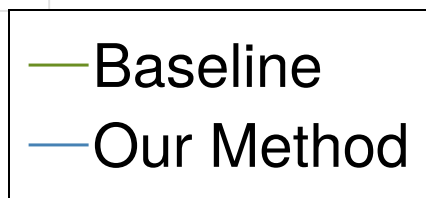


Trajectory Error [m]



0.00

0.05

0.10

Noise Level  $\sigma$  [m]

0

50

100