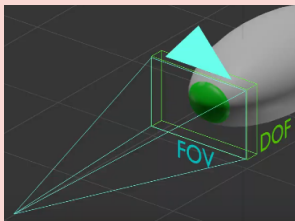


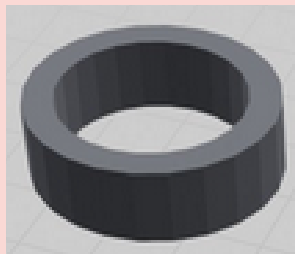
Camera Model



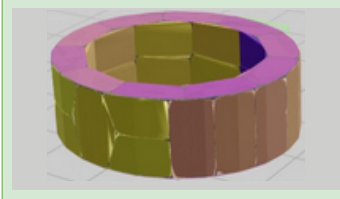
Pointcloud Resampling



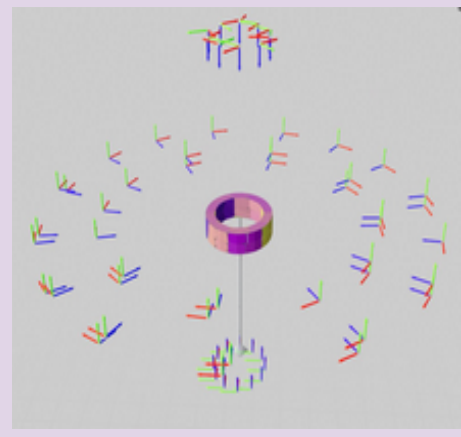
Surface Model



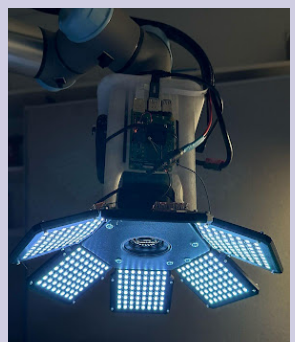
Camera based K-Means Segmentation



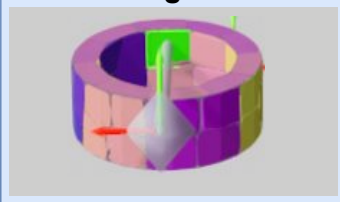
Viewpoint (VP) Generation



Image



Optimize VP for Line of Sight



Order VP for Traversal

