Array Concepts

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Agenda

Array Concepts

- Terminology
- Declarations
- Syntax
- Expressions
- Intrinsic functions
- Allocatable arrays





Array Terminology

```
real, dimension(15) :: A
real, dimension(-4:0,0:2) :: B
real C(5,3), D(0:4,0:2)
```

```
A:
rank=1, size=15, shape=15
B:
rank=2, size=15, shape=5x3
C:
rank=2, size=15, shape=5x3
D:
rank=2, size=15, shape=5x3
```

B,C,D are conformable

- rank : number of dimensions
- bounds: upper and lower limits of indices
- extent : number of elements in dimensions
- size: total number of elements
- shape : rank and extents
- conformable: same shape, B and C and D





Array Declarations

Literals and constants can be used in array declarations,

```
real, dimension(15) :: A
real, dimension(-4:0,0:2) :: B

integer, dimension(20) :: N

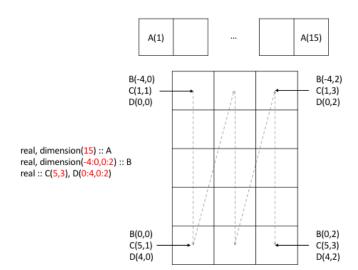
integer, parameter :: UB = 5
real, dimension(0:UB-1) :: Y
real, dimension(1+UB*UB,10) :: Z
```

- Default lower bound is 1
- Bounds can begin and end anywhere
- Arrays can be zero-sized





Array visualization





Array Syntax

Using the earlier declarations, references can be made to:

• whole arrays (conformable)

$$\begin{array}{l} \mathsf{A} = \mathsf{0} \leftarrow \mathsf{sets} \ \mathsf{whole} \ \mathsf{array} \ \mathsf{A} \ \mathsf{to} \ \mathsf{zero} \\ \mathsf{B} = \mathsf{C} + \mathsf{1} \leftarrow \mathsf{adds} \ \mathsf{one} \ \mathsf{to} \ \mathsf{all} \ \mathsf{elements}, \ \mathsf{of} \ \mathsf{C} \\ \mathsf{and} \ \mathsf{then} \ \mathsf{assigns} \ \mathsf{each} \ \mathsf{element} \ \mathsf{to} \ \mathsf{the} \ \mathsf{corresponding} \\ \mathsf{element} \ \mathsf{of} \ \mathsf{B} \end{array}$$

elements

$$A(1) = 0.0 \leftarrow$$
 sets one element to zero $B = A(3) + C(5,1) \leftarrow$ sets whole array B to the sum of two elements

array sections

$$A(2:6) = 0 \leftarrow sets \ section \ of \ A \ to \ zero$$
 $B(-1:0,1:2) = C(1:2,2:3) + 1 \leftarrow adds \ one \ to \ the \ subsection$
of C and assigns it to the subsection of B



Array Expressions

Arrays can be treated like a single variable in that:

- can use intrinsic operators between conformable arrays (or sections)
 - B = C * D B**2
- elemental intrinsic functions can be used
 - $B = \sin(C) + \cos(D)$





An array can be subscripted by a *subscript-triplet* giving rise to a sub-array of the original. The general form is:

```
(start:end:stride)
```

the section starts at *start* and ends at ot before *end.stride* is the increment by which the locations are selected.

start, end, stride must all be scalar integer expressions. Thus, these are all valid:



1



Array Inquiry

Consider the declaration:

REAL, **DIMENSION**(-10:10,23,14:28) :: A

Then:

- LBOUND(SOURCE[,DIM]) lower bounds of an array (or bound in an optionally specified dimension).
 - LBOUND(A) is (/-10,1,14/) (array).
 - LBOUND(A,1) is -10 (scalar)
- UBOUND(SOURCE[,DIM]) upper bounds of an array (or bound in an optionally specified dimension).
- SHAPE(SOURCE) shape of an array.
 - SHAPE(A) is (/21,23,15/) (array).
 - SHAPE((/4/)) is (/1/) (array)
- SIZE(SOURCE[,DIM]) total number of array elements (in an optionally specified dimension).
 - SIZE(A,1) is 21.
 - SIZE(A) is 7245
- ALLOCATED(SOURCE) array allocation status





Array Constructors

Used to give arrays or sections of arrays specific values. For example,

Then:

- constructors and array sections must conform.
- must be 1D.
- for higher rank arrays use RESHAPE intrinsic





RESHAPE

RESHAPE is a general intrinsic function which delivers an array of a specific shape:

RESHAPE(SOURCE, SHAPE)

e.g.:

$$A = RESHAPE((/1,2,3,4/),(/2,2/))$$

A is filled in array element order and looks like:

- 1
- 2 4





Array Constructors in Initialization Statements

Named array constants can be created

In the second statement all strings must be same length.





Allocatable Arrays

Fortran allows arrays to be created on-the-fly; these are known as *deferred-shape* arrays and use dynamic heap storage.

Deferred-shape arrays are

- declared like explicit-shape arrays but without the extents and with the ALLOCATABLE attribute.
 - integer, dimension(:), ALLOCATABLE :: ages
 - real, dimension(:,:), ALLOCATABLE :: speed
- given a size in an ALLOCATE statement which assigns an area of memory to the object.
 - ALLOCATE(ages(1:10), STAT=ierr)
 - ALLOCATE(speed(-lwb:upb,-50:0),STAT=ierr)
- the optional STAT= field reports on the success of the storage request. If the INTEGER variable ierr is zero the request was successful otherwise it failed.





Deallocating Arrays

Heap storage can be reclaimed using the DEALLOCATE statement:

- it is an error to deallocate an array without the ALLOCATE attribute or one that has not been previously allocated space.
- there is an intrinsic function, ALLOCATED, which returns a scalar LOGICAL values reporting on the status of an array.
- the STAT= field is optional but its use is recommended
- if a procedure containing an allocatable array which does not have the SAVE attribute is exited without the array being DEALLOCATE d then this storage becomes inaccessible





Masked Array Assignment - Where Statement

This is achieved using WHERE

WHERE
$$(I /= 0) A = B/I$$

the LHS of the assignment must be array valued and the mask, (the logical expression,) and the RHS of the assignment must all conform. For example, if

$$B = \begin{pmatrix} 1.0 & 2.0 \\ 3.0 & 4.0 \end{pmatrix}$$

and

$$I = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$$

then

$$A = \begin{pmatrix} 0.5 & -\\ - & 2.0 \end{pmatrix}$$

Only the elements, corresponding to the non-zero elements of I, have been assigned to.



Where Construct

There is a block form of masked assignment

```
1 WHERE(A > 0.0)
2 B = LOG(A)
3 C = SQRT(A)
4 ELSEWHERE
5 B = 0.0
6 ENDWHERE
```

- the mask must conform to the RHS of each assignment; A, B and C must conform
- WHERE ... END WHERE is not a control construct and cannot currently be nested
- the STAT= field is optional but its use is recommended
- the execution sequence is as follows: evaluate the mask, execute the WHERE block (in full) then execute the ELSEWHERE block



• the separate assignment statements are executed sequentially but the individual elemental assignments within each statement are (conceptually) executed in parallel



Vector-valued subscripts

A 1D array can be used to subscript an array in a dimension. Consider

```
integer, dimension(5) :: V = (/1,4,8,12,10/) integer, dimension(3) :: W = (/1,2,2/)
```

- A(V) is A(1), A(4), A(8), A(12), and A(10).
- the following are valid assignments:

$$A(V) = 3.5$$

 $C(1:3,1) = A(W)$

- it would be invalid to assign values to A(W) as A(2) is referred to twice
- only 1D vector subscripts are allowed, for example

$$A(1) = SUM(C(V,W))$$





Exercise

We will solve a computational problem that converts temperatures in Fahrenheit to Kelvin

$$K = \frac{5}{9}(F - 32) + 273.15 \tag{1}$$

Using a text editor open the file arrays_exercise.F90 and *complete* the empty code blocks. You will:

- Perform the conversion
- Print the F and K values
- Print the log of F (careful!)

Then build the executable and run the code using the provided Makefile.

