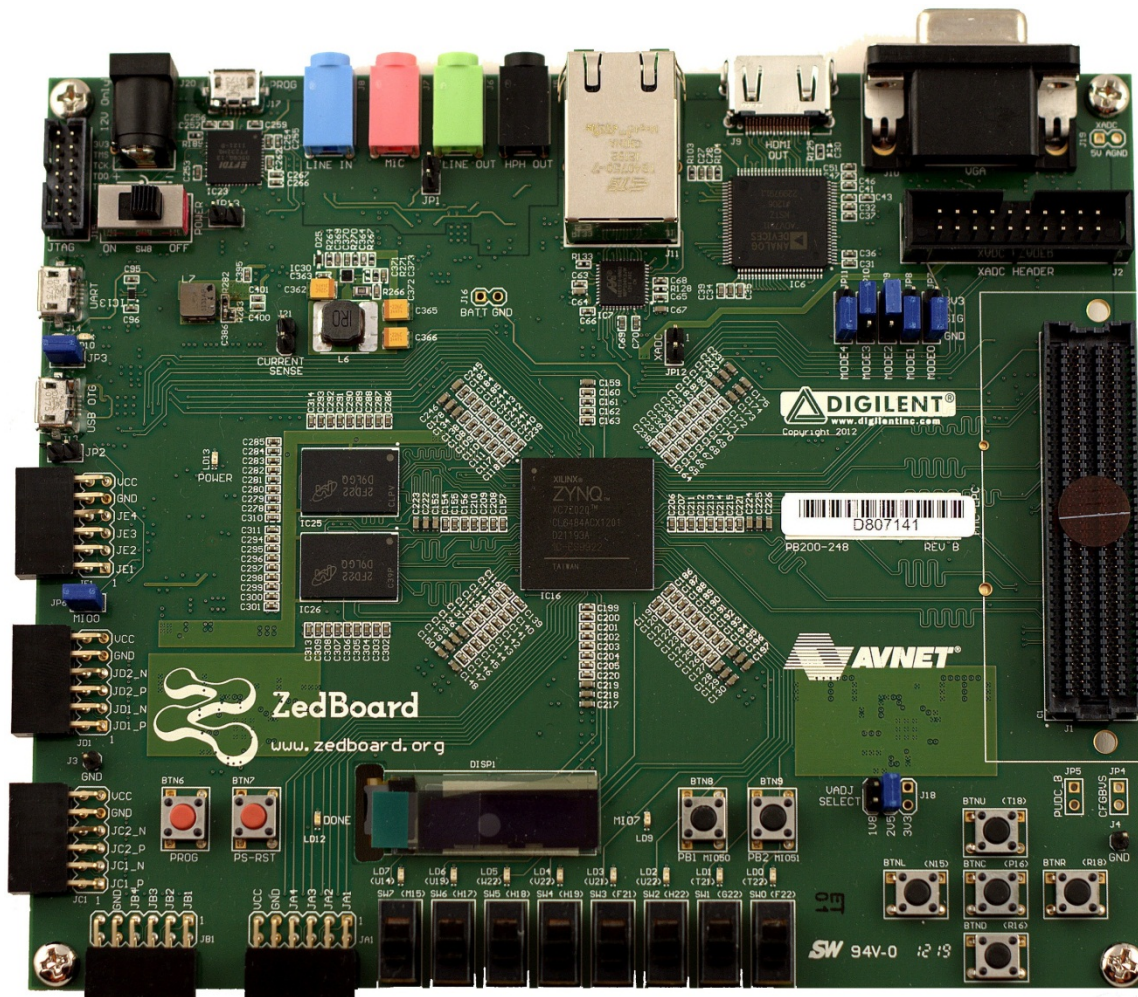


ZedBoard

(Zynq™ Evaluation and Development)

Configuration and Booting Guide



Version 1.1
August 2012

Table of Contents

Introduction.....	2
Reference Design Requirements.....	2
Software	2
Hardware.....	2
Hardware Design Block Diagram.....	3
Supplied Files.....	4
First Things First.....	5
Setting Up the ZedBoard Development Board	5
Extract the Zip File	6
PC Setup.....	6
Installing the UART Driver and Virtual COM Port	6
Installing a Serial Console on a Windows 7 Host.....	6
JTAG Configuration Mode	7
Application Download	7
GPIO Test Demo.....	9
SDK Software Tasks.....	10
Create the SDK Workspace	10
Create the Board Support Package	14
Import the GPIO Test Software Application	16
Running the GPIO Test Software Application	18
Create the First Stage Boot Loader	23
Create the Boot Image	24
Booting From the SD Card	26
Prepare the SD Card.....	26
GPIO Test Demo.....	27
Booting From QSPI Flash.....	28
Program the QSPI Flash.....	28
GPIO Test Demo.....	36
Where to Get More Information	37
ZedBoard Website	37
Xilinx Website	37
Revision History	37

Introduction

This document provides an introduction to the available configuration and processor boot modes of the Avnet ZedBoard development board. The example design used in this guide is a basic Zynq™-7000 All Programmable SoC design implemented and tested on the Avnet ZedBoard development board. For more information about this provided design or to build it for yourself please consult the ZedBoard: Zynq-7000 EPP Concepts, Tools, and Techniques hands-on guide found at www.zedboard.org/design. Using this example design this guide will show you how to use the JTAG configuration mode of the ZedBoard as well as how to boot the processor and configure the programmable logic of the Zynq-7000 device using the SD card and QSPI boot modes. The tasks performed in this guide follow a logical progression such that it is expected that users will start at the beginning and work their way toward the end.

Reference Design Requirements

Software

The software requirements for this reference design are:

- Linux, Windows XP, Windows 7
www.xilinx.com/ise/ossupport/index.htm
- Xilinx ISE Design Suite 14.1, with PlanAhead and SDK

Hardware

The hardware setup for this reference design is:

- Computer with 1.1 GB RAM and 1.1 GB virtual memory (recommended)
www.xilinx.com/ise/products/memory.htm
- Avnet ZedBoard development board
- USB-A to micro-B cables
 - UART
 - JTAG
- Power supply (12V)

Hardware Design Block Diagram

The hardware platform for this guide is based on the Processor System (PS) configuration and Programmable Logic (PL) bitstream described in the ZedBoard: Zynq-7000 EPP Concepts, Tools, and Techniques hands-on guide found at www.zedboard.org/design. The following figure shows a high-level block diagram of the hardware design. The design requires:

- Z7020 Zynq-7000 AP SoC
- 512MB DDR3 SDRAM
- 256Mbit QSPI Flash
- USB UART Bridge Serial Port
- LEDs and push button switches
- Timer

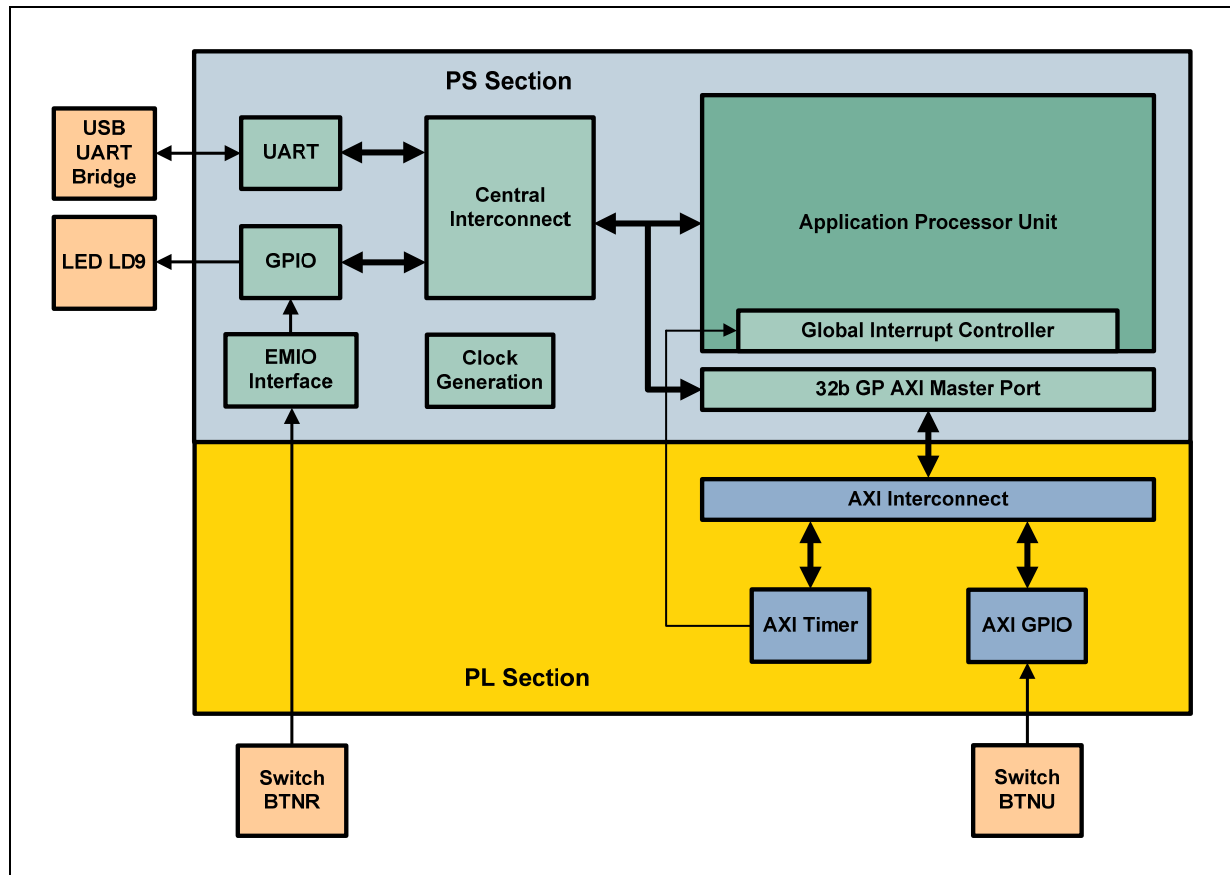


Figure 1 – Reference Design Block Diagram

Supplied Files

The following directory structure is included with this reference design:

boot_image: Empty folder to use to create new BOOT.BIN boot image.

demo: Contains the script files, boot image, and application executables:

BOOT.BIN: Boot image of First Stage Boot Loader (FSBL), PL bistream, and GPIO test application.

bootimage.bif: Boot image information text file.

cp_from_sdk.bat: Batch file to copy hardware bitstream and software executables from the SDK workspace.

gpio_test_0.elf: The golden ARM executable for the GPIO test application.

load_bits.tcl: TCL script to load the PL bitstream via XMD.

make_bootbin.bat: Batch file to run the command to create the boot image file.

ps7_init.tcl: TCL script to initialize the ARM processor.

run_gpio_test.bat: Batch file to run the commands to load the PL bitstream of the hardware design, initialize the processor, and download the GPIO test application.

run_uboot.bat: Batch file to run the commands to initialize the processor and download the u-boot application.

system.bit: The golden FPGA bitstream of the hardware design required to run the GPIO test application.

u-boot_autoboot_disabled.elf: The golden ARM executable for the u-boot application used to program the QSPI Flash.

xmd.ini: Command file used by XMD to configure the PL with the hardware bitstream, initialize the processor, and download the software applications.

zynq_fsbl_0.elf: The golden ARM executable for the Zynq FSBL.

doc: Contains documentation for this design:

ZedBoard_boot_guide_IDS14_1_v1_1.pdf: This document.

pa: Contains the PlanAhead hardware project and SDK workspace files and folders.

SDK_sw: Contains the GPIO test software application source files.

boot_image_golden.zip: Contains pre-built BOOT.BIN boot image for this design.

demo_golden.zip: Contains the golden copies of the files in the demo folder.

First Things First

Setting Up the ZedBoard Development Board

Refer to the following figure and perform the following steps to set up the board for running the applications.

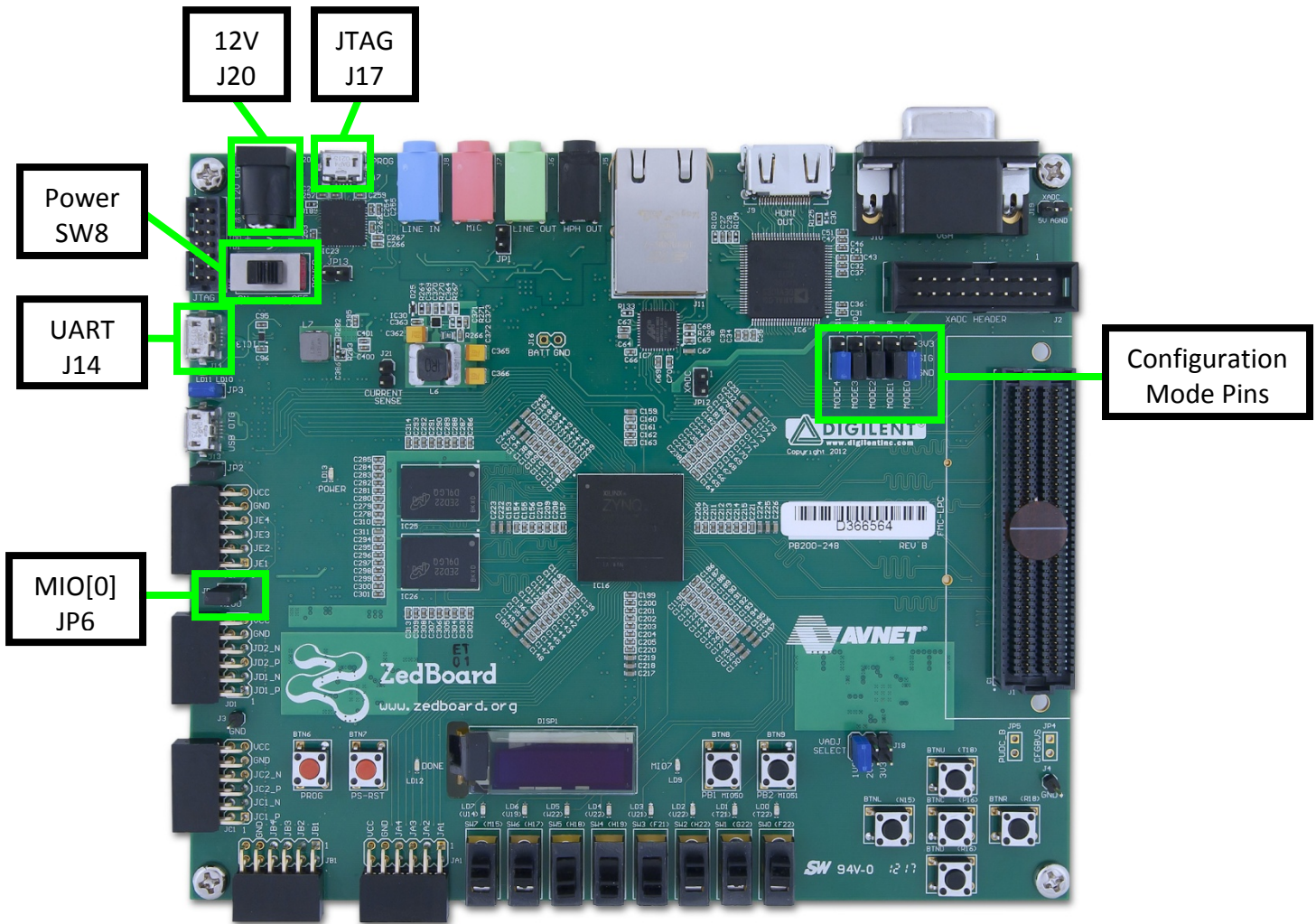


Figure 2 - ZedBoard Development Board

1. Verify a jumper is installed on JP6 to enable the processor to boot from the SD card.
2. Plug a USB cable into the PC and the JTAG micro-B USB connector (J17).
3. Plug a USB cable into the PC and the UART micro-B USB connector (J14).
4. Plug the 12V power supply into the barrel jack (J20). Do not turn the board on.

Extract the Zip File

Since you are reading this guide you have probably already extracted the zip file associated with this tutorial guide. Using Windows™ Explorer navigate to the folder where the zip file was extracted (<installation> folder). ***Make sure there are NO SPACES in this path.*** The Xilinx SDK, which is used later in this guide, does not tolerate spaces in this file path.

PC Setup

Follow the figure below to connect the ZedBoard to the development host PC to establish the USB connections for the UART and JTAG programming.

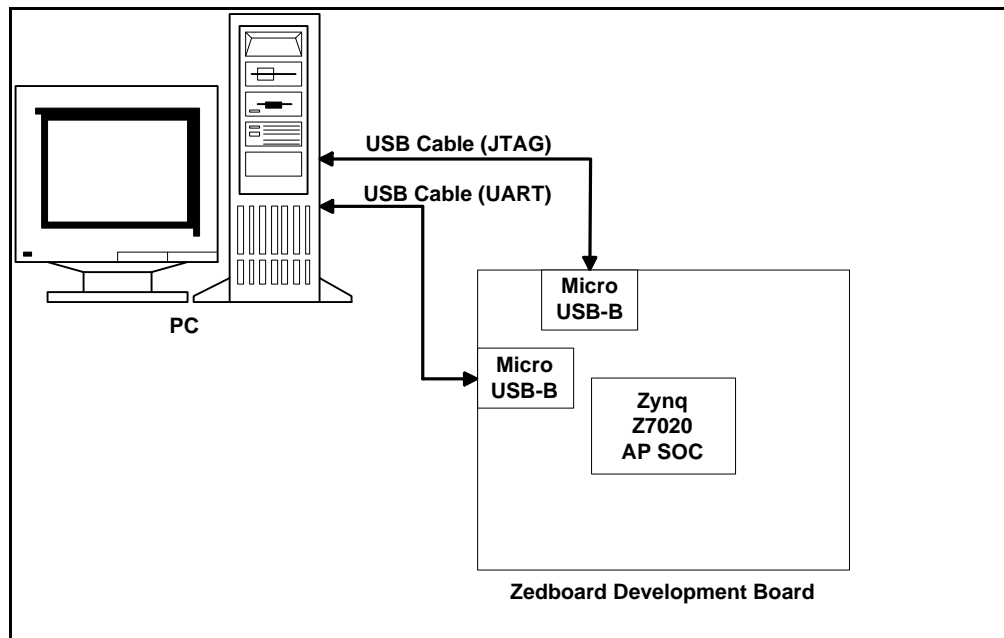


Figure 3 – Board Connection Setup

Installing the UART Driver and Virtual COM Port

If the ZedBoard development board has not been connected to the host PC before, it may be necessary to install the software driver for the virtual COM port. The driver installation for the Cypress CY7C64225 USB-UART bridge is described in detail in the [CY7C64225 Setup Guide](http://www.zedboard.org/sites/default/files/CY7C64225_Setup_Guide_1_1.pdf) available at http://www.zedboard.org/sites/default/files/CY7C64225_Setup_Guide_1_1.pdf.

Installing a Serial Console on a Windows 7 Host

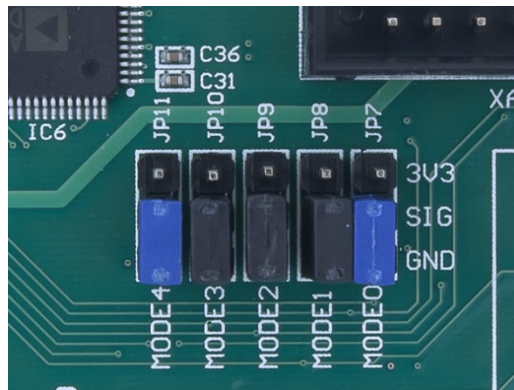
Starting with Windows 7, Microsoft no longer includes the HyperTerminal terminal emulator software. However, this example design requires use of terminal emulation software for a serial console connection to the ZedBoard Development Board. A suitable free and open-source replacement for HyperTerminal is TeraTerm. Download and install instructions for TeraTerm can be found at <http://en.sourceforge.jp/projects/ttssh2>. As an alternative the Terminal applet in the Xilinx SDK may also be used.

JTAG Configuration Mode

You can load the FPGA and run the example software application without building the design by using the demo scripts and the pre-built hardware bitstream and software application elf files. You must have the Xilinx tools installed on your host, and have the hardware set up and connected as per the previous steps.

Application Download

1. Verify the ZedBoard is powered off and that the configuration Mode jumpers are set for JTAG mode (all pins shunted to GND) as in the figure below:



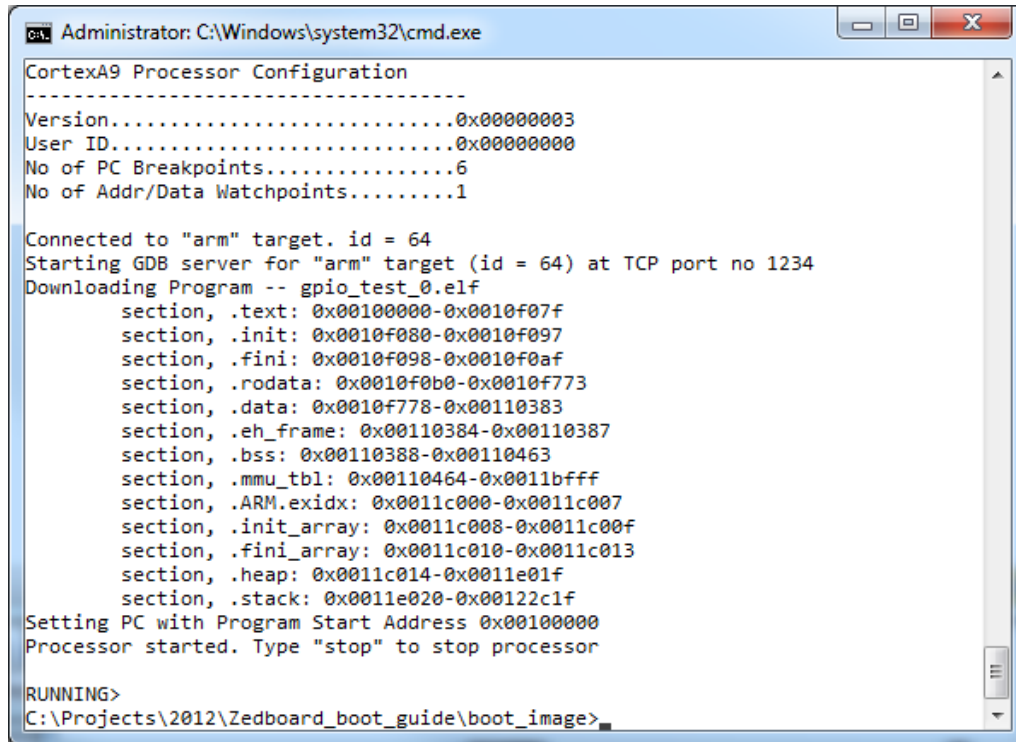
2. Slide the power switch (SW8) to the ON position. You will see the green 'power good' LED (LD13) illuminate.
3. Navigate to Control Panel → Device Manager → Ports (COM & LPT) and identify the COM port connected to the ZedBoard. Start a serial terminal session for the identified COM port and set the serial port parameters to **115200** baud rate, **no** parity, **8** bits, **1** stop bit and no flow control.
4. Open a command window in the **<installation>\demo** folder and enter:

```
run_gpio_test.bat
```

This batch file sets the proper environment variables and creates the xmd.ini script of commands to be used by the Xilinx Microprocessor Debugger (XMD) tool to program the PL bitstream, initialize the processor, download the application code, and begin execution on the system by performing the following commands automatically:

```
source load_bits.tcl
connect arm hw
source ps7_init.tcl
ps7_init
dow gpio_test_0.elf
run
exit
```


- The FPGA bitstream will be downloaded, followed by the executable file for the software application. Do not close the command window.

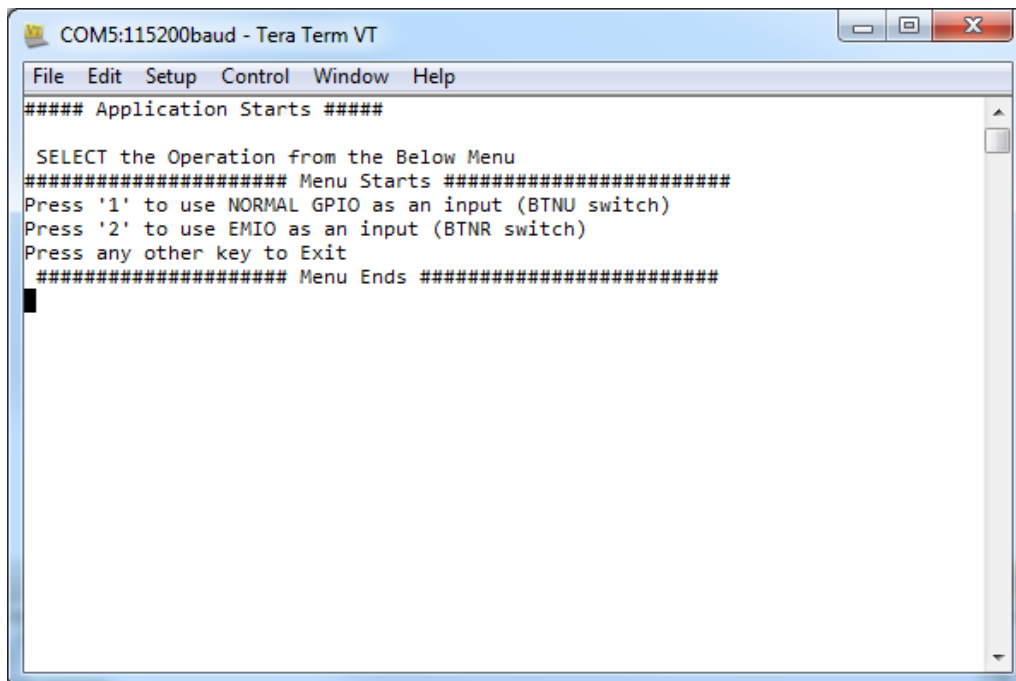


```
Administrator: C:\Windows\system32\cmd.exe
CortexA9 Processor Configuration
-----
Version.....0x00000003
User ID.....0x00000000
No of PC Breakpoints.....6
No of Addr/Data Watchpoints.....1

Connected to "arm" target. id = 64
Starting GDB server for "arm" target (id = 64) at TCP port no 1234
Downloading Program -- gpio_test_0.elf
    section, .text: 0x00100000-0x0010f07f
    section, .init: 0x0010f080-0x0010f097
    section, .fini: 0x0010f098-0x0010f0af
    section, .rodata: 0x0010f0b0-0x0010f773
    section, .data: 0x0010f778-0x00110383
    section, .eh_frame: 0x00110384-0x00110387
    section, .bss: 0x00110388-0x00110463
    section, .mmu_tbl: 0x00110464-0x0011bfff
    section, .ARM.exidx: 0x0011c000-0x0011c007
    section, .init_array: 0x0011c008-0x0011c00f
    section, .fini_array: 0x0011c010-0x0011c013
    section, .heap: 0x0011c014-0x0011e01f
    section, .stack: 0x0011e020-0x00122c1f
Setting PC with Program Start Address 0x00100000
Processor started. Type "stop" to stop processor

RUNNING>
C:\Projects\2012\Zedboard_boot_guide\boot_image>
```

- When the executable has finished loading and is ready to run you should see the following in your serial terminal window:



```
COM5:115200baud - Tera Term VT
File Edit Setup Control Window Help
##### Application Starts #####

  SELECT the Operation from the Below Menu
##### Menu Starts #####
Press '1' to use NORMAL GPIO as an input (BTNU switch)
Press '2' to use EMIO as an input (BTNR switch)
Press any other key to Exit
##### Menu Ends #####
```

GPIO Test Demo

The GPIO Test application running on the ZedBoard takes user input to select which push-button switch is used to trigger the timer to turn the LED on and off.

1. Follow the screen prompts to select the push button input. One push button is routed to the AXI GPIO peripheral (BTNU) and the other is routed to the CPU GPIO (BTNR) through the EMIO interface between the PS and PL sections. Run the application as many times as you wish and alternate which push button is selected. Leave the terminal window open when you are done. We will reuse this terminal session again later.

```

COM5:115200baud - Tera Term VT
File Edit Setup Control Window Help
Select =
Press Switch 'BTNU' push button on board
$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$
BTNU PUSH Button pressed
LED 'LD9' Turned OFF
timer start
Wait for the Timer interrupt to trigger
$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$

@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@
Inside Timer ISR
LED 'LD9' Turned ON
Timer ISR Exit

@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@

#####
Press '0' to go to Main Menu
Press any other key to remain in AXI GPIO Test
#####

```

SDK Software Tasks

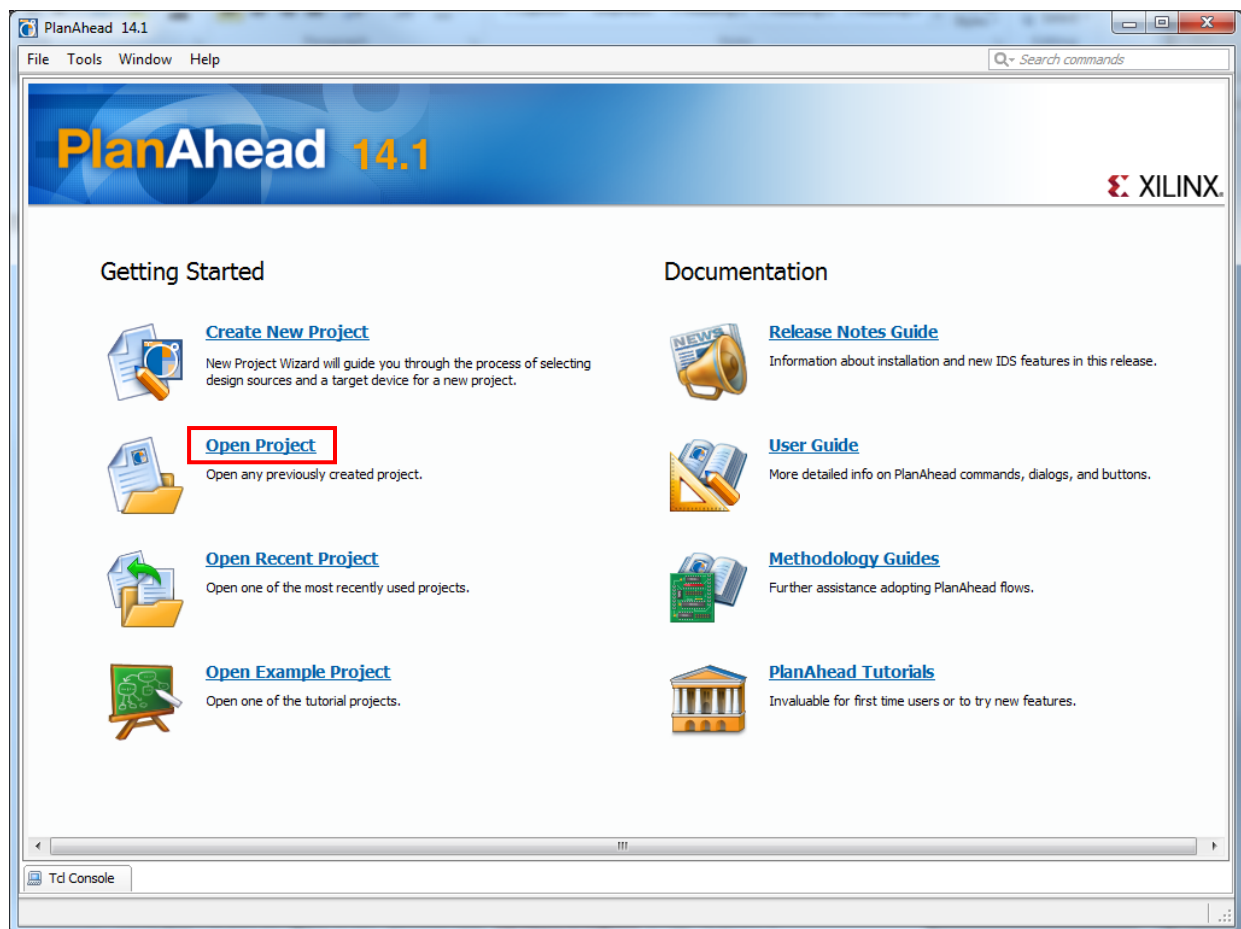
This aspect of the design is performed inside a SDK workspace. As you may know, the Xilinx SDK is the Integrated Design Environment (IDE) where all software related tasks are performed for both Linux and standalone (bare metal) software application development. Here we will import the pre-built GPIO test software application that is described in the ZedBoard CTT guide and create the Zynq First Stage Boot Loader (FSBL) that we will copy to the SD card and boot on the ZedBoard.

Create the SDK Workspace

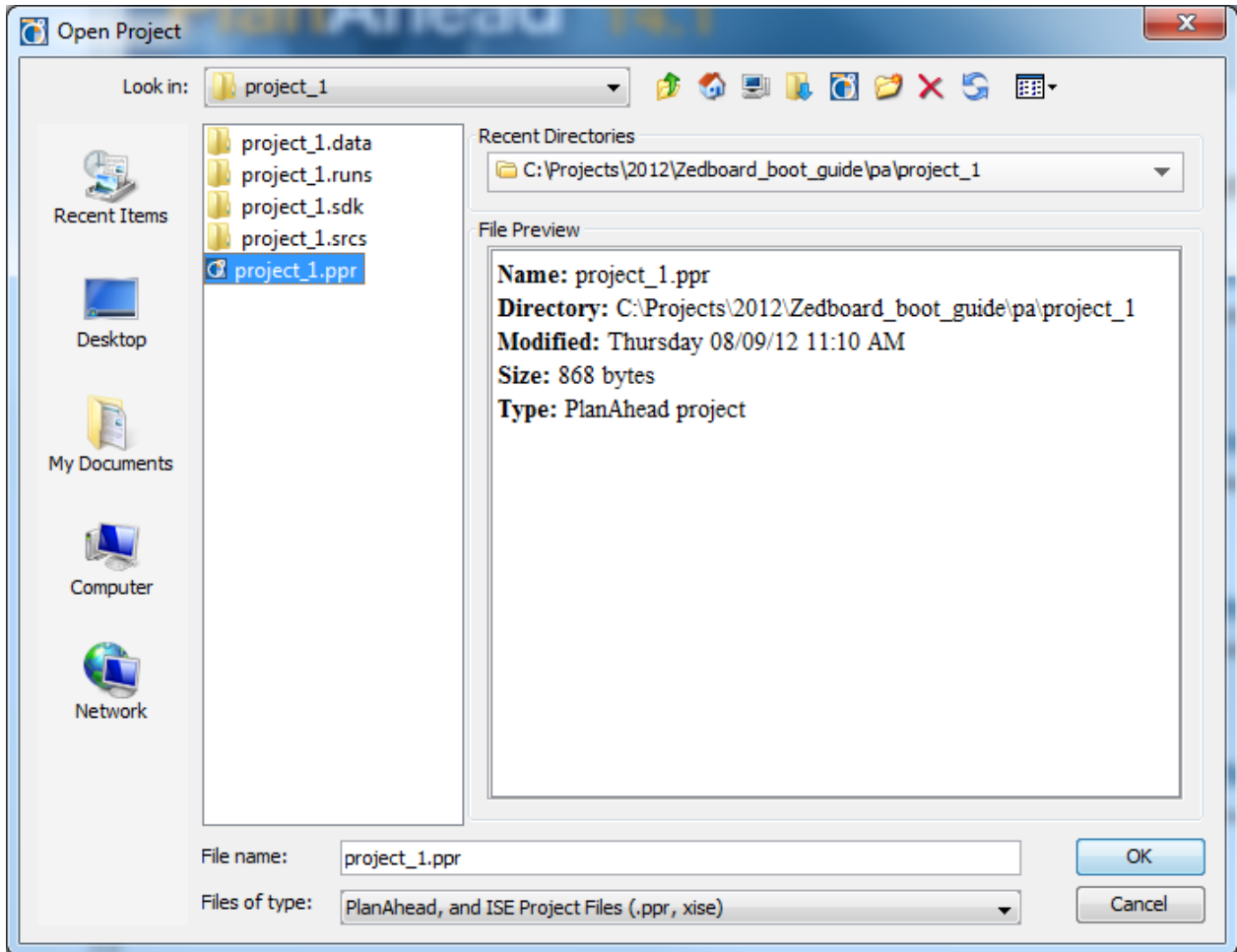
1. Start in PlanAhead to generate an empty SDK workspace based on the pre-built hardware platform described in the ZedBoard CTT guide. Navigate the Windows™



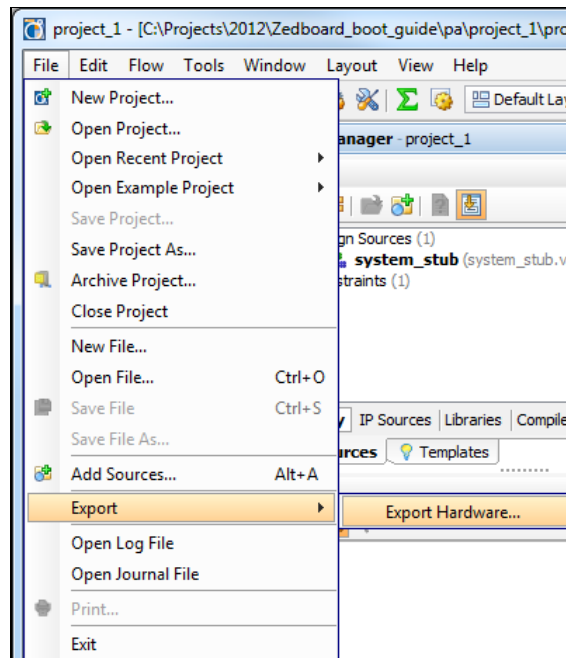
Start Menu or double click on the icon on your desktop to open PlanAhead and select **Open Project**.



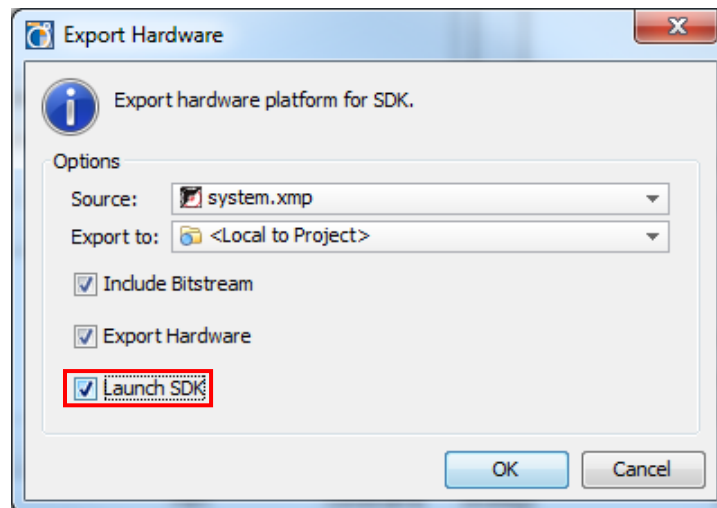
2. Navigate to the <installation>\pa\project_1 folder and select the **project_1.ppr** project file. Click **OK** to continue.



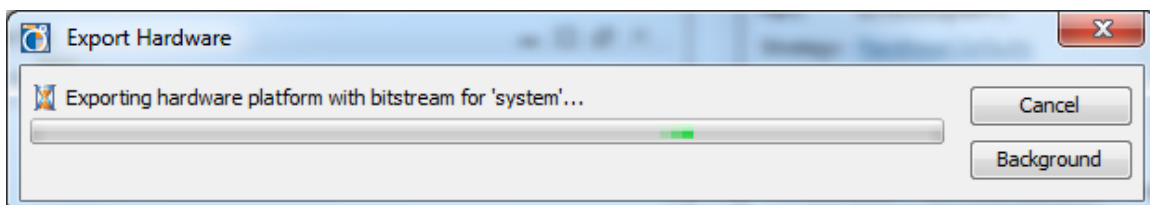
- The project will open and display the **Flow Navigator** and **Project Manager** view with the **Project Summary**. Select **File** → **Export** → **Export Hardware...** from the PlanAhead GUI.



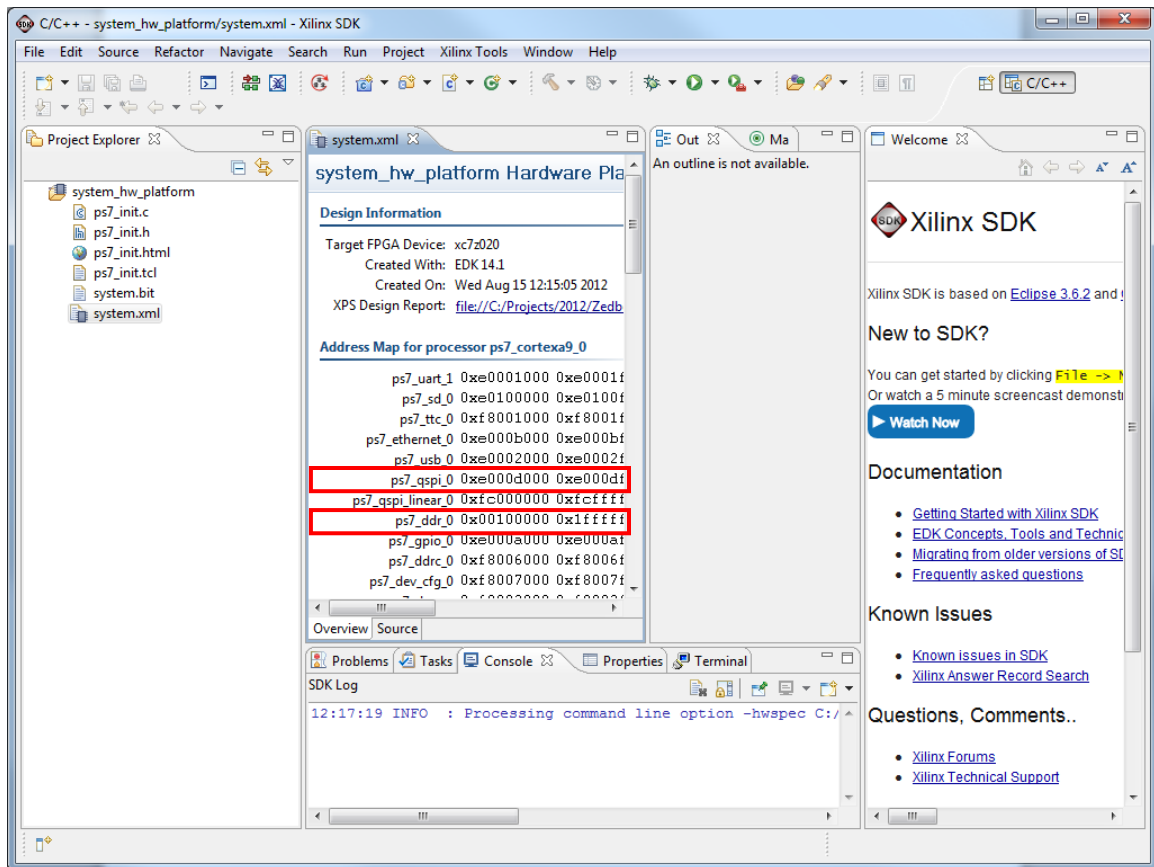
- Accept the defaults and check the box to **Launch SDK**. Click **OK** to continue.



PlanAhead will display the following window while the SDK workspace is created:



- The SDK will open with a new empty workspace with just the imported `system_hw_platform` similar to the window shown below.

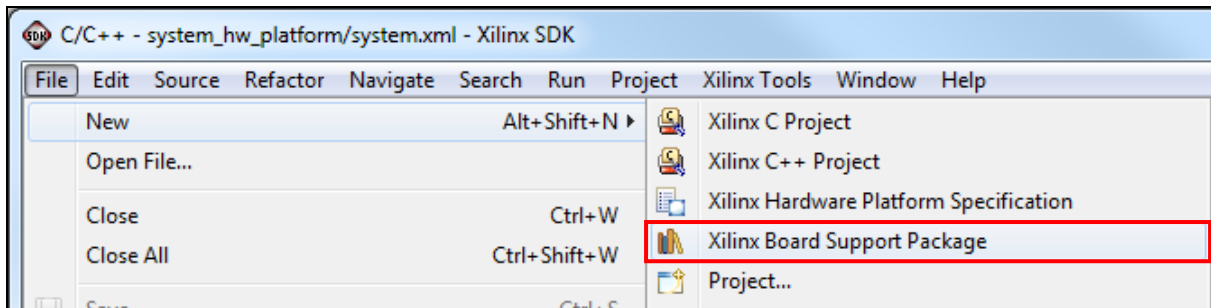


- Make note of the base address for the DDR3 SDRAM (`ps7_ddr_0 - 0x00100000`) and the QSPI Flash (`ps7_qspi_0 - 0xe000d000`). We will need to know this when we program the QSPI Flash later when we prepare to boot the ZedBoard in QSPI boot mode.

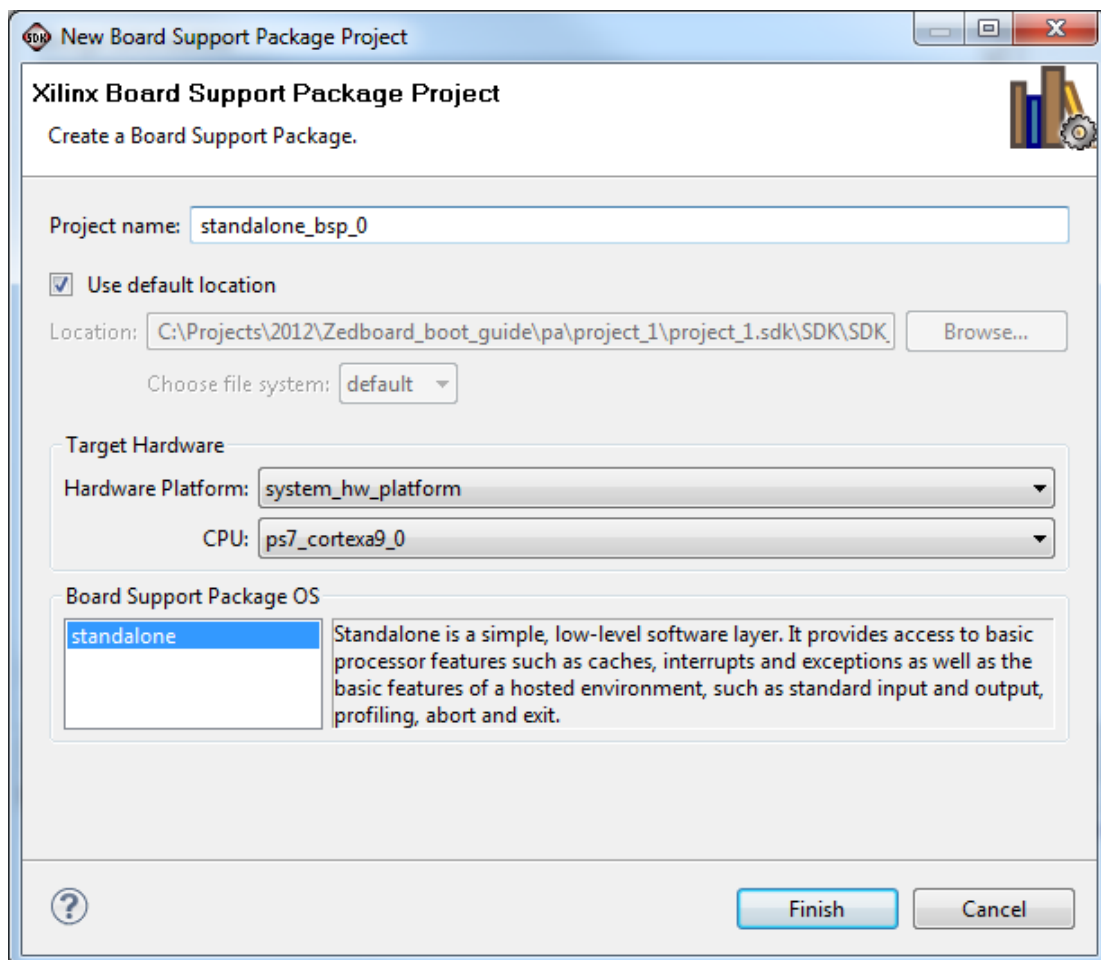
Create the Board Support Package

The first thing we need to create in our empty workspace is a Board Support Package (BSP) on which individual projects can be built. Multiple BSPs and multiple application projects can be held in a single SDK workspace. To begin, create a basic BSP that is adequate for the GPIO test and FSBL applications we intend to run.

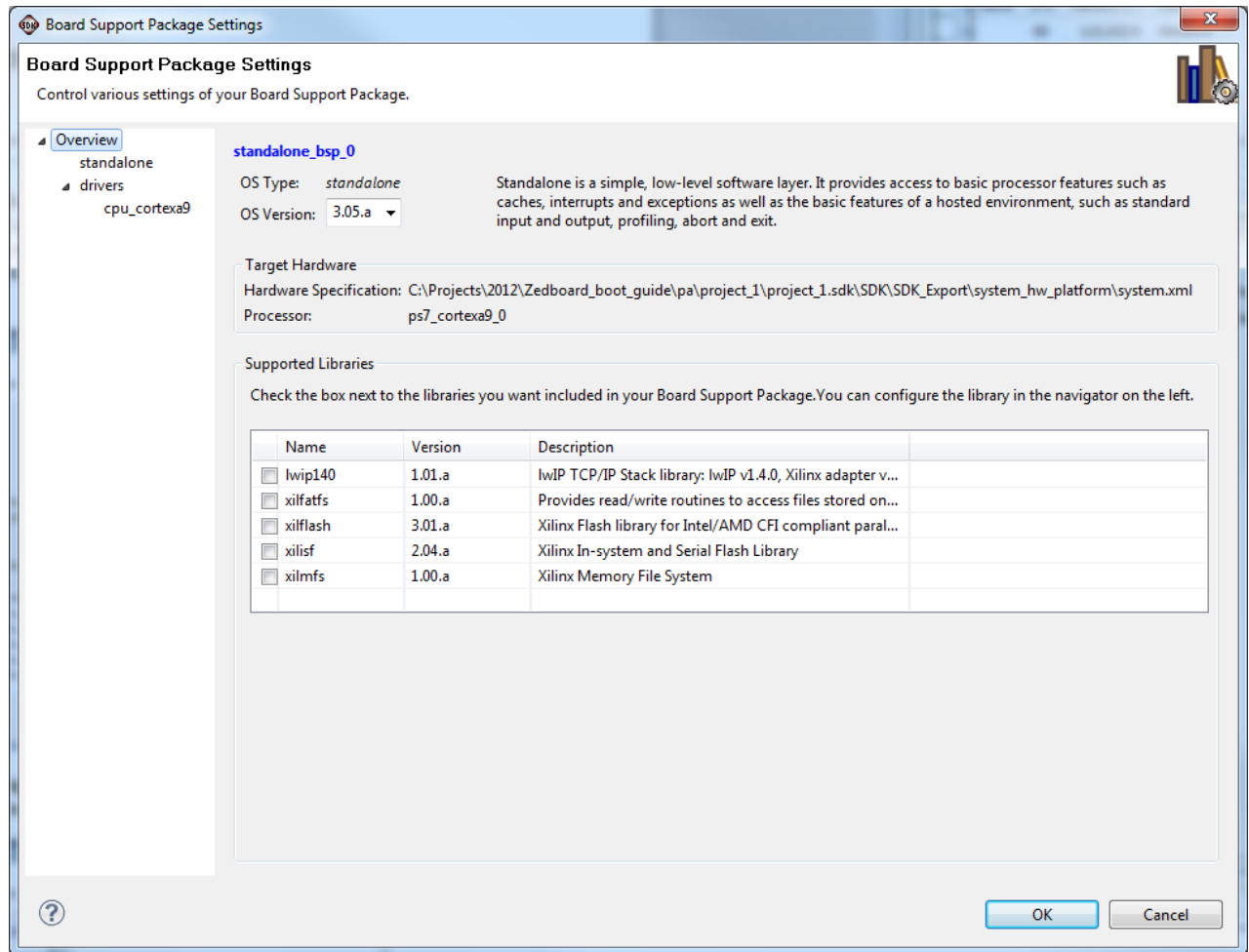
1. From the SDK main menu, select **File → New → Xilinx Board Support Package**.



2. Accept the defaults for the **Project name**, **Hardware Platform**, **CPU**, and **OS**. Click **Finish** to continue.



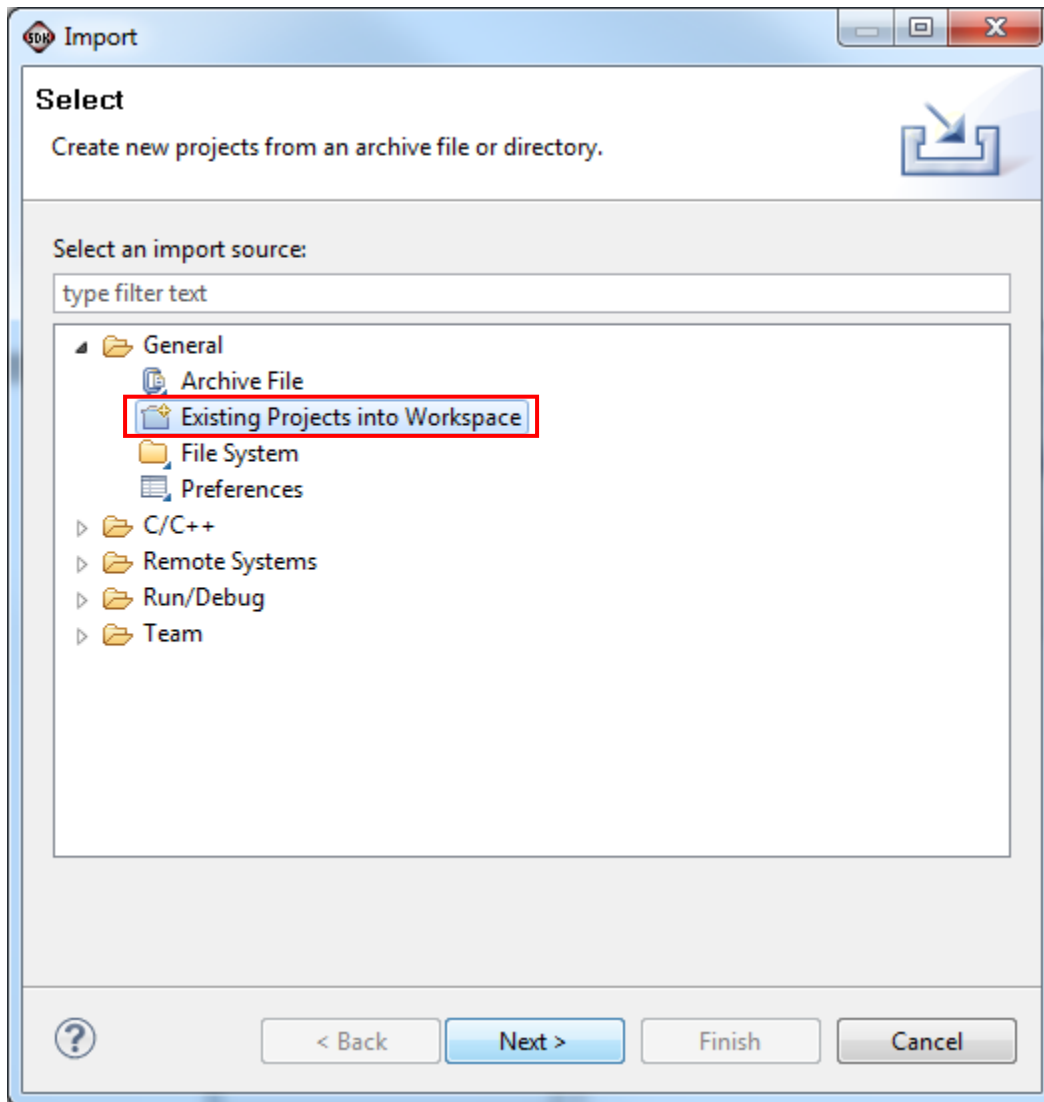
- At this point the basic software platform to build general applications for this board has been created. We do not need to add additional software libraries to the BSP or change any settings, so click **OK** to continue and the software platform will automatically compile link.



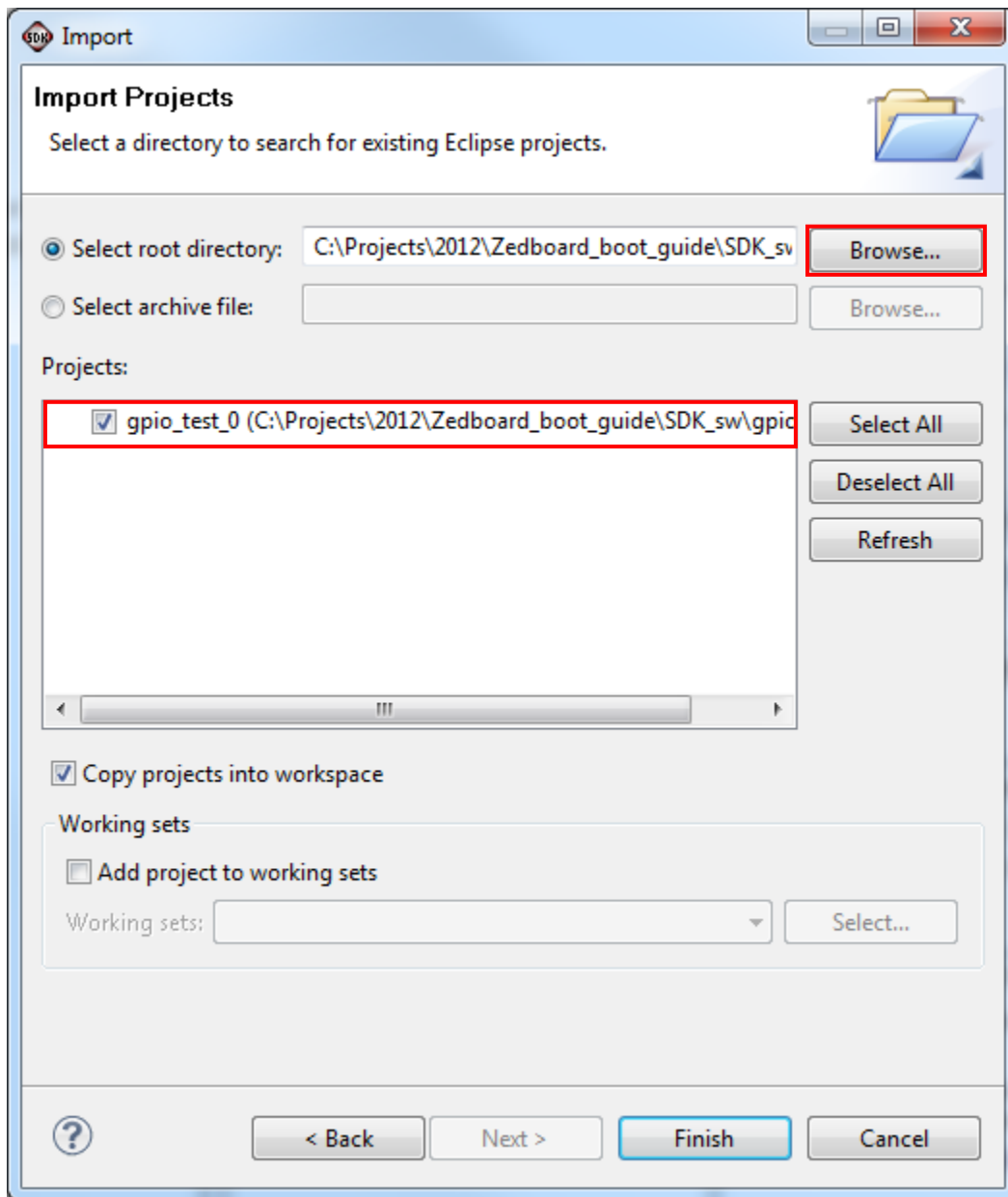
Import the GPIO Test Software Application

The GPIO test application is described in the Appendix A of the ZedBoard CTT and is pre-built for us to use here. Feel free to examine and become familiar with the source code for this application. The next step is to import this application so we can build and run it on the board.

1. Go to **File** → **Import** → **General** → **Existing Projects into Workspace**



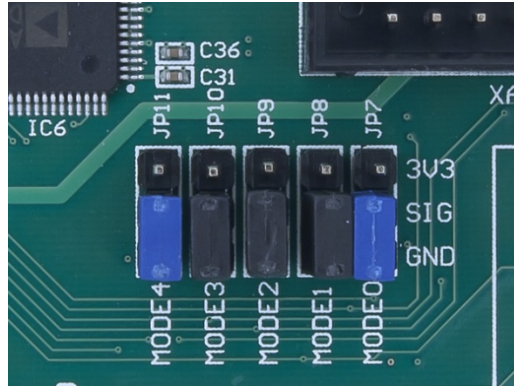
- Click **Browse...** and navigate to the <installation>\SDK_sw\gpio_test_0 folder. Check the box to **Copy projects into workspace** and click **Finish** to continue. The software application will automatically build and be added to the SDK workspace.




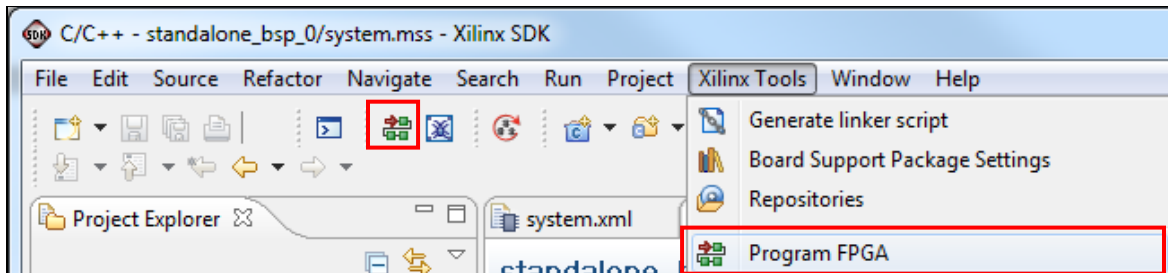
At this point the gpio_test_0 application is ready to run, but first we must setup the Xilinx Microprocessor Debugger (XMD) options to download and run the software application.

Running the GPIO Test Software Application

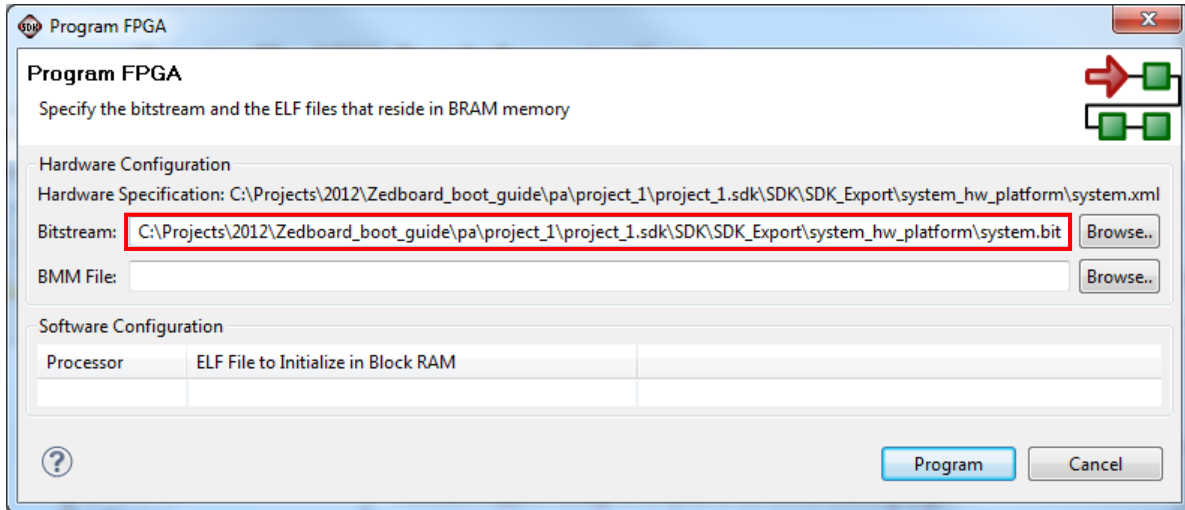
1. Turn off the ZedBoard if it is turned on. Verify the Configuration Mode jumpers are set for JTAG mode (all pins shunted to GND) as in the figure below:



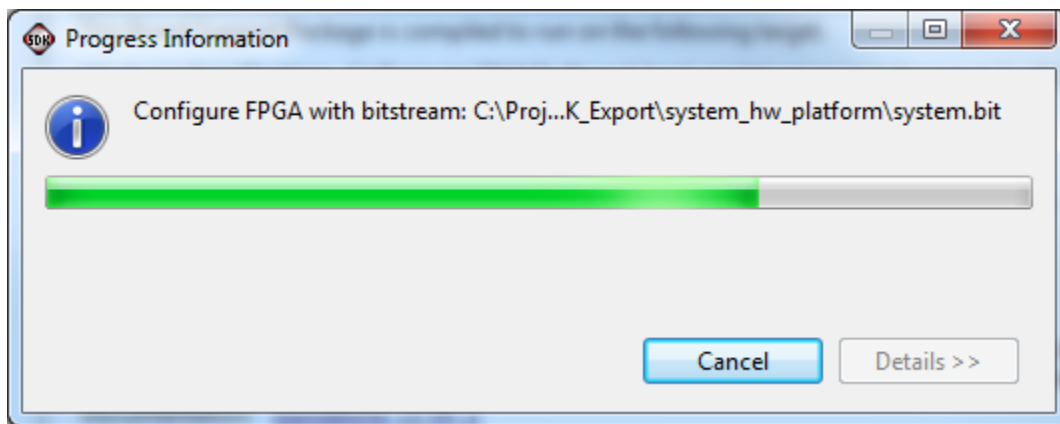
2. Slide the power switch (SW8) to the ON position. You will see the green ‘power good’ LED (LD13) illuminate.
3. To prepare for running the gpio_test_0 software application later we will configure the Zynq device with the PL bitstream that includes the AXI timer and GPIO peripherals. In the SDK main menu, select **Xilinx Tools** → **Program FPGA** or click on the  on the SDK toolbar:



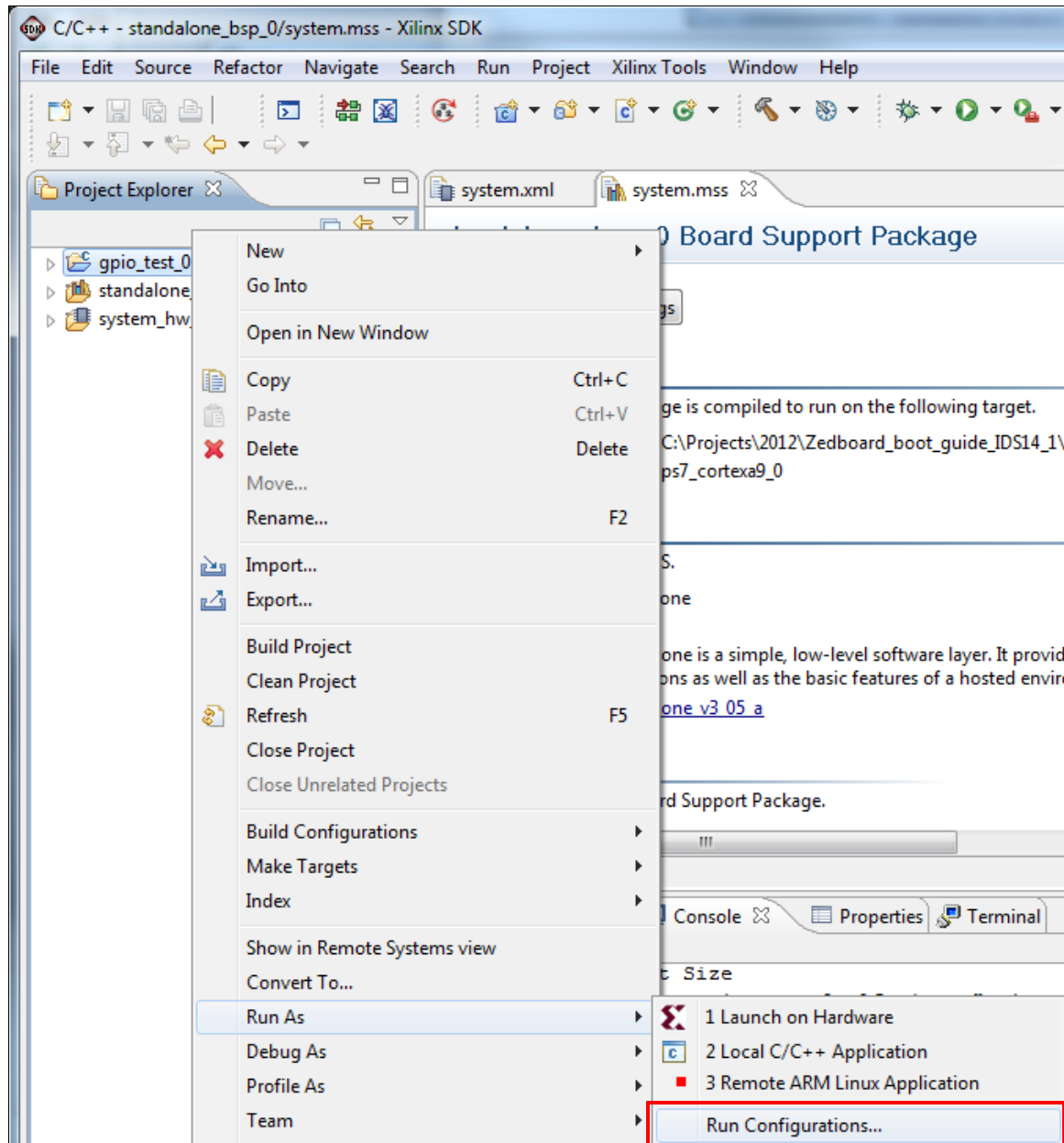
4. Since this is a Zynq hardware platform there is no BMM file or ELF file to initialize in Block RAM, so accept the default for the system.bit file for the PL bitstream that was exported from the PlanAhead hardware project earlier. Click **Program** to continue:





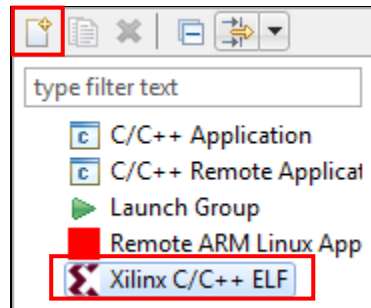
You will see the following window while the PL bitstream is downloaded. Once this is complete the blue 'DONE' LED (LD12) will illuminate.



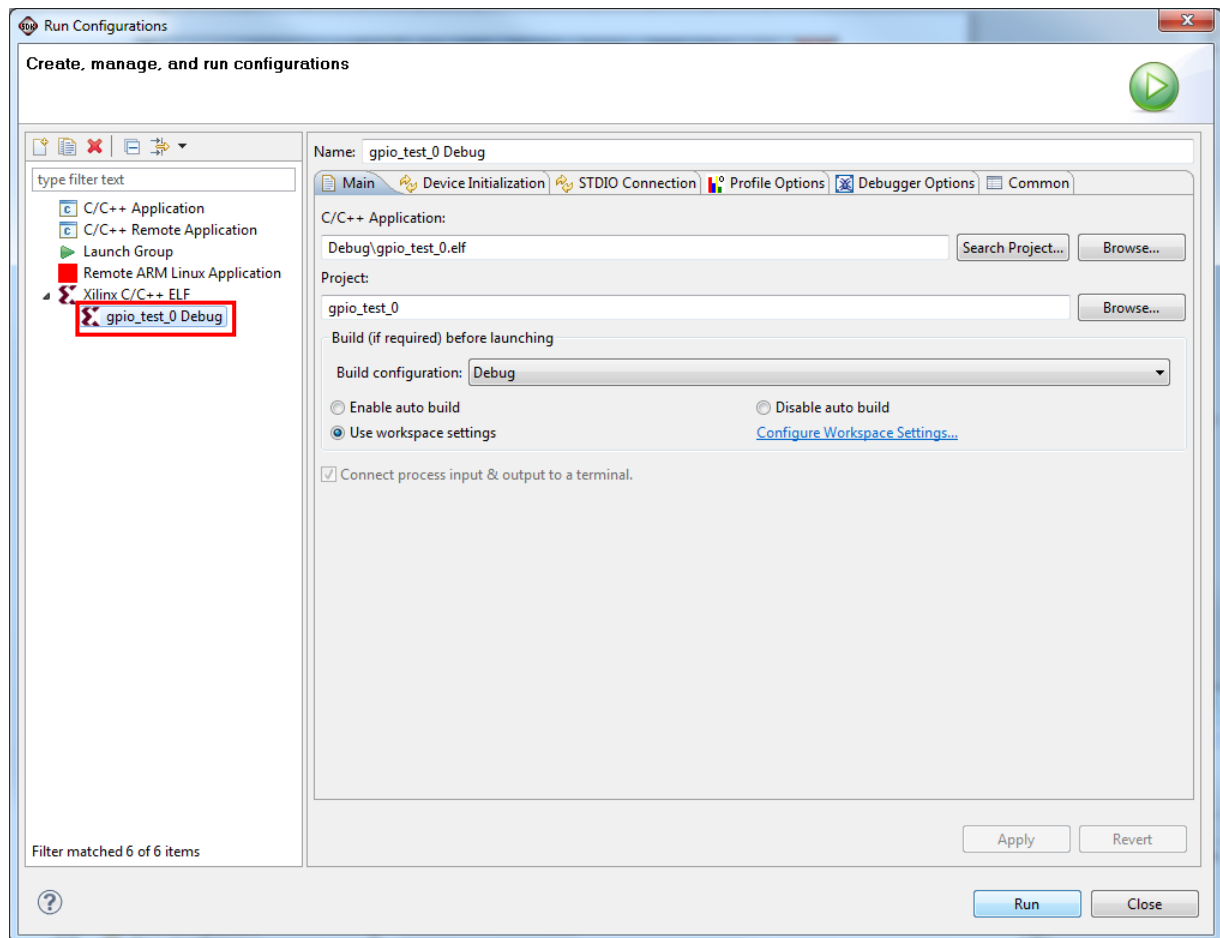
5. In the **Project Explorer** window pane select the **gpio_test_0** application and right-click to select **Run As → Run Configurations...**



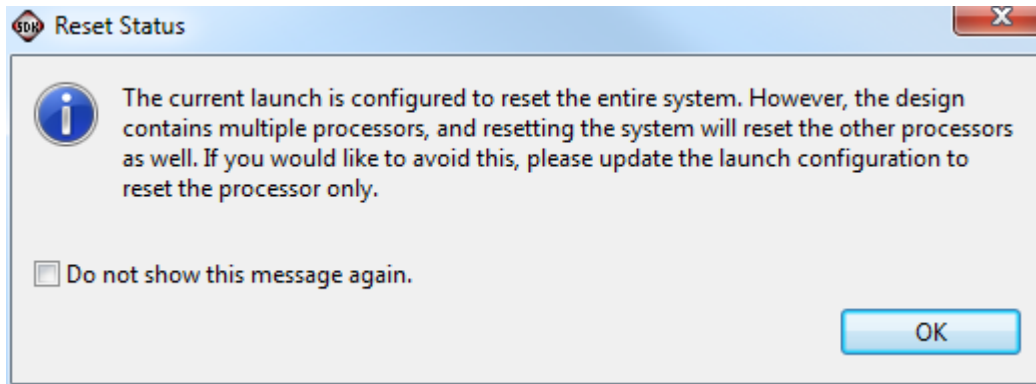
6. Click on the  **Xilinx C/C++ ELF** option in the left panel and press the  **New** to create a new Debug run configuration for the **gpio_test_0** software application.



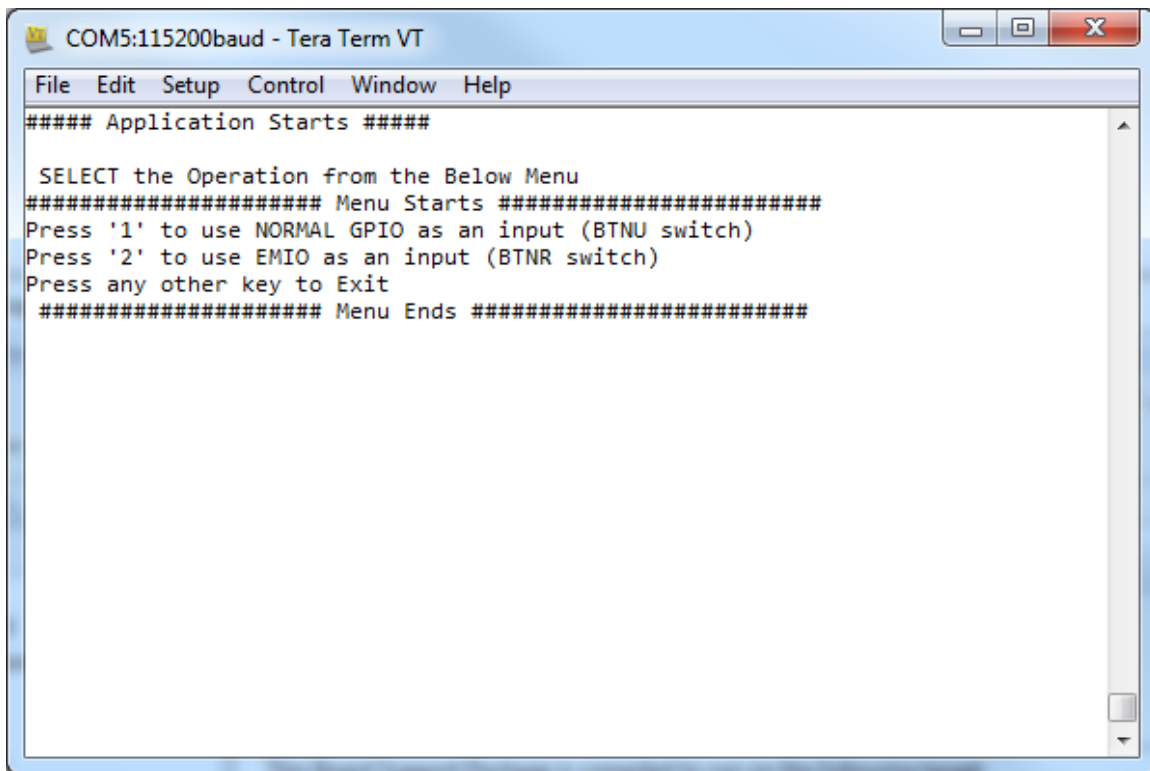
7. Select the new **gpio_test_0 Debug** run configuration. Click **Run** continue.



8. You will see the following window warning you that both CPU cores will be reset. Since this system only uses one of the CPU cores it doesn't matter that both will be reset and we can ignore this warning. Click OK to continue.



9. You should see the following on the serial console:

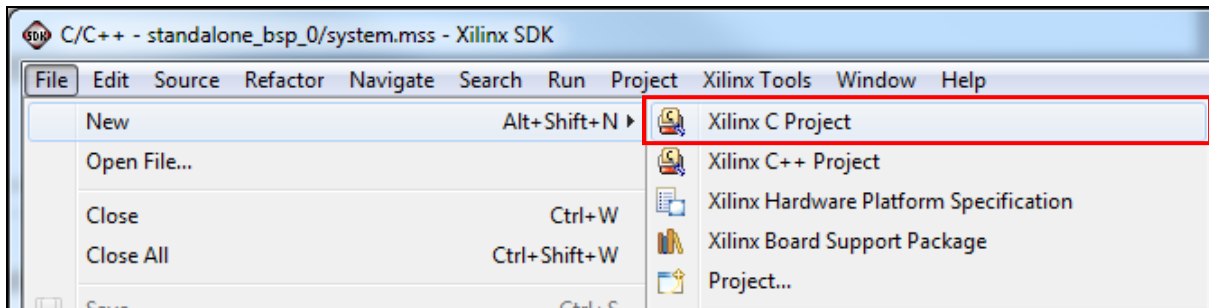


10. You are now ready to run the GPIO test software application. The steps to run the application are the same as running the demo you probably used earlier, except the steps of downloading the PL bitstream and application executable are already completed. Leave the terminal window open when you are done. We will reuse this terminal session again later.

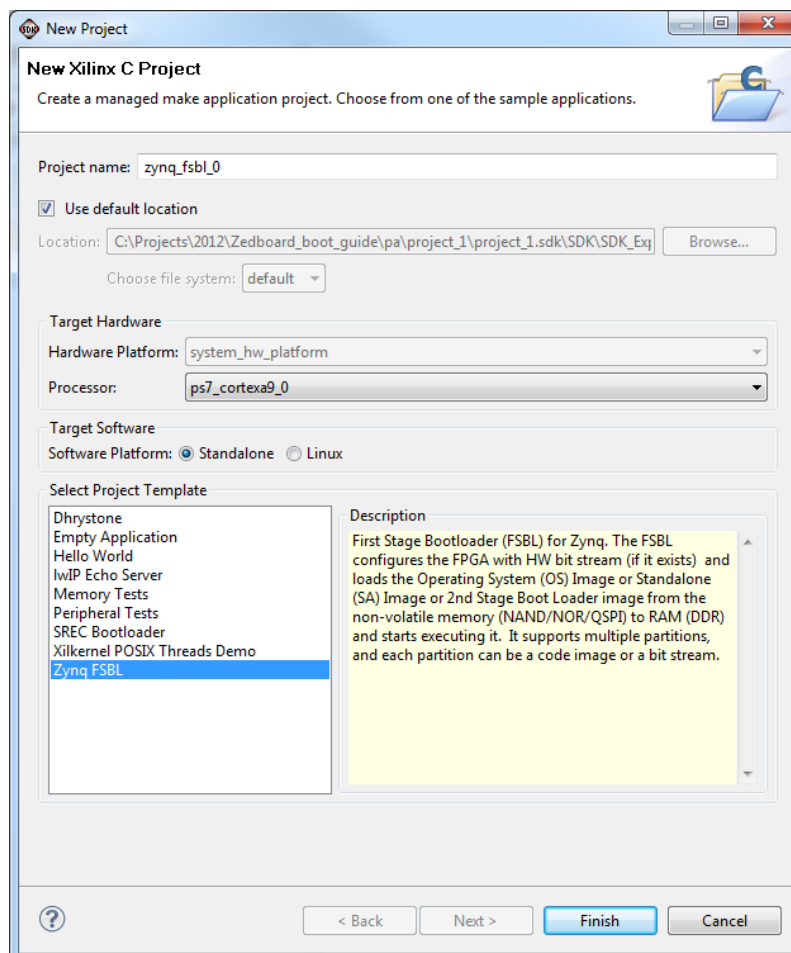
Create the First Stage Boot Loader

To prepare for booting the gpio_test_0 software application at power-up later we will need to create the first stage boot loader application. This application is one of the example software applications built into the SDK.

1. Go to **File → New → Xilinx C Project** to open the window to select from the available example software applications.



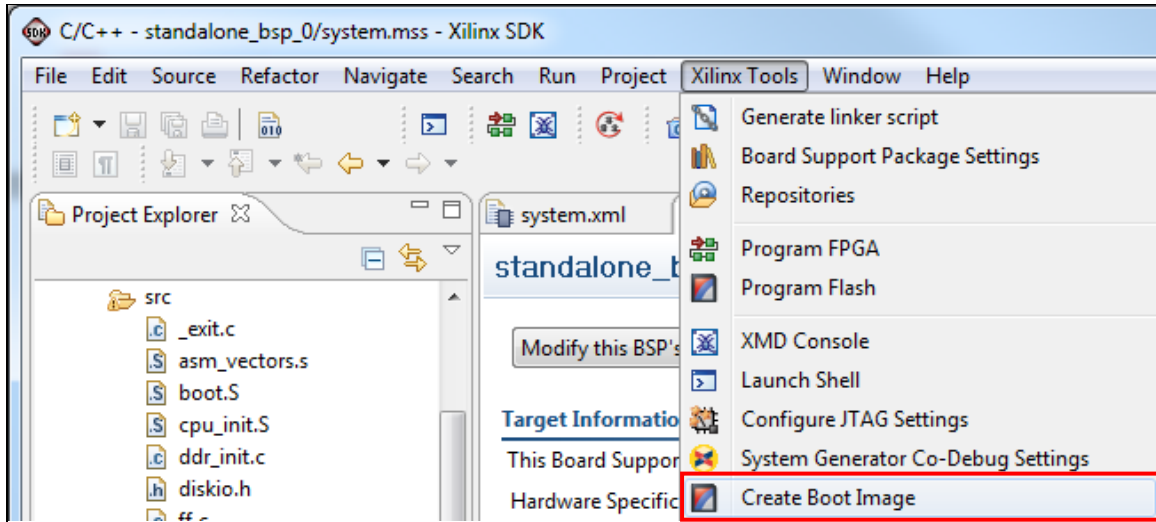
2. Select the Zynq FSBL project template. Accept the defaults for the **Project Name** and **Target Hardware Platform**. Click **Finish** to continue:



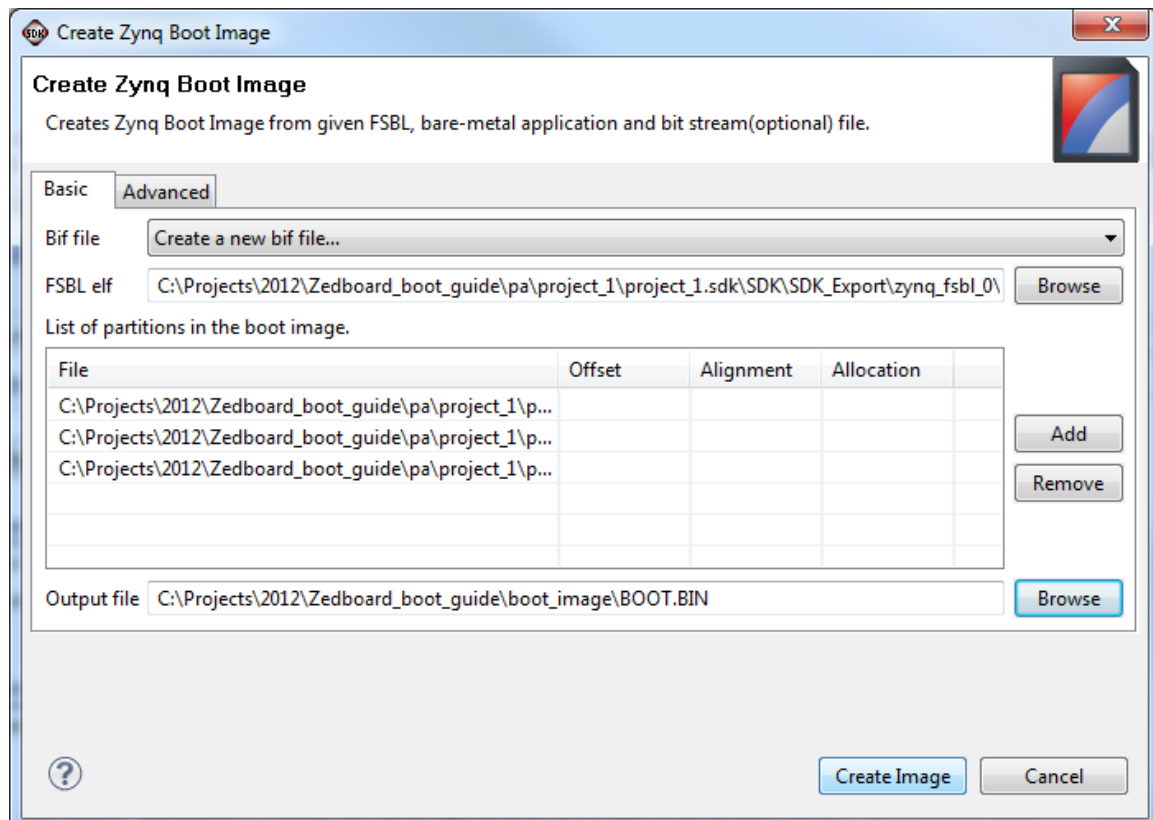
Create the Boot Image

To boot the GPIO test application and configure the PL with the hardware bitstream at power on we first need to create the boot image to be copied to our boot media. The boot image is actually the GPIO test and FSBL application executable files and PL bitstream packaged into a single BOOT.BIN file. The Zynq boot ROM will look for this file on the boot media. It must be named BOOT.BIN in upper-case letters.

1. Go to **Xilinx Tools** → **Create Boot Image**.



2. There are a few tasks we need to do while in this window. The PL bitstream and GPIO test application elf file are added in the order they are needed during boot. Since the PL needs to be configured before the PS runs the application executable the PL bitstream is added first:
 - a. Accept the **Bif file** default **Create a new bif file...** The Bif file is a text file that describes the contents of the boot image. This file can subsequently be used to recreate or modify the BOOT.BIN boot image file
 - b. To specify the **FSBL elf** file click on **Browse** and navigate to `<installation>\pa\project_1\project_1.sdk\SDK\SDK_Export\zynq_fsbl_0\Debug` and select the `zynq_fsbl_0.elf` file.
 - c. To add the PL bitstream click on **Add** and navigate to `<installation>\pa\project_1\project_1.sdk\SDK\SDK_Export\system_hw_platform` and select the `system.bit` file.
 - d. To add the GPIO test software application executable click on **Add** again and navigate to `<installation>\pa\project_1\project_1.sdk\SDK\SDK_Export\gpio_test_0\Debug` and select the `gpio_test_0.elf` file.
 - e. To specify the **Output file** click on **Browse** and navigate to `<installation>\boot_image` and name the file **BOOT.BIN**.
 - f. Click **Create Image** to continue:

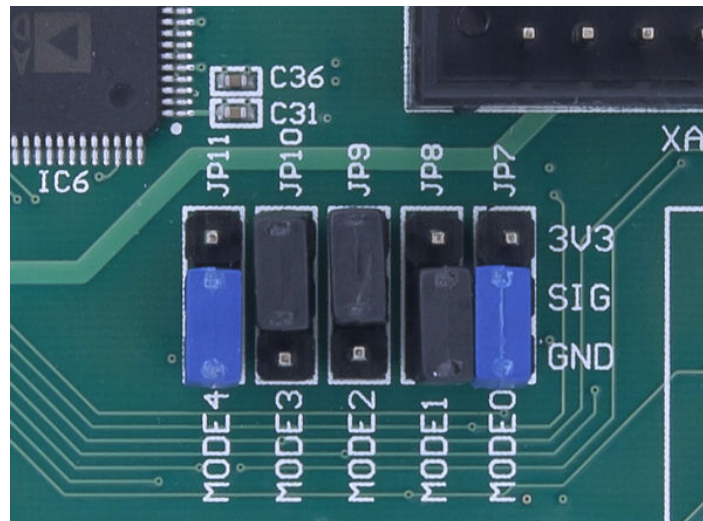


Booting From the SD Card

With the SDK tasks completed, we are now ready to boot our system from the SD card.

Prepare the SD Card

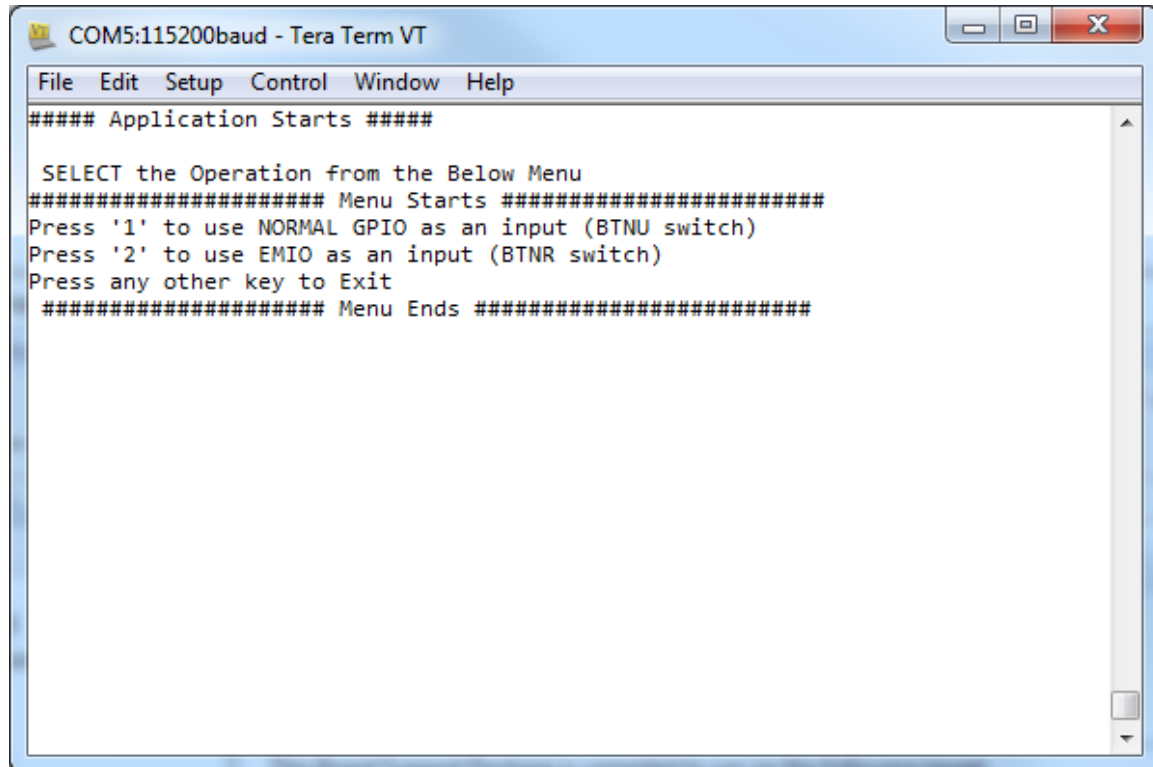
1. Take the SD card that came with the ZedBoard and install it in an open SD card slot on your PC host. Using Windows Explorer identify the drive letter where the SD card is mounted and backup the SD card contents to a folder of your choice on your PC host. Once the SD card files are backed up on the PC, delete them from the SD card.
2. In Windows Explorer navigate to <installation>\boot_image and copy the **BOOT.BIN** file to the SD card.
3. Turn off the ZedBoard if it is turned on. Verify the Configuration Mode jumpers are set for SD card mode as described and in the figure below:
 - MODE3 (JP10) shunted to 3.3V
 - MODE2 (JP9) shunted to 3.3V
 - All other MODE pins shunted to GND



4. Remove the SD card from the PC and insert it in the SD card slot of the ZedBoard.
5. Slide the power switch (SW8) to the ON position. You will see the green 'power good' LED (LD13) will illuminate immediately and the blue 'DONE' LED (LD12) will illuminate once the processor has been initialized and then configures the PL. When booting from SD card this may take 10-15 seconds.

GPIO Test Demo

1. At power on the Zynq boot ROM samples the boot mode strapping pins and determines the boot method. Once the boot method is determined the boot ROM will search the boot media for the BOOT.BIN file and attempt to execute the First Stage Boot Loader (FSBL). The FSBL will then configure the PL if a bitstream is found and hand over system execution to the application executable. When booting from SD card this process may take 10-15 seconds. You should see the following on the serial console when the system has completed booting:



```
COM5:115200baud - Tera Term VT
File Edit Setup Control Window Help
##### Application Starts #####

  SELECT the Operation from the Below Menu
##### Menu Starts #####
Press '1' to use NORMAL GPIO as an input (BTNU switch)
Press '2' to use EMIO as an input (BTNR switch)
Press any other key to Exit
##### Menu Ends #####
```

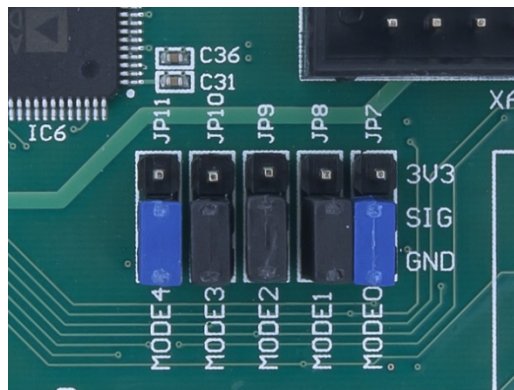
2. You are now ready to run the GPIO test software application. The steps to run the application are the same as running the demo you probably used earlier, except the system has now booted from the SD card and the steps of configuring the PL with the hardware bitstream and starting the application executable happened automatically at power on. Leave the terminal window open when you are done. We will reuse this terminal session again later.

Booting From QSPI Flash

To boot from QSPI flash the BOOT.BIN file must first be programmed to the base address of the QSPI flash. Normally this could be done using the SDK, but that function is not working with the current SDK tools. Instead we will use the flash programming capabilities of the popular u-boot bootloader. As we did previously when booting the ZedBoard in JTAG mode, we will use command line XMD scripts to initialize the CPU and download the u-boot application to the board for execution.

Program the QSPI Flash

1. Verify the ZedBoard is powered off and that the configuration Mode jumpers are set for JTAG mode (all pins shunted to GND) as in the figure below:



2. Verify the SD card is installed in the ZedBoard. We will be copying the BOOT.BIN file on the SD card into DDR3 memory and then to QSPI Flash.
3. Slide the power switch (SW8) to the ON position. You will see the green 'power good' LED (LD13) illuminate.
4. Open a command window in the <installation>\demo folder and enter:

```
run_uboot.bat
```

This batch file sets the proper environment variables and creates the xmd.ini script of commands to be used by the Xilinx Microprocessor Debugger (XMD) tool to initialize the processor, download the u-boot software application, and begin execution on the system by performing the following commands automatically:

```
connect arm hw
source ps7_init.tcl
ps7_init
dow u-boot_autoboot_disabled.elf
run
exit
```

- The processor will be initialized and the u-boot application will be downloaded for the execution. Do not close the command window.

```
Administrator: C:\Windows\system32\cmd.exe

Device  ID Code      IR Length  Part Name
1       4ba00477       4          Cortex-A9
2       03727093       6          XC7Z020

CortexA9 Processor Configuration
-----
Version.....0x00000003
User ID.....0x00000000
No of PC Breakpoints.....6
No of Addr/Data Watchpoints.....1

Connected to "arm" target. id = 64
Starting GDB server for "arm" target (id = 64) at TCP port no 1234
warning: FPGA is NOT Configured. Accessing FPGA Address space can
cause the System to hang. Use "fpga" command to Configure the FPGA
Downloading Program -- u-boot_autoboot_disabled.elf
    section, .text: 0x04000000-0x04020407
    section, .rodata: 0x04020408-0x04026bcc
    section, .hash: 0x04026bd0-0x04026c0f
    section, .data: 0x04026c10-0x0402777f
    section, .got.plt: 0x04027780-0x0402778b
    section, .u_boot_cmd: 0x0402778c-0x04027c3b
    section, .rel.dyn: 0x04027c3c-0x0402c4b3
    section, .dynsym: 0x0402c4b4-0x0402c563
    section, .bss: 0x04027c3c-0x0406a91f
Setting PC with Program Start Address 0x04000000
Processor started. Type "stop" to stop processor

RUNNING>
C:\Projects\2012\Zedboard_boot_guide\demo>
```

- When the u-boot executable has finished loading and is ready to run you should see the following in your serial terminal window:

```
COM5:115200baud - Tera Term VT
File Edit Setup Control Window Help

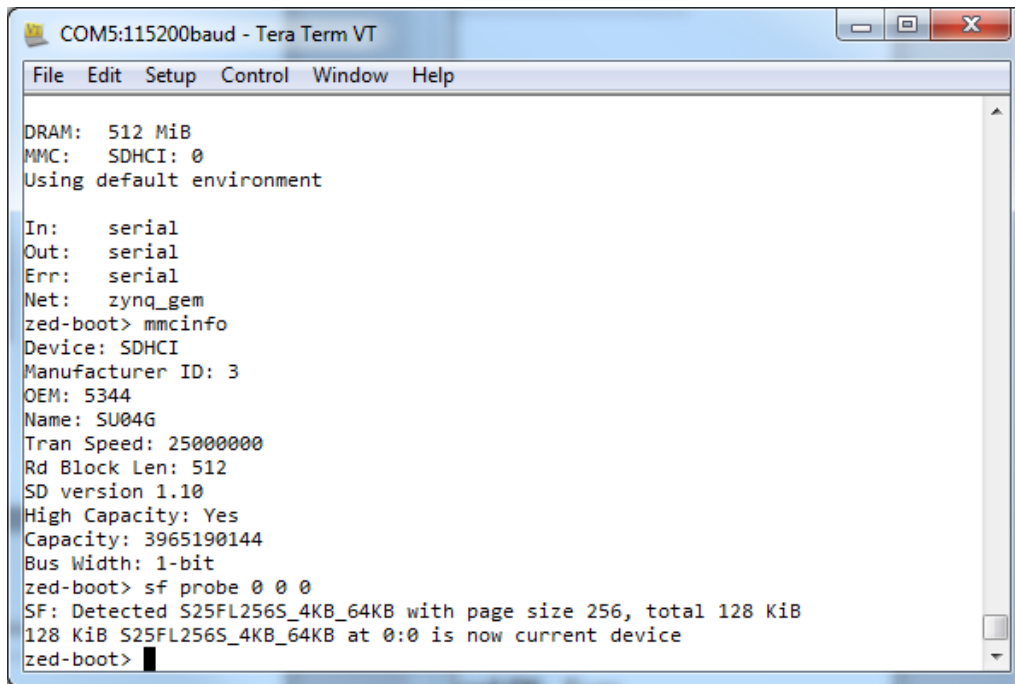
U-Boot 2011.03-dirty (Aug 13 2012 - 13:18:50)

DRAM: 512 MiB
MMC: SDHCI: 0
Using default environment

In: serial
Out: serial
Err: serial
Net: zynq_gem
zed-boot>
```

7. Enter the following commands in the serial terminal window to initialize the SD card and QSPI flash:

```
mmcinfo  
sf probe 0 0 0
```



The screenshot shows a Tera Term VT window titled "COM5:115200baud - Tera Term VT". The window contains the following text:

```
File Edit Setup Control Window Help  
  
DRAM: 512 MiB  
MMC: SDHCI: 0  
Using default environment  
  
In: serial  
Out: serial  
Err: serial  
Net: zynq_gem  
zed-boot> mmcinfo  
Device: SDHCI  
Manufacturer ID: 3  
OEM: 5344  
Name: SU04G  
Tran Speed: 25000000  
Rd Block Len: 512  
SD version 1.10  
High Capacity: Yes  
Capacity: 3965190144  
Bus Width: 1-bit  
zed-boot> sf probe 0 0 0  
SF: Detected S25FL256S_4KB_64KB with page size 256, total 128 KiB  
128 KiB S25FL256S_4KB_64KB at 0:0 is now current device  
zed-boot>
```

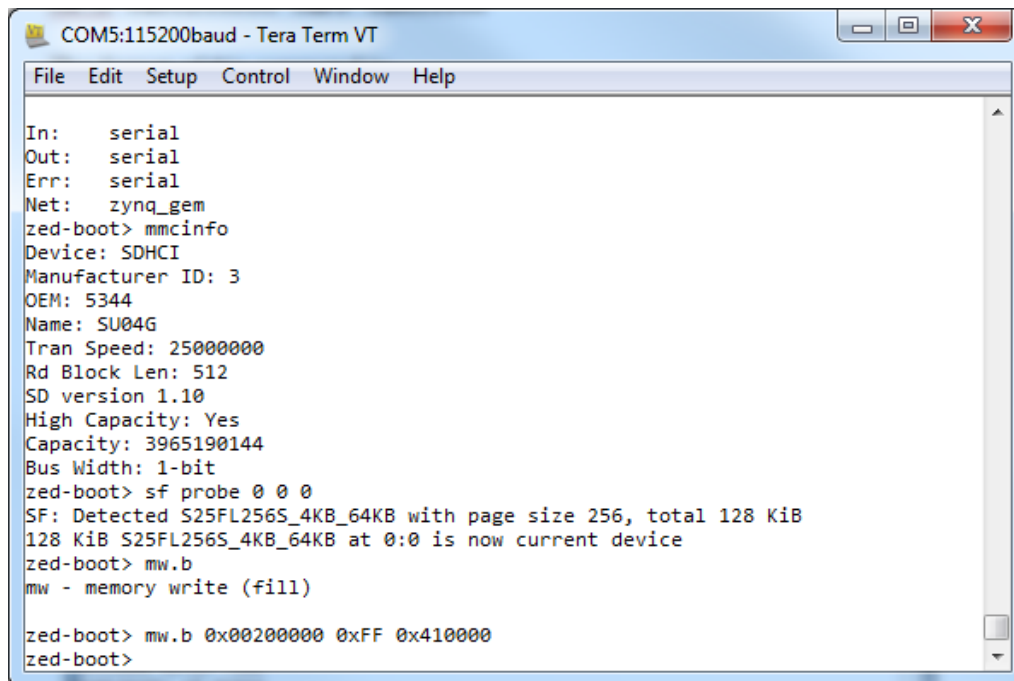
8. Prior to copying the BOOT.BIN file from the SD card to DDR3 memory we need to first write a block of **0xFF** to the area of DDR3 that we will use to temporarily store the BOOT.BIN file. We do this so that when we copy the BOOT.BIN from DDR3 to QSPI Flash, the data we copy beyond the end of the BOOT.BIN file will look like empty memory space to subsequent use of the QSPI Flash. Strictly speaking this is not necessary, but would be a help later if we needed to maximize use of the QSPI flash for other purposes. The size of the boot image (BOOT.BIN) is **0x40D930** bytes, so we will prepare an area slightly larger. Recall earlier when we created the SDK workspace that we made note of the system base address for the DDR3 SDRAM (**ps7_dds_0 - 0x00100000**). We need that information now. Use the u-boot memory write command:

```
mw.b 0x00200000 0xFF 0x410000
```

The format of this command is:

```
mw.b <RAM address> <fill value> <length>
```

NOTE: The **<RAM address>** must be at an offset above the base address where the u-boot application is running.



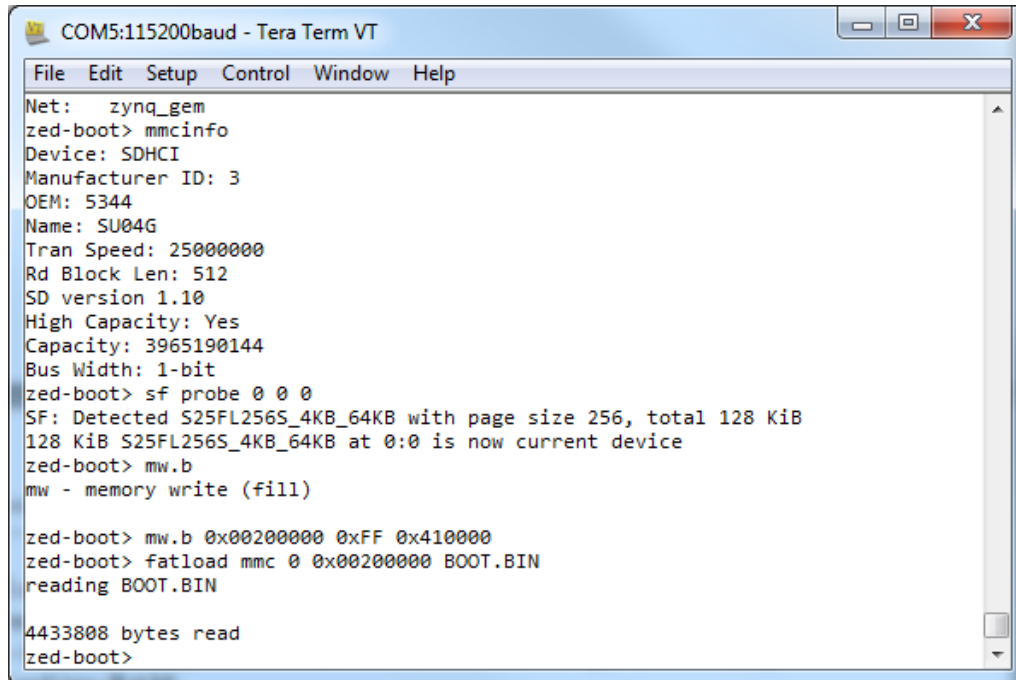
```
COM5:115200baud - Tera Term VT
File Edit Setup Control Window Help
In: serial
Out: serial
Err: serial
Net: zynq_gem
zed-boot> mmcinfo
Device: SDHCI
Manufacturer ID: 3
OEM: 5344
Name: SU04G
Tran Speed: 25000000
Rd Block Len: 512
SD version 1.10
High Capacity: Yes
Capacity: 3965190144
Bus Width: 1-bit
zed-boot> sf probe 0 0 0
SF: Detected S25FL256S_4KB_64KB with page size 256, total 128 KiB
128 KiB S25FL256S_4KB_64KB at 0:0 is now current device
zed-boot> mw.b
mw - memory write (fill)
zed-boot> mw.b 0x00200000 0xFF 0x410000
zed-boot>
```

9. This step will copy the BOOT.BIN file from the SD card to DDR3 memory. Recall earlier when we created the SDK workspace that we made note of the QSPI Flash (**ps7_qspi_0 - 0xE000D000**). We need that information now. Copy the boot image from the SD card into RAM:

```
fatload mmc 0 0x00200000 BOOT.BIN
```

The format of this command is

```
fatload <interface> <device> <RAM address> <filename>
```



The screenshot shows a Tera Term VT window titled "COM5:115200baud - Tera Term VT". The window contains a terminal session with the following text:

```
Net: zynq_gem
zed-boot> mmcinfo
Device: SDHCI
Manufacturer ID: 3
OEM: 5344
Name: SU04G
Tran Speed: 25000000
Rd Block Len: 512
SD version 1.10
High Capacity: Yes
Capacity: 3965190144
Bus Width: 1-bit
zed-boot> sf probe 0 0 0
SF: Detected S25FL256S_4KB_64KB with page size 256, total 128 KiB
128 KiB S25FL256S_4KB_64KB at 0:0 is now current device
zed-boot> mw.b
mw - memory write (fill)

zed-boot> mw.b 0x00200000 0xFF 0x410000
zed-boot> fatload mmc 0 0x00200000 BOOT.BIN
reading BOOT.BIN

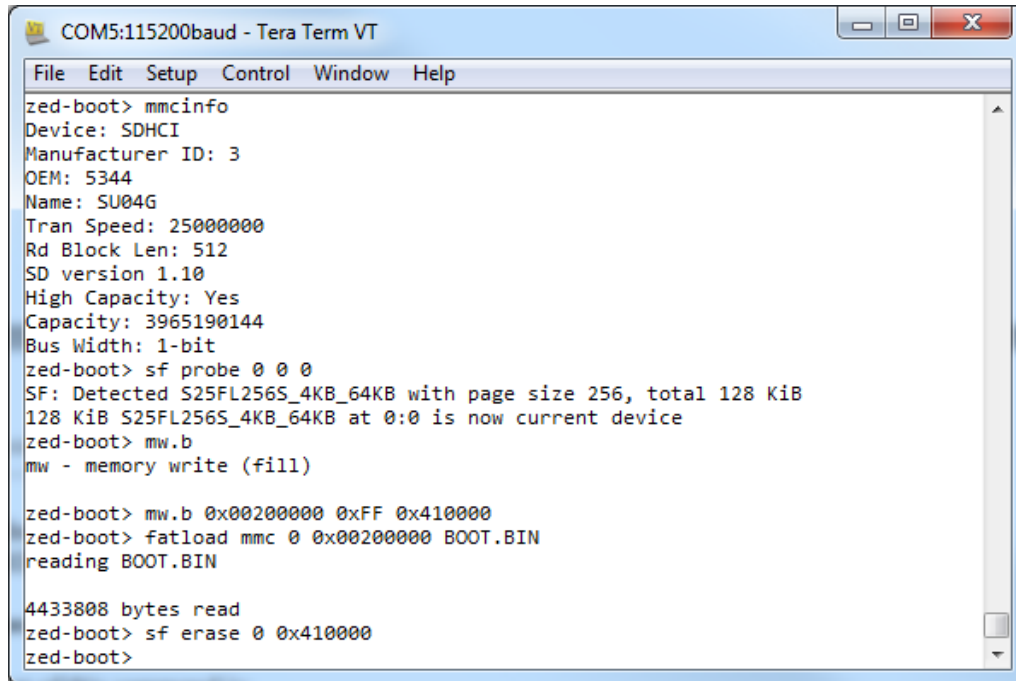
4433808 bytes read
zed-boot>
```

10. Prepare the QSPI Flash. We must erase the area of flash first. The size of the boot image (BOOT.BIN) is 0x40D930 bytes, so we will prepare an area slightly larger:

```
sf erase 0 0x410000
```

The format of this command is:

```
sf erase <offset> <length>
```



```
COM5:115200baud - Tera Term VT
File Edit Setup Control Window Help
zed-boot> mmcinfo
Device: SDHCI
Manufacturer ID: 3
OEM: 5344
Name: SU04G
Tran Speed: 25000000
Rd Block Len: 512
SD version 1.10
High Capacity: Yes
Capacity: 3965190144
Bus Width: 1-bit
zed-boot> sf probe 0 0 0
SF: Detected S25FL256S_4KB_64KB with page size 256, total 128 KiB
128 KiB S25FL256S_4KB_64KB at 0:0 is now current device
zed-boot> mw.b
mw - memory write (fill)

zed-boot> mw.b 0x00200000 0xFF 0x410000
zed-boot> fatload mmc 0 0x00200000 BOOT.BIN
reading BOOT.BIN

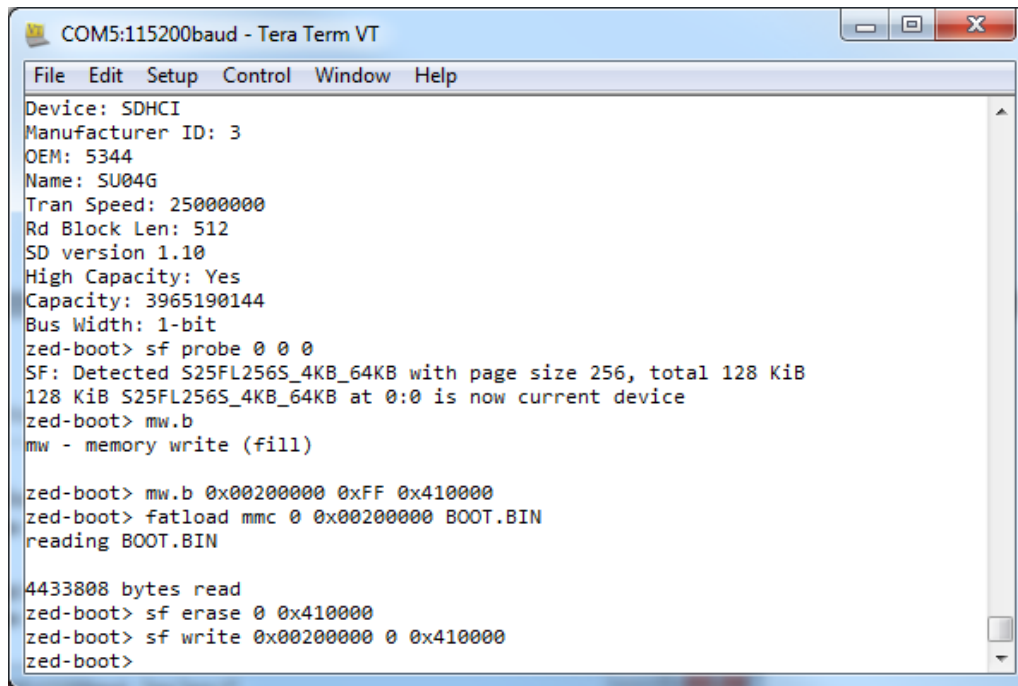
4433808 bytes read
zed-boot> sf erase 0 0x410000
zed-boot>
```

11. Store the boot image to the QSPI Flash:

```
sf write 0x00200000 0 0x410000
```

The format of this command is:

```
sf write <source address> <offset> <length>
```



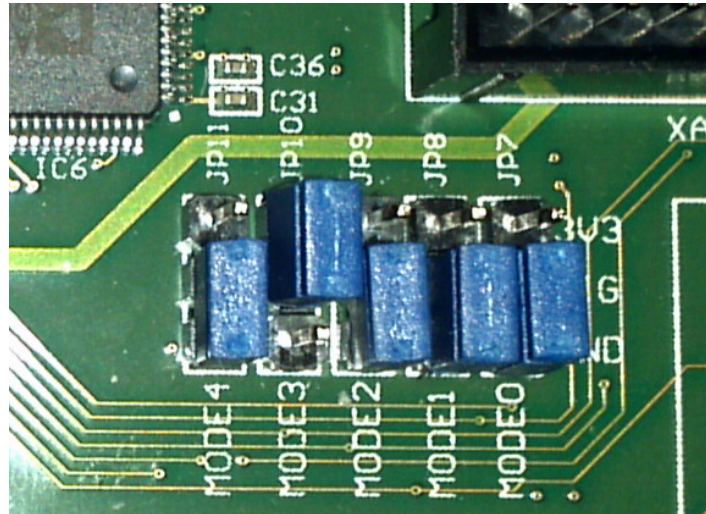
```
COM5:115200baud - Tera Term VT
File Edit Setup Control Window Help
Device: SDHCI
Manufacturer ID: 3
OEM: 5344
Name: SU04G
Tran Speed: 25000000
Rd Block Len: 512
SD version 1.10
High Capacity: Yes
Capacity: 3965190144
Bus Width: 1-bit
zed-boot> sf probe 0 0 0
SF: Detected S25FL256S_4KB_64KB with page size 256, total 128 KiB
128 KiB S25FL256S_4KB_64KB at 0:0 is now current device
zed-boot> mw.b
mw - memory write (fill)

zed-boot> mw.b 0x00200000 0xFF 0x410000
zed-boot> fatload mmc 0 0x00200000 BOOT.BIN
reading BOOT.BIN

4433808 bytes read
zed-boot> sf erase 0 0x410000
zed-boot> sf write 0x00200000 0 0x410000
zed-boot>
```


12. Turn off the ZedBoard. Verify the Configuration Mode jumpers are set for QSPI boot mode as described and in the figure below:

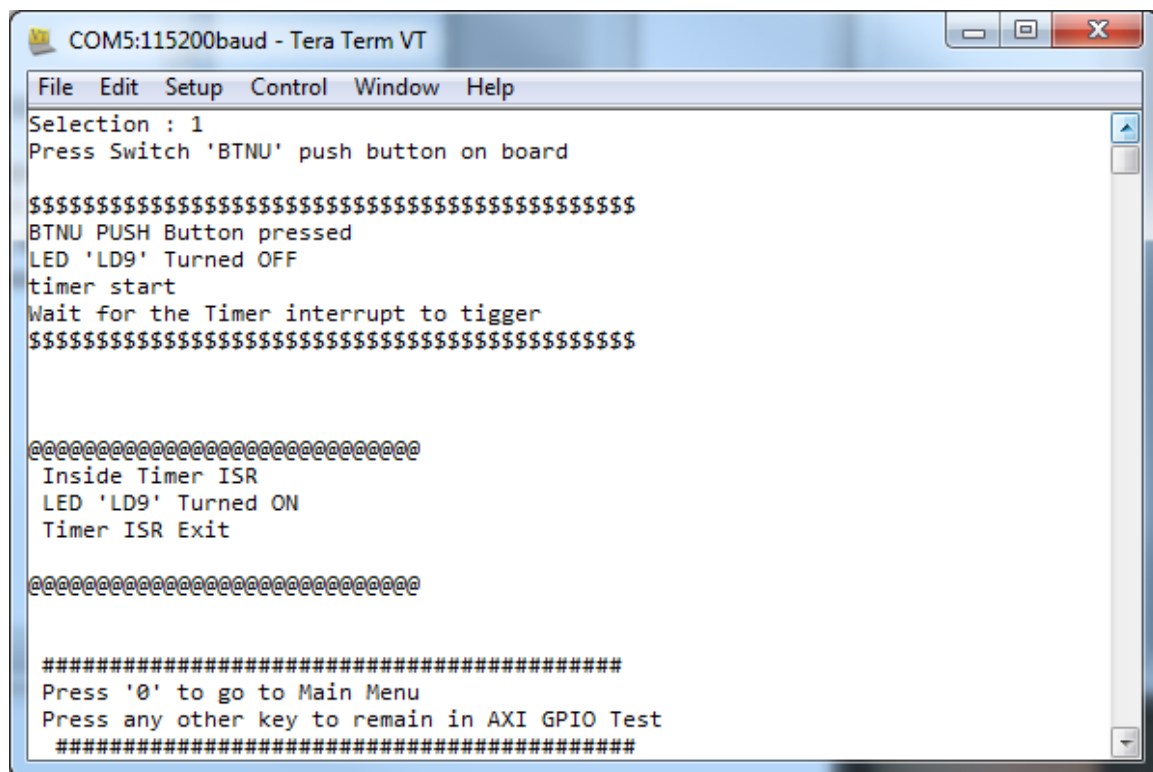
- MODE3 (JP10) shunted to 3.3V
- All other MODE pins shunted to GND



13. Slide the power switch (SW8) to the ON position. You will see the green 'power good' LED (LD13) will illuminate immediately and the blue 'DONE' LED (LD12) will illuminate once the processor has been initialized and then configures the PL. When booting from QSPI Flash this may take a couple of seconds.

GPIO Test Demo

1. At power on the Zynq boot ROM samples the boot mode strapping pins and determines the boot method. Once the boot method is determined the boot ROM will search the boot media for the BOOT.BIN file and attempt to execute the First Stage Boot Loader (FSBL). The FSBL will then configure the PL if a bitstream is found and hand over system execution to the application executable. When booting from QSPI Flash this process happens very quickly. So quickly, in fact, that the GPIO test application starts executing before the USB UART driver has a chance to load on the host PC. This causes the serial terminal window to display a partial GUI or no GUI at all. Based on our previous use of this application throughout this boot guide, though, we know what keys to press to start using the application so proper display of the GUI will resume. To start, press '1' to use NORMAL GPIO as an input (BTNU switch):



2. You are now ready to run the GPIO test software application. The steps to run the application are the same as running the demo you probably used earlier, except the system has now booted from the QSPI Flash and the steps of configuring the PL with the hardware bitstream and starting the application executable happened automatically at power on. Close the terminal and command windows when you are done. This concludes this design tutorial.

Where to Get More Information

ZedBoard Website

- Documentation, Tutorials, and Reference Designs
www.zedboard.org
- ZedBoard Hardware User's Guide
www.zedboard.org/sites/default/files/ZedBoard_HW_UG_v1_3.pdf
- Cypress USB-to-UART Setup Guide
www.zedboard.org/sites/default/files/CY7C64225_Setup_Guide_1_1.pdf
- Concepts, Tools and Techniques Guide
www.zedboard.org/design

Xilinx Website

- All Zynq Documentation
www.xilinx.com/support/documentation/zynq-7000.htm
- Zynq-7000 AP SoC Software Developers Guide
www.xilinx.com/support/documentation/user_guides/ug821-zynq-7000-swdev.pdf

Revision History

Version	Date	Author	Details
1.0	August 16, 2012	TC	Initial release. ISE 14.1
1.1	August 17, 2012	TC	Review notes from group review