

Lab 3 - projectile motion part 1

Learning Outcomes

1. Learn how to use kinematics equations to make predictions based on a physical model.
2. Develop skills in creating and performing scientifically sound experiments that make experimental determinations and predictions of unknown quantities.
3. Use statistical methods, including mean, standard deviation of the mean, and standard error, to analyze the results of a set of measurements.

Materials and Apparatus

1. spring gun
2. "projectile"
3. carbon paper
4. plain paper
5. measuring stick
6. Computer, data interface, and photogate sensors

Safety Awareness

Be aware of your surroundings when working with the spring gun and the projectile. The projectile may move extremely fast and cause injury if it strikes someone. Make sure everyone in the vicinity of the launcher is out of the projectile path and aware of each pending launch.

Activity – Determining launch speed.

The purpose of this activity is to determine the launch speed of a projectile. This launch speed may be used for a follow-up activity.

Set-up

1. Mount the spring gun at a vertical distance h above the target that the ball will strike.
2. Set up the computer, sensors, and data interface so that you are able to record the ball's launch speed.

Acquire the Data

You will be collecting your data in two different ways.

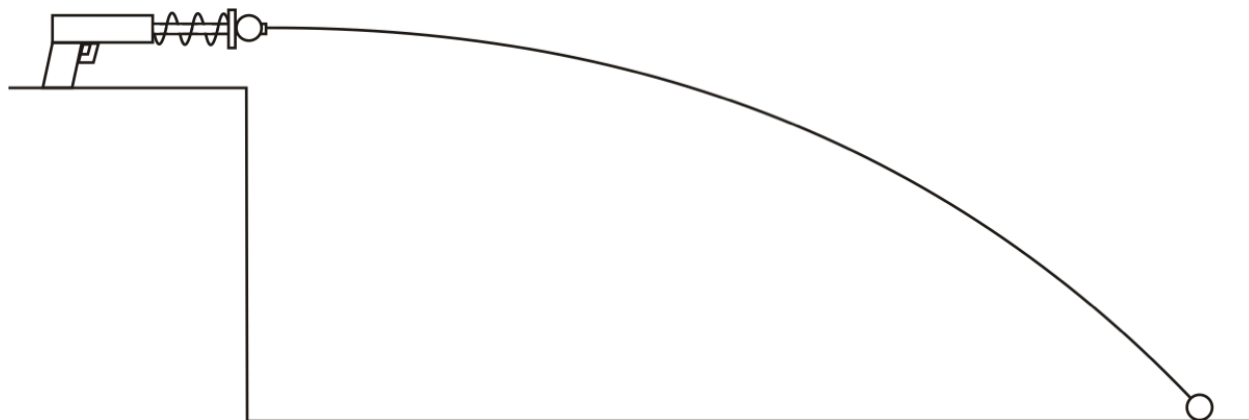
Note: Please read **Method 2** before beginning your data runs. You will need to record data for Method 2 for each shot you make.

Method 1:

Use your data interface and photogate sensors to measure the launch speed for each shot. As directed by the instructor, set up the interface so that you can use the sensor to measure the launch speed for each trial. If the software is able to allow you to measure the launch speed to a variable number of decimal places, then set it to display its data to at least four decimal places (if possible). **Record this data in a data table.**

Method 2:

To determine the launch speed of a cannonball, you will fire a cannonball horizontally from a height h and observe the ball hit the ground R meters away as measured from the base of the cannon.



Find an expression for the cannonball's launch speed v_0 in terms of h , g , and R only.

Measure and record all the data that you need in order to determine the launch speed. The minimum data you need would be one value of h and 10 values of R .

Notes:

- To measure R , you'll need to fire the ball several times and measure the horizontal distance from the launching point to where the ball hits the surface. To do this, In a trial run, fire the ball horizontally, observing the approximate location where the ball hits the surface. Then, place a sheet of carbon paper on top of a sheet of plain paper and center the two sheets on the point where the ball landed during its trial run. You will use these sheets to record and measure the location where the ball hits the surface. (Only the bottom sheet needs to be taped to the surface. DO NOT tape the carbon paper to anything.)

- Reset the gun, being careful that it is positioned in a fixed location. Fire the ball horizontally a minimum of ten times. Measure and record the horizontal distance R from the ball's launch point to where it hit the surface for each trial. Record this data in a data table.

Analysis

Please read and review the page on data analysis in module 0.

Method 1

- Report the initial launch speed, v_0 , for each individual trial with 4 decimal places.
- Use these values to calculate the ball's mean launch speed $\langle v_0 \rangle$.
- Calculate the standard deviation σ for the ball's mean launch speed. The mean plus its standard deviation gives you an estimate of the range of launch speeds for a "typical" shot. Report the estimate of the typical launch speed of a ball for any trial as $v_0 = \langle v_0 \rangle \pm 2\sigma$.

Method 2

- Using the data you collected for R and h , and your equation relating these to v_0 , calculate v_0 for each individual launch.
- Use these values to calculate the ball's mean launch speed $\langle v_0 \rangle$.
- Calculate the standard deviation σ for the ball's mean launch speed. The mean plus its standard deviation gives you an estimate of the range of launch speeds for a "typical" shot. Report the estimate of the typical launch speed of a ball for any trial as $v_0 = \langle v_0 \rangle \pm 2\sigma$.

Compare the two values of the typical launch speed of a fired ball measured with the two different methods by calculating the % difference of the averages. How close do the values match?

Why did I ask you to calculate the percent difference and not the percent error?

Is the typical launch speed calculated by Method 2 within the range of the typical launch speed calculated by Method 1? What about the typical launch speed calculated by Method 1? Is it within the range of the typical launch speed calculated for Method 2? Explain these results.

Using Method 2, compare the launch speed for each of the trials. What is the largest digit where the numbers for v_0 differ? (For example, 3.1415 and 3.1423 differ in the thousandth place.)

Using Method 1, compare the launch speed for each of the trials. What is the largest digit where the numbers for v_0 differ?

Based on your previous answers, what can you say about the precision of Method 1 vs. the precision of Method 2?

Post Lab Questions

- 1. Does a measurement with more precision mean that it's more accurate? Explain.**
- 2. Which of your two measured speeds do you trust more? Why?**

Projectile Motion – Initial Speed

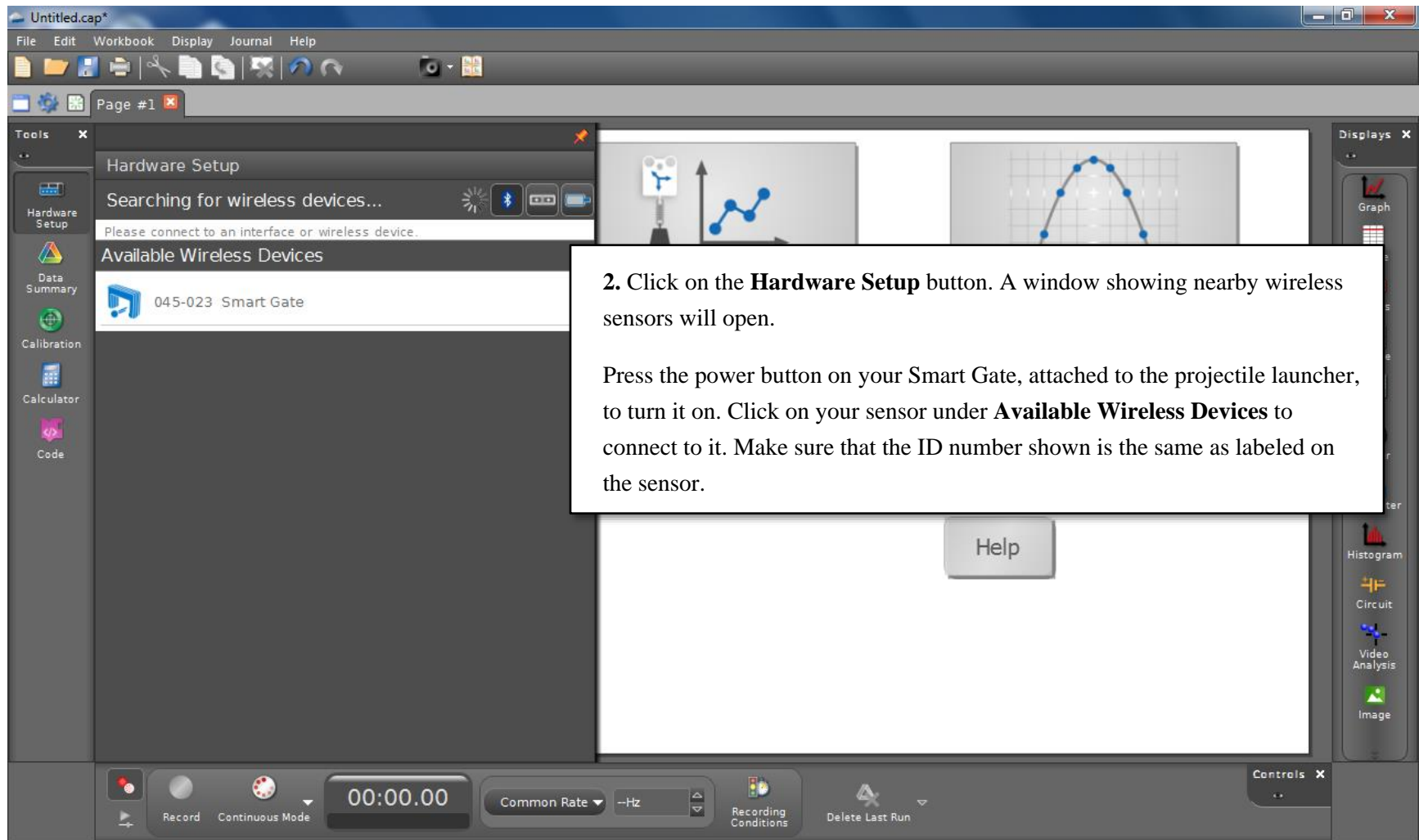
Apparatus

1. Projectile Launcher
2. Smart Gate Bracket
3. Smart Gate
4. Ramrod and Projectile
5. Table Clamp
6. Laptop with Bluetooth

The projectile launchers with the wireless Smart Gate sensors are already set up around the room. Smart Gates are wireless sensors that will be used to measure the speed of the balls launched from the projectile launchers.

Procedure

1. Make sure a Bluetooth adapter is plugged into one of the USB ports on the laptop that you are using. These are small dongles that have a piece of red tape attached to them. Boot the laptop up in Windows and open the Capstone software. A shortcut should be located on the desktop. If the software comes up with a window prompting you to install an update, click on the **Remind Me Later** button.



Untitled.cap*

File Edit Workbook Display Journal Help

Page #1

Tools

Hardware Setup

Searching for wireless devices...

Wireless Smart Gate
045-023 Smart Gate

1 2
3 4

Smart Gate (Single Flag)

Sensor Data

Graph Equation

Help

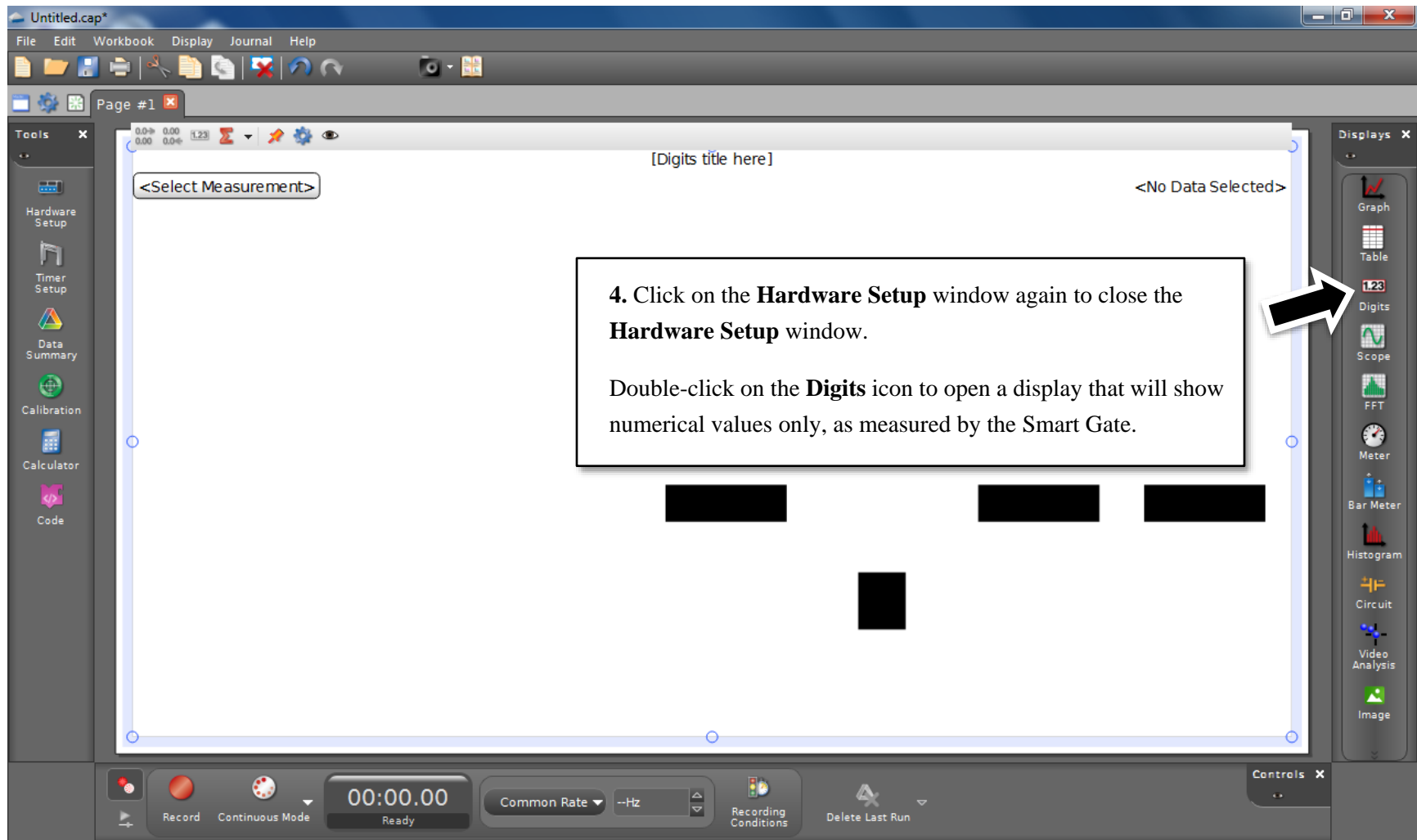
Displays

Graph
Table
Digits
Scope
FFT
Meter
Bar Meter
Histogram
Circuit
Video Analysis
Image

Record Continuous Mode 00:00.00 Ready Common Rate --Hz Recording Conditions Delete Last Run Controls

3. After connecting to your Smart Gate, a picture of the sensor will appear in **Hardware Setup**. Make sure that it is set to **Single Flag** mode.

The screenshot shows a software interface with a menu bar (File, Edit, Workbook, Display, Journal, Help) and a toolbar. The main window is titled 'Untitled.cap*'. On the left, there is a 'Tools' sidebar with icons for Hardware Setup, Timer Setup, Data Summary, Calibration, Calculator, and Code. The 'Hardware Setup' window is open, displaying 'Searching for wireless devices...' and a list of detected devices. The first device is 'Wireless Smart Gate' with ID '045-023 Smart Gate'. Below the list is a picture of the Smart Gate device with numbered ports (1, 2, 3, 4). At the bottom of the list, there is a 'Smart Gate (Single Flag)' entry with a small icon and a gear icon. A callout box with a black arrow points to the gear icon, containing the text: '3. After connecting to your Smart Gate, a picture of the sensor will appear in **Hardware Setup**. Make sure that it is set to **Single Flag** mode.' The main workspace shows two graphs: 'Sensor Data' and 'Graph Equation'. The 'Displays' sidebar on the right contains various display options like Graph, Table, Digits, Scope, FFT, Meter, Bar Meter, Histogram, Circuit, Video Analysis, and Image. The bottom status bar includes buttons for Record, Continuous Mode, a timer (00:00.00), Ready, Common Rate, --Hz, Recording Conditions, and Delete Last Run.



Untitled.cap*

File Edit Workbook Display Journal Help

Page #1

Tools

- Hardware Setup
- Timer Setup
- Data Summary
- Calibration
- Calculator
- Code

[Digits title here]

<Select Measurement>

- Rename
- Smart Gate (Single Flag)
- Speed Between Gates (m/s)
- Velocity Between Gates (m/s)
- Equations/Constants
- Constants
- Time
 - Time (s)
 - Date and Time

<No Data Selected>

Displays

- Graph
- Table
- Digits
- Scope
- FFT
- Meter
- Bar Meter
- Histogram
- Circuit
- Video Analysis
- Image

00:00.00 Ready

Common Rate --Hz

Recording Conditions

Delete Last Run

Controls

5. Click on <Select Measurement> and select **Speed Between Gates (m/s)** below Smart Gate from the menu. The software is now configured to measure the *speed* of the projectile, after being launched, as it passes through the Smart Gate sensor.

Untitled.cap*

File Edit Workbook Display Journal Help

Page #1

Tools

Hardware Setup
Timer Setup
Data Summary
Calibration
Calculator
Code

Speed, Acceleration (m/s)

[Digits title here]

<No Data Selected>

6. Click on the green arrow icon twice to increase the number of significant figures that will be displayed by the software.

-----m/s

Displays

Graph
Table
Digits
Scope
FFT
Meter
Bar Meter
Histogram
Circuit
Video Analysis
Image

Record Continuous Mode 00:00.00 Ready Common Rate --Hz Recording Conditions Delete Last Run Controls

Untitled.cap*

File Edit Workbook Display Journal Help

Page #1

Tools

Hardware Setup
Timer Setup
Data Summary
Calibration
Calculator
Code

Speed Between Gates (m/s)

[Digits title here]

<No Data Selected>

Displays

Graph
Table
Digits
Scope
FFT
Meter
Bar Meter
Histogram
Circuit
Video Analysis
Image

7. Using the protractor on the side of the launcher, set it so that the plumb bob is at an angle of 0° . Load the ball into the launcher using the ramrod. Press down on the spring to one of the three range settings. Make sure to use the same setting for each launch.

Click on the **Record** button after loading the launcher. When the yellow cord is pulled, the projectile will launch, and the software will display a value for the initial speed of the ball.

00:00.00 Common Rate --Hz Recording Conditions Delete Last Run

Begin recording all measurements from each connected sensor

m/s

Error Analysis Formulas

<i>Error Analysis of Single Measurements</i>	
<i>name</i>	<i>formula</i>
<i>best estimate, x_{best}</i>	<i>Determined by estimating the measurement to the nearest reliable value.</i>
<i>reporting a measured value</i>	<i>(measured value of x)</i> $= x_{best} \pm \sigma_{absolute}$
<i>absolute uncertainty in a single measurement</i>	$\sigma_{absolute} = \pm 0.5 \times (\text{smallest unit of measure})$
<i>fractional uncertainty</i>	$\sigma_{fractional} = \frac{\sigma_{absolute}}{ x_{best} }$
<i>percent uncertainty</i>	$\sigma_{percent} = \frac{\sigma_{absolute}}{ x_{best} } \cdot 100\%$
<i>reported value of measurement, x</i>	$x = x_{best} \pm \sigma_x$
<i>reported value of measurement, y</i>	$y = y_{best} \pm \sigma_y$
<i>sum and difference rule</i>	$x \pm y = (x_{best} \pm y_{best}) \pm (\sigma_x + \sigma_y)$
<i>product rule</i>	$xy = (x_{best}y_{best}) \pm \left(\frac{\sigma_x}{ x_{best} } + \frac{\sigma_y}{ y_{best} } \right) \times 100\%$
<i>power rule</i>	$x^n = x_{best}^n \pm n \left(\frac{\sigma_x}{ x_{best} } \times 100\% \right)$
<i>percent error</i>	$\% \text{ error} = \frac{ \text{measured value} - \text{accepted value} }{\text{accepted value}} \times 100\%$
<i>percent difference</i>	$\% \text{ difference} = \frac{ \text{measured value 1} - \text{measured value 2} }{\left(\frac{\text{measured value 1} + \text{measured value 2}}{2} \right)} \times 100\%$

Error Analysis of Statistical Samples													
name	formula												
best estimate, x_{best}	$x_{best} = x_{average} = \langle x_i \rangle \equiv \frac{\sum_{i=1}^N x_i}{N}$												
standard deviation, uncertainty for a set of N measurements of a single quantity	$\sigma_x = \sqrt{\frac{1}{N-1} \sum_{i=1}^N (x - \langle x_i \rangle)^2}$												
best estimate, x	$x_{best} = x_{average}$												
best estimate, y	$y_{best} = y_{average}$												
sum and difference	$x \pm y = (x_{best} \pm y_{best}) \pm \sigma_{xy}$												
uncertainty, sum and difference	$\sigma_{xy} = \sqrt{\sigma_x^2 + \sigma_y^2}$												
product	$xy = (x_{best} y_{best}) \pm \sigma_{xy}$												
product rule, uncertainty	$\sigma_{xy} = \sqrt{\left(\frac{\sigma_x}{x_{best}}\right)^2 + \left(\frac{\sigma_y}{y_{best}}\right)^2}$												
confidence intervals	<table><tr><th>range</th><th>confidence interval</th></tr><tr><td>1σ</td><td>0.6826895</td></tr><tr><td>2σ</td><td>0.9544997</td></tr><tr><td>3σ</td><td>0.9973002</td></tr><tr><td>4σ</td><td>0.9999366</td></tr><tr><td>5σ</td><td>0.9999994</td></tr></table>	range	confidence interval	1σ	0.6826895	2σ	0.9544997	3σ	0.9973002	4σ	0.9999366	5σ	0.9999994
	range	confidence interval											
	1σ	0.6826895											
	2σ	0.9544997											
	3σ	0.9973002											
	4σ	0.9999366											
5σ	0.9999994												