STAT 447 Assignment 2

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Question 1 : Define a Bayesian Model

In order to perform inference on the unknown quantities, we must specify how they relate to the data; i.e., we need a probabilistic model. Assume that every Delta 7925H rocket has the same probability p of failing. For simplicity, let us assume that p is allowed to take values on an evenly space grid

$$p \in \left\{ \frac{k}{K} : k \in \{0, \dots, K\} \right\}$$

for some fixed $k \in \mathbb{N}$. Furthermore, we have access to a collection of numbers ρ_k such that:

$$\forall k \in \{0, \dots, K\} : \mathbb{P}\left(p = \frac{k}{K}\right) = \rho_k$$

Let Y_i denote a binary variable with $Y_i = 1$ encoding a success, and $Y_i = 0$ a failure. We assume that, conditionally on p, the Y_i 's are independent of each other.

We will use the following prior:

$$\rho_k \propto \frac{k}{K} \left(1 - \frac{k}{K} \right)$$

From now on, use K=20

Part 1

What are the unknown quantities in this scenario? And what is the data?

Solution: In this case, we can think of two unknown quantities and one piece of known data. One unknown metric is Y_i , whether or not the rocket is going to fail. The other unknown quantity is the success probability of the rockets - this was denoted p. This is much like the "coin flip" scenario from the previous homework, where Y_i was "whether or not we flip a heads," and the distribution of coin biases (i.e. the probability we pick a coin with bias k/K) was ρ_k .

In this case, the data is given in the setup section, and is simply that as of Jan 2024, Delta 7925H rockets have been launched 3 times, with 0 failed launches. Further, we have ρ_k , the probability that the *true* probability p is k/K for a given discrete k.

Part 2

Here, letting k = 20, we can think of the random Variable X as the probability that the rocket has failure rate k, for $k \in [0, 20]$ i.e.

$$X \sim \text{unif}(\{0, 1, 2, \dots, 20\})$$

Similarly, the conditional distribution of Y_i given X can be written as:

$$Y_i \sim \operatorname{bern}\left(\frac{X}{20}\left(1 - \frac{X}{20}\right)\right)$$

Together, these form the joint distribution $p_{X,Y}(x,y)$ as we saw in lecture, due to the chain rule.

Question 2: Posterior and Point Estimates

To help you answer the following questions, we create the two vectors

prior_probabilities where entry i containing the prior probability ρ_{i-1} defined in Q1 (the minus one reflects the fact that R uses indexing starting at 1), and realizations, a vector of possible realizations of p in the same order, namely (0, 1/K, 2/K..., 1).

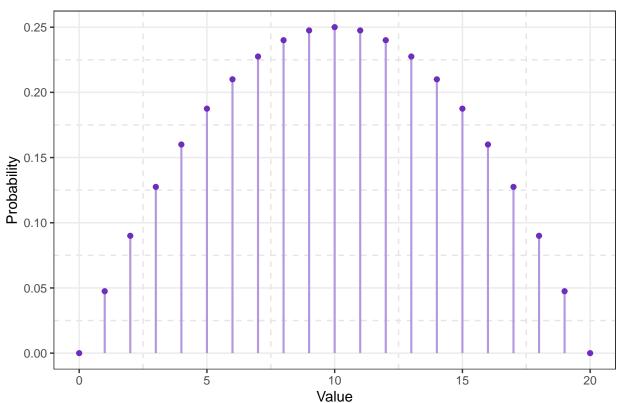
```
K = 20
prior_probabilities = sapply(0:K, function(k){(k / K)*(1 - k/K)})
realizations = sapply(0:K, function(k){k/K})
```

Part 1

Plot the prior PMF. Do you think this is a reasonable prior?

```
plot_data <- data.frame(</pre>
  value = 0:K,
  probability = prior_probabilities
)
# plot prior
p <- ggplot(plot_data, aes(x = value, y = 0, yend = probability)) +</pre>
  geom_segment(aes(xend = value), color = "#b298dc", linewidth = 0.75) +
  geom_point(aes(x = value, y = probability), color = "#6f2dbd") +
  labs(x = "Value", y = "Probability") +
  ggtitle("Plot of Prior Probabilities") + theme_bw() +
  theme(panel.grid.minor = element_line(
    color = "grey90",
    linetype = "dashed",
    linewidth = 0.5
  ))
print(p)
```

Plot of Prior Probabilities



I'm not sure that this prior is exactly reasonable for this specific situation, but it's not bad. My main issue with it is the lower probability placed on higher outcomes. For example, ρ_{20} , i.e. P(p=20/K=1) is assigned the same (zero) probability as ρ_0 , the probability of the rocket being guaranteed to fail. This symmetry in the fail probability likelihoods doesn't exactly square with our existing data (which is fine because we will calculate the posterior). However, we know some information about the history of *all* rocket launches in the past, and we could in theory use this to see if there is, in reality, a "heavier tail" for greater values of k. Also, as was discussed in lecture, it's best not to assume any of the values in the prior are exactly zero.

However, there is nuance to this problem (as in all real-world scenarios.) This prior distribution is quite conservative - i.e., it isn't placing too much potentially risky weight on the historical successes, which is *also* a sensible choice given the cost of these rockets.

Part 2

Let $\pi_k = \mathbb{P}(p = k/K|Y_{1:3} = (1,1,1))$ denote the posterior probabilities, for $k \in \{0,1,2,\ldots,K\}$. Create a vector posterior_probabilities where entry i is π_{i-1} . Plot the posterior PMF.

We can start by computing $P(Y_{1:3} = \vec{1} \mid p = \frac{k}{20})$ using the realizations vector from earlier. This probability decomposes as follows (letting $k/20 = p_{\text{obs}}$ for simplicity):

$$P(Y_{1:3} = \vec{1} \mid p = p_{\text{obs}}) = P(Y_1 = 1 \mid p = p_{\text{obs}})P(Y_2 = 1 \mid Y_1 = 1, p = p_{\text{obs}})P(Y_3 = 1 \mid Y_2 = 1, Y_1 = 1, p = p_{\text{obs}})$$

Which can simplify nicely into:

$$P(Y_{1:3} = \vec{1} \mid p = p_{\text{obs}}) = P(Y_1 = 1 \mid p = p_{\text{obs}})P(Y_2 = 1 \mid p_{\text{obs}})P(Y_3 = 1 \mid p = p_{\text{obs}})$$

Then, assuming the rocket launches are iid bern (p_{obs}) as discussed previously, with success probability p_{obs} , this can be simplified as:

$$P(Y_{1:3} = \vec{1} \mid p = p_{obs}) = (p_{obs})(p_{obs})(p_{obs}) = (p_{obs})^3$$

This is really just a long-winded way of saying we simply take the cube of our realizations vector to get the likelihood.

```
likelihood = (realizations)^3
```

Then, $\gamma(k/20)$ for $k \in \{0, 1, \dots, 20\}$ is simply the product of the prior probabilities with the likelihood.

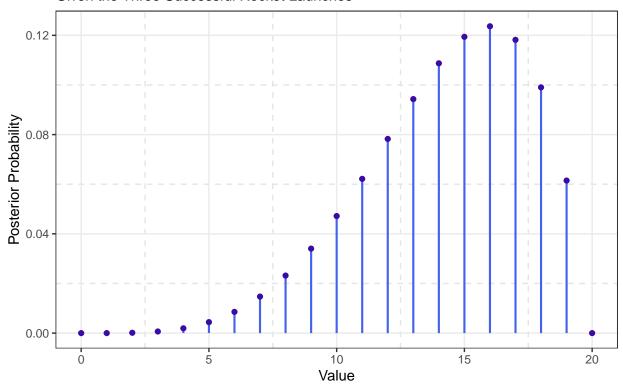
```
gamma = prior_probabilities*likelihood
```

Finally, we divide by the normalizing constant Z so the probabilities sum to 1. This gives π_k , which we calculate and plot below.

```
pi = gamma/sum(gamma)
plot_data_2 <- data.frame(</pre>
  value = 0:K,
  probability = pi
# plot posterior
p2 <- ggplot(plot_data_2, aes(x = value, y = 0, yend = probability)) +</pre>
  geom_segment(aes(xend = value), color = "#4361ee", linewidth = 0.75) +
  geom_point(aes(x = value, y = probability), color = "#3a0ca3") +
  labs(x = "Value", y = "Posterior Probability",
       title = "Plot of Posterior Probabilities",
       subtitle = "Given the Three Successful Rocket Launches") + theme_bw() +
  theme(panel.grid.minor = element_line(
    color = "grey90",
    linetype = "dashed",
    linewidth = 0.5
  ))
print(p2)
```

Plot of Posterior Probabilities

Given the Three Successful Rocket Launches



Part 3

What is the posterior mode?

By definition, we know that:

$$\mathrm{mode}\big(\pi(x)\big) = \operatorname*{argmax}_{x \in X} \big[\pi(x)\big]$$

For our prior distribution, this is found to be:

(0:K) [which.max(pi)]

[1] 16

Corresponding to k = 16, or p = 16/20.

Part 4

Write a function that compute the posterior mean of p. (Hint: you should obtain $\mathbb{E}[p|Y_{1:3}=(1,1,1)]\approx 0.7$.) We know that the posterior mean $\mathbb{E}[p|Y_{1:3}=(1,1,1)]$ can be found by calculating

$$\sum_{\{x \text{ s.t. } \pi(x) > 0\}} x \pi(x)$$

Thankfully, with our realizations and posterior distributions, we already have most of the tools at our disposal to make this calculation.

```
get_posterior_mean <- function(){
   return(sum(realizations*pi))
}
get_posterior_mean()</pre>
```

[1] 0.7124978

Question 3: Bayes Action

Let $a \in \{0,1\}$ be a binary variable denoting the decision of buying the insurance (a=1) or not (a=0)

Part 1

Based on the problem description from the Setup Section, define a loss function L(a, y) that summarizes the cost of having taken decision $a \in \{0, 1\}$ depending on whether the next launch is successful (y = 1) or not (y = 0). Hint: use indicator functions (i.e. binary functions taking either the value zero or one)

Let's first approach this problem by making a table designating potential losses based on outcomes. Here we let the numbers be in millions of dollars.

	y = 1	y = 0
a = 1	Loss of 2 . You	Loss of -100 . The
	don't get your	rocket crashes and
	insurance deposit	you get your money
	back.	back.
a = 0	Loss of 0 . You	Loss of 100. The
	spend nothing on	rocket crashes and
	insurance, and the	you were not in-
	rocket is fine.	sured.

With this in mind, we can write our loss function as follows. **NOTE** the command \mathbb{1} doesn't work in my version of latex, so I used \mathbb{I} for the indicator function instead.

$$L(a,y) = 2\mathbb{I}(a=1,y=1) + 0\mathbb{I}(a=0,y=1) - 100\mathbb{I}(a=1,y=0) + 100\mathbb{I}(a=0,y=0)$$

Which simplifies to:

$$L(a, y) = 2(\mathbb{I}(a = 1)\mathbb{I}(y = 1)) - 100(\mathbb{I}(a = 1)\mathbb{I}(y = 0)) + 100(\mathbb{I}(a = 0)\mathbb{I}(y = 0))$$