AMATH 567 Homework 3

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October 20, 2021

1 Problem 1 (2.2.4)

Consider the multi-valued function $\ln(z^{\alpha})$ where $\alpha \in \mathbb{R}$. By the definition of the complex logarithm and letting $z = Re^{i \arg z}$ for any $k \in \mathbb{Z}$,

$$\ln(z^{\alpha}) = \ln(R^{\alpha}e^{i\alpha \arg z}) = \ln(R^{\alpha}) + i\arg(e^{i\alpha \arg z}) = \alpha \ln R + i\arg(e^{i\alpha \arg z}).$$

Note that we have multi-valued arguments. This setup also gives that

$$\alpha \ln z = \alpha (\ln R + i \arg z) = \alpha \ln R + \alpha i \arg z.$$

We wish to show that the values of these two multi-valued functions are not the same. This amounts to checking whether $\arg(e^{i\alpha\arg z})=\alpha\arg z$ in general. If we let $\alpha=\frac{1}{2}$ and z=1 such that $\arg(z)=0$ (note that we fixed a branch to the principal argument by doing this, so $\arg(w)\in(-\pi,\pi]$ for any $w\in\mathbb{C}$), $\alpha\arg z=0$ but $\arg(e^{i\alpha(\arg z+2\pi k)})=\arg(e^{ik\pi})=\arg(\pm 1)=0,\pi$ where $k\in\mathbb{C}$. Thus, the multivaluedness does not resolve here, so the sets of all values of these functions do not necessarily match.

2 Problem 2

Consider the function $w=z^z$ where $z\in\mathbb{C}$. We first find its real and imaginary parts by letting $z=Re^{i\theta}$ and writing

$$z^{z} = e^{z \ln z} = e^{z(\ln R + i\theta)} = e^{R(\cos \theta + i\sin \theta)(\ln R + i\theta)} = e^{R(\cos \theta \ln R - \theta\sin \theta + i(\sin \theta \ln R + \theta\cos \theta))}$$
$$= e^{R\cos \theta \ln R - R\theta\sin \theta} e^{i(R\sin \theta \ln R + R\theta\cos \theta)}$$
$$= e^{R\cos \theta \ln R - R\theta\sin \theta} (\cos(R\sin \theta \ln R + R\theta\cos \theta) + i\sin(R\sin \theta \ln R + R\theta\cos \theta))$$

Note that R and θ are both real by definition, so we can see that

$$\Re(w) = e^{R\cos\theta \ln R - R\theta\sin\theta} \cos(R\sin\theta \ln R + R\theta\cos\theta)$$

and

$$\Im(w) = e^{R\cos\theta \ln R - R\theta \sin\theta} \sin(R\sin\theta \ln R + R\theta \cos\theta).$$

Let $A = R\cos\theta \ln R - R\theta\sin\theta$ and $B = R\sin\theta \ln R + R\theta\cos\theta$. Then, if we let $u = \Re(w)$ and $v = \Im(w)$, $u = e^A\cos(B)$ and $v = e^A\sin(B)$. Note that $z^z = e^Ae^{iB}$. We compute the partial derivatives of A and B and get

$$A_R = (\ln R + 1)\cos\theta - \theta\sin\theta$$

$$A_\theta = -R(\sin\theta\ln R + \sin\theta + \theta\cos\theta)$$

$$B_R = (\ln R + 1)\sin\theta + \theta\cos\theta$$

$$B_\theta = R(\cos\theta\ln R + \cos\theta - \theta\sin\theta)$$

We have omitted the multivaluedness of the complex logarithm (technically we should have $\theta = \arg x + 2\pi k$ for any $k \in \mathbb{Z}$ but per Piazza, we are permitted to omit this). Note that $RA_R = B_\theta$ and $-RB_R = A_\theta$.

We now wish to find the derivative of w. To ensure that we can do this, we first check that the Cauchy-Riemann equations (in polar form) are satisfied

$$u_R = e^A (A_R \cos B - B_R \sin B)$$

$$v_R = e^A (A_R \sin B + B_R \cos B)$$

$$u_\theta = e^A (A_\theta \cos B - B_\theta \sin B) = Re^A (-B_R \cos B - A_R \sin B) = -Rv_R$$

$$v_\theta = e^A (A_\theta \sin B + B_\theta \cos B) = Re^A (-B_R \sin B + A_R \cos B) = Ru_R.$$

These are precisely the polar-form Cauchy-Riemann equations, so our function is indeed analytic, because the partial derivatives are clearly continuous with the exception of the origin due to the presence of $\ln R$. Thus, we can evaluate

$$w' = e^{-i\theta}(u_R + iv_R) = e^{-i\theta}e^A(A_R\cos B - B_R\sin B + i(A_R\sin B + B_R\cos B))$$

$$= e^{-i\theta}e^A(A_Re^{iB} + iB_R(\cos B + i\sin B)) = e^{-i\theta}(A_Re^Ae^{iB} + iB_Re^Ae^{iB})$$

$$= e^{-i\theta}(A_R + iB_R)z^z = e^{-i\theta}z^z((\ln R + 1)\cos \theta - \theta\sin \theta + i(\ln R + 1)\sin \theta + i\theta\cos \theta)$$

$$= e^{-i\theta}z^z((\ln R + 1)e^{i\theta} + i\theta e^{i\theta}) = z^z(\ln R + i\theta + 1).$$

Now recall that when starting the problem, we glossed over the multivaluedness of the complex logarithm and noted that we should technically have $\theta = \arg x + 2\pi k$. If we make this substitution, then $\ln R + i\theta = \ln(Re^{i\theta}) = \ln z$. Thus, $w' = z^z(\ln z + 1)$, as desired.

Now, we wish to evaluate i^i . We could do so by using the real and imaginary parts of z^z that we found, but it is much cleaner to just use the definitions of the complex power and complex logarithm. Note that i has modulus 1 and argument $\pi/2$.

$$i^{i} = e^{i \ln i} = e^{i(\ln(1) + i(\pi/2 + 2\pi k))} = e^{-(\pi/2 + 2\pi k)}$$

for any $k \in \mathbb{Z}$.

3 Problem 3

Consider the multi-valued function w(z) such that $w^2 = \prod_{j=1}^{n=N} (z-a_j)$ where all $a_j \in \mathbb{C}$ are distinct. The problem statement asks us to consider specific values

of N, but for finding the branch points, we just consider the cases where N is even or odd. In both cases, $z=a_j$ is a branch point for all j. We can see this via a similar argument to the N=2 case on page 32 of the course notes. Taking $z=a_k+\epsilon e^{i\theta}$ for some $1\leq k\leq N$ where $\epsilon>0$ is small,

$$w = (\epsilon e^{i\theta} \prod_{j \neq k} (a_k - a_j + \epsilon e^{i\theta}))^{1/2} \sim \sqrt{\epsilon} (\prod_{j \neq k} (a_k - a_j)^{1/2} e^{i\theta/2}),$$

ignoring terms of order ϵ . In the vicinity of $z=a_k$, this behaves like the n=N-1 case. We know from the notes that the n=2 case holds, so a standard induction argument on n gives the general case.

Now, we consider whether or not ∞ is a branch point which will depend on whether N is odd or even. For very large values of $z, w \sim (z^N)^{1/2}$. If N=2k is even, then $(z^N)^{1/2}=\pm z^k$. This has 2 values, but because $k\in\mathbb{Z}$, w returns to its original value as z traverses a circle of very large radius. Thus, there are two different points at ∞ for w, but the behavior near each of those is single-valued, so ∞ is not a branch point. If N=2k+1 is odd and taking $1/z=t=Re^{i\theta}$ to investigate large z, then

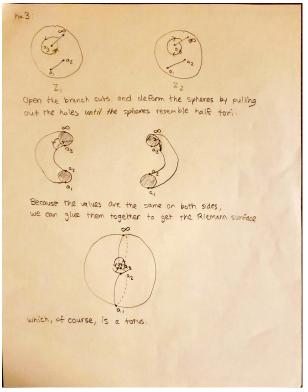
$$w_1 \sim z^{k+1/2} = \left(\frac{1}{Re^{i\theta}}\right)^{k+1/2} = R^{-(k+1/2)}(e^{-i\theta})^{-(k+1/2)} = R^{-(k+1/2)}e^{-i(\theta+2\pi m)(2k+1)/2}$$

and $w_2 = -w_1$.

Note that this is still multi-valued, so the terms do not reconcile by the same logic as our square root example from class. Thus, ∞ is a branch point. We know that these are the only branch points, because the function w is analytic elsewhere.

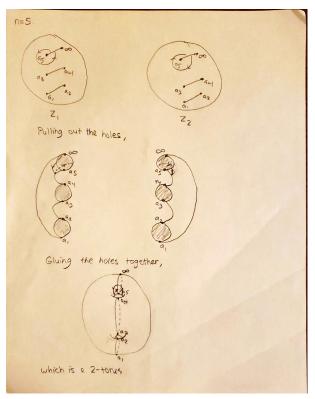
Note: In office hours, Bernard stated that we need not prove that the a_i s are branch points or that there are no other branch points. I have left my rough arguments in for completeness, but they may be vague as a result.

Now that we know what our branch points are, we can consider specific values of N, starting with n = 3. In this case, we have branch points at a_1, a_2, a_3, ∞ , meaning that we can draw two branch cuts arbitrarily (such that all branch points are part of exactly one branch cut). Take the two spheres z_1 and z_2 with these cuts and manipulate as follows (please forgive my poor quality drawings):



In the case n=4, we have the same number of branch points, so everything is the same except $z=a_4$ replaces ∞ as a branch point.

For the case n=5, we have branch points at $a_1,a_2,a_3,a_4,a_5,\infty$, meaning that we can draw 3 branch cuts and do the following:



In general, we will have N branch points if N is even and N+1 branch points if N is odd, meaning that the Riemann surface will be a k-torus for an even N=2k and an odd N=2k-1.

4 Problem 4 (2.2.7)

Consider the function $\Omega(z)=k\ln(z-z_0)$ where $k\in\mathbb{R}$ and $z_0\in\mathbb{C}$ are constants. The velocity potential ϕ and the stream function ψ are just the real and imaginary parts of this function respectively, so $\Omega(z)=k(\ln|z-z_0|+i\arg(z-z_0))$ gives that $\phi(z)=k\ln|z-z_0|$ and $\psi(z)=k\arg(z-z_0)$.

From page 41 of the text, we have that velocity is given by

$$\overline{\Omega}'(z) = \frac{\overline{k}}{z - z_0} = \frac{k}{\overline{z - z_0}} = \frac{k(z - z_0)}{|z - z_0|^2}.$$

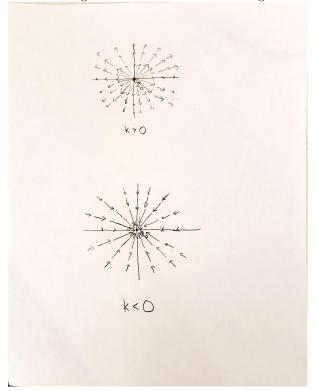
We wish to show that this is purely radial relative to $z=z_0$, so consider a shifted polar coordinate system such that $z-z_0=Re^{i\theta}$. Then,

$$\overline{\Omega}'(z) = \frac{kRe^{i\theta}}{R^2} = \frac{k}{R}e^{i\theta}.$$

Written in vector form, velocity is $(\frac{k}{R}\cos\theta, \frac{k}{R}\sin\theta)$; this is just a normal vector pointing radially outward from the origin (defined relative to z_0) scaled by $\frac{k}{R}$

(as the collection of these vectors is a circle for fixed R). Thus, velocity is purely radial relative to $z=z_0$ (given by $V_r=\frac{k}{R}$).

The following are sketches of the flow configuration for different values of k:



Let $M = \oint_C V_r ds$ where V_r is the radial velocity and ds is the increment of arclength in the direction tangent to the circle C enclosing $z = z_0$. Continuing with our modified coordinate system, let $C = Re^{i\theta}$. Then,

$$M = \oint_C V_r ds = \int_0^{2\pi} (\frac{k}{R})(Rd\theta) = k \int_0^{2\pi} d\theta = 2\pi k.$$