Carson Schubert

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EDUCATION

The University of Texas at Austin

B.S Electrical and Computer Engineering (GPA: 3.89)

Dec 2020

Focus: Communications, Signal Processing, Networks and Systems / Data Science and Information Processing *Relevant Coursework:* Data Structures and Algorithms, Software Design, Embedded Systems, Circuit Theory

RELEVANT EXPERIENCE

NASA Glenn Research Center | Machine Learning Intern

Aug 2018 - Dec 2018

- Developed a reinforcement learning algorithm (agent) to run onboard an orbiting satellite which optimizes data downlink autonomously, maximizing data throughput and reducing human interaction
- Repurposed existing simulation tools written in MATLAB to generate realistic training episodes quickly
- Wrote an OpenAI Gym environment in Python to facilitate the use of training episodes and provide agent rewards
- Trained a neural network inside this simulation environment using PyTorch to approximate agent's policy

Texas Spacecraft Laboratory | Seeker Vision Flight Hardware/Software Lead

Sep 2017 - May 2018

- Developed a visual navigation system capable of running onboard an SBC for NASA JSC's Seeker CubeSat Mission
- · Aided in development of a convolutional neural network for target identification using Google's TensorFlow
- Designed, implemented, and unit tested flight software in C to handle boot sequence, facilitate vision algorithms, and communicate with the main flight computer via Ethernet
- Implemented two tier process monitoring between Bash, C, and Python resulting in zero crashes during testing
- Wrote a custom suite of bash scripts to characterize performance onboard target hardware, leading to development of lean and fast algorithms
- Created technical documents detailing setup of mission hardware/testing procedures to simplify integration
- Final system selected for flight in April 2019 over competing solutions due to its stability when integrated

Nate Controls | *Cloud Engineering Intern*

June 2018 - Aug 2018

- Developed an application to connect an arbitrary number of IOT devices to a wireless access point via a captive portal, allowing set up of devices in the field without company interaction for the first time
- Designed and wrote a new device backend from scratch in Typescript using AWS Lambda, DynamoDB, and S3
- Implemented an automated testing workflow using Jest for use on all future Typescript applications

PROJECTS

IEEE Region 5 Robotics | *Algorithms and Control Lead*

Jan 2017 - May 2017

- Implemented closed-loop control of the robot using infrared sensors, rotary encoders, and a 3-axis gyroscope which increased reliability of robot performance in-game
- Integrated all sensors using I2C based GPIO expanders and custom drivers written in Python

Chain Reaction Robotics (FRC 6171) | Captain

Oct 2015 - Aug 2016

- Co-founded team and secured over \$20,000 in grants and donations to get team off the ground
- Led the development and fabrication of all subsystems to their successful integration in six weeks
- Developed Java software for closed-loop autonomous and piloted control of the robot for precise movement
- · Led the team to the Rookie-All-Star award at Dallas Regional and a spot in World Championships

SKILLS

Programming Languages: C, C++, Python, Java, Javascript, Typescript, Bash, MATLAB

Tools/Software: Git, GitLab CI/CD, PyTorch, OpenCV, AWS, NodeJS, Unix Terminal, Shell/Bash scripting, Jupyter **Instruments & Machines:** 3D Printer, Laser Cutter, Soldering Iron, Drill Press, Belt Sander

ACTIVITIES/HONORS

Student Engineering Council, University of Texas at Austin **1**st **Place,** NASA International SpaceApps Hackathon, Cleveland Event

Sep 2017 – Present Oct 2018