Variance Reduction for Multi-physics Analysis of Moving Systems

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Preliminary Exam

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Introduction

Shutdown Dose Rate (SDR) Analysis

- Fusion Energy Systems (FES)
  - Burning plasma, D-T fusion
  - ${}^{2}_{1}H + {}^{3}_{1}H \rightarrow {}^{4}_{2}He + {}^{1}_{0}n$
- Neutrons penetrate deeply into system components, causing activation
- Radioisotopes persist long after shutdown
- Important to quantify the dose caused by decay photons

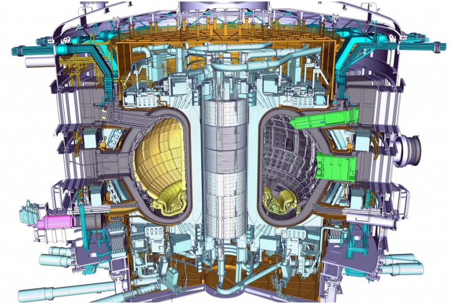
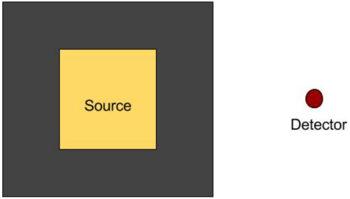


Figure : Cutaway view of ITER drawing.

SDR Analysis: Movement After Shutdown

- FES are designed with modular components
  - Can move during maintenance procedure
- Interested in SDR at a particular location
- SDR will change as a function of the activated component's position over time



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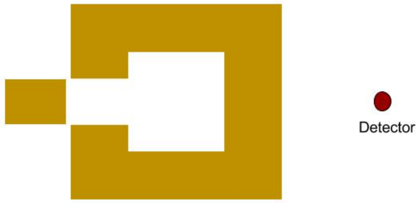

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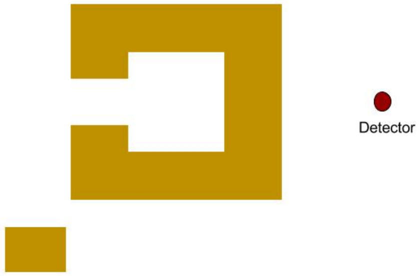

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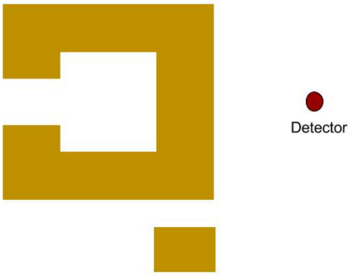

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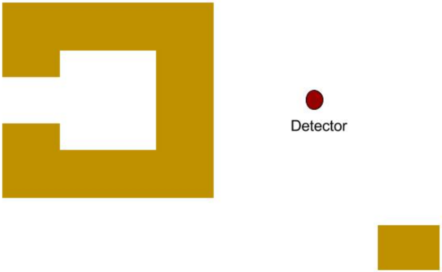

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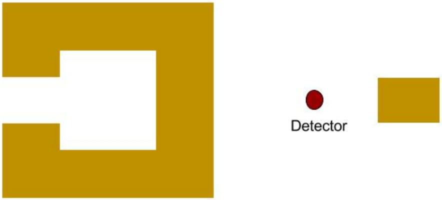

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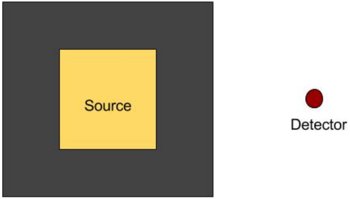
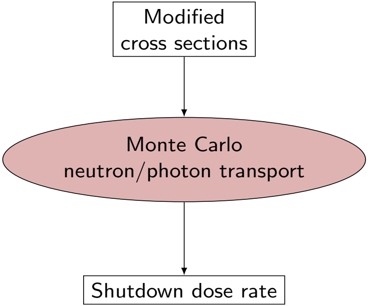


Goal

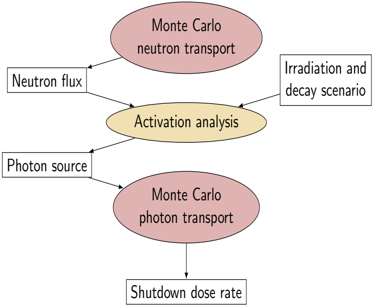
Optimize the calculation of the **shutdown dose rate** at a particular location as activated components are **moving** around the facility.

SDR Solution Methods

Direct 1-Step Method (D1S)



Rigorous 2-Step Method (R2S)



Monte Carlo Radiation Transport

- Monte Carlo (MC) analysis of FES is:
  - Accurate for large, complex models
  - Challenging due to the highly attenuating structural materials
    - Results scored in regions that have low particle flux, have higher statistical uncertainty

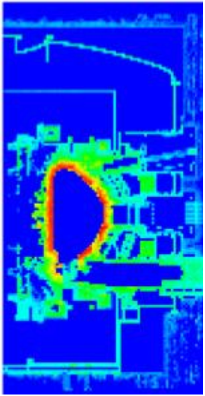


Figure : Photon flux in ITER tokamak building.

Error in MC Calculations

- Uncertainty in MC Calculations:

$$\Re = \frac{\sigma_{\overline{x}}}{\overline{x}} \tag{1}$$

- $\sigma_{\overline{x}}$ is proportional to $1/\sqrt{\#histories}$
- To decrease statistical uncertainty:
  - Increase number of histories
  - Use variance reduction (VR) techniques

MC Variance Reduction Techniques

- Techniques to modify particle behavior
  - **Goal:** preferentially sample events that will contribute to results of interest
- Statistical weight of particles is adjusted to keep playing a fair game

Hybrid Deterministic/MC VR Methods: CADIS

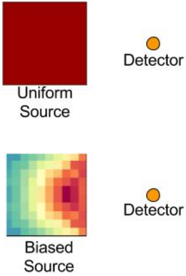
Consistent Adjoint Driven Importance Sampling (CADIS)

- Adjoint flux can define the importance of regions of phase space to the detector response
- Use **deterministic** estimate of the adjoint flux, Ψ^+, to generate **Monte Carlo** VR parameters
- Define detector response function to be the adjoint source

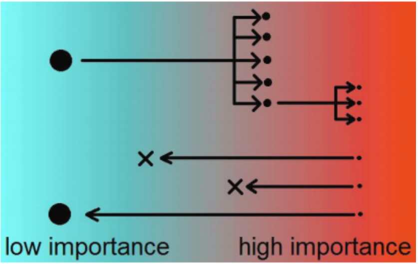
Hybrid Deterministic/MC VR Methods: CADIS

- Use the adjoint flux to generate MC source and transport biasing parameters

Source: biased PDF



Transport: weight windows



Variance Reduction for SDR Analysis

VR for **photon** transport

- **Straightforward**
- Can use CADIS method to direct photons towards detector
  - Flux-to-dose-rate conversion factors define adjoint source

VR for **neutron** transport

- More **complicated**
- Biasing function needs to capture
  1. Potential of regions to become activated
  2. Potential to produce photons that will contribute to the SDR
- Can use CADIS if we can construct adjoint source that will fulfill these criteria

Variance Reduction for SDR Analysis: MS-CADIS

Multi-**S**tep (MS)-CADIS

- VR method to optimize the initial radiation transport step of a coupled, multi-step process
  - Relies upon function that represents importance of particles to final response of interest
- When applied to SDR analysis, MS-CADIS will optimize the neutron transport
  - Use function that represents the importance of the neutrons to the final shutdown dose rate

Variance Reduction for SDR Analysis: GT-CADIS

Groupwise **T**ransmutation (GT)-CADIS

- Implementation of MS-CADIS specifically for SDR analysis
- Provides method to calculate optimal adjoint neutron source, q_n^+, by first calculating, T, a term that relates the neutron flux to photon source

Moving Geometries and Sources

MCNP6 Moving Objects

- Update in future version of MCNP6
- Allows movement of objects, sources, delayed particles during single simulation
- Available for native MCNP geometry descriptions (not mesh)

Mesh Coupled implementation of R2S (MCR2S)

- Capability that allows components to move before photon transport step
- Transformations are applied to copies of moving components
- Original component still in original location, set to void material

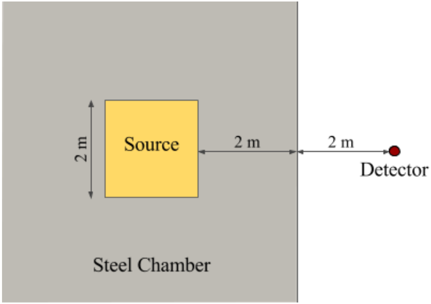
Review

- MC method is most accurate way to obtain detailed particle flux distributions
  - Use MC codes for both neutron and photon transport steps of R2S
  - Need to use VR methods to optimize the transport calculations
- GT-CADIS, an implementation of MS-CADIS, has proven to optimize the neutron transport step of R2S
- MCNP6 and MCR2S have developed some capabilities for performing transport on moving geometries

Demonstration

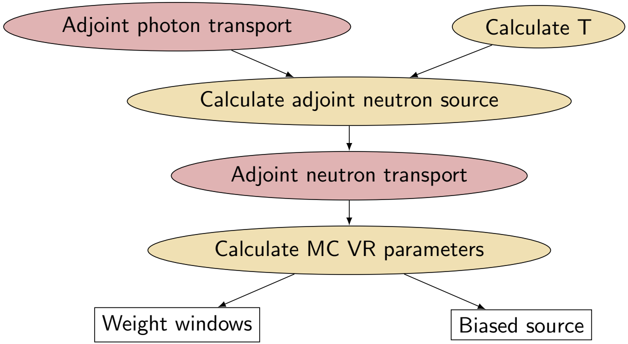
GT-CADIS Demonstration

- Geometry
  - Steel chamber
  - 2m x 2m x 2m central cavity
- Source
  - Volume source in central cavity
  - 13.8-14.2 MeV neutrons
- Detector
- Calculate SDR
- 2m away from chamber



GT-CADIS Demonstration

- GT-CADIS workflow



GT-CADIS Demonstration

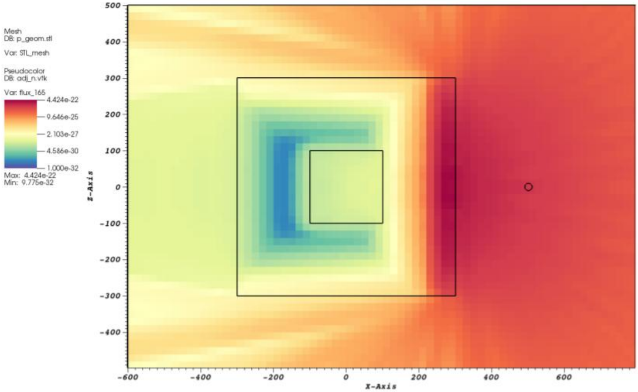


Figure : GT-CADIS adjoint neutron flux. Functions as importance map.

GT-CADIS Demonstration

GT-CADIS importance map is **insufficient** for moving systems.

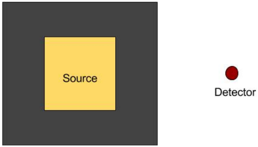
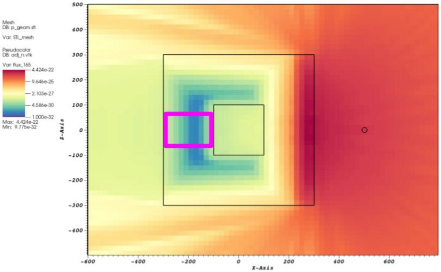


Figure : Demo model.



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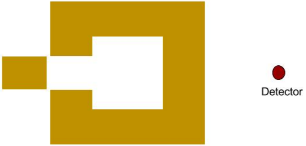

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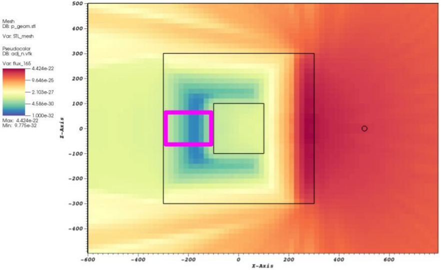

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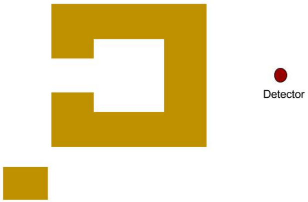

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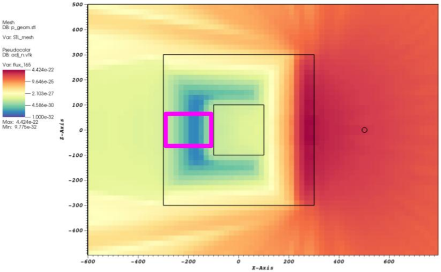

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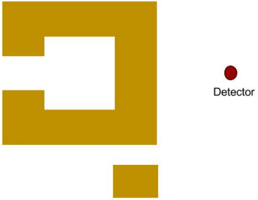

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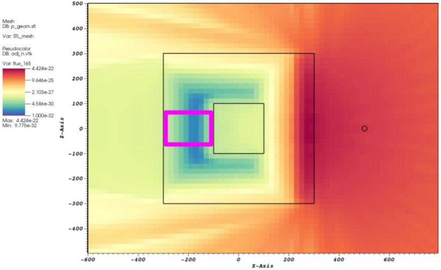

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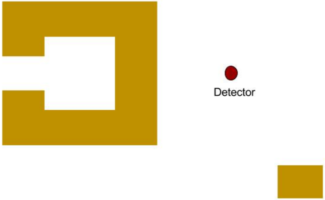

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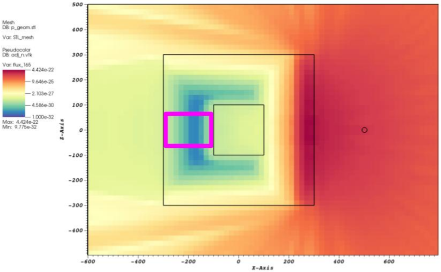

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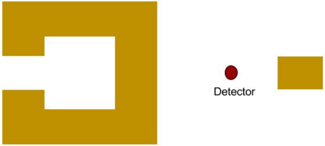

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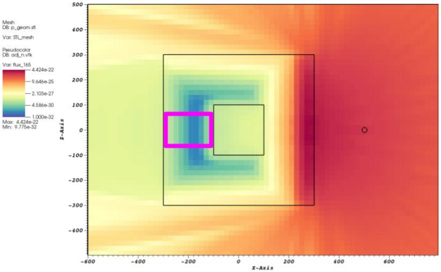

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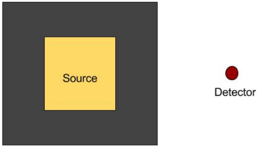

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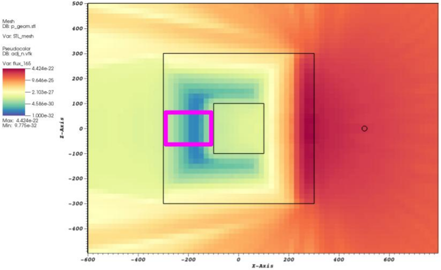

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Proposal

VR for Multi-physics Analysis of Moving Systems

- MS-CADIS optimizes initial radiation transport step in a coupled, multi-step process
- Movement during secondary step changes the construction of the adjoint neutron source

Need to derive new adjoint neutron source

Generalized MS-CADIS

- System of coupled, multi-physics:

$$Primary : H\phi(u) = q(u) \tag{2}$$

$$Secondary : L\Psi(v) = b(v) \tag{3}$$

- Adjoint identities:

$$\langle \phi^{+}, q \rangle = \langle \phi, q^{+} \rangle \tag{4}$$

$$\langle \Psi^{+}, b \rangle = \langle \Psi, b^{+} \rangle \tag{5}$$

- MS-CADIS requires a representation of the relationship between primary and secondary physics:

$$b(v) = \langle \sigma_{b}(u, v), \phi(u) \rangle \tag{6}$$

- Response to secondary physics:

$$R_{final} = \langle \omega_R(v), \psi(v) \rangle \tag{7}$$

- Set ω_R as adjoint source and invoke adjoint identity:

$$R_{final} = \langle \omega_R, \psi \rangle = \langle b, \psi_R^+ \rangle \tag{8}$$

- Substitute Eq. 6 :

$$R_{final} = \Big\langle \ \langle \sigma_b(u, v), \phi(u) \rangle, \ \psi_R^+(v) \ \Big\rangle \tag{9}$$

Generalized MS-CADIS

- Switch the order of integration

$$R_{final} = \Big\langle\ \langle \sigma_b(u,v), \psi_R^+(v) \rangle,\ \phi(u)\ \Big\rangle \tag{10}$$

- Set response of primary physics equal to final response of the system and invoke the adjoint identity to solve for q^+:

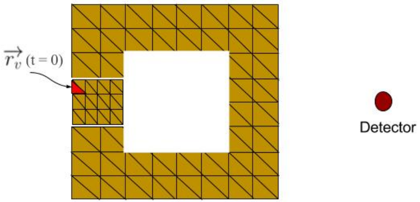
$$R_{final} = \Big\langle\ \langle \sigma_b(u,v), \psi_R^+(v) \rangle,\ \phi(u)\ \Big\rangle = \langle q(u), \phi_R^+(u) \rangle \tag{11}$$

$$q^+(u) \equiv \langle \sigma_b(u,v), \psi_R^+(v) \rangle \tag{12}$$

Time-integrated Adjoint Primary Source

- Geometry movement during secondary physics effects the construction of the adjoint neutron source
  - Adjoint flux in volume element v at time t: $\Psi^{+}(\vec{r}_v(t), t)$
  - Position of volume element v at time t: $\vec{r}_v(t)$

$$q_v^{+} = \int_t \Psi^{+}(\vec{r}_v(t), t)\sigma_{b,v}(t)\, dt \tag{13}$$



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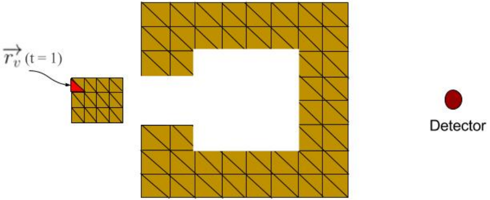

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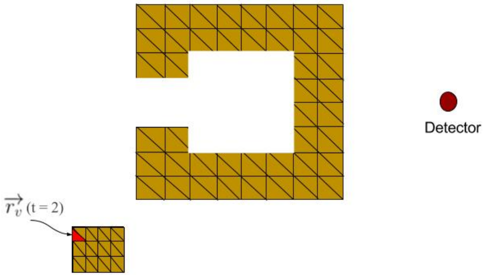

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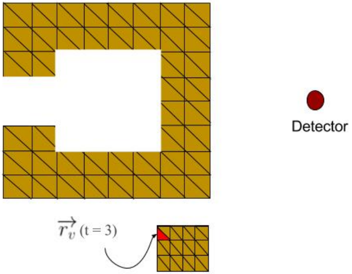

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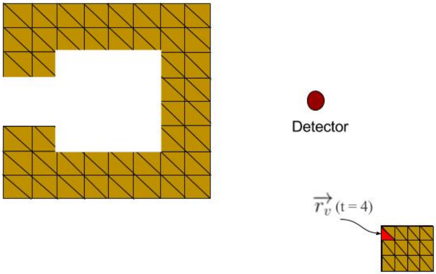

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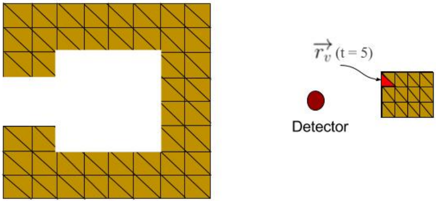


Time-integrated GT-CADIS

- To apply time-integration to GT-CADIS:
  1. Perform adjoint photon transport at each time step of geometry movement
  2. Integrate over time

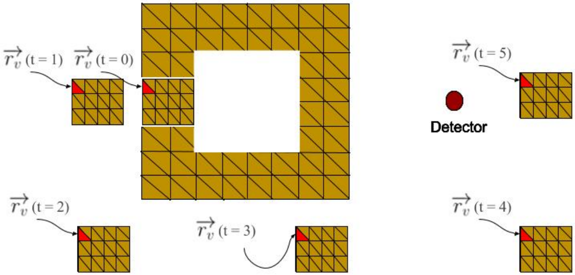
$$q^+_{n,v}(E_n) = \int_t \int_{E_\gamma} T_v(E_n, E_\gamma, t)\phi^+_\gamma(\overrightarrow{r}_v(t), E_\gamma, t)\, dE_\gamma\, dt \tag{14}$$

- $\phi^+_\gamma(\overrightarrow{r}_v(t), E_\gamma, t)$ is the adjoint flux of photons of energy E_γ, in volume element v, at time t
- $T_v(E_n, E_\gamma, t)$ is the T value of the material in volume element v, at decay time t

Time-integrated Adjoint Neutron Source

- Average the adjoint photon flux calculated at each time step

$$\phi^{+}_{\gamma,v,h} = \frac{\sum_{t_{mov}} \phi^{+}_{\gamma,v,h,t_{mov}} \Delta t_{mov}}{t_{tot}} \tag{15}$$



Time-integrated Adjoint Neutron Source

- Calculate T for each voxel

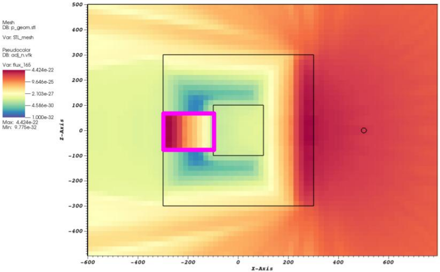
$$T_{v,g,h} = \frac{q_{\gamma,v,h}(\phi_{n,v,g})}{\phi_{n,v,g}} \tag{16}$$

- Combine with adjoint photon flux in each voxel

$$q^{+}_{n,v,g} = \frac{\sum_{t_{mov}} \left(\sum_{h} T_{v,g,h} \phi^{+}_{\gamma,v,h,t_{mov}} \right) \Delta t_{mov}}{t_{tot}} \tag{17}$$

Time-integrated (T)GT-CADIS

- Perform deterministic adjoint neutron transport using the time-integrated source
- Resultant adjoint neutron flux should look something like this:



- Use this adjoint neutron flux to generate biasing parameters that will optimize the MC neutron transport step of R2S

Implementation Plan

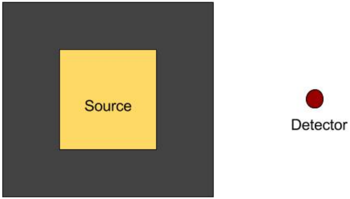
TGT-CADIS: Generate VR Parameters

- Generate geometry files at each time step of movement after shutdown

DAGMC geom at $t_{mov} = 0$

DAGMC transform tool

DAGMC geom at t_{mov}



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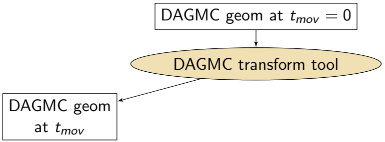

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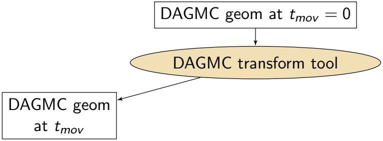
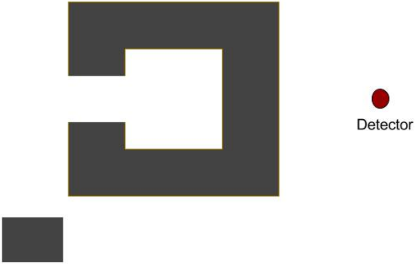
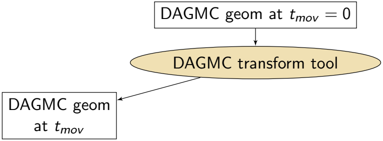
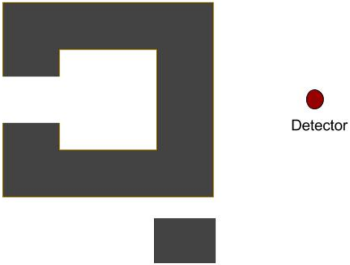




TGT-CADIS: Generate VR Parameters

- Generate geometry files at each time step of movement after shutdown





TGT-CADIS: Generate VR Parameters

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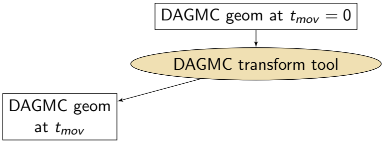
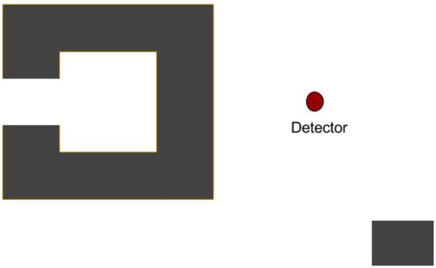
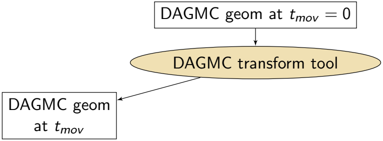




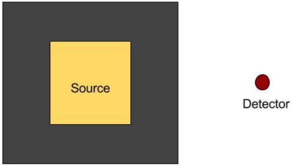
TGT-CADIS: Generate VR Parameters

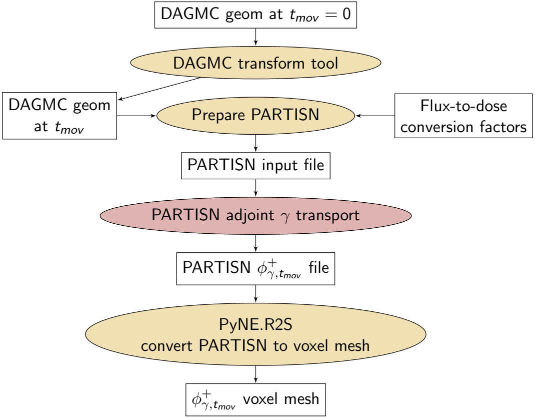
- Generate geometry files at each time step of movement after shutdown



TGT-CADIS: Generate VR Parameters

- Perform adjoint photon transport at each time step





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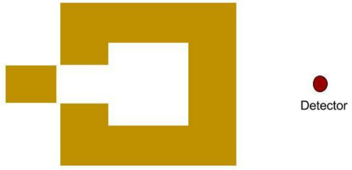
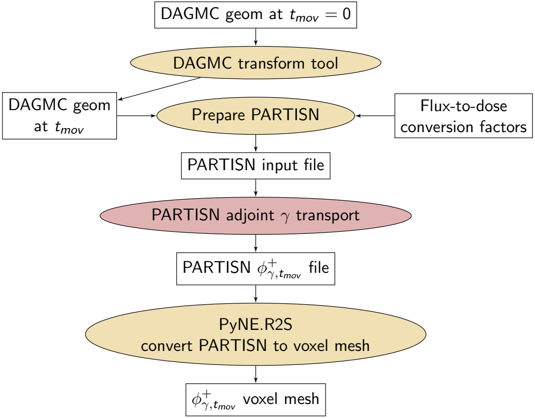
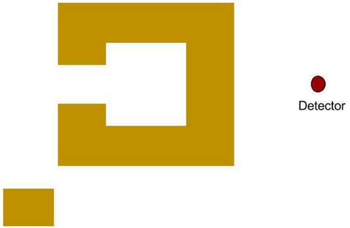
- Perform adjoint photon transport at each time step

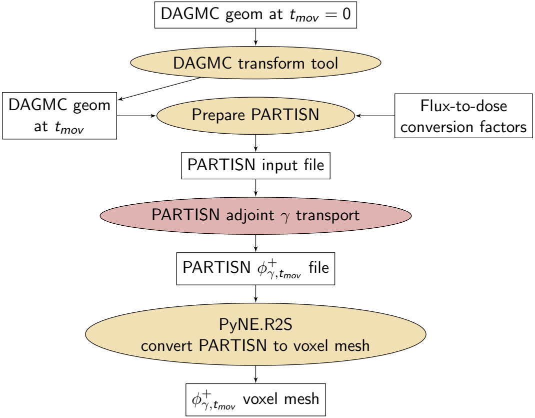




TGT-CADIS: Generate VR Parameters

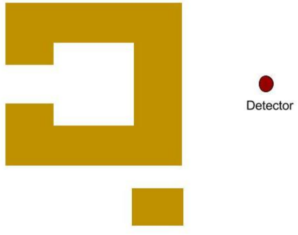
- Perform adjoint photon transport at each time step

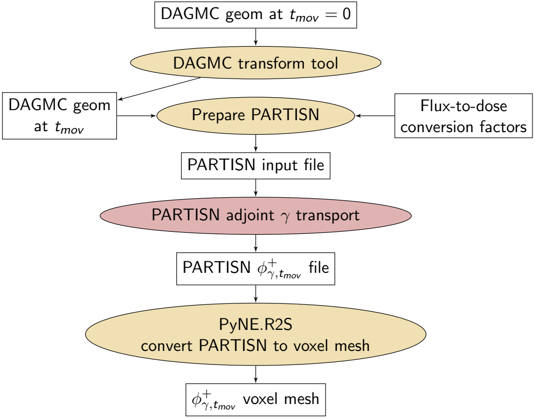




TGT-CADIS: Generate VR Parameters

- Perform adjoint photon transport at each time step





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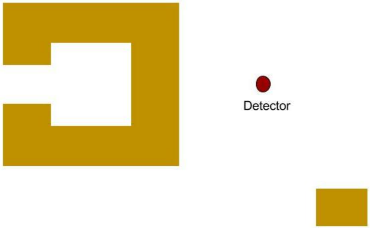
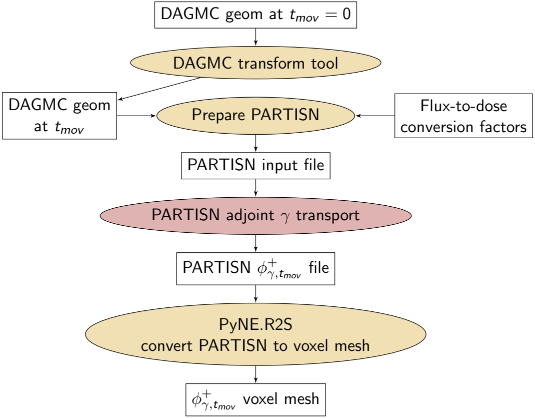
- Perform adjoint photon transport at each time step





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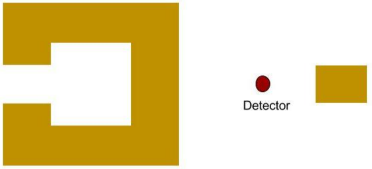
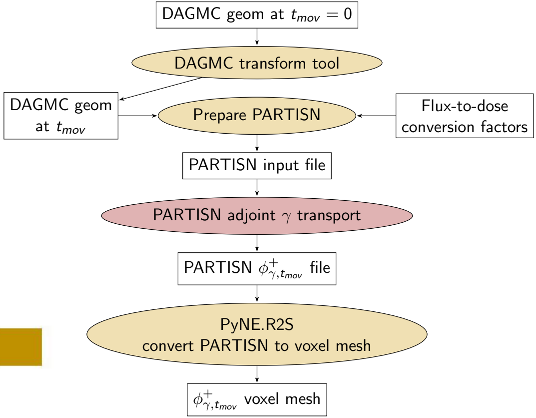
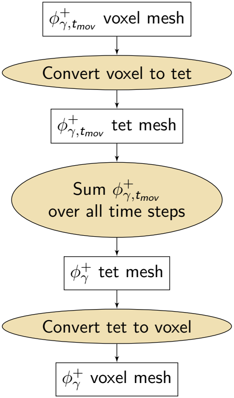
- Perform adjoint photon transport at each time step

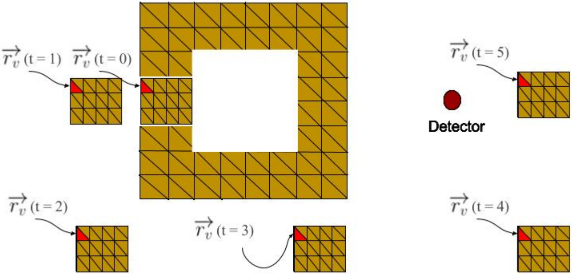




TGT-CADIS: Generate VR Parameters

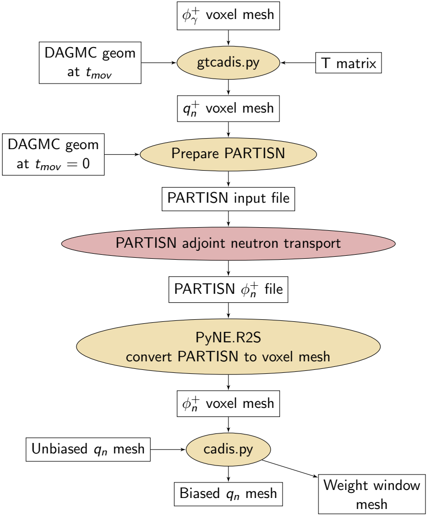
- Map the voxel mesh to a tetrahedral mesh
- Average the adjoint photon flux calculated at each time step





TGT-CADIS: Generate VR Parameters

- Calculate T of each voxel
- Calculate adjoint neutron source
- Perform adjoint neutron transport
- Generate biased source and weight window mesh

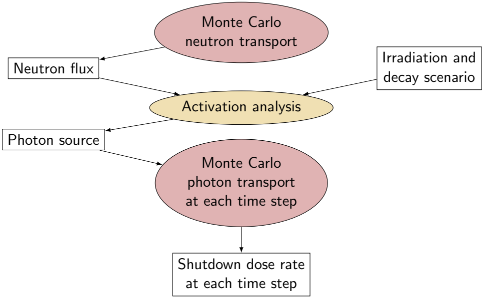


Experiment

Experiment: Toy Problem

Experimental Steps:

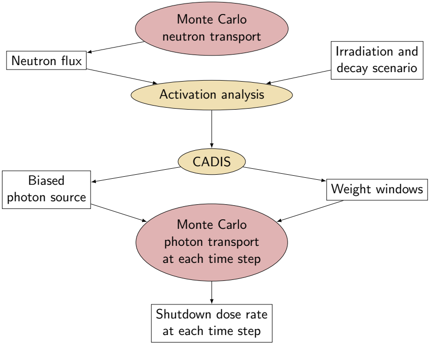
1. No VR



Experiment: Toy Problem

Experimental Steps:

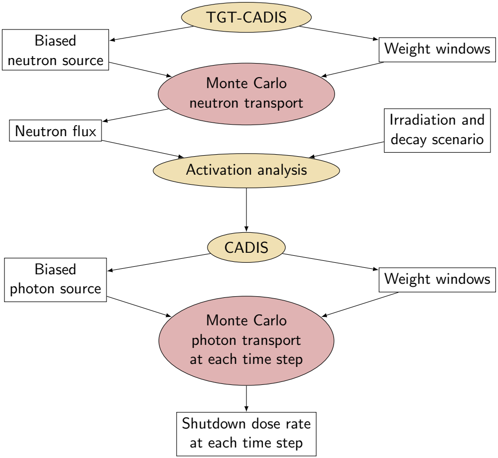
1. No VR
2. Photon VR: CADIS



Experiment: Toy Problem

Experimental Steps:

1. No VR
2. Photon VR: CADIS
3. Neutron and Photon VR: TGT-CADIS



Experiment: Toy Problem

- Incrementally add optimization
- Calculate figure of merit (FOM) to assess utility of TGT-CADIS method

Progress

MC Moving Geometry Simulations

- Tools to update position of geometry based on user-defined motion data
  1. Production of step-wise geometry files
  2. DAGMC update to facilitate on-the-fly geometry transformations
- Motion data:
  - Time-dependent translation or rotation vector, total length of time, number or desired time steps
  - Relocation transform
- Common functionality:
  - Read tag data that specifies type of transformation
  - Identify starting position of each component
  - Update position according to transformation

Conclusions

Assumptions

- Photon transport occurs much faster than geometry movement $\therefore$ reasonable to do quasi-static simulation
- Period of geometry movement is short enough that the photon source will not change appreciably $\therefore$ can use same photon source for all MC calculations

Challenges

- Depending on complexity of model and fidelity of time resolution, can amass large number of CAD geometry files, volume mesh tally files
- Need to optimize this workflow in order to keep file storage at minimum

Summary

- Accurate quantification of the SDR during maintenance procedures is crucial to the design and operation of FES
- GT-CADIS has proven to accurately quantify the SDR in static FES
- TGT-CADIS aims to provide the capabilities necessary to calculate the SDR at various time points during operations that involve activated components moving around the facility

Questions?

TODO

- REFERENCES
- labels on tet mesh time slices
- Overall alignment/sizing/spacing
- Add more on moving geom progress