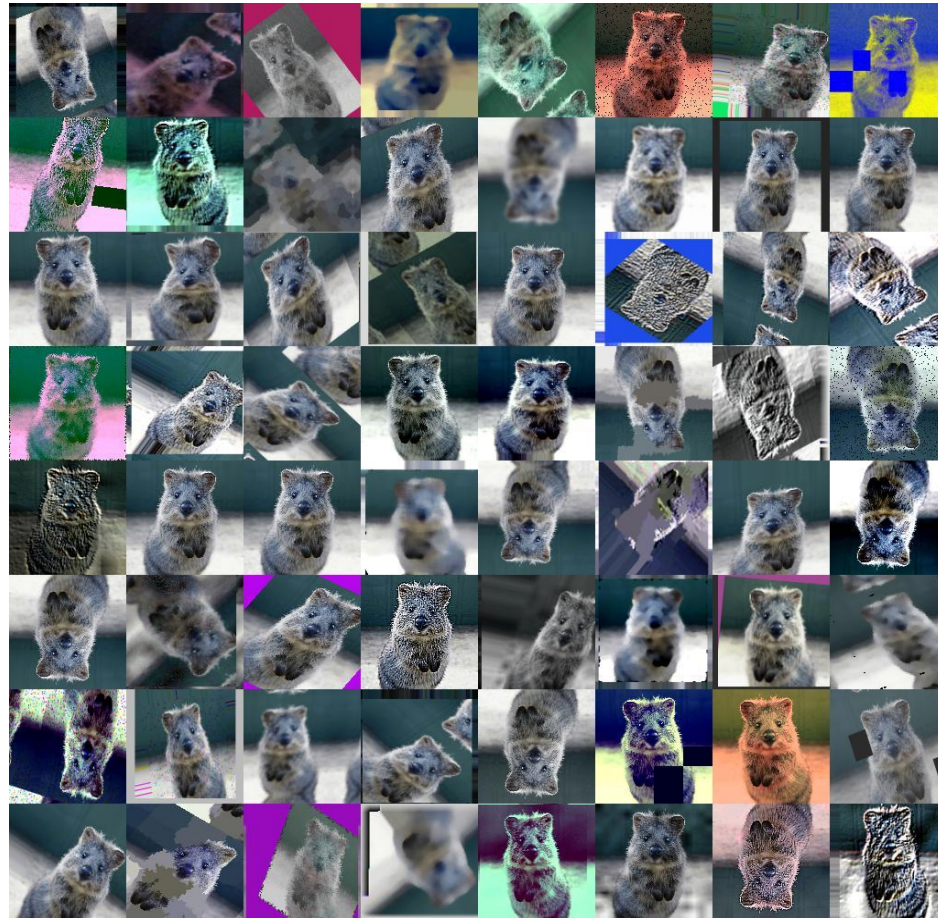


# Image Pre-Processing & Augmentation

# What is Image Augmentation?



# What do we need Image Processing?

- Need for large datasets
- Prevent Overfitting
- Feature Extraction
- Class Imbalances
- Stability of Network

# Types of Augmentation

## **Offline Augmentation**

- Used on smaller datasets
- Used to create more data from original data
- Done prior to training
- Transformations done in the beginning

## **Online Augmentation**

- Used when dataset is large
- Used to randomly modify existing data
- Done during training
- Transformations done on minibatches in dataloader

```
class ImageData(Dataset):
    def __init__(self, df, data_dir, transform=None):
        self.df = df
        self.data_dir = data_dir
        self.transform = transform

    def __len__(self):
        return len(self.df)

    def __getitem__(self, index):
        img_path = os.path.join(self.data_dir, self.df.iloc[index, 0])
        labels = torch.tensor(self.df.iloc[index, 1:], dtype=torch.long)
        img = Image.open(img_path).convert('RGB')
        if self.transform:
            image = self.transform(img)
        return (image, labels)
```

Online Augmentation code example

# Types of Transformation

## Geometric transformations

1. Flipping
2. Cropping
3. Scaling
4. Translating
5. Rotating
6. Adding Noise
7. Warping/Distorting

Original



Horizontal Flipped



Vertically Flipped



+90 Rotation



-90 Rotation



+60 Rotation



Resized from 500X500 to 100X100



Rescaled to 10:1



Cropped

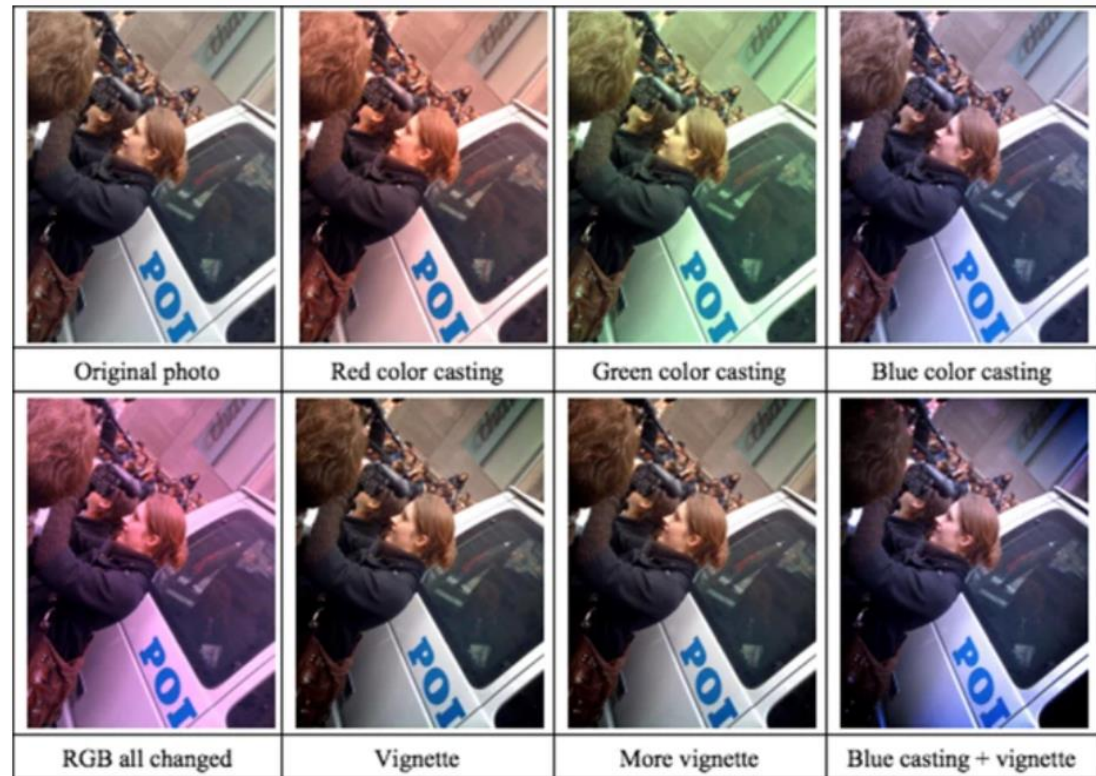
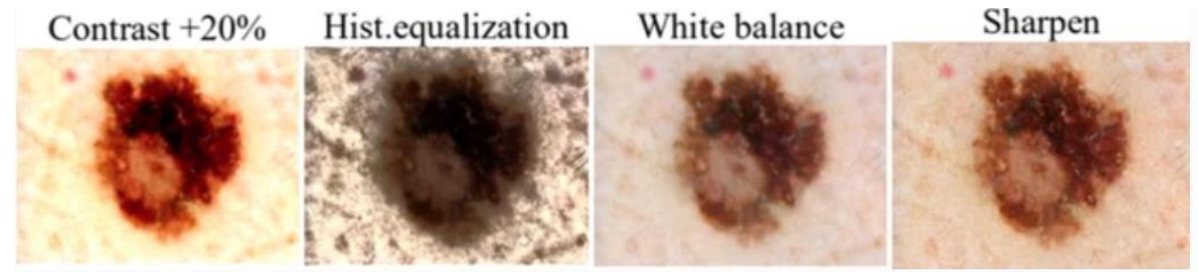




# Types of Transformations

## Colour Space Transformations

1. Colour shifting
2. Contrast
3. Sharpness
4. Blurring
5. Brightness



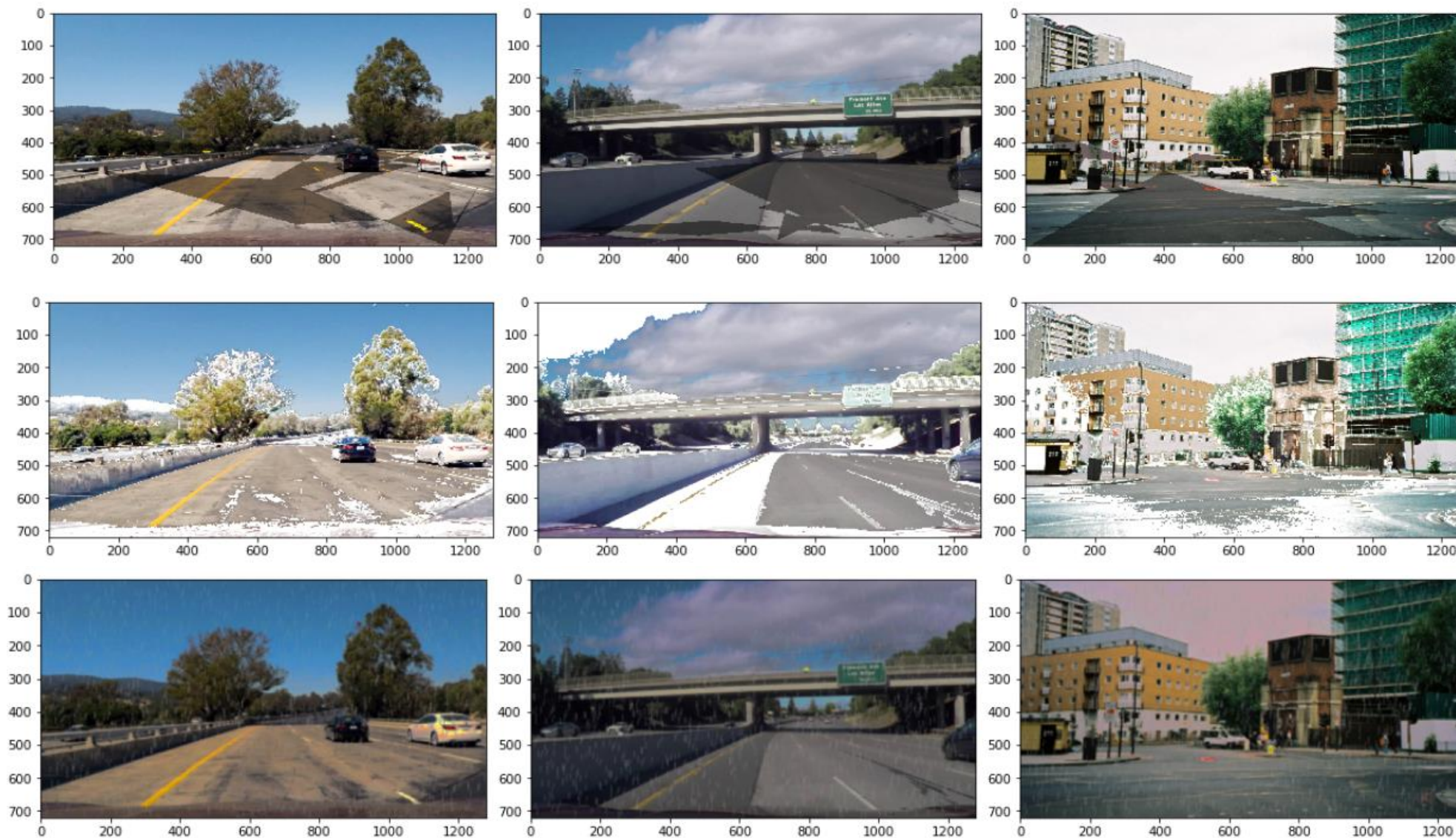
# Types of Transformations

## **Other Techniques**

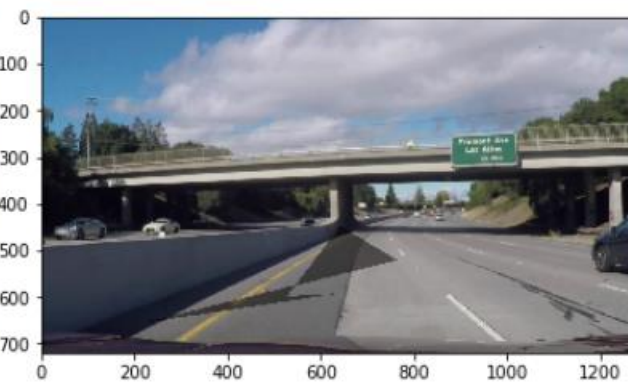
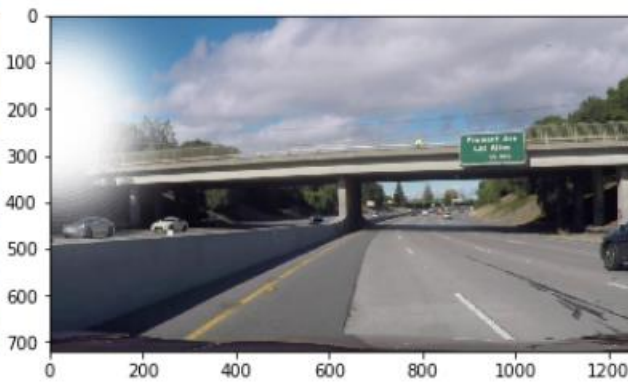
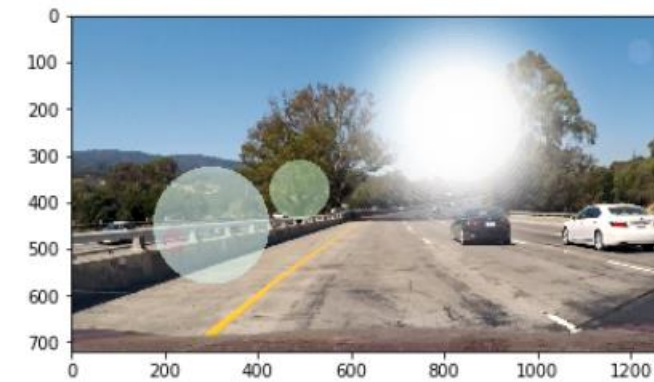
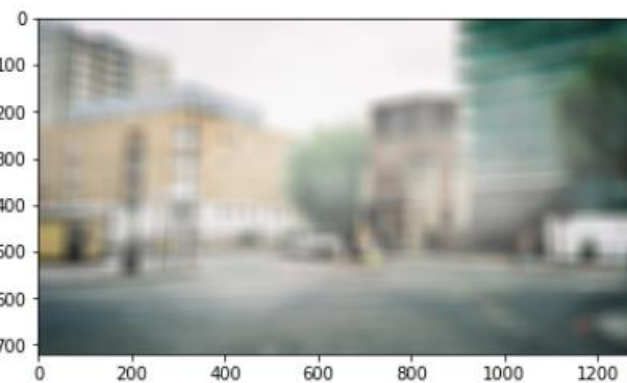
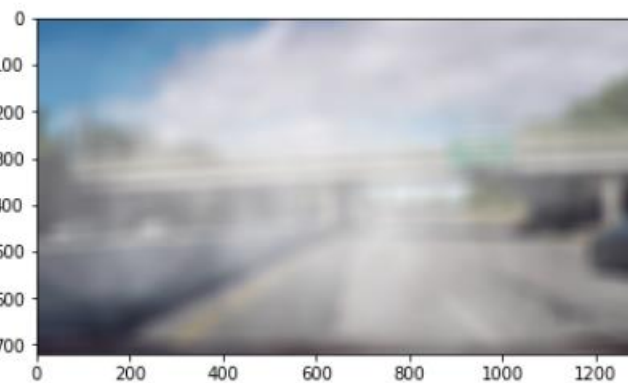
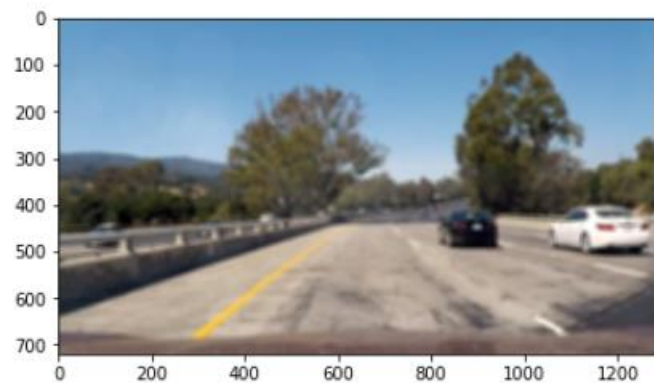
1. Pixel Dropout
2. Jitter
3. Adding
  1. Rain
  2. Snow
  3. Sunflare
  4. Shadow



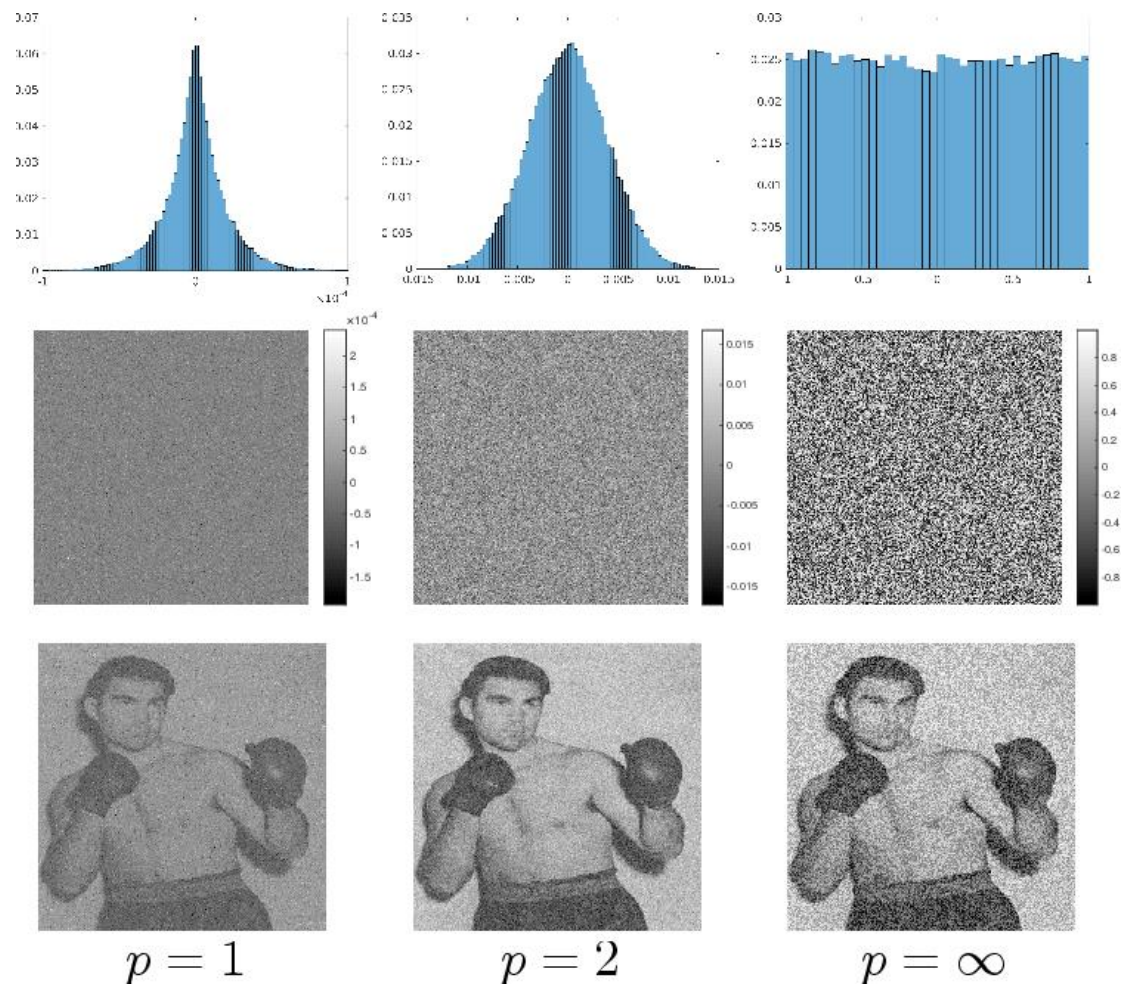
# Albumentation (Automold)







# Gaussian Noise





# Feature Invariances

- Translation
- Scaling
- Rotation



# Understanding effect of some fundamental transformations

---

## Visualizing and Understanding Convolutional Networks

---

**Matthew D. Zeiler**

Dept. of Computer Science, Courant Institute, New York University

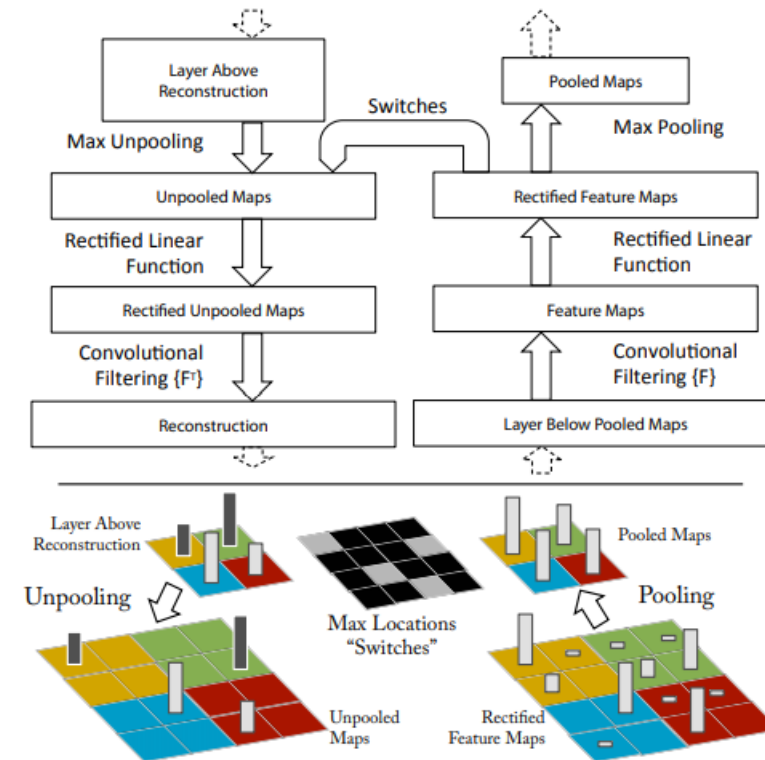
**Rob Fergus**

Dept. of Computer Science, Courant Institute, New York University

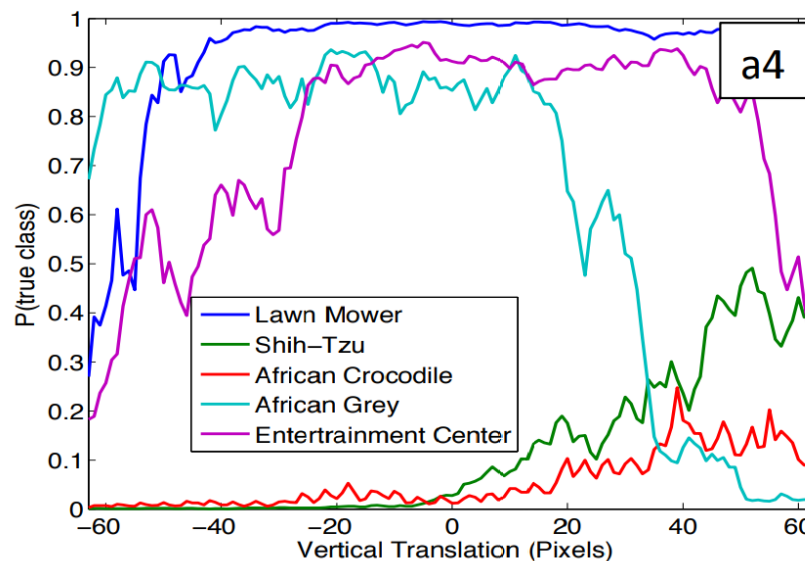
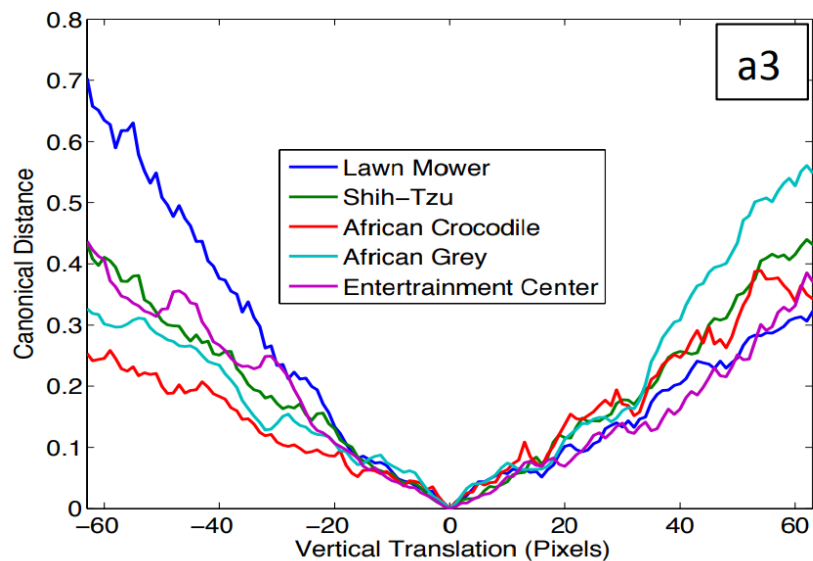
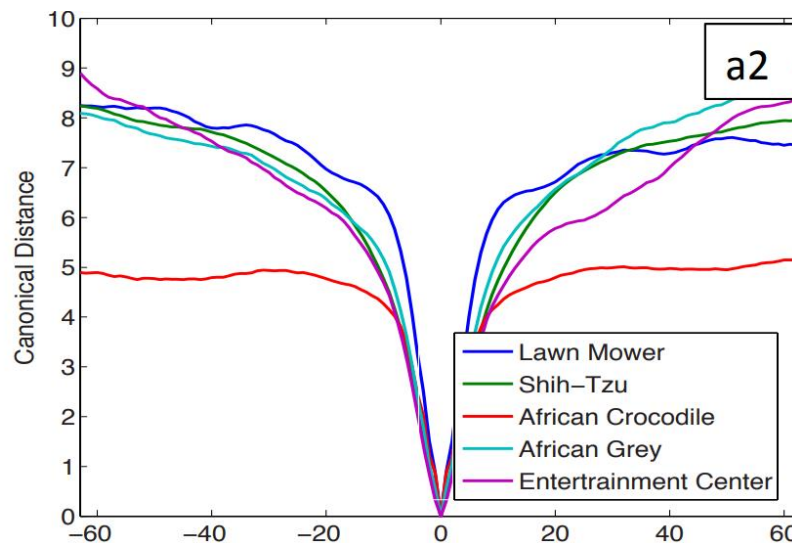
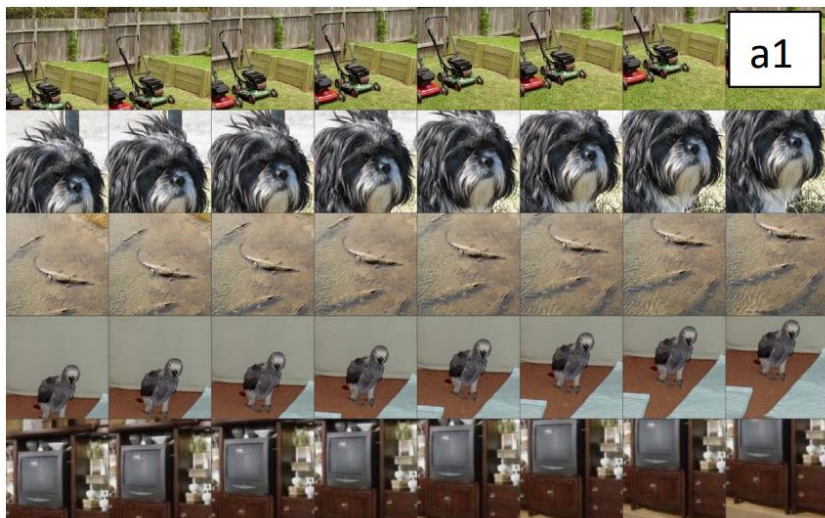
ZEILER@CS.NYU.EDU

FERGUS@CS.NYU.EDU

Link: <https://arxiv.org/abs/1311.2901>

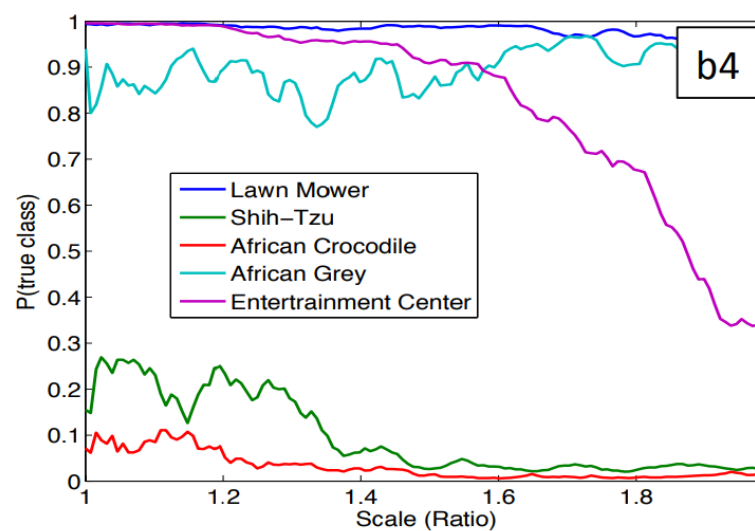
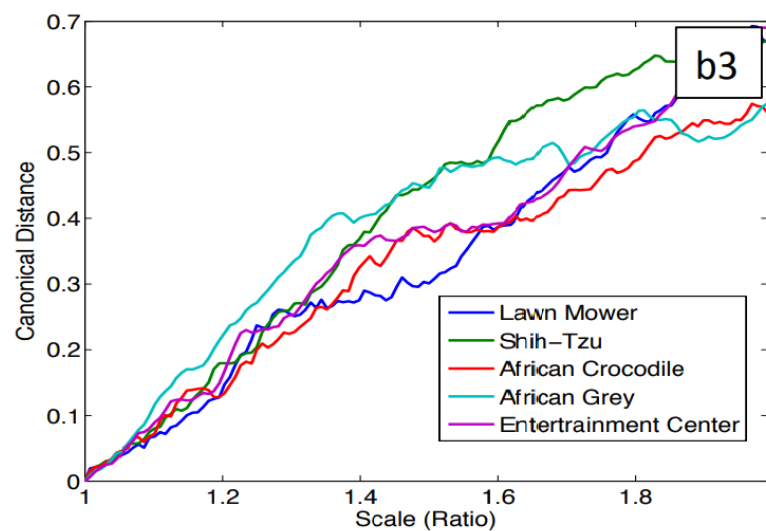
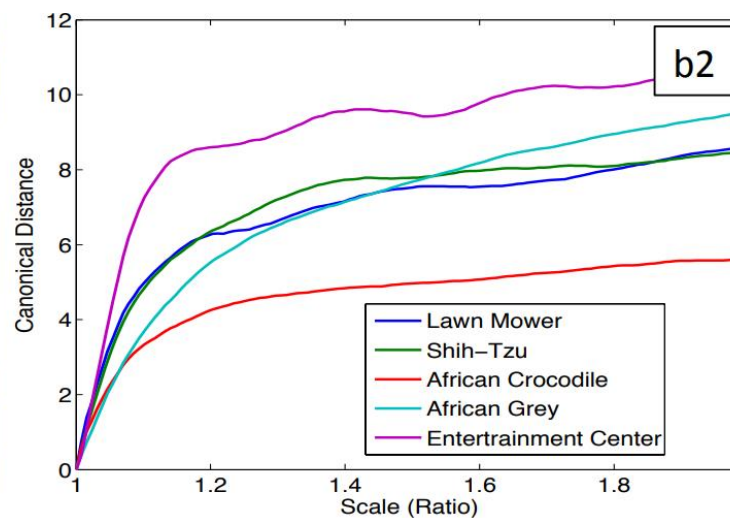


# TRANSLATION

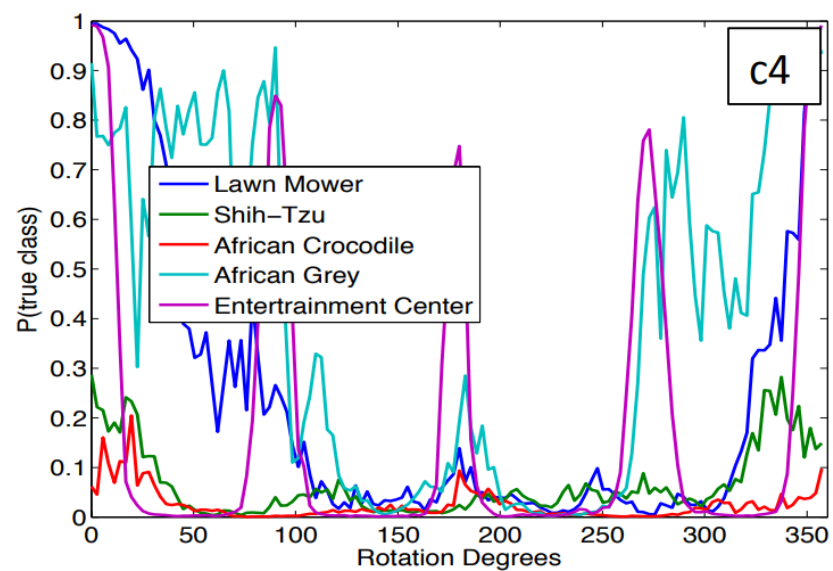
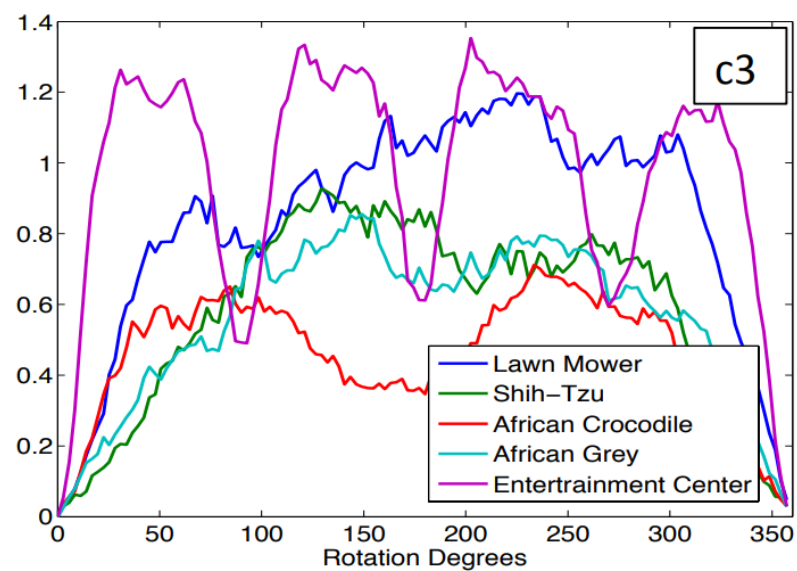
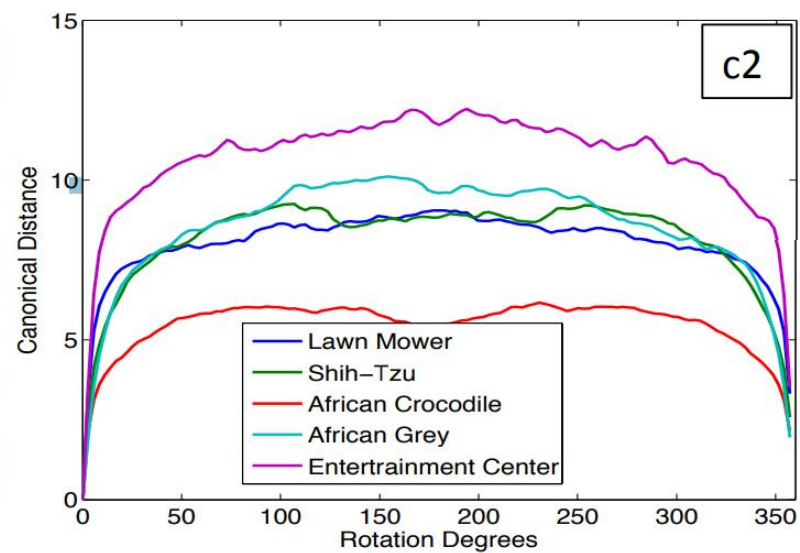
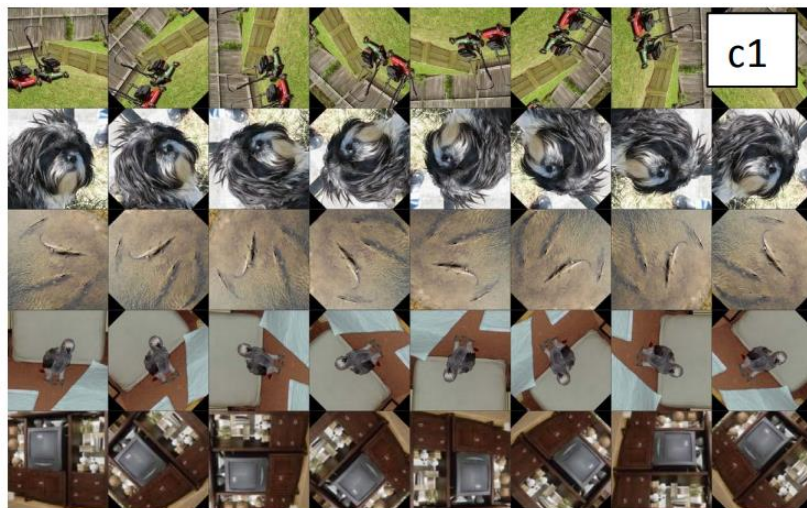




# SCALING



# ROTATION



# OBSERVATIONS

- 1<sup>st</sup> layer shows dramatic difference in output for any transformation
- 7<sup>th</sup> layer has lesser impact and is quasi-linear for translation and scaling
- Rotations are not corrected in the last layer unless the object is rotationally symmetric

# CONCLUSION

Network output is stable to translation and scaling but is not invariant to rotation



# Albumentation



Albumentations is a fast image augmentation library and easy to use wrapper around other libraries.

Albumentations package is written based on numpy, OpenCV, and imgaug. It is a very popular package written by Kaggle masters and used widely in Kaggle competitions.

# Features

Albumentations package is capable of:

- Over 60 pixel-level and spatial-level transformations;
- Transforming images with masks, bounding boxes, and keypoints;
- The library is faster than other libraries on most of the transformations;
- Organizing augmentations into pipelines;
- PyTorch integration;
- Was used to get top results in many DL competitions at Kaggle, topcoder, CVPR, MICCAI;
- Written by Kaggle Masters.



# Pixel-Level Transforms

Pixel-level transforms will change just an input image and will leave any additional targets such as masks, bounding boxes, and keypoints unchanged. The list of pixel-level transforms:

- Blur
- CLAHE
- ChannelShuffle
- HueSaturationValue
- RGBShift
- RandomBrightnessContrast
- ToGray
- GaussNoise

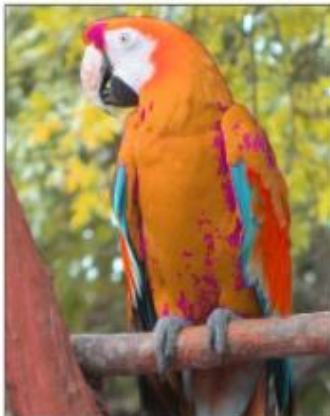
Original image



RGBShift



HueSaturationValue



ChannelShuffle



CLAHE



RandomContrast



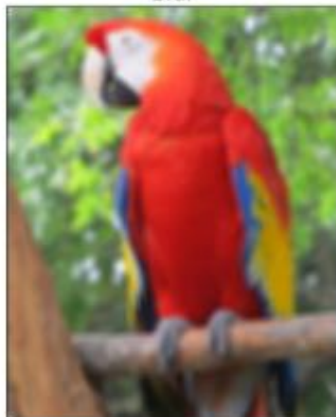
RandomGamma



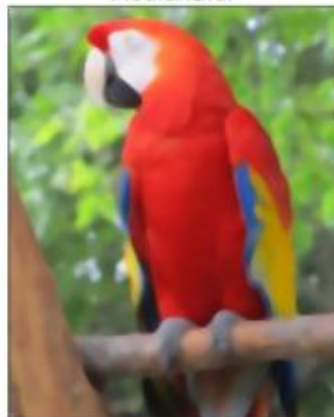
RandomBrightness



Blur



MedianBlur



ToGray



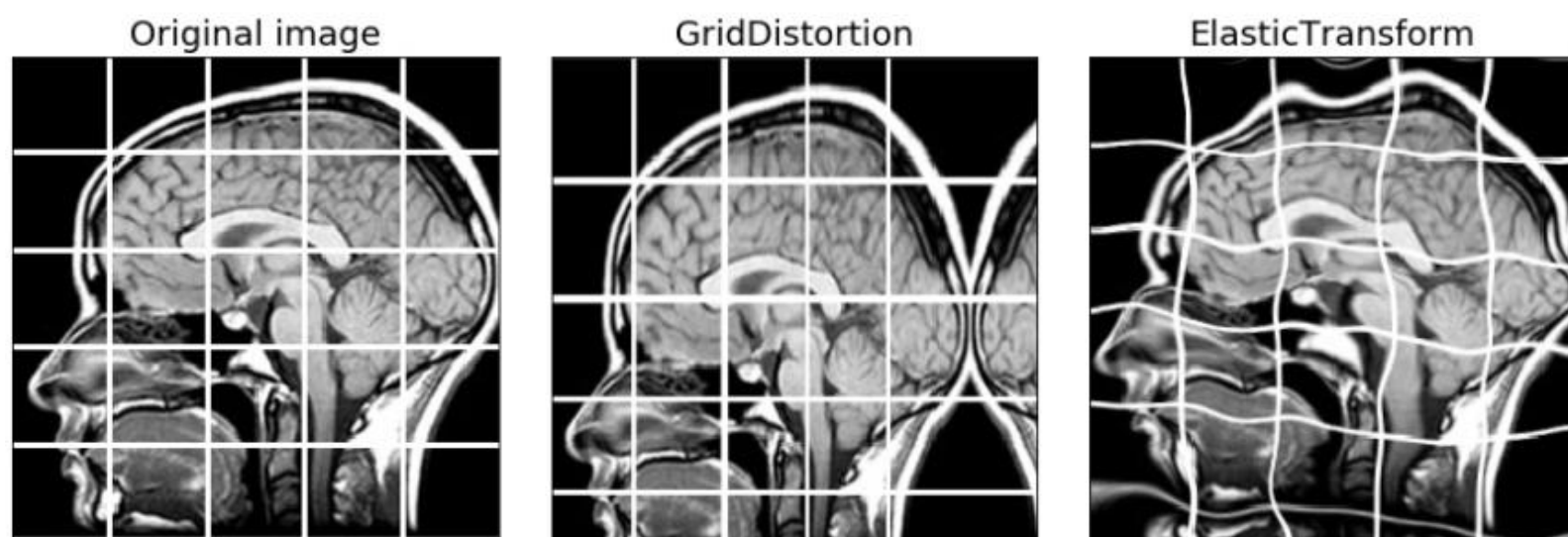
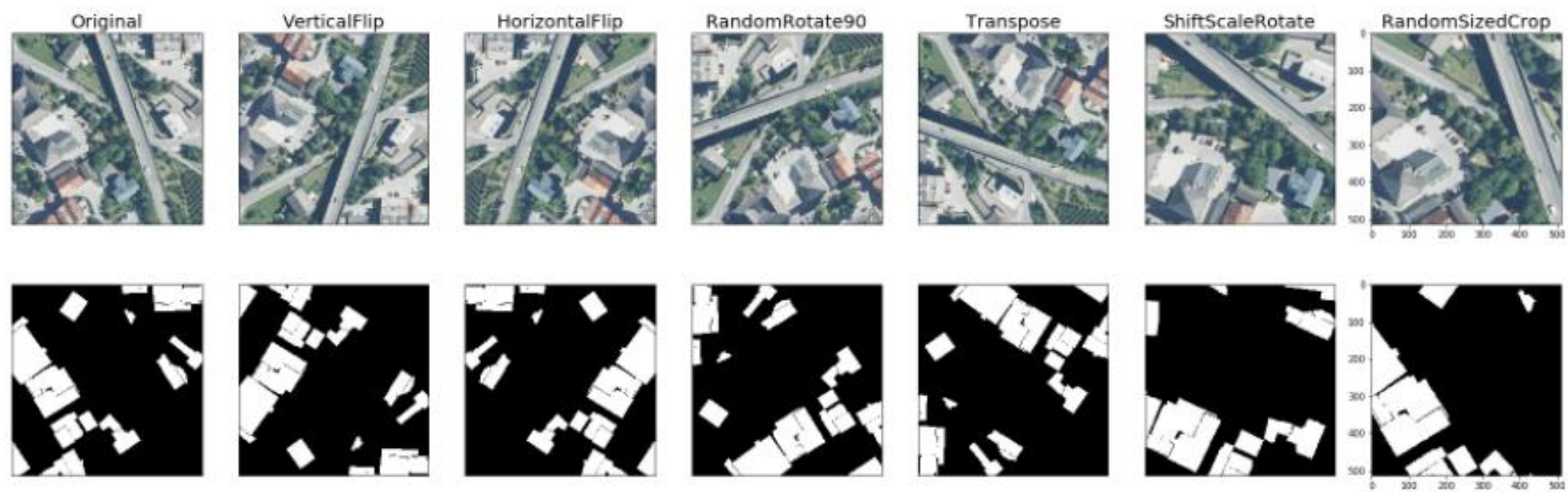
JpegCompression



# Spatial-level Transforms

Spatial-level transforms will simultaneously change both an input image as well as additional targets such as masks, bounding boxes, and keypoints.

- VerticalFlip
- HorizontalFlip
- RandomRotate90
- Transpose
- RandomResizedCrop
- GridDistortion
- ElasticTransform

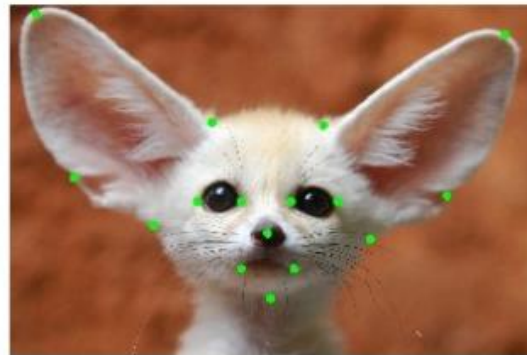




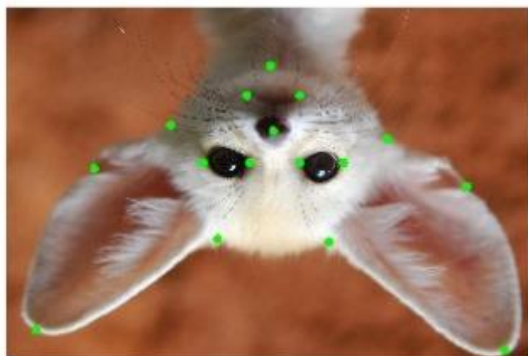
Original



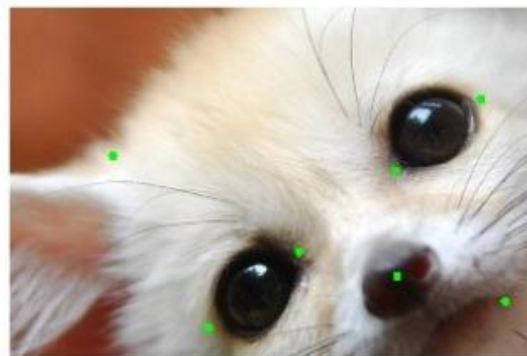
HorizontalFlip



VerticalFlip



ShiftScaleRotate



Original image



Augmented image



Original mask



Augmented mask



# Pipelines

We want to stack many transformations together into a single pipeline. Depending on the framework we are using there are different methods.

```
>>> transforms.Compose([  
>>>     transforms.CenterCrop(10),  
>>>     transforms.ToTensor(),  
>>> ])
```



```
1 # Compose a complex augmentation pipeline
2 augmentation_pipeline = A.Compose(
3     [
4         A.HorizontalFlip(p = 0.5), # apply horizontal flip to 50% of images
5         A.OneOf(
6             [
7                 # apply one of transforms to 50% of images
8                 A.RandomContrast(), # apply random contrast
9                 A.RandomGamma(), # apply random gamma
10                A.RandomBrightness(), # apply random brightness
11            ],
12            p = 0.5
13        ),
14        A.OneOf(
15            [
16                # apply one of transforms to 50% images
17                A.ElasticTransform(
18                    alpha = 120,
19                    sigma = 120 * 0.05,
20                    alpha_affine = 120 * 0.03
21                ),
22                A.GridDistortion(),
23                A.OpticalDistortion(
24                    distort_limit = 2,
25                    shift_limit = 0.5
26                ),
27            ],
28            p = 0.5
29        )
30    ],
31    p = 1
32 )
```

```

1  # Import pytorch utilities from albumentations
2  from albumentations.pytorch import ToTensor
3
4  # Define the augmentation pipeline
5  augmentation_pipeline = A.Compose(
6      [
7          A.HorizontalFlip(p = 0.5), # apply horizontal flip to 50% of images
8          A.OneOf(
9              [
10                 # apply one of transforms to 50% of images
11                 A.RandomContrast(), # apply random contrast
12                 A.RandomGamma(), # apply random gamma
13                 A.RandomBrightness(), # apply random brightness
14             ],
15             p = 0.5
16         ),
17
18         A.Normalize(
19             mean=[0.485, 0.456, 0.406],
20             std=[0.229, 0.224, 0.225]),
21
22         ToTensor() # convert the image to PyTorch tensor
23     ],
24     p = 1
25 )
26
27 # Load the augmented data

```

```

29 # Define the demo dataset
30 class DogDataset2(Dataset):
31     '''
32     Sample dataset for Albumentations demonstration.
33     The dataset will consist of just one sample image.
34     '''
35
36     def __init__(self, image, augmentations = None):
37         self.image = image
38         self.augmentations = augmentations # save the augmentations
39
40     def __len__(self):
41         return 1 # return 1 as we have only one image
42
43     def __getitem__(self, idx):
44         # return the augmented image
45         # no need to convert to tensor, because image is converted to tensor already by the p
46         augmented = self.augmentations(image = self.image)
47         return augmented['image']
48
49 # Initialize the dataset, pass the augmentation pipeline as an argument to init function
50 train_ds = DogDataset2(image, augmentations = augmentation_pipeline)
51
52 # Initilize the dataloader
53 trainloader = DataLoader(train_ds, batch_size=1, shuffle=True, num_workers=0)

```

OPEN CV & PIL

```

class TorchvisionDataset(Dataset):
    def __init__(self, file_paths, labels, transform=None):
        self.file_paths = file_paths
        self.labels = labels
        self.transform = transform

    def __len__(self):
        return len(self.file_paths)

    def __getitem__(self, idx):
        label = self.labels[idx]
        file_path = self.file_paths[idx]

        # Read an image with PIL
        image = Image.open(file_path)
        if self.transform:
            image = self.transform(image)
        return image, label

torchvision_transform = transforms.Compose([
    transforms.Resize((256, 256)),
    transforms.RandomCrop(224),
    transforms.RandomHorizontalFlip(),
    transforms.ToTensor(),
    transforms.Normalize(
        mean=[0.485, 0.456, 0.406],
        std=[0.229, 0.224, 0.225],
    )
])

```

```

class AlbumentationsDataset(Dataset):
    """__init__ and __len__ functions are the same as in TorchvisionDataset"""
    def __init__(self, file_paths, labels, transform=None):
        self.file_paths = file_paths
        self.labels = labels
        self.transform = transform

    def __len__(self):
        return len(self.file_paths)

    def __getitem__(self, idx):
        label = self.labels[idx]
        file_path = self.file_paths[idx]

        # Read an image with OpenCV
        image = cv2.imread(file_path)

        # By default OpenCV uses BGR color space for color images,
        # so we need to convert the image to RGB color space.
        image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
        if self.transform:
            augmented = self.transform(image=image)
            image = augmented['image']
        return image, label

albumentations_transform = A.Compose([
    A.Resize(256, 256),
    A.RandomCrop(224, 224),
    A.HorizontalFlip(),
    A.Normalize(
        mean=[0.485, 0.456, 0.406],
        std=[0.229, 0.224, 0.225],
    ),
    ToTensorV2()
])

```

# Data Augmentation as a subfield

Fig. 2

