

# Bounded Diameter Minimum Spanning Trees

## Literature Survey and Related Problems

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Given a set of points  $P = \{p_i\}_{i=1}^n$ . The euclidean graph  $G$  induced by  $P$  is a weighted complete graph  $G = (V, E)$ , where cost(or weight) of each edge is distance between the two points.

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# BDBCST Problem

- Given graph  $G = (V, E)$  and a cost function  $W(e) \in \mathbb{Z}^+ \forall e \in E$  and two positive integers  $C$  and  $D$ .
- Find a spanning tree  $T$  for  $G$  such that  $\sum_{e \in p} W(e) \leq C$  and  $\sum_{e \in p} W(e) \leq D$  for all simple paths  $p$  in  $T$ .

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- Given graph  $G = (V, E)$  and a cost function  $W(e) \in \mathbb{Z}^+ \forall e \in E$  and two positive integers  $C$  and  $R$  and also a distinguished vertex  $v \in V$  as root.
- Find a spanning tree  $T$  for  $G$  such that  $\sum_{e \in p} W(e) \leq C$  and  $\sum_{e \in p} W(e) \leq R$  for all simple paths  $p$  in  $T$  starting from  $v$ .

# Steiner MDST Problem

- Given graph  $G = (V, E)$  a subset of  $S$  of  $V$ , and a cost function  $W(e) \in \mathbb{Z}^+ \forall e \in E$
- Find a steiner tree  $T = (V_T, E_T)$  where  $S \subseteq V_T \subseteq V$  of  $G$  such that  $\max_{\text{simple path } p \in T} \sum_{e \in p} W(e)$  is minimised.

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## GMDST Problem and Analysis

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Recall Geometric Minimum Diameter Spanning Tree Problem. Authors of the paper [1] tried to a  $\mathcal{O}(n^3)$  algorithm for solving the problem. Let's first see two definitions,

- A point P in set S is **monopole** if all the the remaining points are connected to it.
- A spanning tree of n point set is **monopolar** if there exists a monopole.
- A spanning tree of n point set is **dipolar** if there exist two points such that all the remaining points are directly connected to either of two points

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## Algorithm Analysis Continued...

- **FIND-MIN-DPST(S)**: for every two points  $p_i$  and  $p_j \in S$ , where  $i \neq j$  as possible centers of dipolar MDST and select that pair that give minimum diameter

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- Here we have presented an  $\theta(n^3)$  algorithm for finding minimum diameter spanning tree of set of  $n$  point in the plane.
- This result is applicable to any graphs whose edge satisfies triangle inequality.
- It is also proven that finding minimum diameter min cost spanning tree is NP Hard. But bounded diameter bounded cost spanning tree is NP complete.
- The proof BDBCST problem is in NP comes from the fact that the most heavy weighted simple path must be a path connecting two leaf nodes, we may randomly guess  $n-1$  edges and check if the tree satisfies the constraints in polynomial time.

# References I



J.-M. Ho, D. Lee, C.-H. Chang, and C. Wong, “Minimum diameter spanning trees and related problems,” *SIAM J. Comput.*, vol. 20, pp. 987–997, 10 1991.

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