

The RC/RL circuit (1)

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Linear 1st order with a constant coefficient partial differential equations (PDEs)

→ Linear 1st order P.D.E

① The form : $Ax' + Bx = f(t) \dots \textcircled{I}$

- A and B are constants. & $x \Leftrightarrow x(t)$

- $f(t)$: a known eq. ; i.e., t or $2t$ or $1, 2, 3 \dots$

② Solve for \textcircled{I} : means find $x(t)$

③ Two types of sols for $x(t)$

- Homogeneous sol = natural response: $\boxed{\textcircled{A} X_h}$

$$f(t) = "0"$$

- Particular sol = forced response: $\boxed{\textcircled{B} X_p}$

$$f(t) = \text{"Something"}$$

Therefore,

$$f(t) = \textcircled{A} + \textcircled{B} = 0 + \text{Something} = \text{Something}.$$

(Make sense !!!)

Let's do elaboration, Let's prove it \rightarrow

Let's prove ③ via **SUPERPOSITION** principle

Suppose X_p is a sol to ①

Again, where

$$Ax' + Bx = f(t) \dots \text{①}$$

$$\textcircled{*} \rightarrow AX_p' + BX_p = f(t)$$

And X_h is a homogeneous sol to ①

$$\textcircled{*} \rightarrow AX_h' + BX_h = f(t) = 0$$

Then $X = X_p + X_h$ is a sol for ①

What we want to prove

<proof>

$$Ax' + Bx \overset{\text{Find!!}}{\boxed{?}} f$$

$$A(x_p' + x_h') + B(x_p + x_h) \overset{?}{\boxed{=}} f$$

$$\begin{array}{c} \textcircled{*} \underbrace{Ax_p' + Bx_p}_{f(t)} + \underbrace{Ax_h' + Bx_h}_{\textcircled{*} 0} \overset{?}{\boxed{=}} f \end{array}$$

$$\therefore f(t) + 0 = f(t) \quad // \text{ Done!}$$

<Example>

$$X' + 4X = \boxed{3}$$

① Homogeneous : $X_h' + 4X_h = 0$
(Everywhere is 0 for this function)

$$X_h' = -4X_h$$

A scale version of.

- The Derivative of a function still has its Original form
⇒ An exponential function!!!

$$\circ \circ \quad X_h = C \cdot e^{-4t}$$

$$\left(\begin{array}{l} \text{check!} \quad X_h' = -4C e^{-4t} \\ \quad \quad \quad = -4 \cdot C e^{-4t} = -4X_h \end{array} \right)$$

② Particular sol : $X_p = A$

(based on $X' + 4x = \boxed{3}$ this)
a constant.

You plug what you guessed into.

- ① Guess
- ② Try (substitute)
- ③ Check

$$X_p' + 4X_p = 3$$

$$(A)' + 4 \cdot A = 3 \Rightarrow 0 + 4A = 3 \therefore A = 3/4.$$

$$(3) \text{ As } X = X_p + X_h \Rightarrow 3/4 + C \cdot e^{-4t} = X(t)$$

(solve for C via any extra condition given)

Another way to solve

(can we solve the PDE without homo... particular sols?)..

A formal way to solve for $AX' + BX = f(t)$,
when $f(t)=D$ (a constant)

$$A X' + B X = f(t)$$

$$A X' + B X = D$$

$$X' + \frac{X}{\frac{A}{B}} = \frac{D}{A} \quad // \quad \text{Let } \frac{A}{B} = \tau \text{ and } \boxed{\frac{D}{A}} = K$$

→ another constant

$$\left(\frac{dX}{dt} \right) + \frac{X}{\tau} = K \iff \frac{dX}{dt} = K - \frac{X}{\tau}$$

$$\frac{dX}{dt} = \frac{K\tau - X}{\tau} \iff \frac{dX}{K\tau - X} = \frac{dt}{\tau}$$

$$\int \frac{dx}{x - k\tau} = \int \frac{dt}{\tau}$$

\Downarrow

$$\int \frac{dx}{x - k\tau} = - \int \frac{dt}{\tau} \quad \xLeftrightarrow[\text{Integration property}]$$

$$x - k\tau = u \text{ then } du = dx$$

$$\int \frac{du}{u} = \ln|u| + A$$

$$\ln(x - k\tau) = -\frac{t}{\tau} + \text{Constant}$$

$$\log_A B^C \Leftrightarrow B^C = A$$

$$e^{(-\frac{t}{\tau} + \text{Constant})}$$

$$= x - k\tau$$

// x is a function of t

$$e^{-\frac{t}{\tau}} \cdot e^{\text{Constant}} = x(t) - k\tau$$

$$x(t) = \underbrace{k\tau}_{\uparrow} + \boxed{e^{\text{Constant}}} e^{-\frac{t}{\tau}}$$

↳ Another constant such as k_1, k_2, \dots

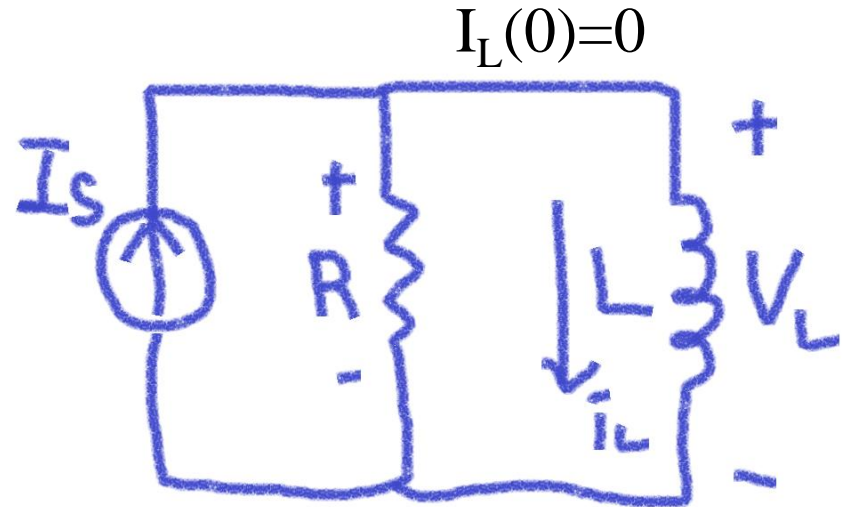
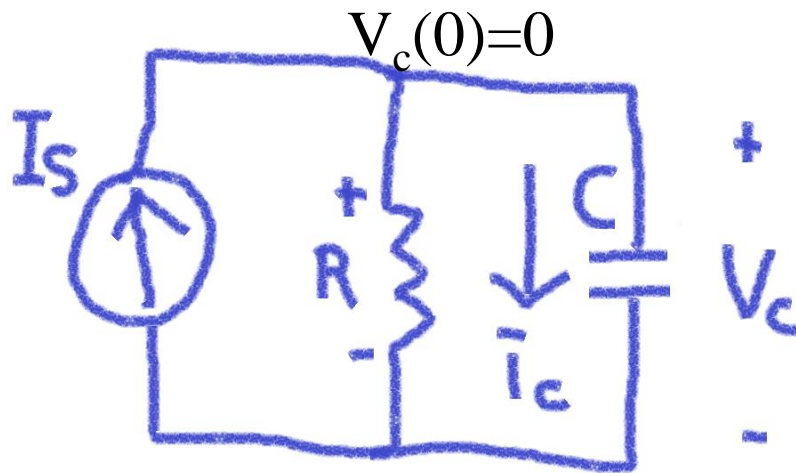
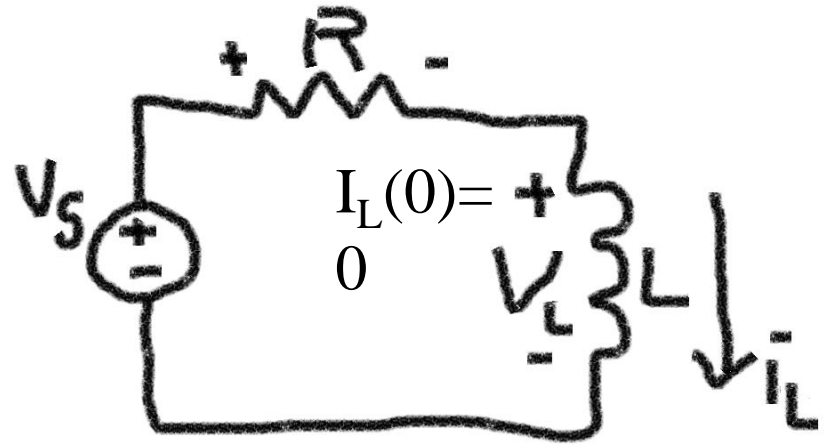
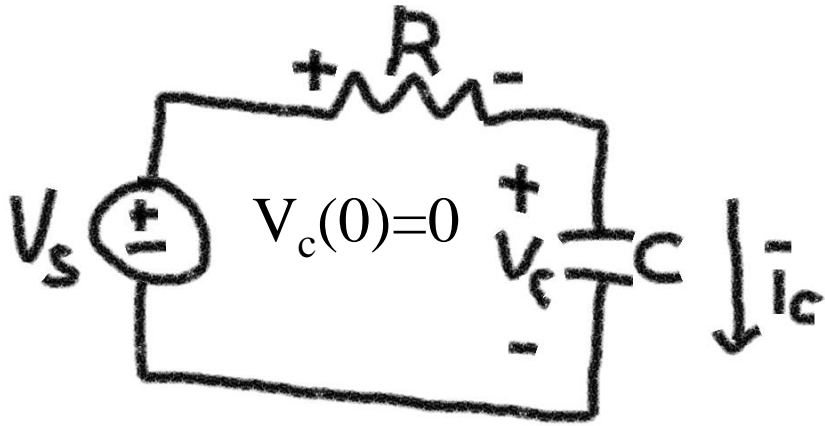
Particular sol./Forced R.

Homogen sol./Natural R.

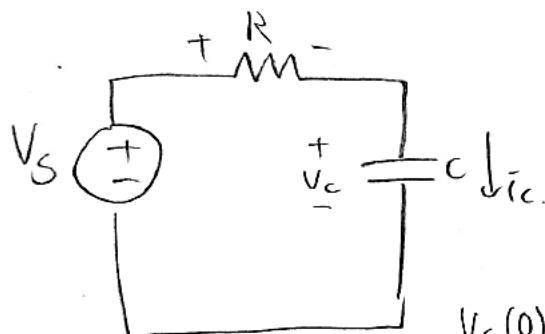
Relation	Resistor (R)	Capacitor (C)	Inductor (L)
v - i :	$v = iR$	$v = \frac{1}{C} \int_{t_0}^t i \, dt + v(t_0)$	$v = L \frac{di}{dt}$
i - v :	$i = v/R$	$i = C \frac{dv}{dt}$	$i = \frac{1}{L} \int_{t_0}^t v \, dt + i(t_0)$
p or w :	$p = i^2 R = \frac{v^2}{R}$	$w = \frac{1}{2} C v^2$	$w = \frac{1}{2} L i^2$
Series:	$R_{eq} = R_1 + R_2$	$C_{eq} = \frac{C_1 C_2}{C_1 + C_2}$	$L_{eq} = L_1 + L_2$
Parallel:	$R_{eq} = \frac{R_1 R_2}{R_1 + R_2}$	$C_{eq} = C_1 + C_2$	$L_{eq} = \frac{L_1 L_2}{L_1 + L_2}$
At dc:	Same	Open circuit	Short circuit
Circuit variable that cannot change abruptly:	Not applicable	v	i

Practice examples and solutions

1st order PDEs with a constant source



1. Construct a 1st order partial differential equation
2. Solve for 1, based on the given initial condition at $t=0$



$$i_C = C \cdot \frac{d}{dt} V_C$$

$$V_C(0) = 0$$

PDE

$$V_S = RC \cdot \frac{d}{dt} V_C + V_C$$

$$\because V_S = R i_C + V_C$$

$$V_S = R \cdot C \cdot \frac{d}{dt} V_C + V_C$$

Solve for $V_C(t)$

$$V_C(t) = V_h + V_p$$

$$V_h \rightarrow RC \cdot \frac{d}{dt} V_h + V_h = 0$$

$$V_h = -RC \cdot \frac{d}{dt} V_h$$

$$\therefore V_h = K_1 \cdot e^{-t/RC}$$

$$V_h' = -\frac{1}{RC} \cdot K_1 \cdot e^{-t/RC}$$

$$= -\frac{K_1}{RC} e^{-t/RC}$$

$$V_h = -RC \cdot \underbrace{\left[\frac{-K_1}{RC} e^{-t/RC} \right]}_{V_h'} = K_1 \cdot e^{-t/RC} = V_h$$

$$V_p \rightarrow X \text{ (a constant)}$$

$$RC \cdot \frac{d}{dt} V_p + V_p = V_S$$

$$RC \cdot \frac{d}{dt} X + X = V_S$$

$$\therefore X = V_S = V_p$$

(1)

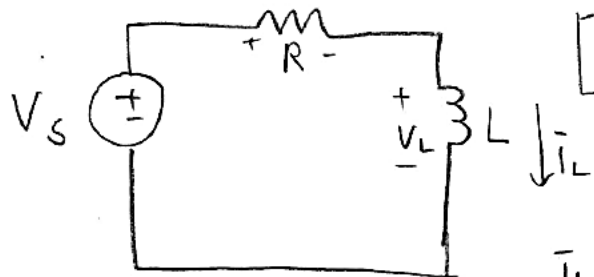
$$V_C(t) = V_h + V_p = K_1 \cdot e^{-t/RC} + V_S$$

$$\text{as } V_C(0) = 0$$

$$V_C(0) = K_1 \cdot \underbrace{e^{-0/RC}}_1 + V_S = 0$$

$$K_1 + V_S = 0, K_1 = -V_S$$

$$\therefore V_C(t) = V_S (1 - e^{-t/RC}) \text{ [V]}$$



$$V_L = L \cdot \frac{d}{dt} \bar{i}_L$$

$$\bar{i}_L(0) = 0 \quad \text{Ⓢ}$$

$$V_s = R \cdot \bar{i}_L + V_L$$

PDE

$$V_s = R \cdot \bar{i}_L + L \cdot \frac{d}{dt} \bar{i}_L$$

Solve for

$$\bar{i}_L(t) \rightarrow \bar{i}_L(t) = \bar{i}_h(t) + \bar{i}_p(t)$$

$$\bar{i}_h \rightarrow R \cdot \bar{i}_h + L \cdot \frac{d}{dt} \bar{i}_h = 0$$

$$\bar{i}_h = -\frac{L}{R} \frac{d}{dt} \bar{i}_h$$

$$\therefore \bar{i}_h(t) = K_1 \cdot e^{-t/\tau_R} = K_1 \cdot e^{-\frac{R}{L}t}$$

check

$$\bar{i}_h' = K_1 \left(-\frac{R}{L}\right) e^{-\frac{R}{L}t}$$

$$\bar{i}_h = -\frac{L}{R} \bar{i}_h' = -\frac{L}{R} \cdot K_1 \left(-\frac{R}{L}\right) e^{-\frac{R}{L}t} = K_1 e^{-\frac{R}{L}t}$$

$$\bar{i}_p \rightarrow X \text{ (a constant)}$$

(2)

$$V_s = R \bar{i}_p + L \cdot \frac{d}{dt} \bar{i}_p$$

$$= R \cdot X + L \cdot \frac{d}{dt} X$$

$$\therefore X = \frac{V_s}{R} = \bar{i}_p$$

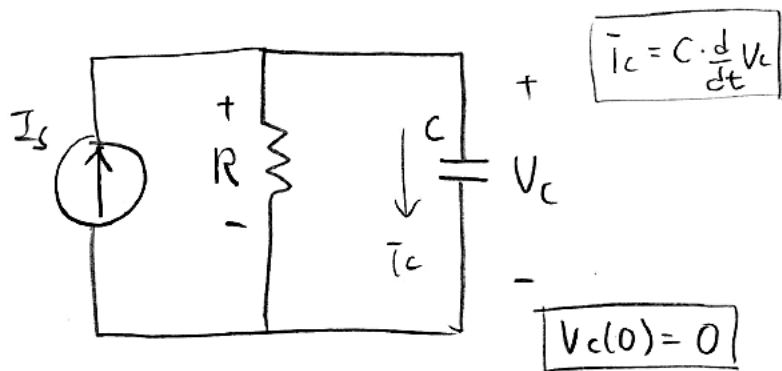
$$\bar{i}_L(t) = \bar{i}_h + \bar{i}_p = K_1 \cdot e^{-\frac{R}{L}t} + \frac{V_s}{R}$$

$$\text{as } \bar{i}_L(0) = 0 \text{ (given Ⓢ)}$$

$$K_1 \cdot e^{-\frac{R}{L} \cdot 0} + \frac{V_s}{R} = 0$$

$$\therefore K_1 = -\frac{V_s}{R}$$

$$\therefore \bar{i}_L(t) = \frac{V_s}{R} (1 - e^{-\frac{R}{L}t}) \text{ [A]}$$



$$I_s = \frac{V_c}{R} + i_c = \frac{V_c}{R} + C \cdot \frac{dV_c}{dt}$$

PDE $\Rightarrow \boxed{I_s = \frac{V_c}{R} + C \cdot \frac{dV_c}{dt}}$

Solve for $V_c(t)$ where

$$V_c(t) = V_p(t) + V_h(t), //$$

$$V_h \rightarrow \frac{V_h}{R} + C \cdot \frac{dV_h}{dt} = 0$$

$$V_h = -RC \cdot \frac{dV_h}{dt} \quad \therefore V_h = K_1 e^{-\frac{t}{RC}}$$

(check) $V_h = -RC V_h' = -RC \left(-\frac{1}{RC}\right) K_1 e^{-\frac{t}{RC}} = K_1 e^{-\frac{t}{RC}} = V_h$

$$V_p = X \text{ (a constant)}$$

(3)

$$\frac{V_p}{R} + C \cdot \frac{dV_p}{dt} = I_s$$

$$\Rightarrow \frac{X}{R} + C \cdot \frac{dX}{dt} = I_s$$

$$\boxed{X = R \cdot I_s = V_p}$$

$$V_c(t) = V_p + V_h = R \cdot I_s + K_1 e^{-\frac{t}{RC}}$$

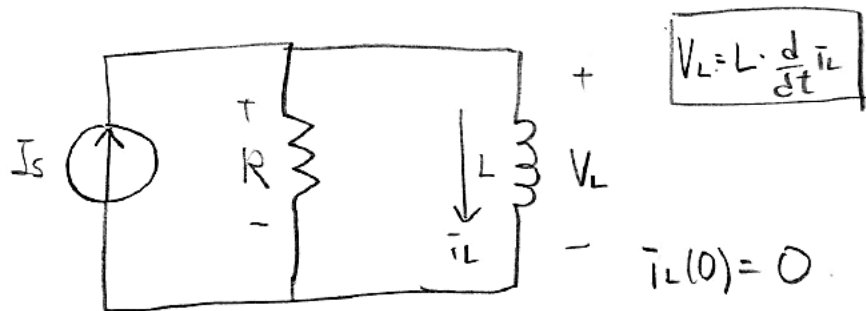
$$\text{as } V_c(0) = 0$$

$$V_c(0) = R \cdot I_s + K_1 \cdot \underbrace{e^{-0/RC}}_1 = 0$$

$$\therefore \boxed{K_1 = -RI_s}$$

$$\therefore V_c(t) = RI_s - RI_s e^{-\frac{t}{RC}}$$

$$= RI_s (1 - e^{-\frac{t}{RC}}) [V]$$



$$I_s = \frac{V_L}{R} + \bar{i}_L$$

PDE \rightarrow

$$I_s = \frac{L}{R} \frac{d \bar{i}_L}{dt} + \bar{i}_L$$

Solve for $\bar{i}_L(t)$.

$$\bar{i}_L(t) = \bar{i}_h(t) + \bar{i}_p(t)$$

$$\bar{i}_h \rightarrow \frac{L}{R} \frac{d \bar{i}_h}{dt} + \bar{i}_h = 0$$

$$\bar{i}_h = -\frac{L}{R} \frac{d \bar{i}_h}{dt} \quad \therefore \bar{i}_h(t) = K_1 e^{-\frac{R}{L}t}$$

check

$$\bar{i}_h = -\frac{L}{R} \frac{d \bar{i}_h}{dt} = -\frac{L}{R} \cdot K_1 \cdot \left(-\frac{R}{L}\right) \cdot e^{-\frac{R}{L}t} = K_1 \cdot e^{-\frac{R}{L}t} = \bar{i}_h$$

$$\bar{i}_p = X \text{ (a constant)} \quad (4)$$

$$I_s = \frac{L}{R} \frac{d \bar{i}_p}{dt} + \bar{i}_p = \frac{L}{R} \frac{d X}{dt} + X$$

$$X = \underline{I_s} = \bar{i}_p$$

$$\bar{i}_L(t) = \bar{i}_h + \bar{i}_p = K_1 e^{-\frac{R}{L}t} + I_s$$

$$\text{as } \bar{i}_L(0) = 0$$

$$\bar{i}_L(0) = K_1 \cdot \underbrace{e^{-\frac{R}{L} \cdot 0}}_1 + I_s = K_1 + I_s = 0$$

$$\therefore K_1 = -I_s$$

$$\bar{i}_L(t) = I_s (1 - e^{-\frac{R}{L}t}) \text{ [A]}$$