

# Chetan Sharma

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## EDUCATION

### MIT

CANDIDATE FOR MASTERS IN EECS  
BS IN EECS  
MINOR IN MECHE  
Cambridge, MA  
Cum. GPA: 4.4

### WESTVIEW HIGH SCHOOL

Grad. May 2015 | San Diego, CA  
Cum. GPA: 4.3

## COURSEWORK

### EECS

Advances in Computer Vision  
Computational Photography  
Machine Learning  
Autonomous Vehicles  
Algorithms  
Software Construction  
Control System Design  
Signals and Systems  
Analog Electronics Lab  
Computation Structures

### MECHANICAL ENGINEERING

Biomimetic Robotics  
Precision Machine Design (Graduate)  
Medical Device Design (Graduate)  
Dynamics and Control  
Mechanics and Materials  
Mechanical Engineering Tools  
MATLAB Numerical Computation  
Differential Equations

## SKILLS

### Software Packages

ROS • Altium Designer • LTSpice •  
Solidworks • Autodesk Inventor •  
LabView • Flask • Pandas

### Programming Languages

Python • Java • C++ • MATLAB •  $\text{\LaTeX}$  •  
CSS • HTML • JavaScript

### Fabrication

Machine Tools • NC Equipment •  
Board Fab

## LINKS

Portfolio: [cactode.club](https://cactode.club/)  
GitHub: [github.com/cactode](https://github.com/cactode)  
LinkedIn: [linkedin.com/in/cactode](https://www.linkedin.com/in/cactode)

## EXPERIENCE

### ANDURIL INDUSTRIES | MECHANICAL / CONTROLS INTERN

May 2019 - August 2019 | Santa Ana, CA

- Created newest revision of high-reliability pan-tilt unit for defense applications
- Handled all mechanical/electrical/controls/planning aspects of design
- Used computer-driven optimization to increase positioning speed by 3x

### NVIDIA CORPORATION | RF VALIDATION INTERN

May 2018 - August 2018 | Santa Clara, CA

- Created an internal analytics tool to automate RF data visualization
- Eliminated a large portion of the prior RF validation pipeline
- Took full ownership of a project while coordinating the needs of multiple users

### DISTRIBUTED ROBOTICS LAB | RESEARCHER

September 2017 - January 2019 | Cambridge, MA

- Designed novel autonomous robot capable of 2D fabrication using a jigsaw
- Optimized structure of shearing auxetic materials (paper published)

### AMAZON ROBOTICS | GLOBAL OPERATIONS INTERN

May 2017 - August 2017 | Seattle, WA

- Optimized automation technologies with projected savings of \$100,000
- Automated analysis on 200k data points to inform purchasing decisions

### NASA JET PROPULSION LAB | POWER ELECTRONICS INTERN

May 2016 - Aug 2016 | Los Angeles, CA

- Created & tested power subsystems for Mars 2020 instrumentation
- Designed high-reliability switched regulators & sourced specialty components

## PERSONAL PROJECTS

### BATTLEBOTS SEASON 4 COMPETITOR | December 2018 - April 2019

Worked with a team to build a 250lb combat robot for Discovery Channel's Battlebots television show. Contributed to design, manufacturing, and funding of robot. Robot placed highly in final rankings.

### DORM KITCHEN CLEANLINESS WEB APP | July 2018 - August 2018

Created a secure Flask web application that allows dormitory residents to monitor kitchen cleanliness and identify individuals that leave behind dishes.

### AUTOMATIC VORTEX RING LAUNCHER | January 2018

Designed and programmed a 40lb machine that would track the faces of passerby and fire vortex rings in their direction. Project required extensive research into vortex ring formation theory. OpenCV, MATLAB, and Solidworks were used in design.

## AWARDS

2018	First Place	QVC Prize @ HackMIT Hackathon
2017	Third Place	Assistive Technologies Hackathon
2017	Third Place	MakeMIT Hardware Hackathon
2016	First Place	MakeMIT Hardware Hackathon