

# Variance Reduction for Multi-physics Analysis of Moving Systems

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# Introduction

# Shutdown Dose Rate (SDR) Analysis



- Fusion Energy Systems (FES)
  - Burning plasma, D-T fusion
  - ${}^2_1\text{H} + {}^3_1\text{H} \rightarrow {}^4_2\text{He} + {}^1_0\text{n}$
- Neutrons penetrate deeply into system components, causing activation
- Radioisotopes persist long after shutdown
- Important to quantify the dose caused by decay photons

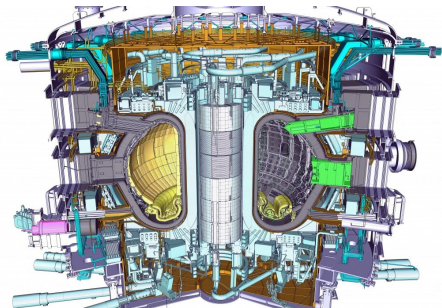
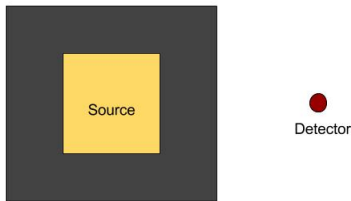


Figure : Cutaway view of ITER drawing.

- Example: maintenance procedure
  - Need to move component(s) around facility
  - Interested in SDR at a particular location
  - SDR will change as a function of the activated component's position over time



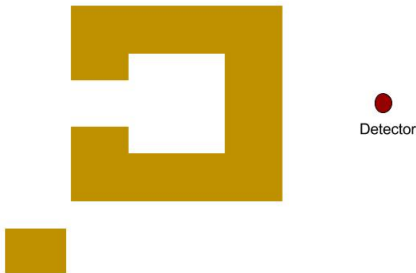
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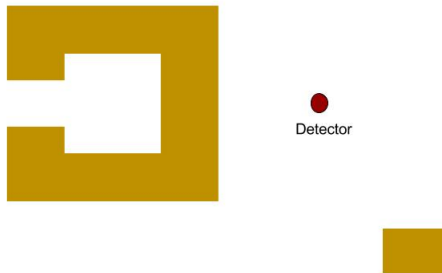


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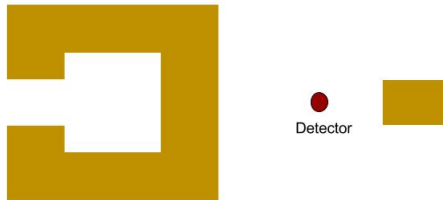




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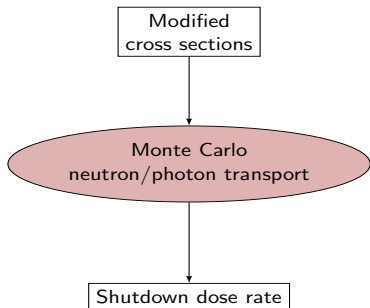


**Optimize** the **radiation transport** simulation used to calculate the **shutdown dose rate** at a particular location as activated components are **moving** around the facility.



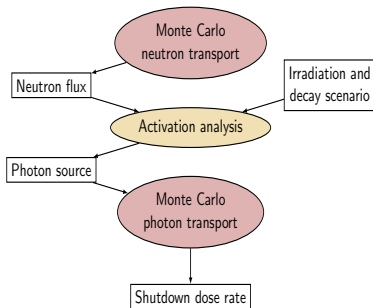
Deterministic vs. MC

- Direct 1-Step Method (D1S)



Add pros/cons of D1S, R2S

- Rigorous 2-Step Method (R2S)



- Monte Carlo (MC) analysis of fusion energy systems is:
  - Accurate for large, complex models
  - Challenging due to the highly attenuating structural materials
    - Results scored in regions that have low particle flux, have higher statistical uncertainty
- To decrease statistical uncertainty:
  - Increase number of histories
  - Use variance reduction (VR) techniques

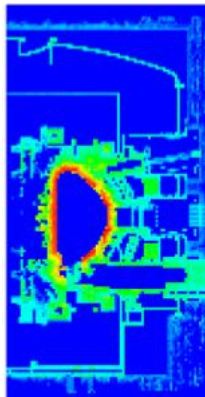


Figure : Photon flux in ITER tokamak building.







- Techniques to modify particle behavior
  - **Goal:** preferentially sample events that will contribute to results of interest
- Statistical weight of particles is adjusted to keep playing a fair game

## Consistent Adjoint Driven Importance Sampling (CADIS)

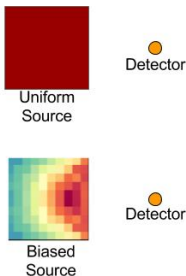
- Adjoint flux can define the importance of regions of phase space to the detector response
- Use **deterministic** estimate of the adjoint flux,  $\Psi^+$ , to generate **Monte Carlo** VR parameters in a **consistent** manner
  - Define detector response function to be the adjoint source

$$H^+ \Psi^+ = q^+ \quad (1)$$

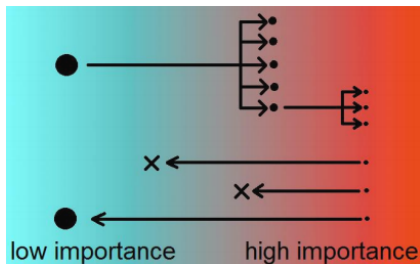
$$H^+ = -\hat{\Omega} \cdot \nabla + \sigma_t(\vec{r}, E) - \int_0^\infty dE' \int_{4\pi} d\Omega' \sigma_s(\vec{r}, E \rightarrow E', \hat{\Omega} \rightarrow \hat{\Omega}') \quad (2)$$

- Use the adjoint flux to generate MC source and transport biasing parameters

Source: sample from biased PDF



Transport: weight windows





## VR for **photon** transport

- **Straightforward**
- Can use CADIS method to direct photons towards detector
  - Flux-to-dose-rate conversion factors define adjoint source

## VR for **neutron** transport

- More **complicated**
- Biasing function needs to capture
  - ① Potential of regions to become activated
  - ② Potential to produce photons that will contribute to the SDR
- Can use CADIS if we can construct adjoint source that will fulfill these criteria



## Multi-Step (MS)-CADIS

- VR method to optimize the initial radiation transport step of a coupled, multi-step process
  - Relies upon function that represents importance of particles to final response of interest
- When applied to SDR analysis, MS-CADIS will optimize the neutron transport
  - Use function that represents the importance of the neutrons to the final dose rate

- **Groupwise Transmutation (GT)-CADIS**
  - Implementation of MS-CADIS specifically for SDR analysis
  - Provides method to calculate optimal adjoint neutron source,  $q_n^+$ , by first calculating,  $T$ , a term that relates the neutron flux to photon source
  - Calculate  $T$ : (move this to later slide)
    - ① Irradiate each material with neutrons from a single energy group,  $g$
    - ② Record resulting photon emission in each energy group,  $h$

$$T_{g,h} = \frac{q_{\gamma,h}(\phi_{n,g})}{\phi_{n,g}} \quad (3)$$



- MOVE: Use  $T$  to solve for adjoint neutron source:

$$q_n^+(E_n) = \int_{E_\gamma} T(E_n, E_\gamma) \phi_\gamma^+(E_\gamma) dE_\gamma \quad (4)$$



## MCNP6 Moving Objects

- Update in future version of MCNP6
- Allows movement of objects, sources, delayed particles during single simulation
- Available for native MCNP geometry descriptions (not mesh)

## Mesh Coupled implementation of R2S (MCR2S)

- Capability that allows components to move before photon transport step
- Transformations are applied to copies of moving components
- Original component still in original location, set to void material

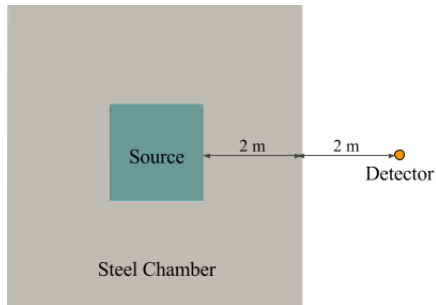




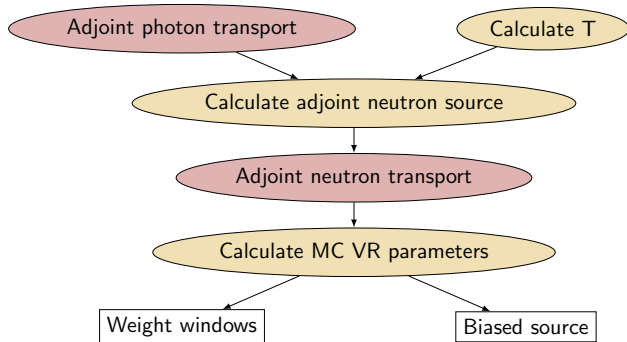
- MC method is most accurate way to obtain detailed particle flux distributions
  - Use MC codes for both neutron and photon transport steps of R2S
  - Need to use VR methods to optimize the transport calculations
- GT-CADIS, an implementation of MS-CADIS, has proven to optimize the neutron transport step of R2S
- MCNP6 and MCR2S have developed some capabilities for performing transport on moving geometries

## Demonstration

- Geometry
  - Steel chamber
  - 2m x 2m x 2m central cavity
- Source
  - Volume source in central cavity
  - 13.8-14.2 MeV neutrons



- GT-CADIS workflow



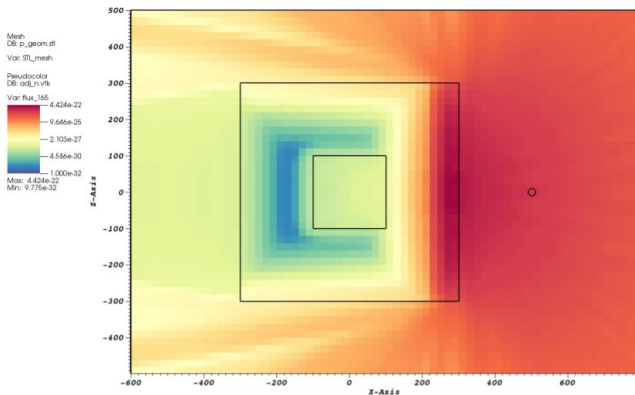
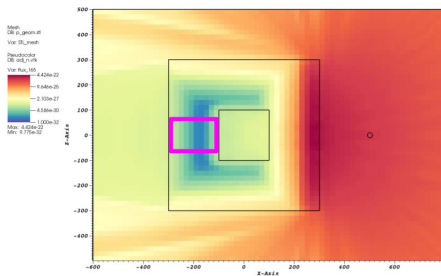


Figure : GT-CADIS adjoint neutron flux. Functions as importance map.

GT-CADIS importance map is **insufficient** for moving systems.



**Figure :** Demo model. Steel chamber, walls are 2 m thick. 14 MeV neutron source in center. Chamber surrounded by air.

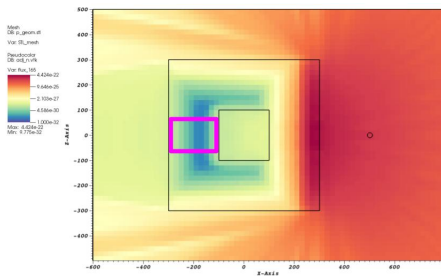


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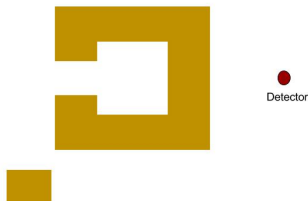


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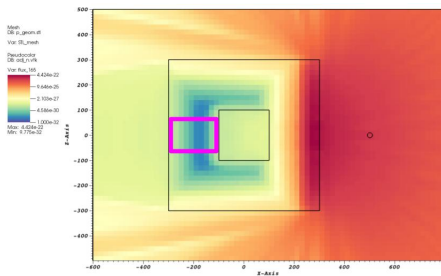


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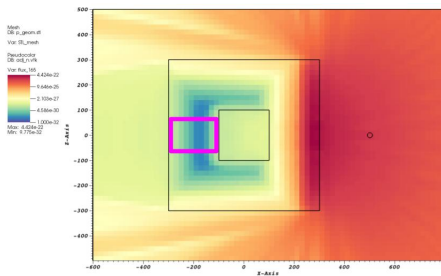
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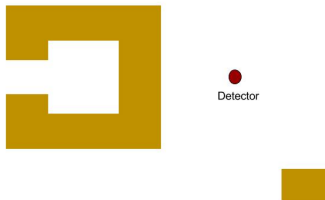


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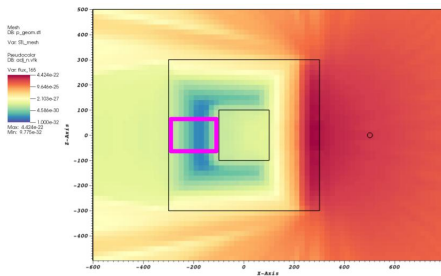


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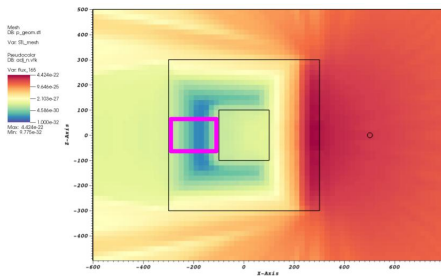


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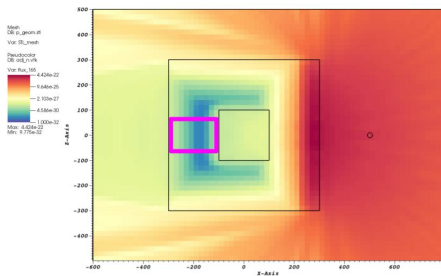


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# Proposal



- MS-CADIS optimizes initial radiation transport step in a coupled, multi-step process
- Need to derive new adj neutron source

- System of coupled, multi-physics:

$$\textit{Primary} : H\phi(u) = q(u) \quad (5)$$

$$\textit{Secondary} : L\Psi(v) = b(v) \quad (6)$$

- Adjoint identities:

$$\langle \phi^+, q \rangle = \langle \phi, q^+ \rangle \quad (7)$$

$$\langle \Psi^+, b \rangle = \langle \Psi, b^+ \rangle \quad (8)$$

- MS-CADIS requires a representation of the relationship between primary and secondary physics:

$$b(v) = \langle \sigma_b(u, v), \phi(u) \rangle, \quad (9)$$



- Response to secondary physics:

$$R_{final} = \langle \omega_R(v), \psi(v) \rangle \quad (10)$$

- Set  $\omega_R$  as adjoint source and invoke adjoint identity:

$$R_{final} = \langle \omega_R, \psi \rangle = \langle b, \psi_R^+ \rangle \quad (11)$$

- Substitute Eq. 9 :

$$R_{final} = \langle \langle \sigma_b(u, v), \phi(u) \rangle, \psi_R^+(v) \rangle \quad (12)$$



- Switch the order of integration

$$R_{final} = \langle \langle \sigma_b(u, v), \psi_R^+(v) \rangle, \phi(u) \rangle \quad (13)$$

- Set response of primary physics equal to final response of the system and invoke the adjoint identity to solve for  $q^+$ :

$$R_{final} = \langle \langle \sigma_b(u, v), \psi_R^+(v) \rangle, \phi(u) \rangle = \langle q(u), \phi_R^+(u) \rangle, \quad (14)$$

$$q^+(u) \equiv \langle \sigma_b(u, v), \psi_R^+(v) \rangle. \quad (15)$$

- Geometry movement during secondary physics effects the construction of the adjoint neutron source

$$q_v^+ = \int_t \Psi^+(\vec{r}_v(t), t) \sigma_{c,v}(t) dt \quad (16)$$

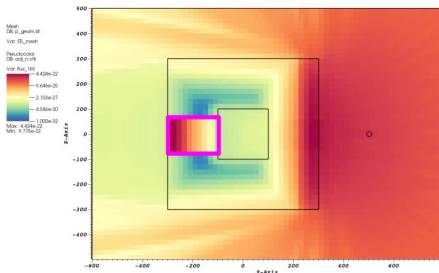
- Adjoint flux in volume element  $v$  at time  $t$ :  $\Psi^+(\vec{r}_v(t), t)$
- Position of volume element  $v$  at time  $t$ :  $\vec{r}_v(t)$

- To apply time-integration to GT-CADIS:
  - 1 Perform adjoint photon transport at each time step of geometry movement
  - 2 Integrate over time

$$q_{n,v}^+(E_n) = \int_t \int_{E_\gamma} T_v(E_n, E_\gamma, t) \phi_\gamma^+(\vec{r}_v(t), E_\gamma, t) dE_\gamma dt \quad (17)$$

- $\phi_\gamma^+(\vec{r}_v(t), E_\gamma, t)$  is the adjoint flux of photons of energy  $E_\gamma$ , in volume element  $v$ , at time  $t$
- $T_v(E_n, E_\gamma, t)$  is the  $T$  value of the material in volume element  $v$ , at decay time  $t$

- Perform deterministic adjoint neutron transport using the time-integrated source
- Resultant adjoint neutron flux should look something like this:



- Use this adjoint neutron flux to generate biasing parameters that will optimize the MC neutron transport step of R2S.

- Discrete form:

$$T_{v,g,h} = \frac{q_{\gamma,v,h}(\phi_{n,v,g})}{\phi_{n,v,g}} \quad (18)$$

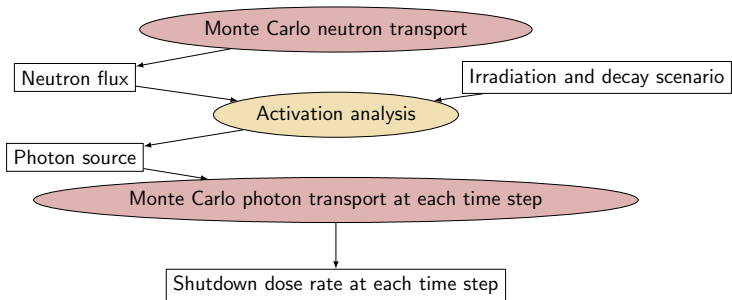
$$q_{n,v,g}^+ = \frac{\sum_{t_{mov}} (\sum_h T_{v,g,h} \phi_{\gamma,v,h,t_{mov}}^+) \Delta t_{mov}}{t_{tot}} \quad (19)$$



- Tools to update position of geometry based on user-defined motion data
  - ① Tool to produce step-wise geometry files
  - ② DAGMC update to facilitate on-the-fly geometry transformations
- Common functionality:
  -



- R2S workflow for geometry movement after shutdown





- Assumptions
  - Photon transport occurs much faster than geometry movement  $\therefore$  reasonable to do quasi-static simulation
  - Period of geometry movement is short enough that the photon source will not change appreciably  $\therefore$  can use same photon source for all MC calculations
- Challenges
  - Depending on complexity of model and fidelity of time resolution, can amass large number of CAD geometry files, volume mesh tally files
  - Need to optimize this workflow in order to keep file storage at minimum



Questions?