

# Chetan Sharma

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## EDUCATION

### MIT

CANDIDATE FOR MASTERS IN EECS  
BS IN EECS '19  
MINOR IN MECHE  
Cambridge, MA  
Cum. GPA: 4.4

### WESTVIEW HIGH SCHOOL

Grad. May 2015 | San Diego, CA  
Cum. GPA: 4.3

## COURSEWORK

### EECS

Advances in Computer Vision (Grad)  
Computational Photography (Grad)  
Machine Learning  
Autonomous Vehicles  
Algorithms  
Control System Design  
Analog Electronics Lab

### MECHANICAL ENGINEERING

Biomimetic Robotics (Grad)  
Precision Machine Design (Grad)  
Medical Device Design (Grad)  
Dynamics and Control  
Mechanics and Materials  
MATLAB Numerical Computation

## SKILLS

### Software Packages

ROS • Altium Designer • LTSpice  
Solidworks • Autodesk Inventor  
LabView • Flask • Pandas

### Programming Languages

Python • Java • C++ • MATLAB  
L<sup>A</sup>T<sub>E</sub>X • CSS • HTML • JavaScript  
Fabrication

Machine Tools • CNC Equipment  
Board Fab

## LINKS

Portfolio: [cactode.club](https://cactode.club)  
GitHub: [github.com/cactode](https://github.com/cactode)  
LinkedIn: [linkedin.com/in/cactode](https://www.linkedin.com/in/cactode)

## EXPERIENCE

### ALFA LAB @ CSAIL | RESEARCHER

August 2019 - Ongoing | Cambridge, MA

- Researching the prediction of malware evolution over time
- Exploring data-driven methods to predict future strains and protect against them

### ANDURIL INDUSTRIES | MECHANICAL & CONTROLS INTERN

May 2019 - August 2019 | Santa Ana, CA

- Created newest revision of high-reliability pan-tilt unit for defense applications
- Handled all mechanical/electrical/controls/planning aspects of design
- Used computer-driven optimization to increase positioning speed by 3x

### NVIDIA CORPORATION | RF VALIDATION INTERN

May 2018 - August 2018 | Santa Clara, CA

- Created an internal analytics tool to automate RF data visualization
- Eliminated a large portion of the prior RF validation pipeline
- Took full ownership of a project while coordinating the needs of multiple users

### DISTRIBUTED ROBOTICS LAB @ CSAIL | RESEARCHER

September 2017 - January 2019 | Cambridge, MA

- Designed novel autonomous robot capable of 2D fabrication using a jigsaw
- Optimized structure of shearing auxetic materials (paper published)

### AMAZON ROBOTICS | GLOBAL OPERATIONS INTERN

May 2017 - August 2017 | Seattle, WA

- Optimized automation technologies with projected savings of \$100,000
- Automated analysis on 200k data points to inform purchasing decisions

## PERSONAL PROJECTS

### DORM KITCHEN CLEANLINESS WEB APP | July 2018 - August 2018

Created a secure Flask web application that allows dormitory residents to monitor kitchen cleanliness and identify individuals that leave behind dishes.

### TWITCH-CONTROLLED CRANE GAME | September 2018

Programmed and constructed a 10ft x 10ft super-sized claw machine for HackMIT. Machine parsed commands from Twitch chat and allowed for teleoperation of crane. Won QVC First Place prize; demoed to their executives.

### AUTOMATIC VORTEX RING LAUNCHER | January 2018

Designed and programmed a 40lb machine that would track the faces of passerby and fire vortex rings in their direction. Project required extensive research into vortex ring formation theory. OpenCV, MATLAB, and Solidworks were used in design.

## AWARDS

2018	First Place	QVC Prize @ HackMIT Hackathon
2017	Third Place	Assistive Technologies Hackathon
2017	Third Place	MakeMIT Hardware Hackathon
2016	First Place	MakeMIT Hardware Hackathon