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Date: 02/29/2016
CS 261
Assignment 7

GRAPH TRAVERSALS

1. *How is the graph stored in the provided code -- adjacency matrix or edge list?*

All the graphs are stored in *edge list* representation. This is possible to see since the *Warshall's algorithm* for the adjacency matrix representation is not applying in any of the graphs provided.

2. *Which of the graphs are connected? How can you tell?*

All the graphs are connected except for Graph #3. It can be seen by observing the reachability among vertexes. In Graph #3, we have several unreachable vertexes, whereas all the vertexes are reachable in the other graphs. It makes sense since Graph #3 has fewer edges than vertexes, which makes impossible for all the vertexes to be connected.

3. *Imagine that we ran each search in the other direction (from destination to source, instead of source to destination) -- would the output change at all? What if the graphs were directed graphs?*

The output would change only if the graphs were directed. In this case, the label given to a vertex does not matter since we are manipulating an indirect graph, which means that all of connected vertices are reachable to each other in any direction.

4. *What are a few pros and cons of DFS vs. BFS?*

	PROS	CONS
DFS	<ul style="list-style-type: none">• DFS may take less because you don't necessarily have to store all of the child pointers at each level.	<ul style="list-style-type: none">• It's like a single person working a maze.• If solution is rare and may be deep, DFS might look a long time.
BFS	<ul style="list-style-type: none">• It is like a wave flowing through a maze.• If solution is close to the root, BFS might be better and will find it quickly.	BFS may take up more space because it looks at all paths of a specific length at once.

5. *What's the Big O execution time to determine if a node is reachable from another node?*

Taking into account that the total execution time of both DFS and BFS is $O(\text{Vertexes} + \text{Edges})$, I believe the execution time to determine if a node is reachable from another node depends on the number of neighbors that the vertex being evaluated has. Something like $O(n)$, where n is the number of neighbors a particular node has.