In the lab we analyzed filtering 60 Hz power-line noise from ECG signal using a digital (signal processing) filter. Now let's try to an analog (circuit) filter approach to remove the 60 Hz line-noise. Following is an active twin-T notch filter with transfer function:

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H(\omega) = \frac{Z(\omega)}{X(\omega)} = \frac{(1+m)((2/\omega RC)^2+1)}{(2/\omega RC)^2+4(1-m)/\omega RC+1} Here m is the ratio of the two feedback resistance which determines the gain and quality for the filter. The drop frequency of this twin-T notch filter is f_{stars} = 1/4 RMS. For designing a 60 Hz drop filter, let's use R=10 k\Omega and C=133 nF. (a) For m={0.8, 0.9} plot the magnitude and phase response of H (\omega) with a range
```

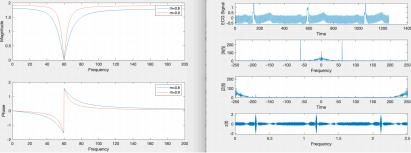
(b) Consider the ECG signal used during the class (ecg_signal.mat) as the input (x(t)=ecg) of a 60 Hz twin-T notch filter with m=0.9. Using the functions fftt() and ifft(), determine the $X(\omega)$, $Z(\omega)$, and Z(t)[Z(t) is the output signal from the twin-T notch filter]. Plot X(t), X(t), Z(t), and Z(t) in a 4x1 subplot for the range of $-250 \le f \le 250$ and $0 \le f \le 2.5$. [Please pay attention to the proper use of fftshift() and ifftshift() while solving this problem.]

Summarv:

of $f = \omega/2\pi = [0, 200 \text{ Hz}]$.

We define H(w) as above for m = 0.8 and 0.9. We plot the phase and magnitude of each. We then plot the ecg signal x(t) and X(f), Z(f), and z(t) using fft().

Results:



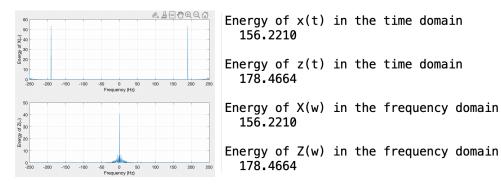
```
Code:
R = 10000; % define variables and ranges
C = 133e-9;
F = linspace(0, 200, 1000);
W = 2*pi*F;
M = 0.8;
H1 = ((1+M).*((2*1j*W*R*C).^2+1))./((2*1j*W*R*C).^2+(4*(1-M).*(1j*W*R*C))+1); % h for m = 0.8
M = 0.9;
 H2 = ((1+M).*((2*1j*W*R*C).^2+1))./((2*1j*W*R*C).^2+(4*(1-M).*(1j*W*R*C))+1); % \ h \ for \ m = 0.9 
subplot(2, 1, 1)
plot(F, abs(H1), 'DisplayName', 'm=0.8') % plot magnitude for m = 0.8
hold on:
plot(F, abs(H2), 'DisplayName', 'm=0.9') % plot magnitude for m = 0.9
legend show;
ylabel('Magnitude')
xlabel('Frequency')
subplot(2, 1, 2)
plot(F, angle(H1), 'DisplayName', 'm=0.8') % plot phase for m = 0.8
hold on:
plot(F, angle(H2), 'DisplayName', 'm=0.9') % plot phase for m = 0.9
legend show;
ylabel('Phase')
xlabel('Frequency')
load ecg_signal.mat; % load for part B
F = linspace(-250, 250, length(ecg)); % define new variables
W=2*pi*F;
H = ((1+M).*((2*1j*W*R*C).^2+1))./((2*1j*W*R*C).^2+(4*(1-M).*(1j*W*R*C))+1);
figure;
subplot(4, 1, 1)
plot(ecg) % plot ecg signal
ylabel('ECG Signal')
xlabel('Time')
subplot(4, 1, 2)
plot(F, abs(fftshift(fft(ecg)))); % plot magnitude of X(f)
ylabel('|X(f)|')
xlabel('Frequency')
subplot(4, 1, 3)
plot(F, abs(fftshift(fftshift(ecg)).*H))) % plot magnitude of <math>Z(f)
ylabel('|Z(f)|')
xlabel('Time')
subplot(4, 1, 4)
plot(t, real(ifft(fftshift(fft(ecg)).*H))) % plot z(t)
vlabel('z(t)')
xlabel('Frequency')
```

2. Calculate the energy of time domain signal x(t) and z(t) for the range of $0 \le t \le 2.5$. Also calculate the energy of these signals in frequency domain using Parseval's theorem. Plot Energy(X) and Energy(Z) as a function of frequency f in a 2x1 subplot (Energy vs frequency plot is known as energy spectrum of a signal).

Summary:

We define H as in problem 1, X using fft(ecg), and Z using fft(X).*H. We calculate the energies of x and z in the time and frequency domains and print. We then plot Energy vs frequency for Z(w) and X(w).

Results:



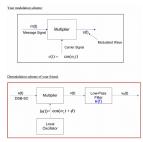
Code:

```
load ecg signal.mat;
R = 10000; % define constants
C = 133e-9;
M = 0.9;
F = linspace(-250, 250, length(ecg)); % define range
W = 2 * pi * F;
 \label{eq:hamiltonian} \texttt{H} = ((1 + \texttt{M}).*((2*1j*W*R*C).^2+1))./((2*1j*W*R*C).^2+(4*(1-\texttt{M}).*(1j*W*R*C))+1); \; \% \; \texttt{calc freq} 
response
X = fft(ecg); % time domain output signal
Z = fftshift(X).*H; % filtered signal Z(f)
z = ifft(Z);
energyx = sum(abs(ecg).^2); % calc energies
energyz = sum(abs(z).^2);
disp("Energy of x(t) in the time domain");
disp(energyx);
disp("Energy of z(t) in the time domain");
disp(energyz);
frequencyEnergyX = sum(abs(X).^2)/length(X);
disp("Energy of X(w) in the frequency domain")
disp(frequencyEnergyX);
frequencyEnergyZ = sum(abs(Z).^2)/length(Z);
disp("Energy of Z(w) in the frequency domain");
disp(frequencyEnergyZ);
frequencyEX = (abs(X).^2)/length(X); % array of the values computed for the energy
frequencyEZ = (abs(Z).^2)/length(Z);
figure(1); % plot energy spectrums
subplot(2,1,1);
plot(F, frequencyEX);
xlabel("Frequency (Hz)")
ylabel("Energy of X(\omega)");
grid on:
subplot(2,1,2);
plot(F, frequencyEZ);
xlabel("Frequency (Hz)")
ylabel("Energy of Z(\omega)")
grid on;
```

3. Let's say you are using a Double-Sideband Suppressed Carrier Modulation (DSB-SC) scheme to transmit a message $m=\{6\ 0\ 4\ -6\ 2\}$ to your friend at San Jose over a communication channel that has good transmission characteristics in the frequency range of 400 kHz to 600 kHz. You decided to modulate your message with carrier signal $c(t)\!=\!\cos(1000\times10^3\pi t)$ and encode your message m(t) at 1/10 of the carrier frequency (i.e. 50 kHz). Your friend received the signal you transmitted and demodulated it by multiplying with a local oscillator signal $10(t)\!=\!\cos(1000\times10^3\pi t\!+\!\pi/3)$ and then passing the signal through a low-pass filter with transfer function H(t) where:

$$H(f) = \begin{cases} 2_r |f| < 500 \times 10^3 \text{ Hz} \\ 0_r \text{ elsewhere} \end{cases}$$

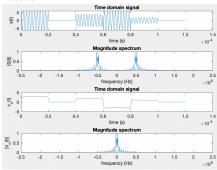
In a 4x1 subplot show the time domain signal transmitted s(t), frequency domain magnitude of the transmitted signal |S(t)|, time domain demodulated and low-pass filtered output signal vo(t) and corresponding frequency domain spectrum |Vo(t)|.



Summary:

We define the above constants, signals, and functions. We plot s(t) and its magnitude spectrum and v o(t) and its magnitude spectrum.

Results:



Code:

```
mFrequency = 5e4; % define the constants and the signals
cFrequency = 5e5;
cTime = 1/10/cFrequency; % Sampling period with 10 samples per
time = 0:cTime:6/mFrequency; % Time vector
message = [6, 0, 4, -6, 2];
mArray = zeros(size(time)); % array for the message signal values
intervals = (0:length(message))/mFrequency;% generate the message signal
for i = 1:length(message) % loop each interval assigning corresponding char
  mArray((time >= intervals(i)) & (time < intervals(i+1))) = message(i);</pre>
end
s = mArray.*cos(2*pi*cFrequency*time); % define the DSB-SC signal
v = s.*cos(2*pi*cFrequency*time+pi/3); % define the Demodulated signal
freq = (-(N-1)/2:N/2)*1/cTime/N; % frequency axis for the fast fourier transform function
fftv = zeros(size(v)); % Performing the low-pass filtering
fftw = fftshift(fft(v));
for i = 1:length(freq)
  if(abs(freq(i))<5e5)</pre>
      fftv(i) = 2*fftw(i); % passing low pass frequencies
  end
end
v_out = ifft(ifftshift(fftv));
subplot(4, 1, 1); % plot signals and spectrums
plot(time, s);
xlabel('time (s)');
ylabel('s(t)');
title('Time domain signal');
subplot(4, 1, 2);
plot(freq, fftshift(abs(fft(s)))/N);
xlabel('frequency (Hz)');
ylabel('|S(f)|');
title('Magnitude spectrum');
subplot(4, 1, 3);
plot(time, v_out);
xlabel('time (s)');
ylabel('v o(t)');
title('Time domain signal');
subplot(4, 1, 4);
plot(freq, fftshift(abs(fft(v_out)))/N);
xlabel('frequency (Hz)');
ylabel('|V_o(f)|');
title('Magnitude spectrum');
```