

Variance Reduction for Multi-physics Analysis of Moving Systems

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Preliminary Exam

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Introduction

Shutdown Dose Rate (SDR) Analysis

- Fusion Energy Systems (FES)
 - Burning plasma, D-T fusion
 - ${}_1^2H + {}_1^3H \rightarrow {}_2^4He + {}_0^1n$
- Neutrons penetrate deeply into system components, causing activation
- Radioisotopes persist long after shutdown
- Important to quantify the dose caused by decay photons

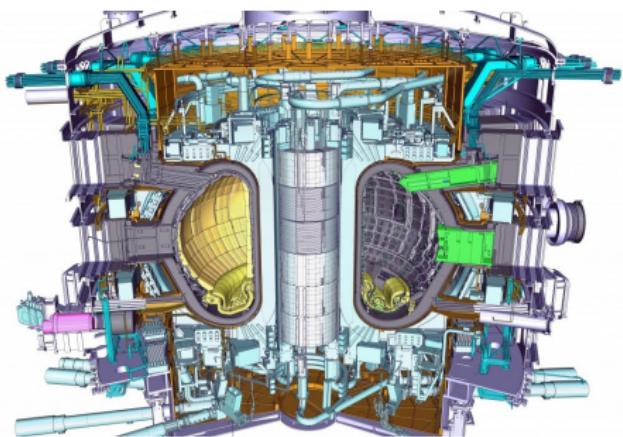
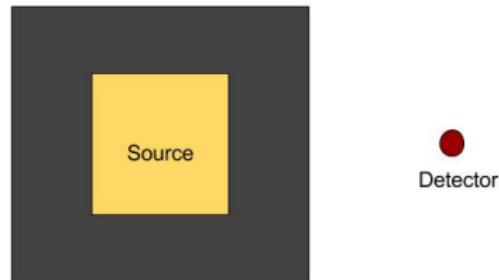


Figure: Cutaway view of ITER drawing.

SDR Analysis: Movement After Shutdown

- FES are designed with modular components
 - Can move during maintenance procedure
- Interested in SDR at a particular location
- SDR will change as a function of the activated component's position over time



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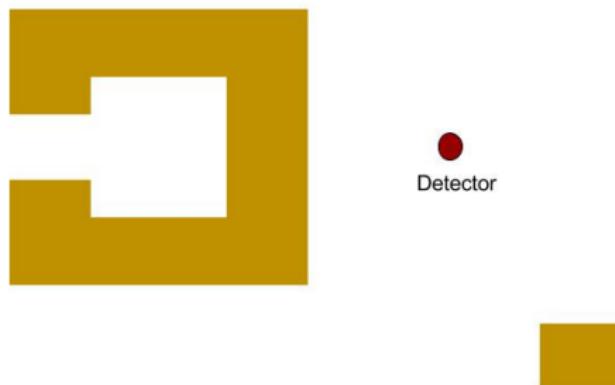
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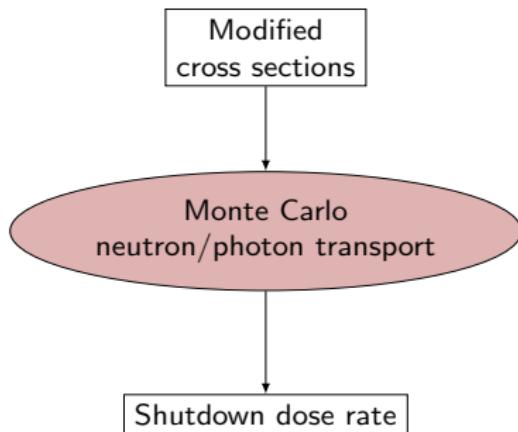




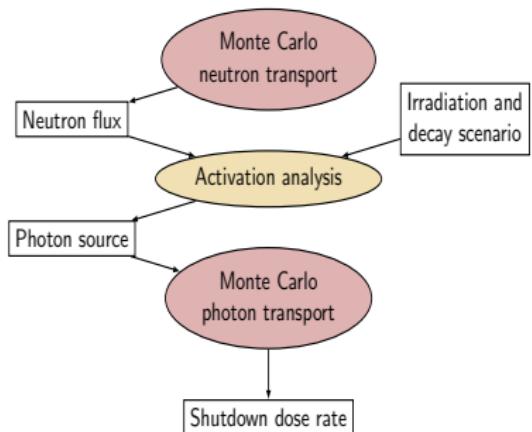
Optimize the calculation of the **shutdown dose rate** at a particular location as activated components are **moving** around the facility.

SDR Solution Methods

Direct 1-Step Method (D1S)



Rigorous 2-Step Method (R2S)



Monte Carlo Radiation Transport

- Monte Carlo (MC) analysis of FES is:
 - Accurate for large, complex models
 - Challenging due to the highly attenuating structural materials
 - Results scored in regions that have low particle flux, have higher statistical uncertainty

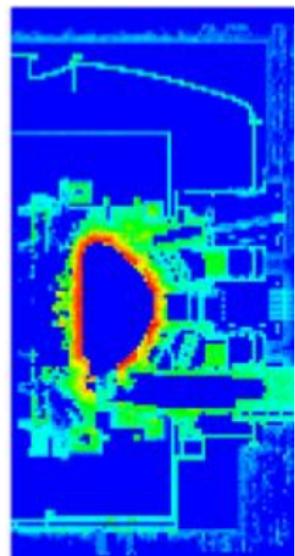


Figure: Photon source in ITER tokamak building.



Error in MC Calculations

- Uncertainty in MC calculations:

$$\mathfrak{R} = \frac{\sigma_{\bar{x}}}{\bar{x}} \quad (1)$$

$$\sigma_{\bar{x}} \propto \frac{1}{\sqrt{N}}$$

- To decrease statistical uncertainty:
 - Increase number of histories, N
 - Use variance reduction (VR) techniques

MC Variance Reduction Techniques

- Techniques to modify particle behavior
 - **Goal:** preferentially sample events that will contribute to results of interest
- Statistical weight of particles is adjusted to keep playing a fair game
- Types
 - **Modified Sampling:** source direction and energy biasing
 - **Population Control:** geometry and energy splitting/rouletting

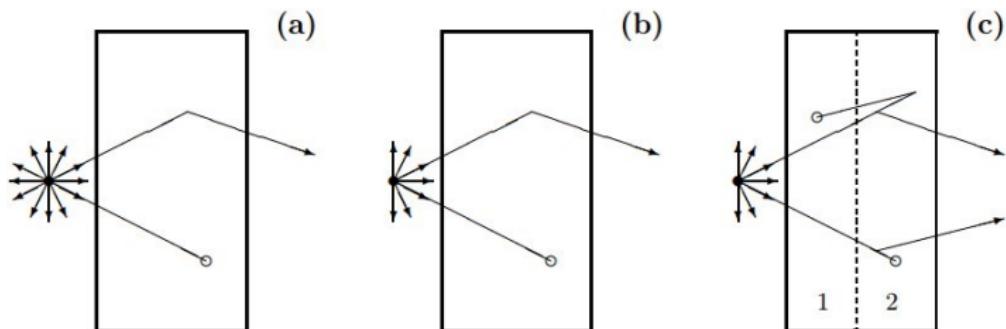


Figure: a) Analog b) Source biasing c) Splitting/roulettting



Hybrid Deterministic/MC VR Methods

- Use **deterministic** estimate of the adjoint flux, Ψ^+ , to generate **Monte Carlo** VR parameters
- Adjoint flux can define the importance of regions of phase space to the detector response
- Define detector response function to be the adjoint source

Forward:

$$H\Psi(\vec{r}, E, \hat{\Omega}) = q(\vec{r}, E, \hat{\Omega}) \quad (2)$$

$$H = \hat{\Omega} \cdot \nabla + \sigma_t(\vec{r}, E) - \int_0^\infty dE' \int_{4\pi} d\Omega' \sigma_s(\vec{r}, E' \rightarrow E, \hat{\Omega}' \rightarrow \hat{\Omega})$$

Adjoint:

$$\langle \Psi^+, q \rangle = \langle \Psi, q^+ \rangle \quad (3)$$

$$H^+ \Psi^+(\vec{r}, E, \hat{\Omega}) = q^+(\vec{r}, E, \hat{\Omega}) \quad (4)$$

$$H^+ = -\hat{\Omega} \cdot \nabla + \sigma_t(\vec{r}, E) - \int_0^\infty dE' \int_{4\pi} d\Omega' \sigma_s(\vec{r}, E \rightarrow E', \hat{\Omega} \rightarrow \hat{\Omega}')$$



Consistent Adjoint Driven Importance Sampling (CADIS)

- Use the adjoint flux, Ψ^+ , to generate MC source and transport biasing parameters
- Biased source:

$$\hat{q}(\vec{r}, E, \hat{\Omega}) = \frac{\Psi^+(\vec{r}, E, \hat{\Omega}) q(\vec{r}, E, \hat{\Omega})}{R} \quad (5)$$

- Weight window lower bounds:

$$w_l(\vec{r}, E, \hat{\Omega}) = \frac{R}{\Psi^+(\vec{r}, E, \hat{\Omega})(\frac{\alpha+1}{2})} \quad (6)$$



Variance Reduction for SDR Analysis

VR for **photon** transport

- **Straightforward**
- Can use CADIS method to direct photons towards detector
 - Flux-to-dose-rate conversion factors define adjoint source

VR for **neutron** transport

- More **complicated**
- Biasing function needs to capture
 - ① Potential of regions to become activated
 - ② Potential to produce photons that will contribute to the SDR
- Can use CADIS if we can construct adjoint source that will fulfill these criteria



Multi-Step (MS)-CADIS

- VR method to optimize the initial radiation transport step of a coupled, multi-step process
 - Relies upon biasing function that represents importance of particles to final response of interest
- When applied to SDR analysis, MS-CADIS will optimize the neutron transport step of R2S



Generalized MS-CADIS

- System of coupled, multi-physics:

$$\text{Primary} : H\phi(u) = q(u) \quad (7)$$

$$\text{Secondary} : L\psi(v) = b(v) \quad (8)$$

$$b(v) = f(\phi(u))$$

- Adjoint identities:

$$\langle \phi^+, q \rangle = \langle \phi, q^+ \rangle \quad (9)$$

$$\langle \psi^+, b \rangle = \langle \psi, b^+ \rangle \quad (10)$$



Generalized MS-CADIS

- Response to secondary physics:

$$R_{final} = \langle \omega_R(v), \psi(v) \rangle \quad (11)$$

- Define $b^+ \equiv \omega_R$ and apply adjoint identity:

$$R_{final} = \langle \omega_R, \psi \rangle = \langle b, \psi_R^+ \rangle \quad (12)$$

- ψ_R^+ represents importance function for R_{final}
- Set primary response to final response and apply adjoint identity:

$$R_{final} = \langle q^+, \phi \rangle = \langle q, \phi_R^+ \rangle \quad (13)$$

- Solving for q^+ requires this unique relationship:

$$b(v) = \langle \sigma_b(u, v), \phi(u) \rangle \quad (14)$$

Generalized MS-CADIS

- Substitute Eq. 14 and set primary response equal to secondary :

$$R_{final} = \langle q^+(u), \phi(u) \rangle = \langle \langle \sigma_b(u, v), \phi(u) \rangle, \psi_R^+(v) \rangle \quad (15)$$

- Switch the order of integration

$$R_{final} = \langle q^+(u), \phi(u) \rangle = \langle \langle \sigma_b(u, v), \psi_R^+(v) \rangle, \phi(u) \rangle \quad (16)$$

- MS-CADIS adjoint primary source:

$$q^+(u) \equiv \langle \sigma_b(u, v), \psi_R^+(v) \rangle \quad (17)$$

- Prompt photon production: $\sigma_b(u, v) \equiv \sigma_{n,\gamma}(E_n, E_\gamma)$

Generalized MS-CADIS

- MS-CADIS adjoint primary source:

$$q^+(u) \equiv \langle \sigma_b(u, v), \psi_R^+(v) \rangle \quad (18)$$

- Apply MS-CADIS to coupled neutron-photon physics:

- $q^+(u) \equiv q_n^+(E_n)$

- $\psi^+(v) \equiv \phi_\gamma^+$

- Prompt photon production: $\sigma_b(u, v) \equiv \sigma_{n,\gamma}(E_n, E_\gamma)$

- Delayed photon production: $\sigma_b(u, v) \equiv T_{n,\gamma}(E_n, E_\gamma)$



Groupwise Transmutation (GT)-CADIS

- Implementation of MS-CADIS specifically for SDR analysis
- Provides method to calculate optimal adjoint neutron source, q_n^+ :

$$q_n^+(E_n) = \langle T(E_n, E_\gamma), \phi_\gamma^+(E_\gamma) \rangle \quad (19)$$

- $T(E_n, E_\gamma)$
 - Approximation of the transmutation process
 - Solution exits when SNILB criteria are met
 - Defined by this relationship:

$$q_\gamma(E_\gamma) = \langle T(E_n, E_\gamma), \phi_n(E_n) \rangle \quad (20)$$

- Calculate by performing single-energy-group irradiations of each material and recording the resultant photon emission densities

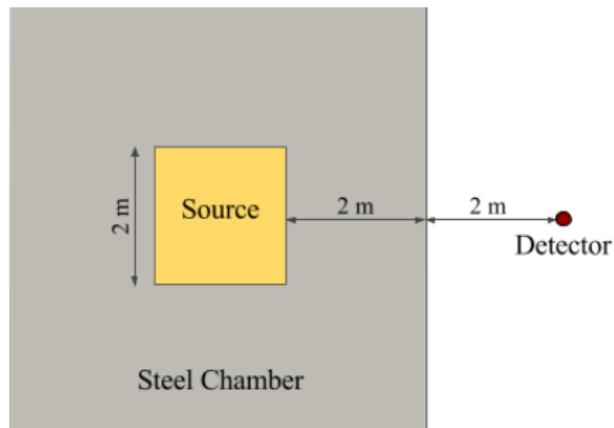
$$T_{g,h} = \frac{q_{\gamma,h}(\phi_{n,g})}{\phi_{n,g}} \quad (21)$$

Demonstration

GT-CADIS Demonstration: Problem Description



- Geometry
 - Steel chamber
 - 2m x 2m x 2m central cavity
- Source
 - Volume source in central cavity
 - 13.8-14.2 MeV neutrons
- Detector
- Calculate SDR
- 2m away from chamber



GT-CADIS Demonstration: Adjoint Photon Transport

GT-CADIS workflow

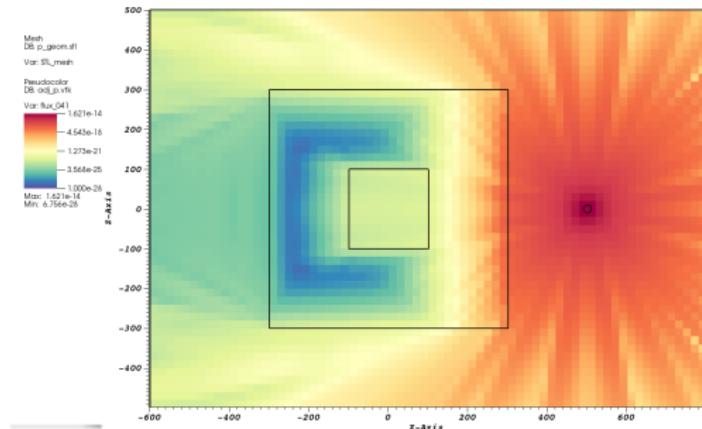
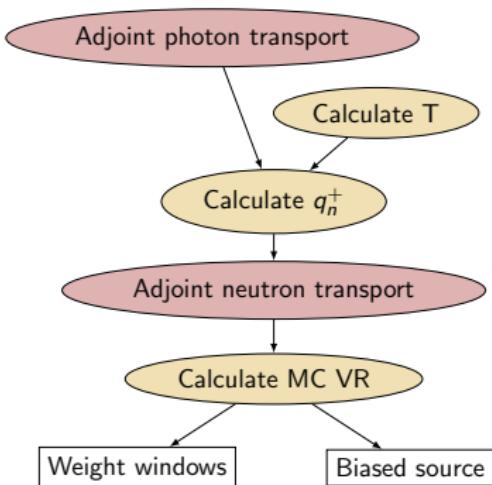


Figure: Adjoint photon flux used to generate adjoint neutron source according to the GT-CADIS method.

GT-CADIS Demonstration: Adjoint Neutron Transport

GT-CADIS workflow

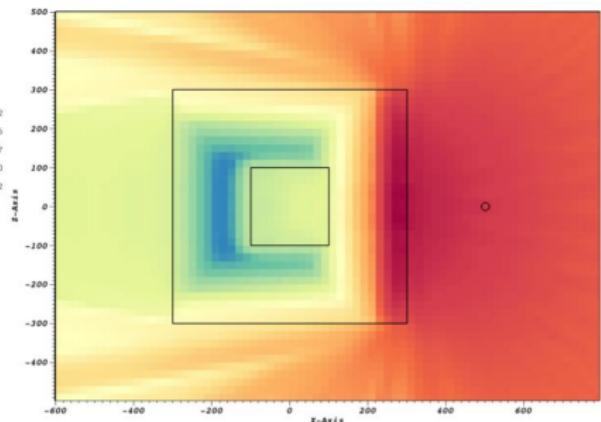
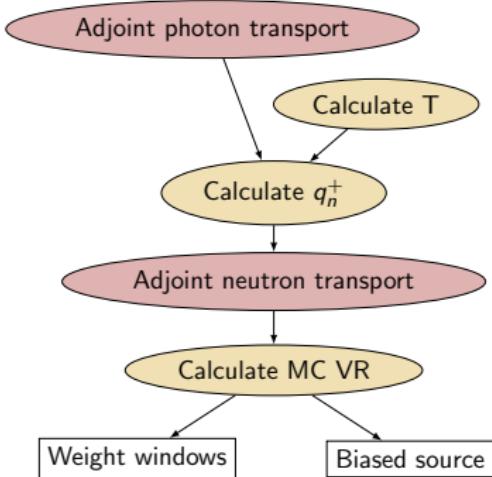


Figure: GT-CADIS adjoint neutron flux.
Functions as importance map.

GT-CADIS Demonstration: Variance Reduction Parameters

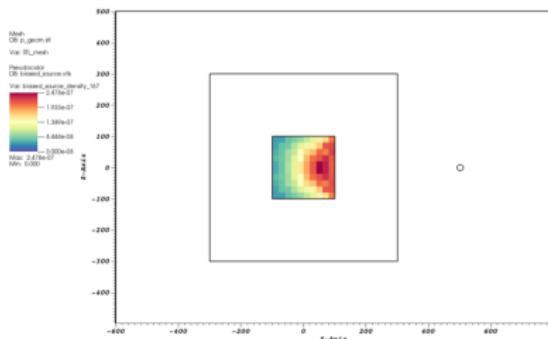


Figure: Biased neutron source generated with GT-CADIS method.

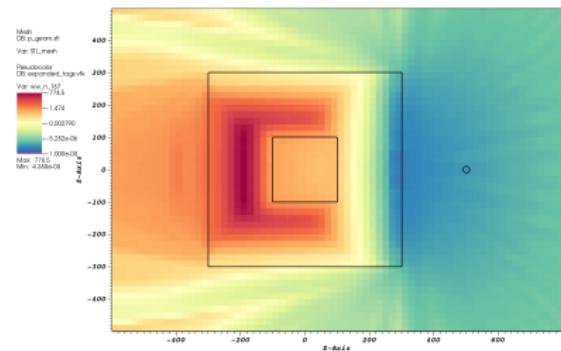


Figure: Weight window mesh generated with GT-CADIS method.

GT-CADIS Demonstration: Forward Neutron Flux

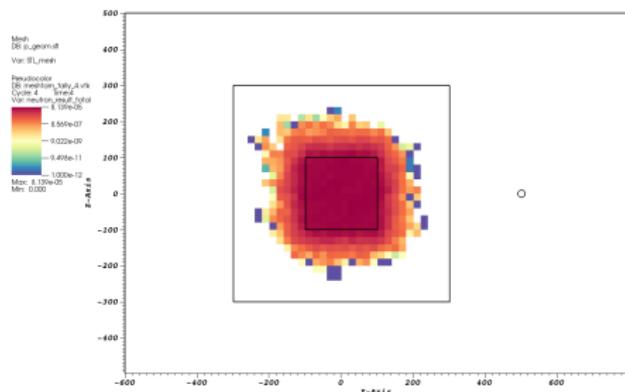


Figure: Neutron flux resulting from analog MC simulation.

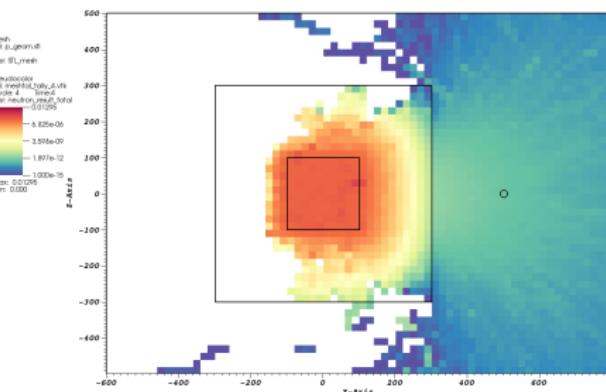


Figure: Neutron flux resulting from MC simulation using GT-CADIS biased source and weight window mesh.

GT-CADIS Demonstration: Forward Photon Source

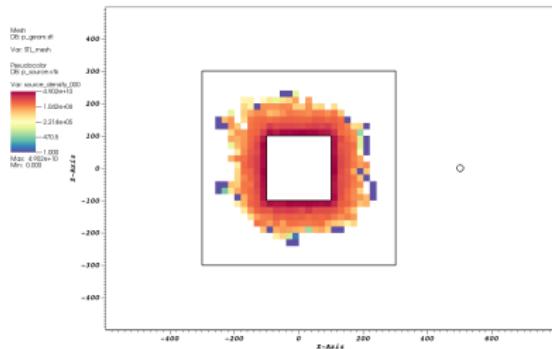


Figure: Photon source generated by ALARA activation calculation using the analog MC neutron transport result.

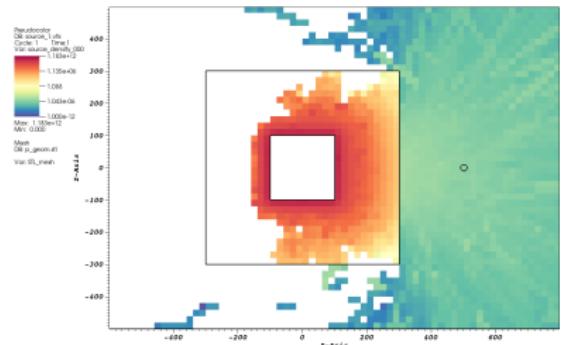


Figure: Photon source generated after ALARA activation calculation using the GT-CADIS optimized neutron transport result.

GT-CADIS Speedups

- VR parameters produced by GT-CADIS method result in much faster convergence of the neutron transport flux in comparison to analog and FW-CADIS methods

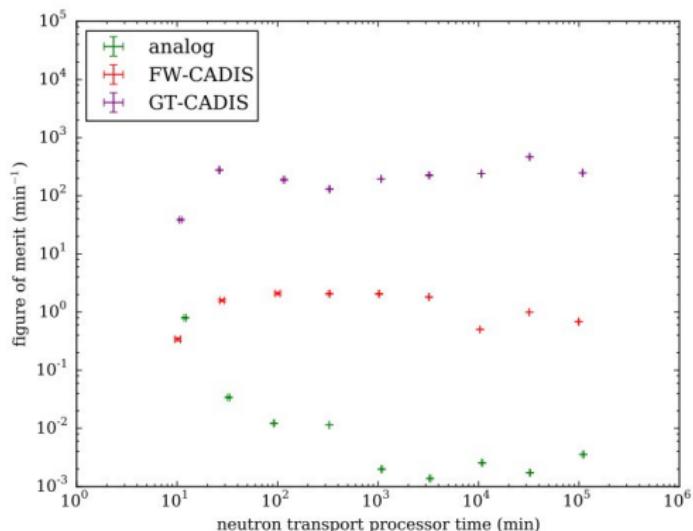


Figure: FOM as function of neutron transport processor time

GT-CADIS Demonstration

GT-CADIS importance map is **insufficient** for moving systems.

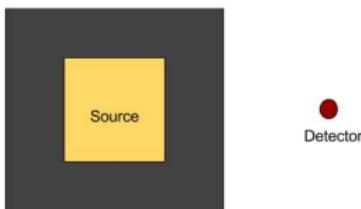


Figure: Demo model.

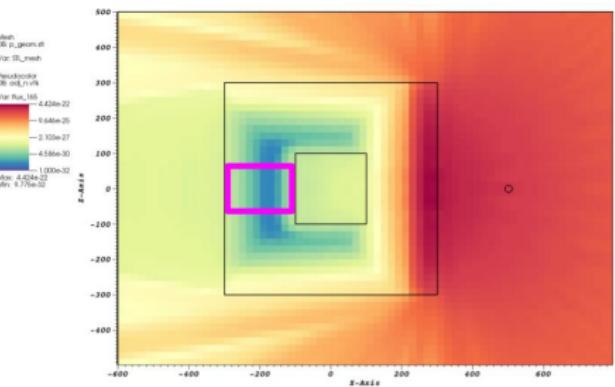


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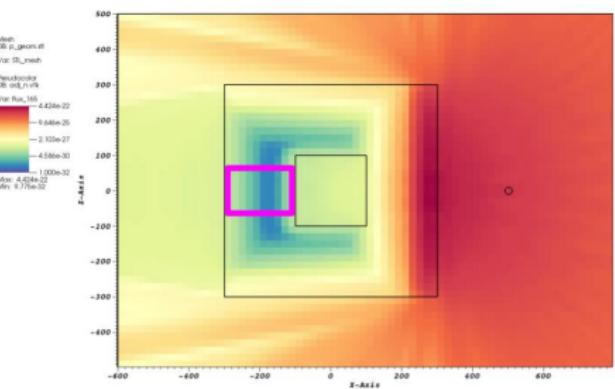


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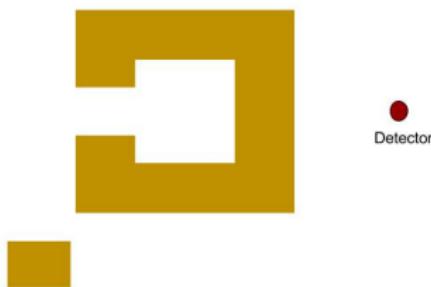


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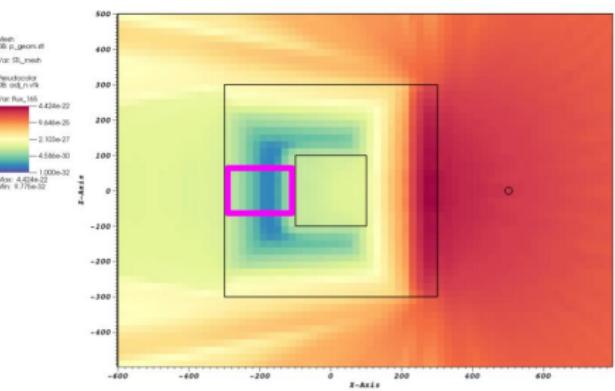


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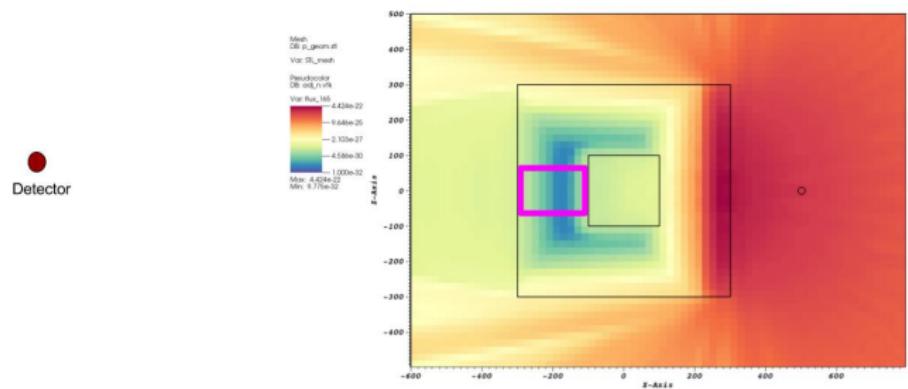


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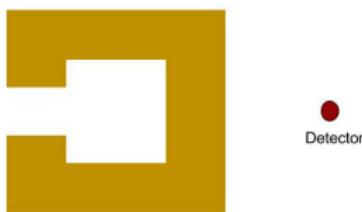


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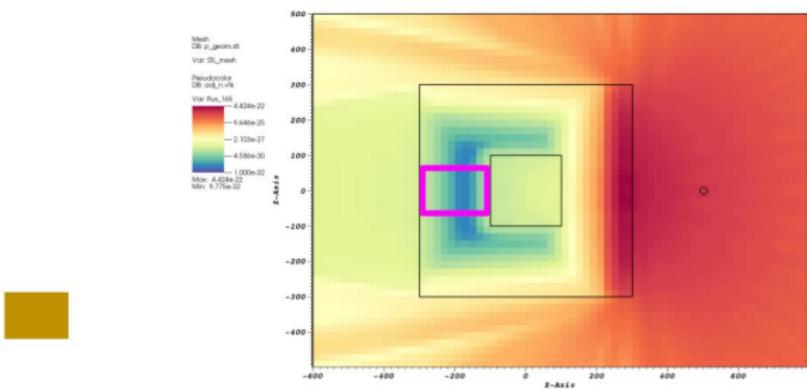


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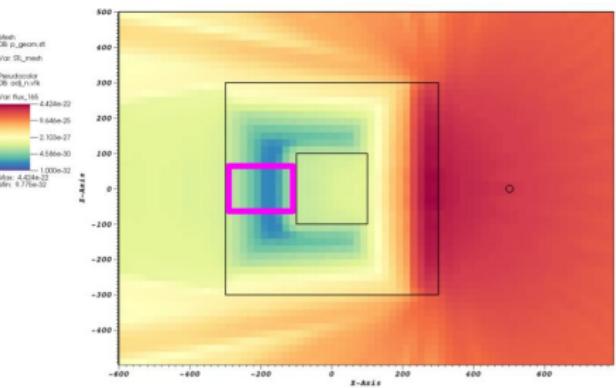


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Functions as importance map.



Moving Geometries and Sources

MCNP6 Moving Objects

- Update in future version of MCNP6
- Allows movement of objects, sources, delayed particles during single simulation
- Available for native MCNP geometry descriptions (not mesh)



Moving Geometries and Sources

Mesh Coupled R2S (MCR2S)

- Capability that allows components to move before photon transport step
- Transformations are applied to copies of moving components
- Original component still in original location, set to void material



Review

- MC method is most accurate way to obtain detailed particle flux distributions
 - Use MC codes for both neutron and photon transport steps of R2S
 - Need to use VR methods to optimize the transport calculations
- GT-CADIS, an implementation of MS-CADIS, has proven to optimize the neutron transport step of R2S
- MCNP6 and MCR2S have developed some capabilities for performing transport on moving geometries
- No automated VR for optimizing neutron transport in systems that move after shutdown

Proposal



VR for SDR Analysis of Moving Systems

- GT-CADIS optimizes neutron transport step in static systems

$$q_n^+(E_n) = \langle T(E_n, E_\gamma), \phi_\gamma^+(E_\gamma) \rangle$$

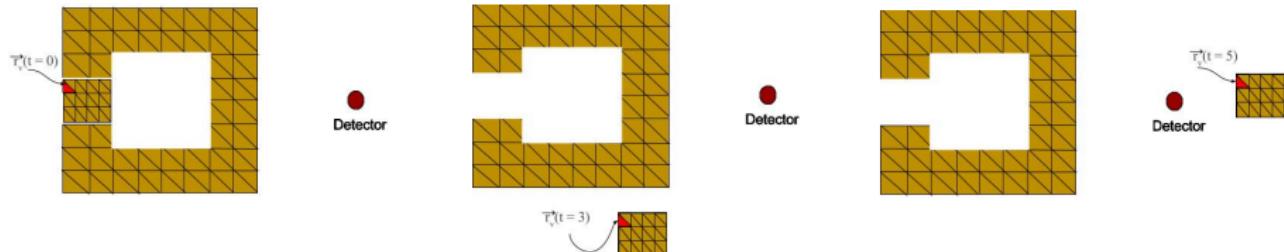
- Movement after shutdown, during photon transport, changes the construction of the adjoint primary source

Derive time-integrated adjoint neutron source

Time-integrated Adjoint Neutron Source

- Score adjoint photon flux in discrete volume elements at each time step
 - Adjoint flux in volume element v at time t : $\phi_{\gamma}^{+}(\vec{r}_v(t), t)$
 - Position of volume element v at time t : $\vec{r}_v(t)$
- Integrate over time

$$q_n^{+} = \frac{\int_t \phi_{\gamma}^{+}(\vec{r}_v(t), t) T_v(t) dt}{\int_t dt} \quad (22)$$



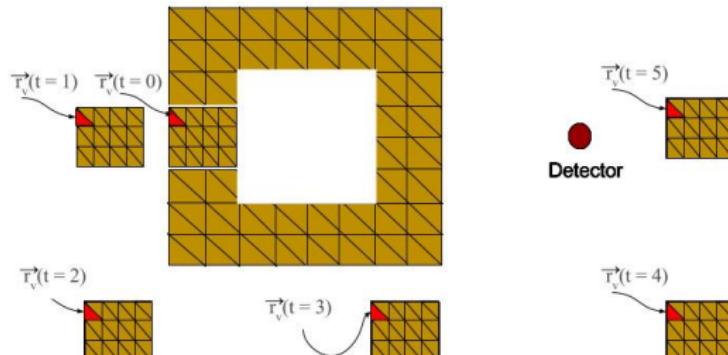
TGT-CADIS: Adjoint Neutron Source

- Calculate coupling term, T , for each volume element

$$T_{v,g,h} = \frac{q_{\gamma,v,h}(\phi_{n,v,g})}{\phi_{n,v,g}} \quad (23)$$

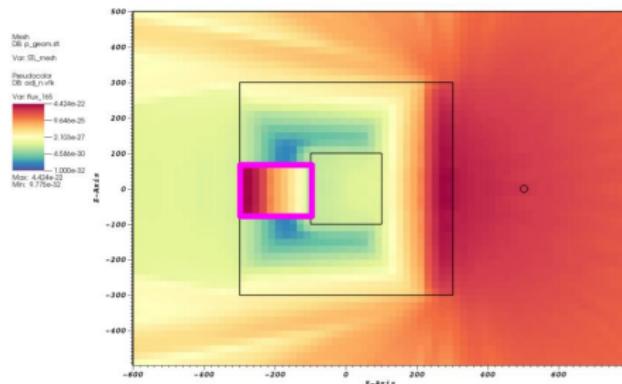
- Combine with adjoint photon flux in each volume element

$$q_{n,v,g}^+ = \frac{\sum_{t_{mov}} (\sum_h T_{v,g,h} \phi_{\gamma,v,h,t_{mov}}^+) \Delta t_{mov}}{t_{tot}} \quad (24)$$



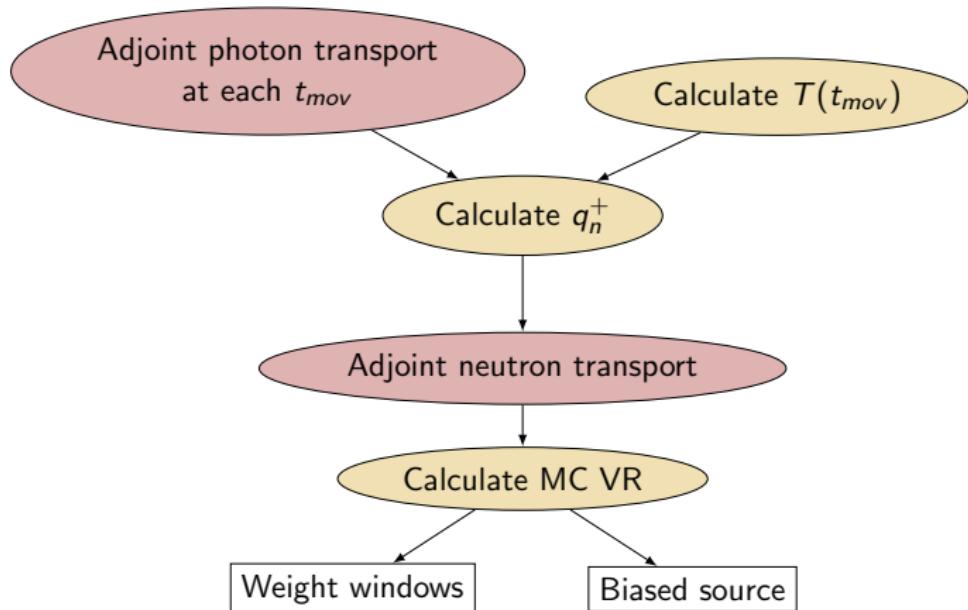
Time-integrated (T)GT-CADIS

- Perform deterministic adjoint neutron transport using the time-integrated source
- Resultant adjoint neutron flux should look something like this:



- Use this adjoint neutron flux to generate biasing parameters that will optimize the MC neutron transport step of R2S

Time-integrated (T)GT-CADIS: Workflow



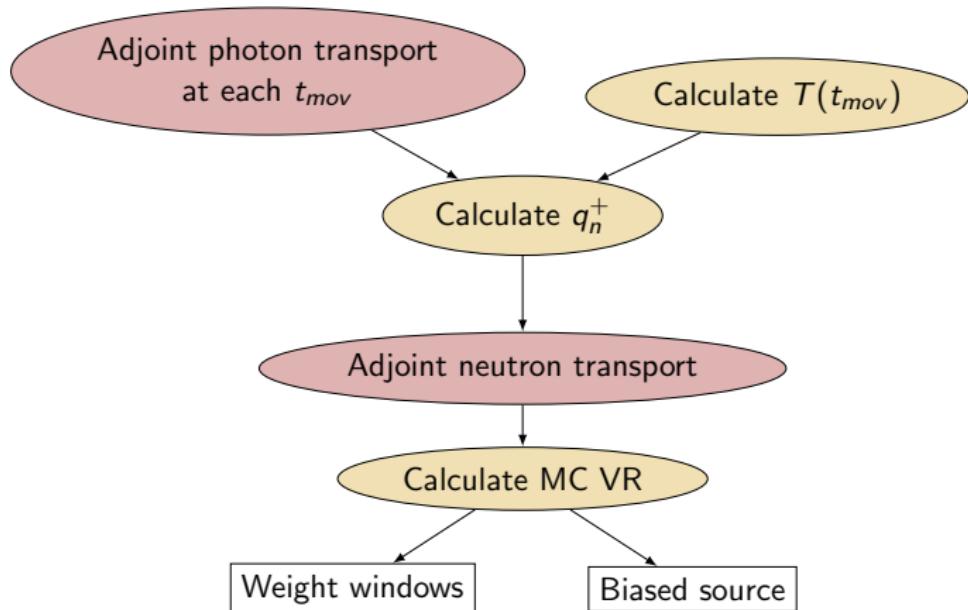
Implementation Plan



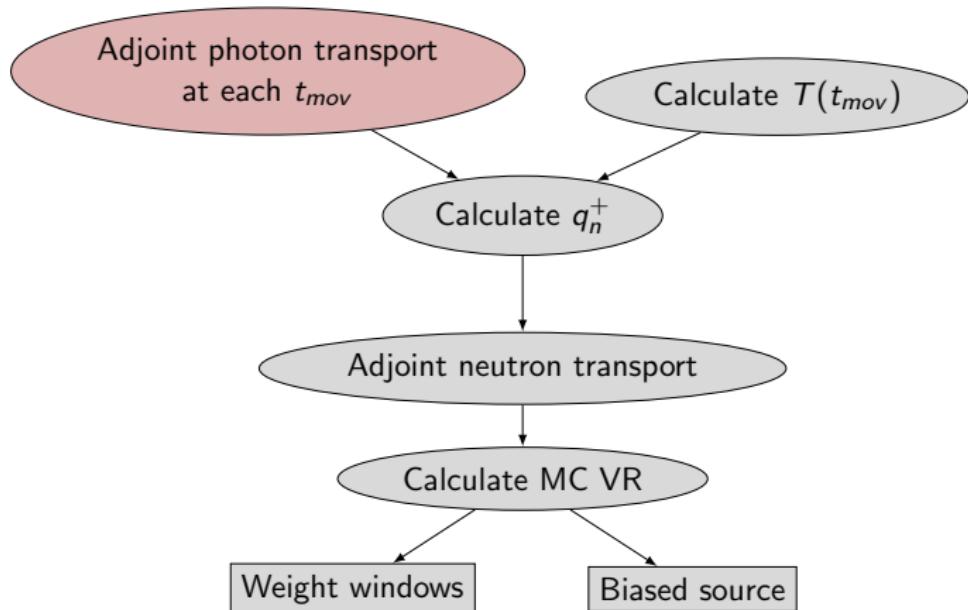
Software

- **PARallel, TIme-Dependent SN** (PARTISN)
 - Deterministic adjoint transport
- **Direct Accelerated Geometry Monte Carlo MCNP** (DAGMCNP)
 - Forward MC transport on CAD geometry
- **Analytic and Laplacian Adaptive Radioactivity Analysis** (ALARA)
 - Activation analysis
- **Python for Nuclear Engineering** (PyNE)
 - Tools to support transport
- **Mesh-Oriented datABase** (MOAB)
 - Moving geometries

Time-integrated (T)GT-CADIS: Workflow

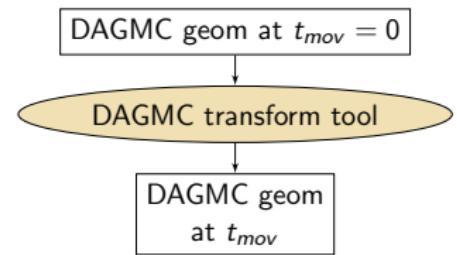
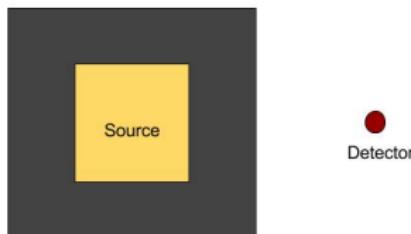


Time-integrated (T)GT-CADIS: Workflow



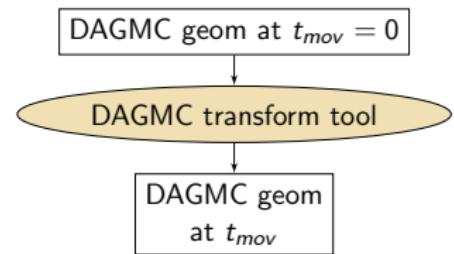
TGT-CADIS: Generate Step-wise Geometries

- Generate geometry files at each time step of movement after shutdown



TGT-CADIS: Generate Step-wise Geometries

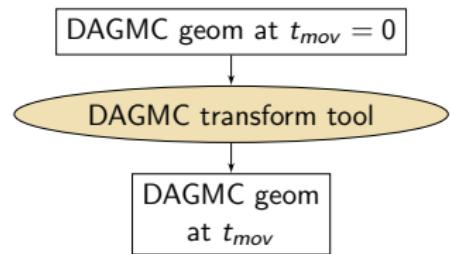
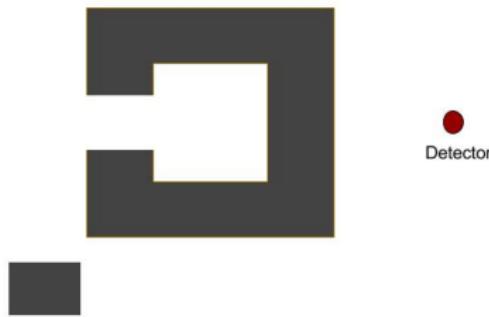
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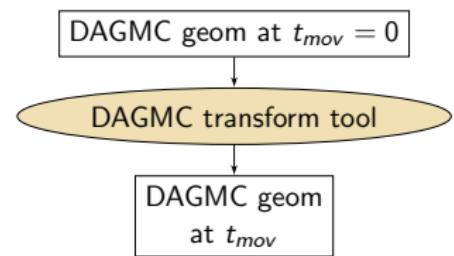


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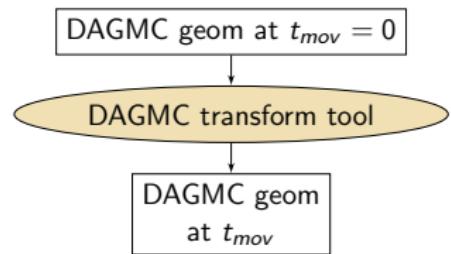
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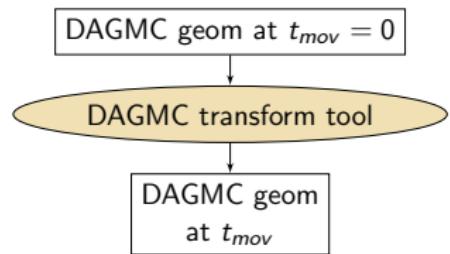
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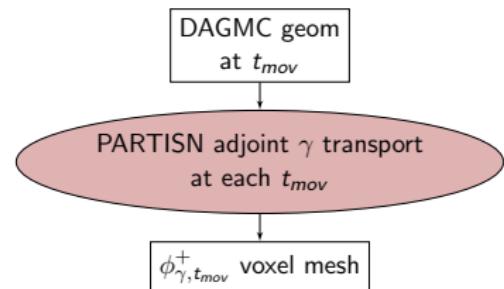
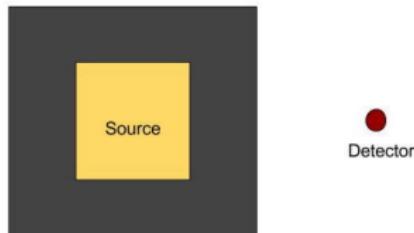
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TGT-CADIS: Generate VR Parameters



- Perform adjoint photon transport at each time step

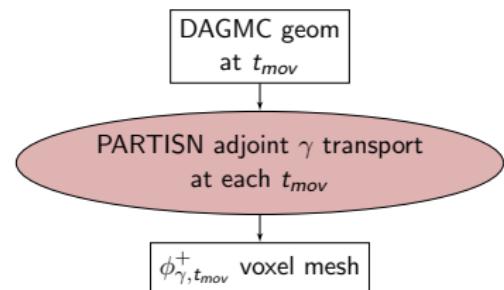


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- Perform adjoint photon transport at each time step



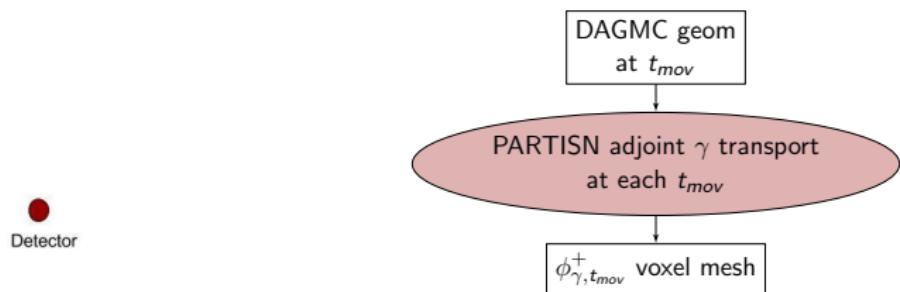
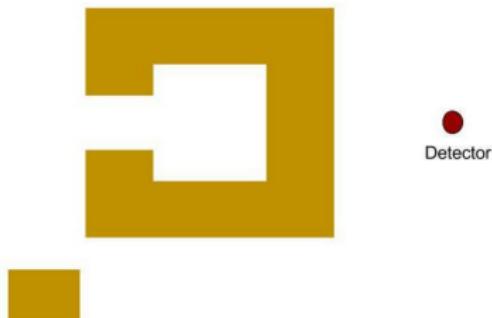
Detector



TGT-CADIS: Generate VR Parameters



- Perform adjoint photon transport at each time step



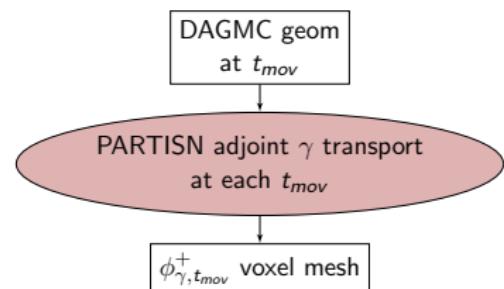
TGT-CADIS: Generate VR Parameters



- Perform adjoint photon transport at each time step



Detector



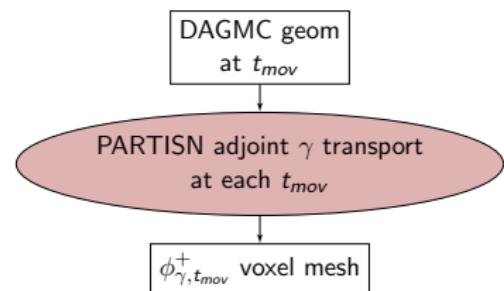
TGT-CADIS: Generate VR Parameters



- Perform adjoint photon transport at each time step



Detector



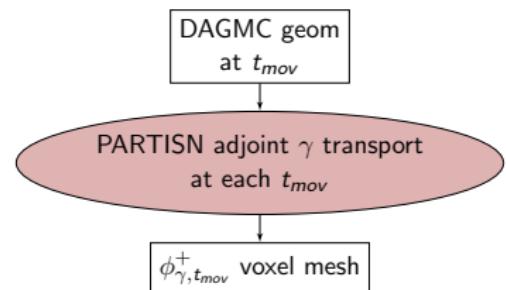
TGT-CADIS: Generate VR Parameters



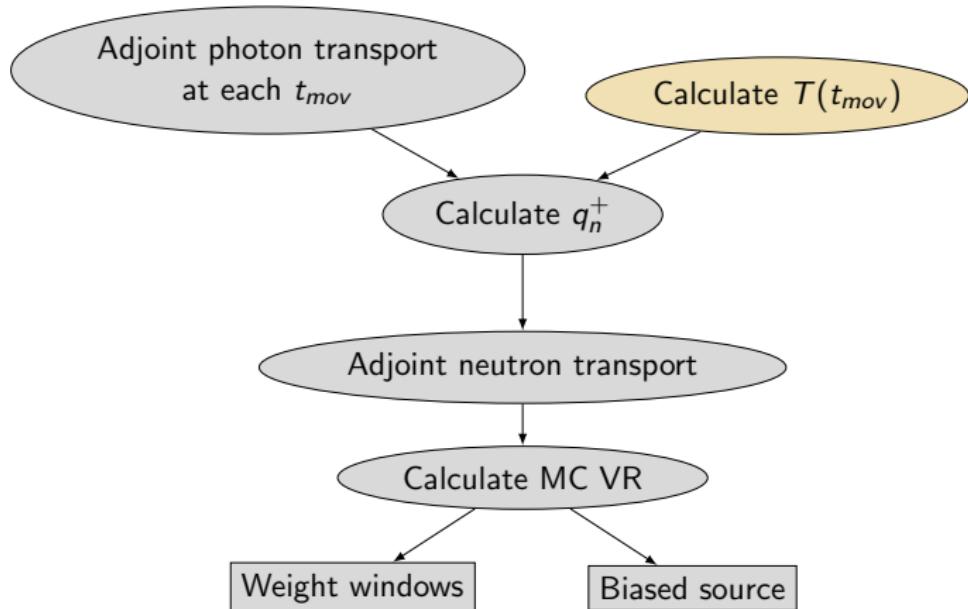
- Perform adjoint photon transport at each time step



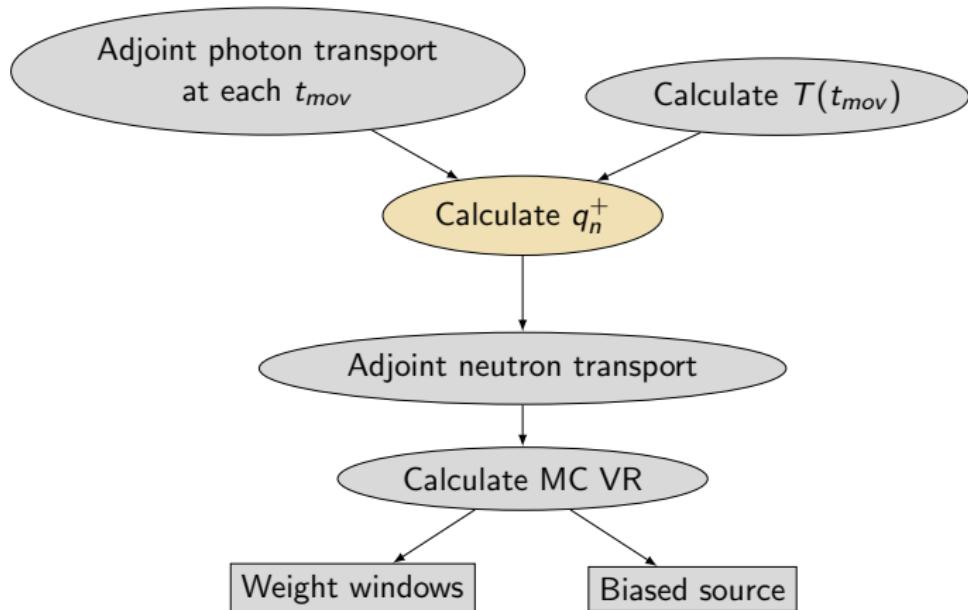
Detector



Time-integrated (T)GT-CADIS: Workflow

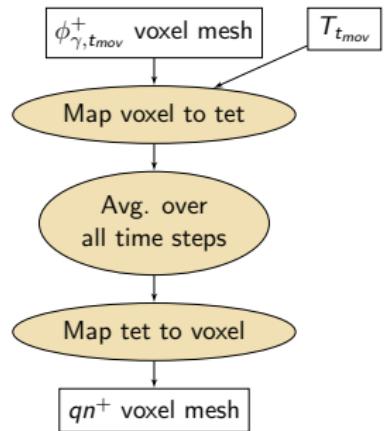
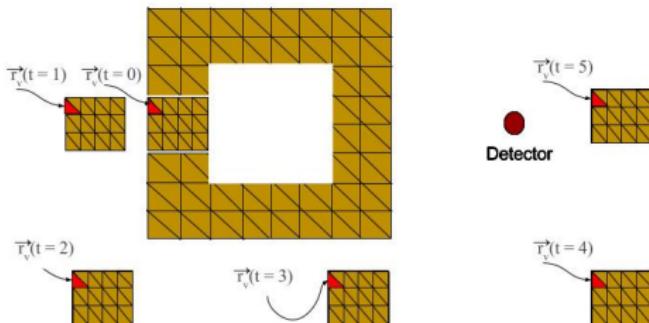


Time-integrated (T)GT-CADIS: Workflow

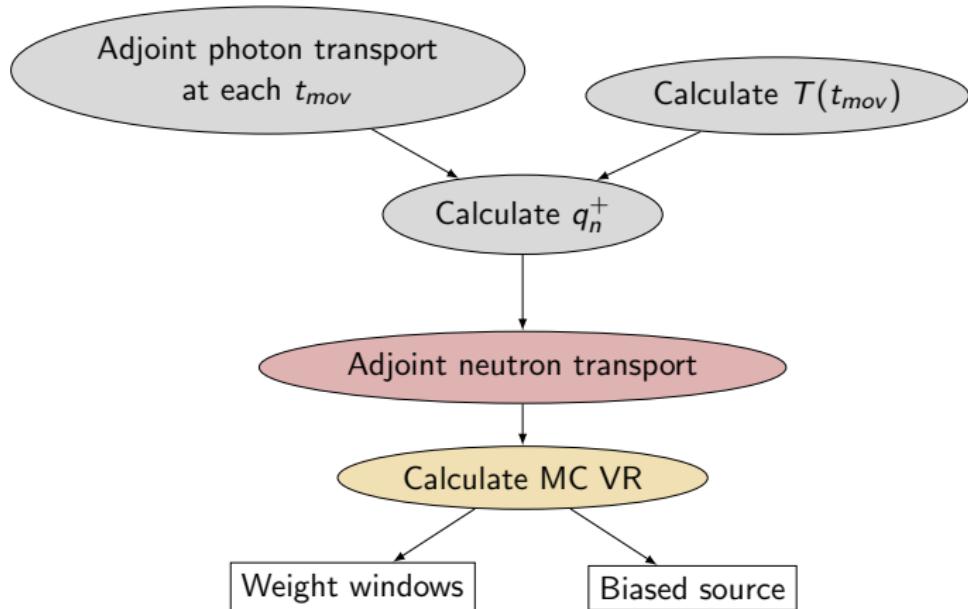


TGT-CADIS: Calculate Adjoint Neutron Source

- Map the structured (voxel) mesh to a tetrahedral mesh
- Combine $\phi_{\gamma, t_{mov}}^+$ and $T_{t_{mov}}$ and average over time

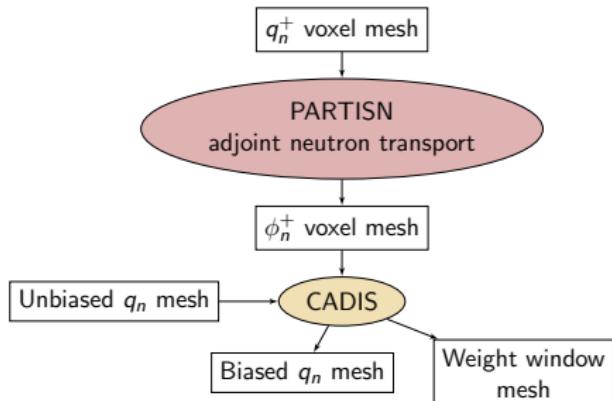


Time-integrated (T)GT-CADIS: Workflow



TGT-CADIS: Generate VR Parameters

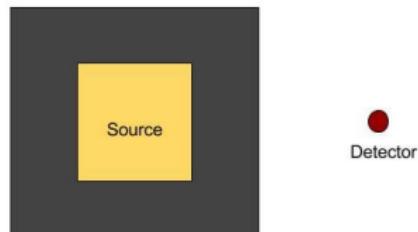
- Perform adjoint neutron transport
- Generate biased source and weight window mesh via CADIS methodology



Experiment

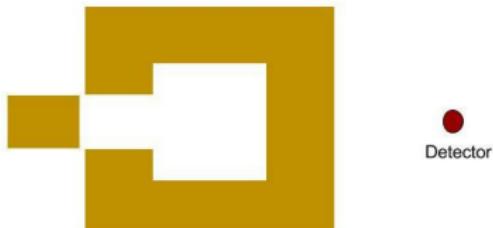
Experiment

- Toy problem to assess utility of TGT-CADIS
 - Steel chamber with moving component
 - Incrementally add optimization
 - Calculate figure of merit (FOM)
- Full-scale FES demonstration



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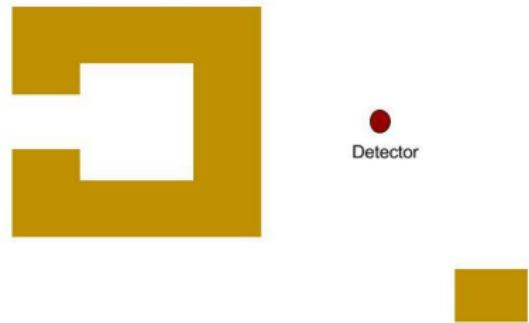
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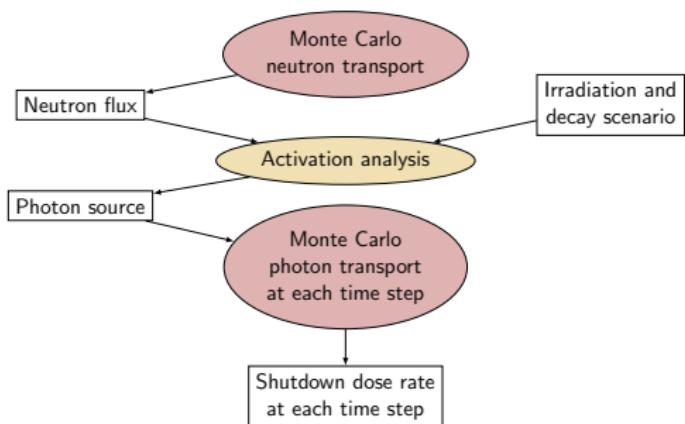
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 - Incrementally add optimization
 - Calculate figure of merit (FOM)
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Experiment: Toy Problem

Experimental Steps:

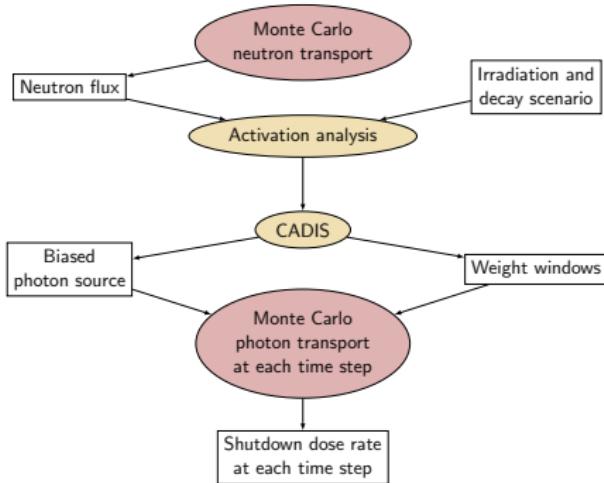
① No VR



Experiment: Toy Problem

Experimental Steps:

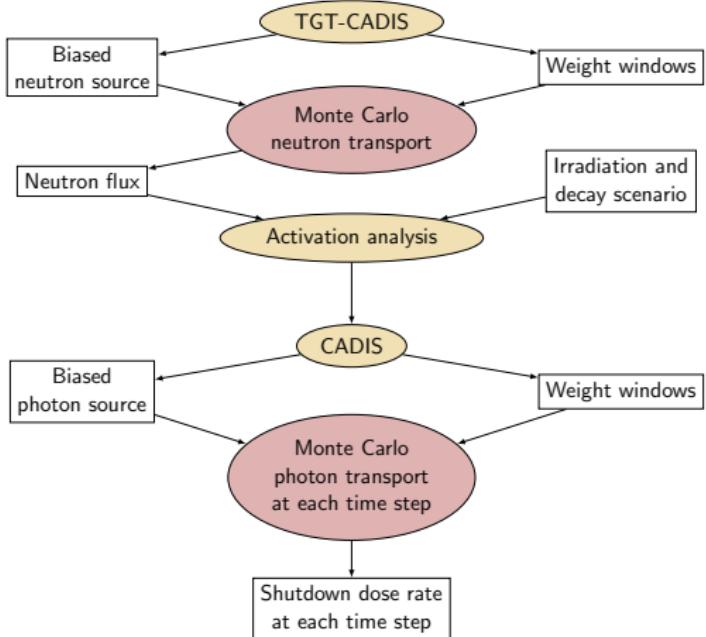
- ① No VR
- ② Photon VR:
CADIS



Experiment: Toy Problem

Experimental Steps:

- ① No VR
- ② Photon VR:
CADIS
- ③ Neutron and
Photon VR:
TGT-CADIS,
CADIS



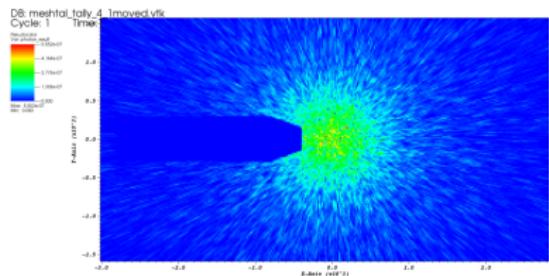
Progress



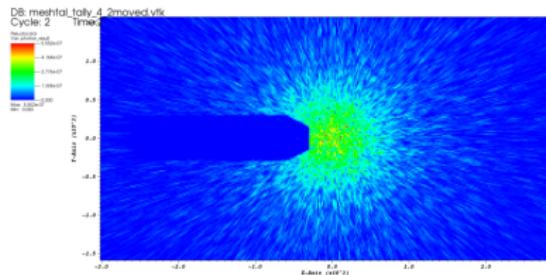
MC Moving Geometry Simulations

- Tools to update position of geometry based on user-defined motion data
 - ① Production of step-wise geometry files
 - ② DAGMC update to facilitate on-the-fly geometry transformations
- Motion data:
 - Time-dependent translation or rotation vector, total length of time, number of desired time steps
 - Relocation transform
- Common functionality:
 - Read tag data that specifies type of transformation
 - Identify starting position of each component
 - Update position according to transformation

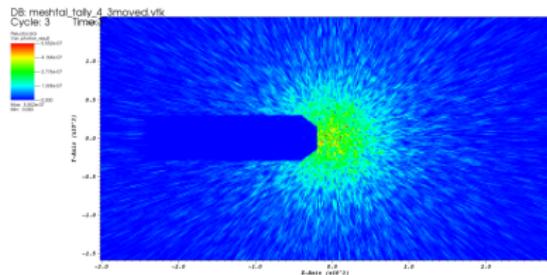
MC Moving Geometry Simulations



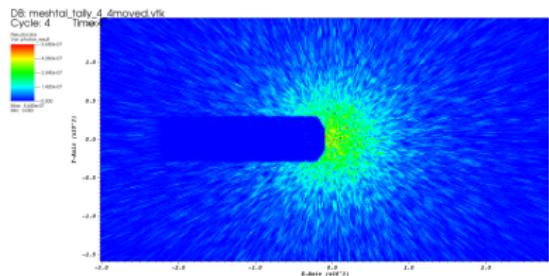
MC Moving Geometry Simulations



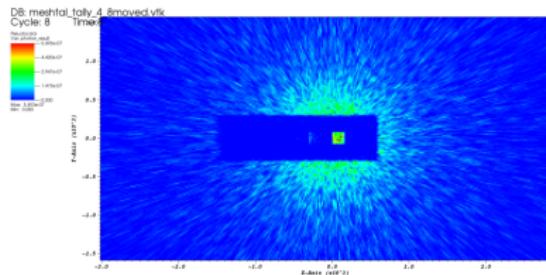
MC Moving Geometry Simulations



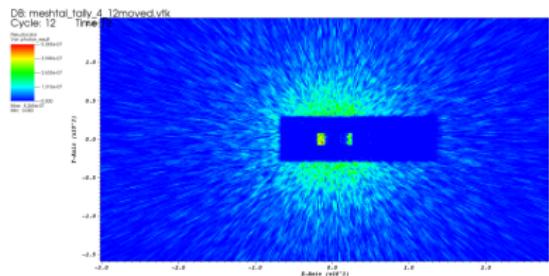
MC Moving Geometry Simulations



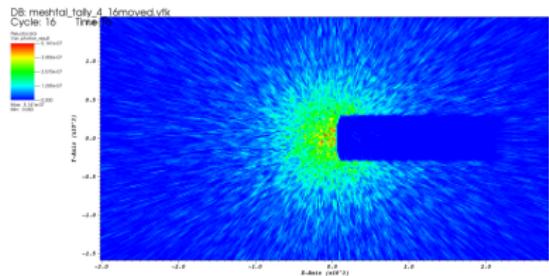
MC Moving Geometry Simulations



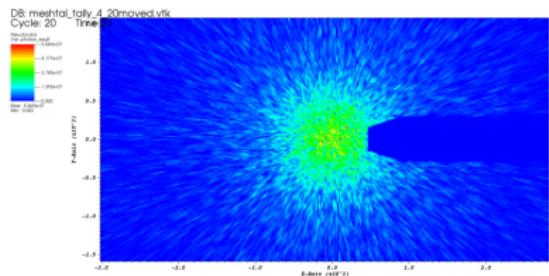
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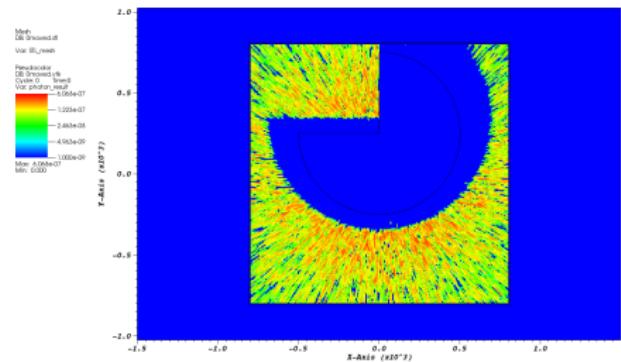
MC Moving Geometry Simulations



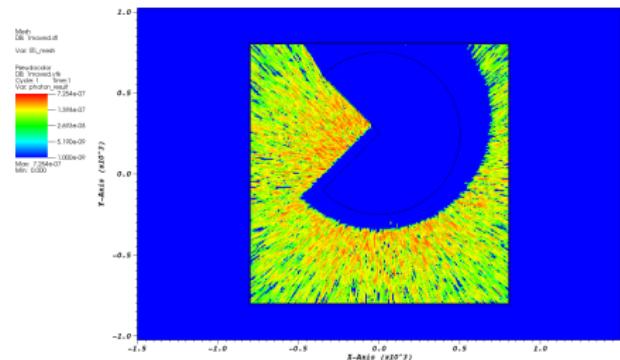
MC Moving Geometry Simulations



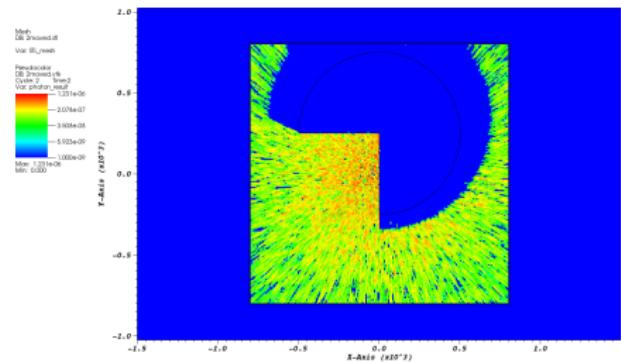
MC Moving Geometry Simulations



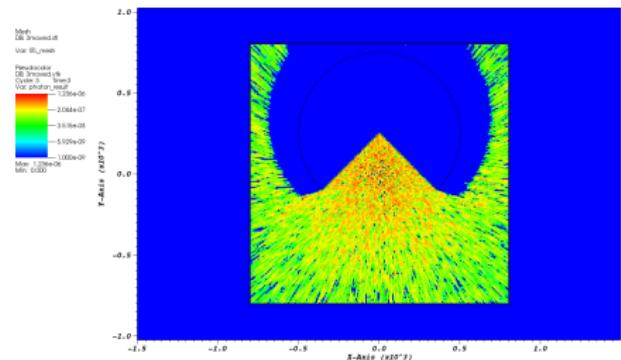
MC Moving Geometry Simulations



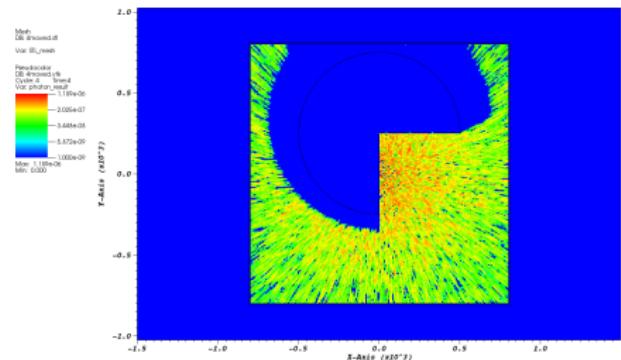
MC Moving Geometry Simulations



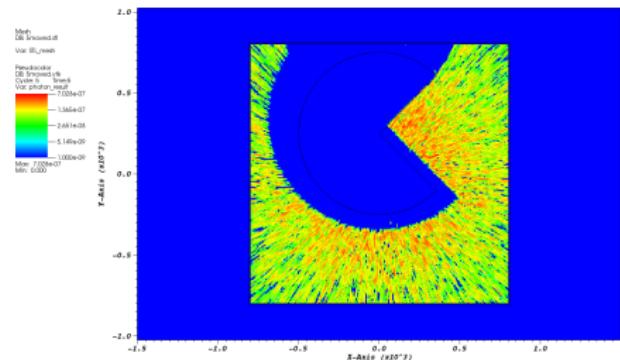
MC Moving Geometry Simulations



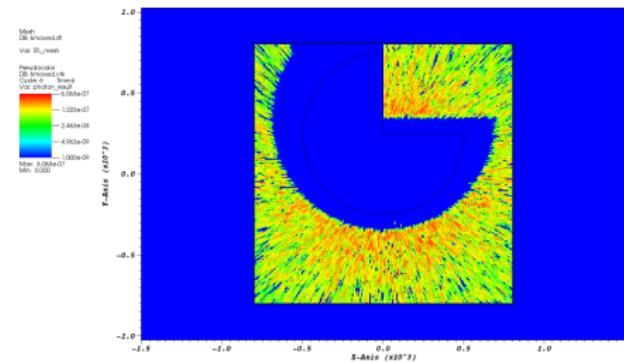
MC Moving Geometry Simulations



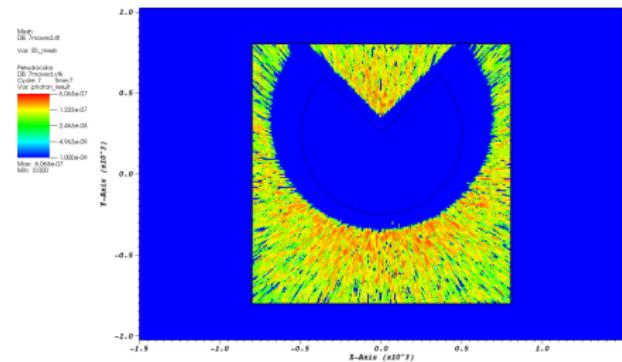
MC Moving Geometry Simulations



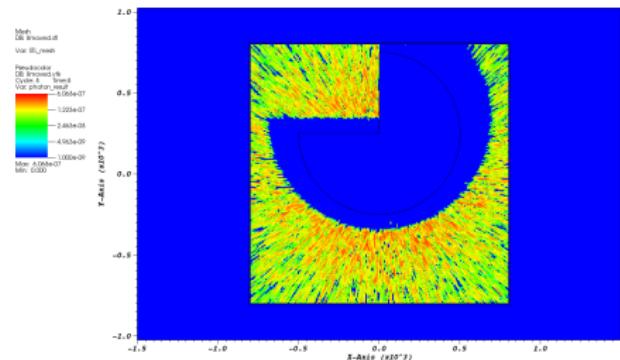
MC Moving Geometry Simulations



MC Moving Geometry Simulations



MC Moving Geometry Simulations



Conclusions



Assumptions

- Photon transport occurs much faster than geometry movement ∴ reasonable to do quasi-static simulation
- Period of geometry movement is short enough that the photon source will not change appreciably ∴ can use same photon source for all MC calculations



Challenges

- Depending on complexity of model and fidelity of time resolution, can amass large number of CAD geometry files, volume mesh tally files
- Need to optimize this workflow in order to keep file storage at minimum



Summary

- Accurate quantification of the SDR during maintenance procedures is crucial to the design and operation of FES
- GT-CADIS has proven to accurately quantify the SDR in static FES
- TGT-CADIS aims to provide the capabilities necessary to calculate the SDR at various time points during operations that involve activated components moving around the facility



Questions?



TODO

- REFERENCES
- Fig numbers
- FW-CADIS
- Pros/cons deterministic/MC
- Intro DAGMC, MOAB
- Too much detail in Gen. MS-CADIS?
- labels on tet mesh time slices
- Overall alignment/sizing/spacing
- Error propagation
- Add more on moving geom progress, movie
- OBB tree optimization