the Wheatstone bridge will be lost.
- The input signal must be gained; therefore, use an op amp with low input offset voltage ($V_{OS}$)
- The input signal must be gained; therefore, use an op amp with enough open-loop gain to provide the required amplification

Product Folder Links: *OPA2182*

### 9.2.1.2 Detailed Design Procedure

The bridge sensor signal flow model is shown in Figure 9-2.
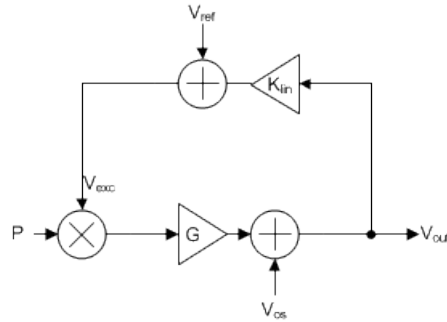


**Figure 9-2. Bridge Sensor Signal Flow Model**

The bridge sensor is modeled as a multiplier, with inputs from an excitation voltage and pressure sensor producing an output voltage given in Equation 1.

$$V_{bridge}(P, V_{exc}) = V_{exc} \times K_p(P)$$

$(1)$

$K_p$ is the sensitivity of the bridge sensor, and is usually specified in mV/V. P represents the pressure relative to the range of the sensor, normalized to a scale from 0 to 1. Solving this equation with the variables given in the signal flow model and solving for $V_{out}$ results in Equation 2.

$$V_{out}(P) = \frac{V_{OS} + V_{ref} \times G \times K_p(P)}{1 - G \times K_{lin} \times K_p(P)}$$

$(2)$

This equation has three variables, $V_{OS}$, G and $K_{lin}$, that require three equations to solve. To solve these equations. values of $K_p$ at no load, midscale and full load conditions are needed for the sensor. With these values, the system can be linearized.

With known values for $K_p$, $K_{lin}$ can be calculated as shown in Equation 3.

$$K_{lin} = \frac{4 \times B_v \times V_{ref}}{(V_{out\_high} - V_{out\_low}) - 2 \times B_v \times (V_{out\_high} + V_{out\_low})}$$

$(3)$

In this equation, $B_v$ represents the bridge nonlinearity which can be calculated as shown in Equation 4.

$$B_v = \frac{K_p(0.5) - \frac{K_p(1) + K_p(0)}{2}}{K_p(1) - K_p(0)}$$

$(4)$

$B_v$ can be solved based on the sensor specifications, and this can then be used to solve for $K_{lin}$. Next the system gain can be calculated using Equation 5 and Equation 6.

$$V_{out\_high} = \frac{V_{OS} + V_{ref} \times G \times K_p(1)}{1 - G \times K_{lin} \times K_p(1)}$$

$(5)$

$$V_{out\_high} = \frac{V_{OS} + V_{ref} \times G \times K_p(0)}{1 - G \times K_{lin} \times K_p(0)}$$

$(6)$

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Solving for $V_{OS}$ in both equations and combining results in Equation 7.

$$V_{out\_high}(1-G\times K_{lin}\times K_p(1)) - V_{ref} \times G\times K_p(1) = V_{out\_low}(1-G\times K_{lin}\times K_p(0)) - V_{ref}\times G\times K_p(0) \tag{7}$$

Solving for G gives Equation 8.

$$G = \frac{V_{out\_high} - V_{out\_low}}{K_p(1)\times(K_{lin}\times V_{out\_high} + V_{ref}) - K_p(0)\times(K_{lin}\times V_{out\_low} + V_{ref})} \tag{8}$$

With both $K_{lin}$ and G now calculated, $V_{OS}$ can be solved as shown in Equation 9.

$$V_{OS} = V_{out\_low}(1-G\times K_{lin}\times K_p(0)) - V_{ref}\times G\times K_p(0) \tag{9}$$

For a sensor with a $K_P$ of 0.0003 mV/V at no load, 0.0017 mV/V mid-scale and 0.00289 mV/V, the corresponding nonlinearity is approximately 4%. Solving for $K_{lin}$, G and $V_{OS}$ will give the values shown in Table 9-1.

**Table 9-1. Example Bridge Calculations**

| $K_{lin}$ | 0.173913 |
|---|---|
| G | 323.8178 |
| VOS | -0.48573 |

### 9.2.1.3 Application Curves

Using the same $K_P$ values used above, the bridge nonlinearity is simulated as 4% peak, the output is a linear 0 to 5V out and the corrected system nonlinearity is approximately ±0.1%.
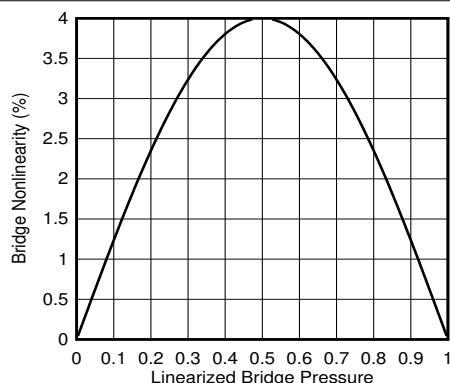


**Figure 9-3. Bridge Nonlinearity**
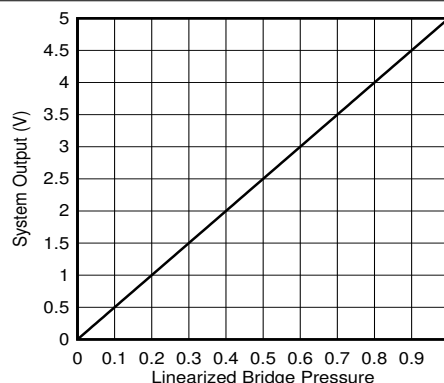


**Figure 9-4. Bridge Output**
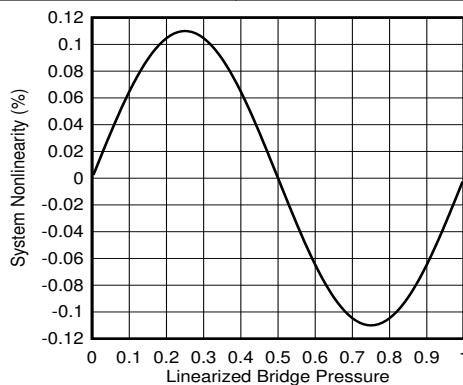


**Figure 9-5. System Nonlinearity**

Product Folder Links: *OPA2182*

### 9.2.2 Rogowski Coil Integrator

Figure 9-6 shows the OPA2182 configured as an active integrator, level shifter and precision voltage reference buffer for a Rogowski coil used to indirectly measure the current of a protection relay with high accuracy. This design has two main signal paths, the first is used to accurately measure the current flowing through the Rogowski coil while a second high-speed path is used to detect a fast transient such as a short circuit. The OPA2182 is selected for this application thanks to its low offset voltage (0.45 µV) and offset drift (0.003 µV/°C) which minimize calibration requirements and ensure higher accuracy across the full temperature range. This device also features flat noise across a wide frequency range which includes DC which improves accuracy and repeatability across a wide range of input currents from the Rogowski coil. Additional information on this design can be found in the *Active Integrator for Rogowski Coil Reference Design with Improved Accuracy for Relay and Breaker*.
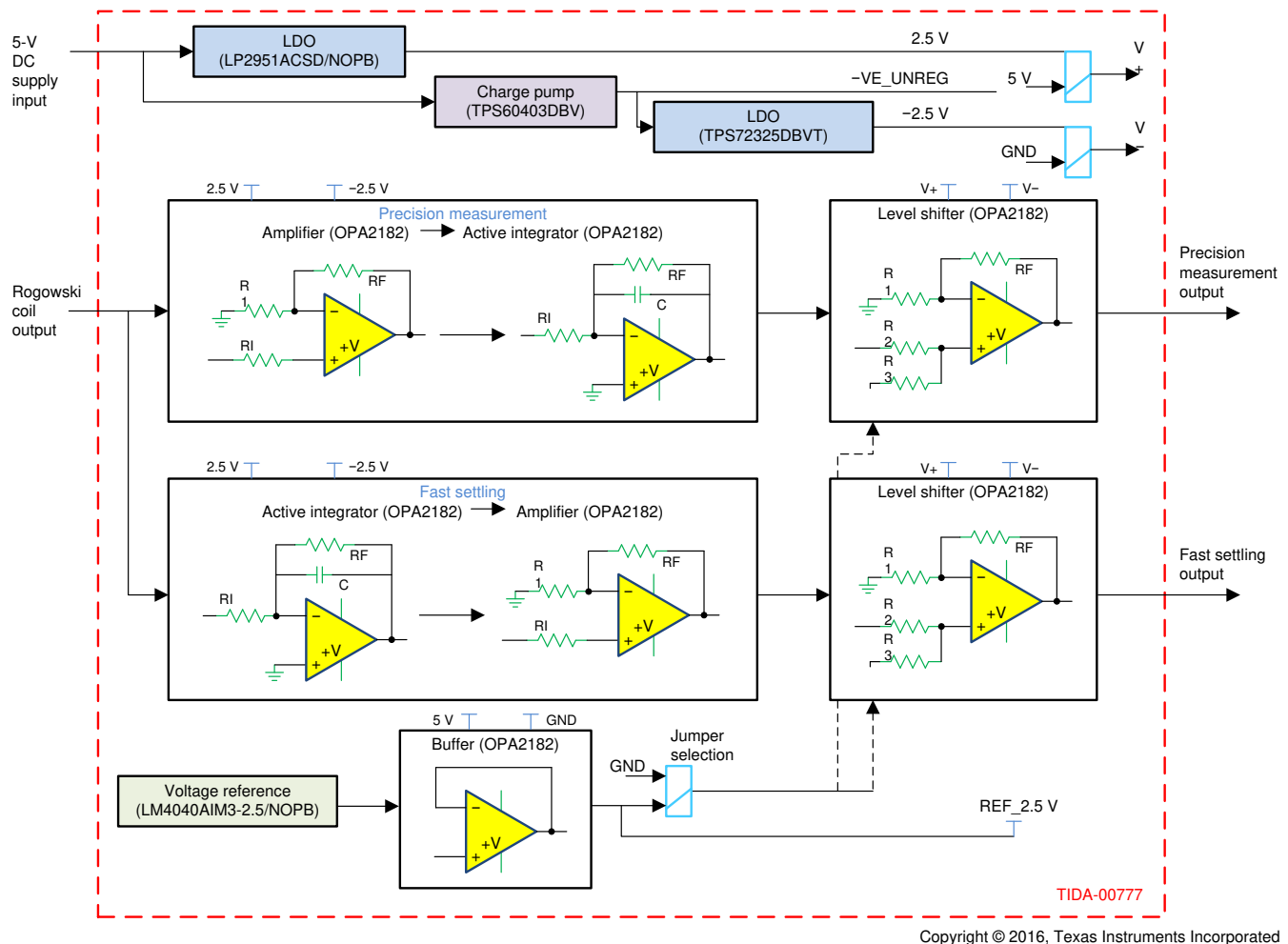


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**Figure 9-6. Programmable Power Supply**

### 9.2.3 System Examples

#### 9.2.3.1 24-Bit, Delta-Sigma, Differential Load Cell or Strain Gauge Sensor Signal Conditioning

OPA2182 is used in a 24-bit, differential load cell or strain gauge sensor signal conditioning system alongside the ADS1225. The OPA2182 amplifier isconfigured in a two-amp instrumentation amplifier (IA) configuration and are band-limited to reduce noise and allow heavy capacitive drive. The load cell is powered by an excitation voltage (denoted $V_{EX}$) of 5-V and provides a differential voltage proportional to force applied. The differential voltage can be quite small and both outputs are biased to $V_{EX}$ / 2.

In this example, the OPA2182 is employed here due to the excellent input offset voltage (0.45 µV) and input offset voltage drift (0.003 µV/°C), the low broadband noise (5.7 nV/$\sqrt{Hz}$) and zero-flicker noise, and excellent linearity and high input impedance. The two-amp IA configuration removes the dc bias and amplifies the differential signal of interest and drives the 24-bit, delta-sigma ADS1225 analog-to-digital converter (ADC) for acquisition and conversion. The ADS1225 features a 100-SPS data rate, single-cycle settling, and simple conversion control with the dedicated START pin.
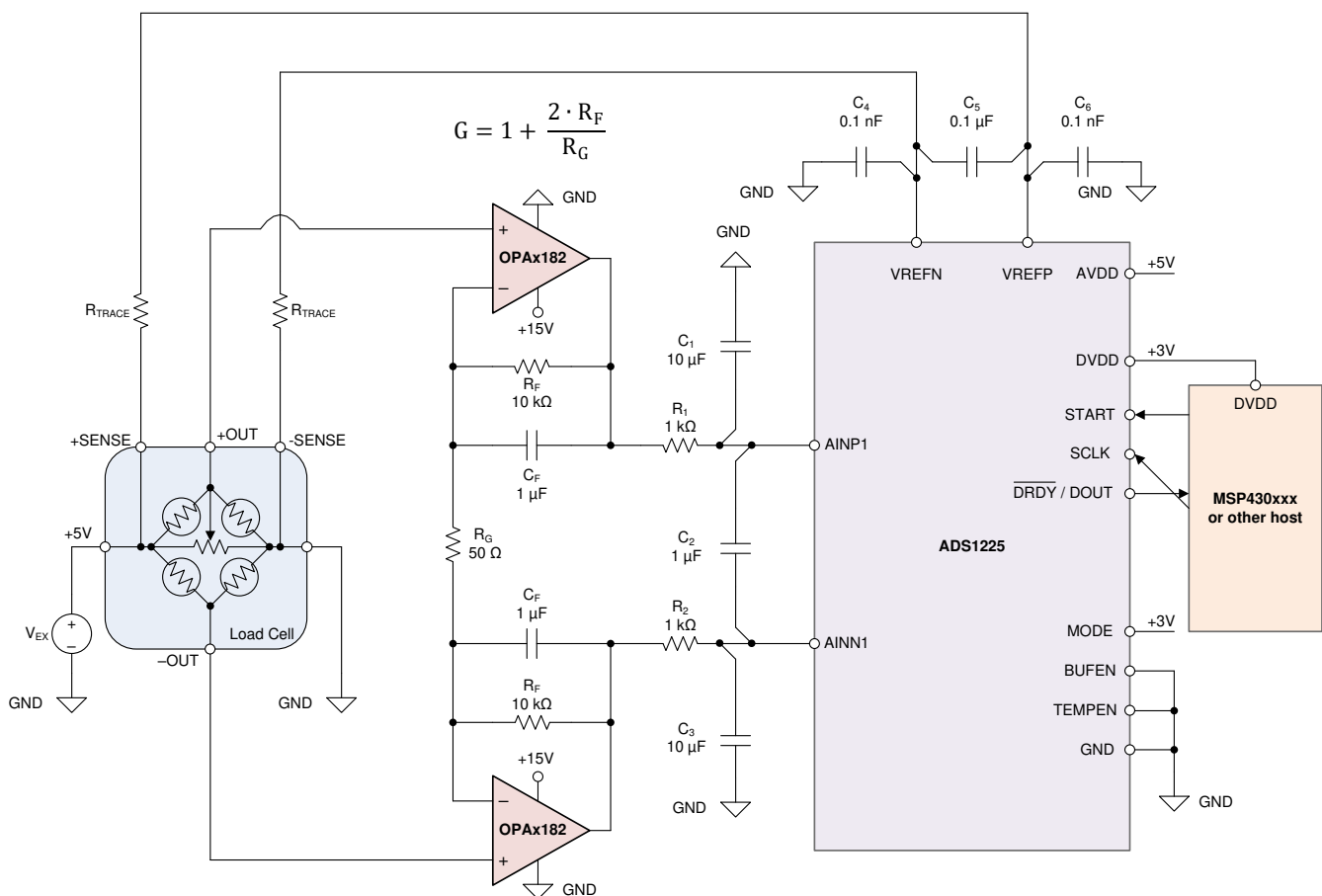


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**Figure 9-7. 24-Bit, Differential Load Cell or Strain Gauge Sensor Signal Conditioning Schematic**

## 9.2.4 Programmable Power Supply

Figure 9-6 shows the OPA2182 configured as a precision programmable power supply using the 16-bit, voltage output DAC8581 and the OPA548 high-current amplifier. This application amplifies the digital-to-analog converter (DAC) voltage by a value of five, and handles a large variety of capacitive and current loads. The OPA2182 in the front-end provides precision and low drift across a wide range of inputs and conditions. Click the following link to download the TINA-TI™ software file: Programmable Power-Supply Circuit.
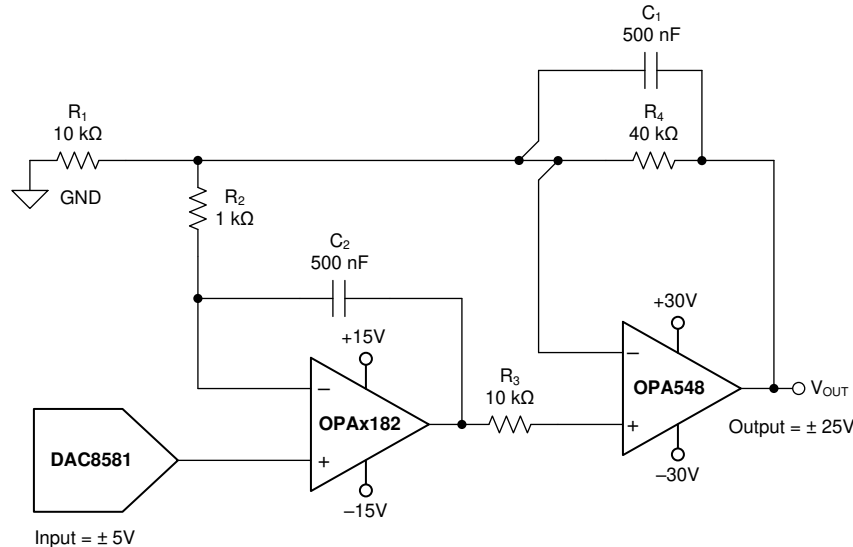


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**Figure 9-8. Programmable Power Supply**

## 9.2.5 RTD Amplifier With Linearization

See *Analog Linearization of Resistance Temperature Detectors* (SLYT442) for an in-depth analysis of Figure 9-9. Click the following link to download the TINA-TI™ software file: RTD Amplifier with Linearization.
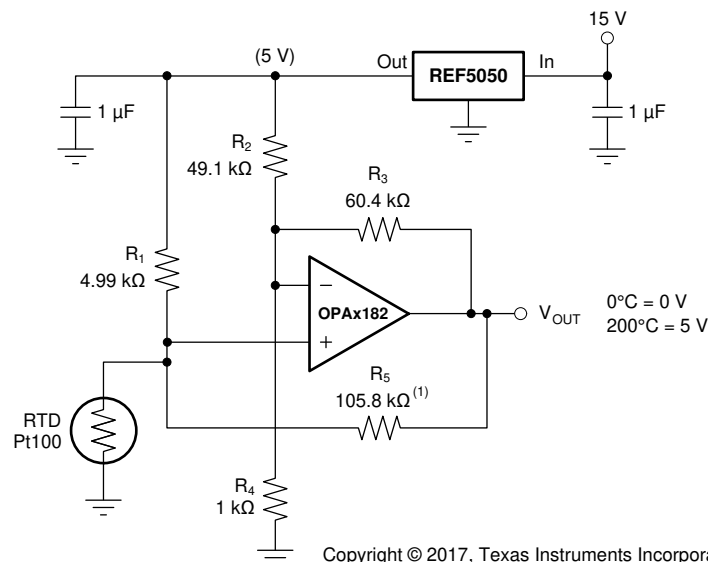


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$R_5$ provides positive-varying excitation to linearize output.

**Figure 9-9. RTD Amplifier With Linearization**

Product Folder Links: *OPA2182*

## 10 Power Supply Recommendations

The OPA2182 is specified for operation from 4.5 V to 36 V (±2.25 V to ±18 V); many specifications apply from –40°C to +125°C. The *Typical Characteristics* presents parameters that can exhibit significant variance with regard to operating voltage or temperature.

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**CAUTION**

Supply voltages larger than 40 V can permanently damage the device (see the *Aboslute Maximum Ratings*).

---

Place 0.1-µF bypass capacitors close to the power-supply pins to reduce errors coupling in from noisy or high-impedance power supplies. For more detailed information on bypass capacitor placement, see the *Layout* section.

## 11 Layout

### 11.1 Layout Guidelines

For best operational performance of the device, use good PCB layout practices, including:

- Noise can propagate into analog circuitry through the power pins of the circuit as a whole and the op amp itself. Bypass capacitors reduce the coupled noise by providing low-impedance power sources local to the analog circuitry.
  - Connect low-ESR, 0.1-µF ceramic bypass capacitors between each supply pin and ground, placed as close as possible to the device. A single bypass capacitor from V+ to ground is applicable for single-supply applications.
- Separate grounding for analog and digital portions of circuitry is one of the simplest and most effective methods of noise suppression. One or more layers on multilayer PCBs are usually devoted to ground planes. A ground plane helps distribute heat and reduces EMI noise pickup. Make sure to physically separate digital and analog grounds paying attention to the flow of the ground current. For more detailed information, see *The PCB is a component of op amp design*.
- To reduce parasitic coupling, run the input traces as far away as possible from the supply or output traces. If these traces cannot be kept separate, crossing the sensitive trace perpendicular is much better as opposed to in parallel with the noisy trace.
- Place the external components as close as possible to the device. As illustrated in Figure 11-1, keep RF and RG close to the inverting input to minimize parasitic capacitance.
- Keep the length of input traces as short as possible. Always remember that the input traces are the most sensitive part of the circuit.
- Consider a driven, low-impedance guard ring around the critical traces. A guard ring can significantly reduce leakage currents from nearby traces that are at different potentials.
- Clean the PCB following board assembly.
- Any precision integrated circuit may experience performance shifts due to moisture ingress into the plastic package. Following any aqueous PCB cleaning process, bake the PCB assembly to remove moisture introduced into the device packaging during the cleaning process. A low temperature, post cleaning bake at 85°C for 30 minutes is sufficient for most circumstances.

For the lowest offset voltage, avoid temperature gradients that create thermoelectric (Seebeck) effects in the thermocouple junctions formed from connecting dissimilar conductors.

- Use low thermoelectric-coefficient conditions (avoid dissimilar metals).
- Thermally isolate components from power supplies or other heat sources.
- Shield operational amplifier and input circuitry from air currents, such as cooling fans.

## 11.2 Layout Example



Place bypass capacitors as close to device as possible (avoid use of vias)

Use ground pours for shielding the input signal pairs

Place components close to device and to each other to reduce parasitic errors

Use a low-ESR, ceramic bypass capacitor
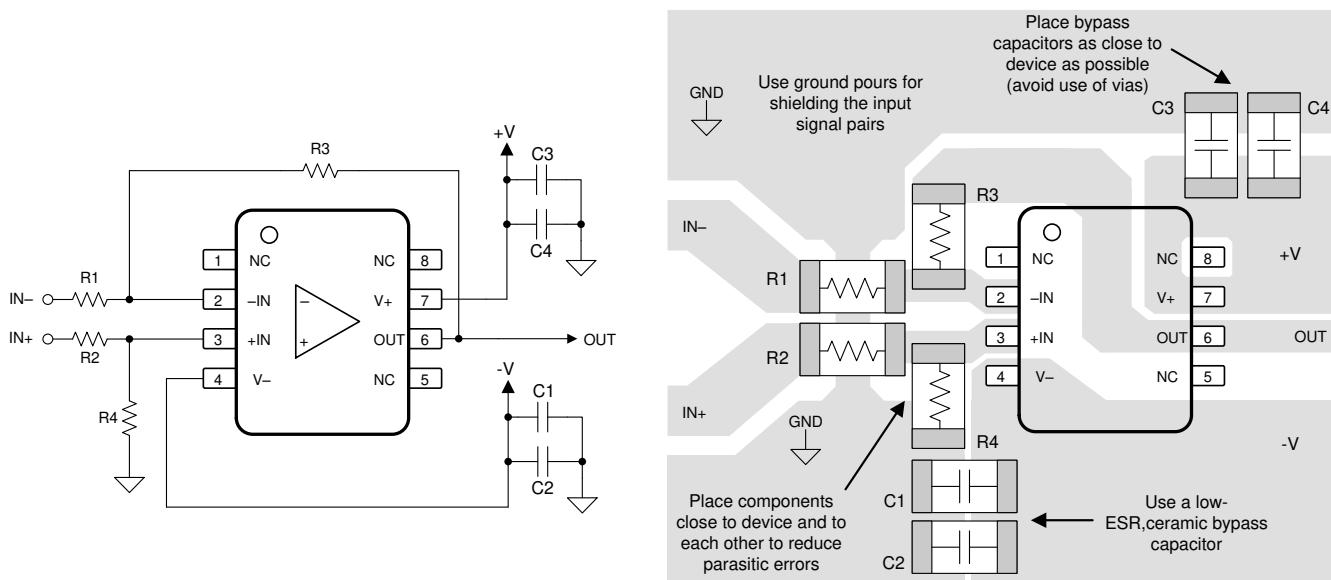
Copyright © 2017, Texas Instruments Incorporated

**Figure 11-1. Operational Amplifier Board Layout for Difference Amplifier Configuration**

Product Folder Links: *OPA2182*

## 12 Device and Documentation Support

### 12.1 Device Support

#### 12.1.1 Development Support

##### 12.1.1.1 TINA-TI™ Simulation Software (Free Download)

TINA-TI™ software is a simple, powerful, and easy-to-use circuit simulation program based on a SPICE engine. TINA-TI simulation software is a free, fully-functional version of the TINA™ software, preloaded with a library of macromodels, in addition to a range of both passive and active models. TINA-TI software provides all the conventional dc, transient, and frequency domain analysis of SPICE, as well as additional design capabilities.

Available as a free download from the Analog eLab Design Center, TINA-TI simulation software offers extensive post-processing capability that allows users to format results in a variety of ways. Virtual instruments offer the ability to select input waveforms and probe circuit nodes, voltages, and waveforms, creating a dynamic quick-start tool.

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**Note**

These files require that either the TINA software or TINA-TI software be installed. Download the free TINA-TI software from the TINA-TI software folder.

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##### 12.1.1.2 TI Precision Designs

TI Precision Designs are available online at http://www.ti.com/ww/en/analog/precision-designs/. TI Precision Designs are analog solutions created by TI's precision analog applications experts and offer the theory of operation, component selection, simulation, complete PCB schematic and layout, bill of materials, and measured performance of many useful circuits.

### 12.2 Documentation Support

#### 12.2.1 Related Documentation

For related documentation see the following:
- Texas Instruments, *Zero-drift Amplifiers: Features and Benefits* application report
- Texas Instruments, *The PCB is a component of op amp design* technical brief
- Texas Instruments, *Operational amplifier gain stability, Part 3: AC gain-error analysis* technical brief
- Texas Instruments, *Operational amplifier gain stability, Part 2: DC gain-error analysis* technical brief
- Texas Instruments, *Using infinite-gain, MFB filter topology in fully differential active filters* technical brief
- Texas Instruments, *Op Amp Performance Analysis* application bulletin
- Texas Instruments, *Single-Supply Operation of Operational Amplifiers* application bulletin
- Texas Instruments, *Tuning in Amplifiers* application bulletin
- Texas Instruments, *Shelf-Life Evaluation of Lead-Free Component Finishes* application report
- Texas Instruments, *Feedback Plots Define Op Amp AC Performance* application bulletin
- Texas Instruments, *EMI Rejection Ratio of Operational Amplifiers* application report
- Texas Instruments, *Analog Linearization of Resistance Temperature Detectors* technical brief
- Texas Instruments, *TI Precision Design TIPD102 High-Side Voltage-to-Current (V-I) Converter* reference guide

### 12.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

### 12.4 Support Resources

TI E2E™ support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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## 12.5 Trademarks

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Bluetooth® is a registered trademark of Bluetooth SIG, Inc.
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## 12.6 Electrostatic Discharge Caution

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

## 12.7 Glossary

**TI Glossary**       This glossary lists and explains terms, acronyms, and definitions.

## 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

## PACKAGING INFORMATION

| Orderable Device | Status (1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan (2) | Lead finish/ Ball material (6) | MSL Peak Temp (3) | Op Temp (°C) | Device Marking (4/5) | Samples |
|---|---|---|---|---|---|---|---|---|---|---|---|
| OPA2182ID | ACTIVE | SOIC | D | 8 | 75 | RoHS & Green | SN | Level-2-260C-1 YEAR | -40 to 125 | OP2182 | Samples |
| OPA2182IDGKR | ACTIVE | VSSOP | DGK | 8 | 2500 | RoHS & Green | SN | Level-2-260C-1 YEAR | -40 to 125 | 26RQ | Samples |
| OPA2182IDGKT | ACTIVE | VSSOP | DGK | 8 | 250 | RoHS & Green | SN | Level-2-260C-1 YEAR | -40 to 125 | 26RQ | Samples |
| OPA2182IDR | ACTIVE | SOIC | D | 8 | 2500 | RoHS & Green | SN | Level-2-260C-1 YEAR | -40 to 125 | OP2182 | Samples |

**(1)** The marketing status values are defined as follows:
**ACTIVE:** Product device recommended for new designs.
**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.
**OBSOLETE:** TI has discontinued the production of the device.

**(2)** **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".
**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.
**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

**(3)** MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

**(4)** There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

**(5)** Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

**(6)** Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

**Important Information and Disclaimer:** The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and

continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

# PACKAGE MATERIALS INFORMATION

## TAPE AND REEL INFORMATION

**REEL DIMENSIONS**



**TAPE DIMENSIONS**



| A0 | Dimension designed to accommodate the component width |
|----|--------------------------------------------------------|
| B0 | Dimension designed to accommodate the component length |
| K0 | Dimension designed to accommodate the component thickness |
| W | Overall width of the carrier tape |
| P1 | Pitch between successive cavity centers |

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**



*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|--------|--------------|-----------------|------|------|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| OPA2182IDGKR | VSSOP | DGK | 8 | 2500 | 330.0 | 12.4 | 5.3 | 3.4 | 1.4 | 8.0 | 12.0 | Q1 |
| OPA2182IDGKT | VSSOP | DGK | 8 | 250 | 330.0 | 12.4 | 5.3 | 3.4 | 1.4 | 8.0 | 12.0 | Q1 |
| OPA2182IDR | SOIC | D | 8 | 2500 | 330.0 | 12.8 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |

**TAPE AND REEL BOX DIMENSIONS**



*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
|---|---|---|---|---|---|---|---|
| OPA2182IDGKR | VSSOP | DGK | 8 | 2500 | 366.0 | 364.0 | 50.0 |
| OPA2182IDGKT | VSSOP | DGK | 8 | 250 | 366.0 | 364.0 | 50.0 |
| OPA2182IDR | SOIC | D | 8 | 2500 | 366.0 | 364.0 | 50.0 |

.228-.244  TYP
[5.80-6.19]

A

PIN 1 ID AREA

1

8

6X .050
[1.27]

2X

.150
[3.81]

.189-.197
[4.81-5.00]
NOTE 3

4

5

B

.150-.157
[3.81-3.98]
NOTE 4

8X .012-.020
[0.31-0.51]

⌖ .010 [0.25] Ⓜ C A B

C

SEATING PLANE

◠ .004 [0.1] C

4X (0°-15°)

.069 MAX
[1.75]

SEE DETAIL A

4X (0°-15°)

.005-.010  TYP
[0.13-0.25]

.010
[0.25]

0° - 8°

.016-.050
[0.41-1.27]

(.041)
[1.04]

.004-.010
[0.11-0.25]

DETAIL A
TYPICAL

4214825/C   02/2019

NOTES:

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches.
   Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
   exceed .006 [0.15] per side.
4. This dimension does not include interlead flash.
5. Reference JEDEC registration MS-012, variation AA.

8X (.061 )
[1.55]

1

8X (.024)
[0.6]

6X (.050 )
[1.27]

4

SYMM
℄

SEE
DETAILS

8

SYMM
℄

(R.002 ) TYP
[0.05]

5

(.213)
[5.4]

LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:8X

METAL

SOLDER MASK
OPENING

EXPOSED
METAL

.0028 MAX
[0.07]
ALL AROUND

NON SOLDER MASK
DEFINED

SOLDER MASK
OPENING

METAL UNDER
SOLDER MASK

EXPOSED
METAL

.0028 MIN
[0.07]
ALL AROUND

SOLDER MASK
DEFINED

SOLDER MASK DETAILS

4214825/C   02/2019

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

8X (.061 )
[1.55]

SYMM
¢

1

8X (.024)
[0.6]

SYMM
¢

8

(R.002 ) TYP
[0.05]

5

6X (.050 )
[1.27]

4

(.213)
[5.4]

SOLDER PASTE EXAMPLE
BASED ON .005 INCH [0.125 MM] THICK STENCIL
SCALE:8X

4214825/C   02/2019

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate
   design recommendations.
9. Board assembly site may have different recommendations for stencil design.

## DGK (S−PDSO−G8)      PLASTIC SMALL−OUTLINE PACKAGE



4073329/E 05/06

NOTES:   A.  All linear dimensions are in millimeters.
          B.  This drawing is subject to change without notice.
       C  Body length does not include mold flash, protrusions, or gate burrs.  Mold flash, protrusions, or gate burrs shall
             not exceed 0.15 per end.
       D  Body width does not include interlead flash. Interlead flash shall not exceed 0.50 per side.
          E.  Falls within JEDEC MO−187 variation AA, except interlead flash.
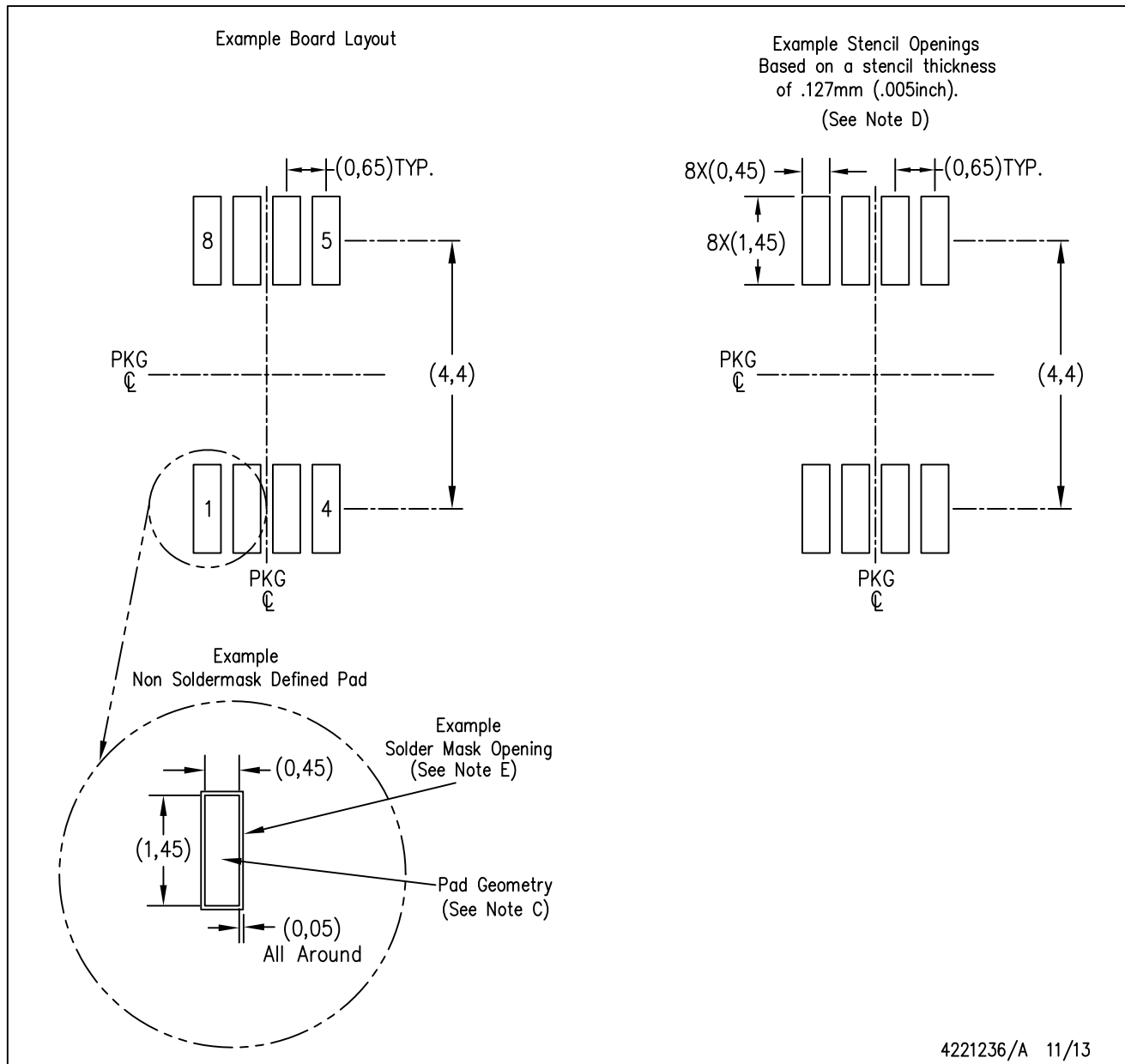
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DGK (S–PDSO–G8)                    PLASTIC SMALL OUTLINE PACKAGE

Example Board Layout

├──┤(0,65)TYP.

8 □□□ 5

PKG ₵ ──────────────── (4,4)

1 □□□ 4

PKG ₵

Example
Non Soldermask Defined Pad

Example
Solder Mask Opening
(See Note E)

├─── (0,45)

(1,45)

├─ (0,05)
All Around

Pad Geometry
(See Note C)

Example Stencil Openings
Based on a stencil thickness
of .127mm (.005inch).
(See Note D)

8X(0,45) ─►|  |◄─    |◄──┤(0,65)TYP.

8X(1,45)

PKG ₵ ──────────────── (4,4)

PKG ₵

4221236/A  11/13

NOTES:  A.  All linear dimensions are in millimeters.
        B.  This drawing is subject to change without notice.
        C.  Publication IPC–7351 is recommended for alternate designs.
        D.  Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should
            contact their board assembly site for stencil design recommendations.  Refer to IPC–7525 for other stencil recommendations.
        E.  Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

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