

# Optimization Problems

LING 572

Advanced Statistical Methods for NLP

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# What is an optimization problem?

- The problem of finding the best solution from all feasible solutions.
- Given a function  $f: X \rightarrow \mathbb{R}$ , find  $x_0$  in  $X$  that optimizes  $f(x)$ .
- $f$  is called
  - an objective function,
  - a loss function or cost function (minimization), or
  - a utility function or fitness function (maximization), etc.
- $X$  is a  $n$ -variable vector:
  - discrete (possible values are countable): combinatorial optimization problem
  - continuous: e.g., constrained problems

# Components of each optimization problem

- Decision variables  $X$ : describe our choices that are under our control.
  - We normally use  $n$  to represent the number of decision variables, and  $x_i$  to represent the  $i$ -th decision variable.
- Objective function  $f$ : the function we wish to optimize
- Constraints: describe the limitations that restrict our choice for decision variables.

# Standard form of a continuous optimization problem

$$\begin{array}{ll}\underset{x}{\text{minimize}} & f(x) \\ \text{subject to} & g_i(x) \leq 0, \quad i = 1, \dots, m \\ & h_i(x) = 0, \quad i = 1, \dots, p\end{array}$$

re

$f(x) : \mathbb{R}^n \rightarrow \mathbb{R}$  is the objective function to be minimized over the  $n$ -variable vector  $x$ ,

$g_i(x) \leq 0$  are called inequality constraints, and

$h_i(x) = 0$  are called equality constraints.

By convention, the standard form defines a minimization problem. A maximization problem can be treated by negating the objective function.

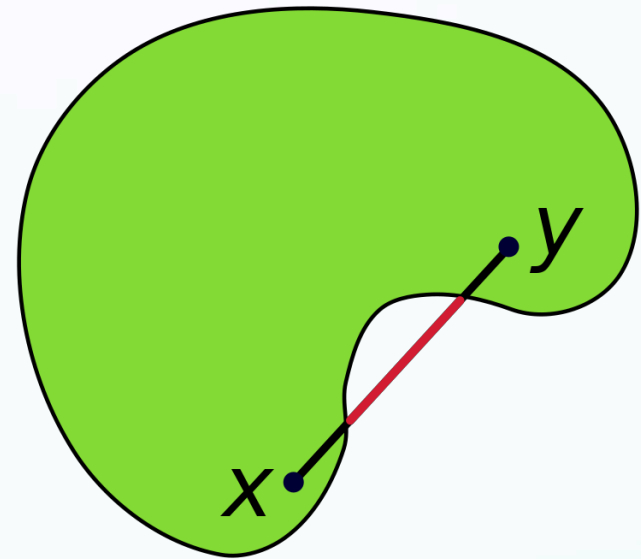
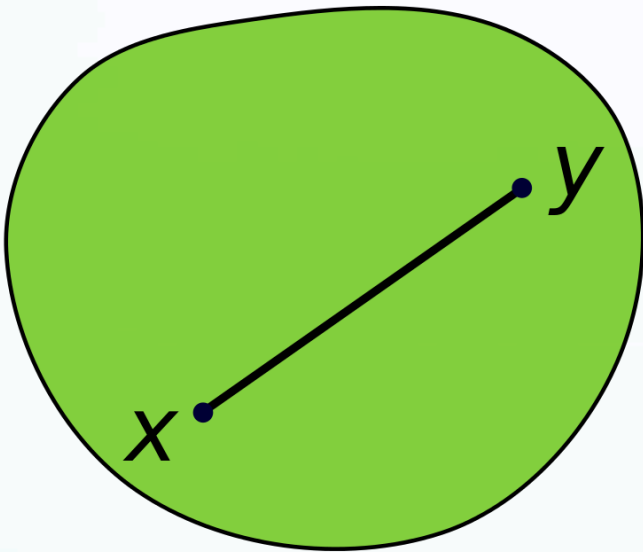
# Common types of optimization problem

- Linear programming (LP) problems:
  - Definition: Both objective function and constraints are linear
  - The problems can be solved in polynomial time.
  - [https://en.wikipedia.org/wiki/Linear\\_programming](https://en.wikipedia.org/wiki/Linear_programming)
- Integer linear programming (ILP) problems:
  - Definition: LP problem in which some or all of the variables are restricted to be integers
  - Often, solving ILP problem is NP-hard.
  - [https://en.wikipedia.org/wiki/Integer\\_programming](https://en.wikipedia.org/wiki/Integer_programming)

# Common types of optimization problem (cont'd)

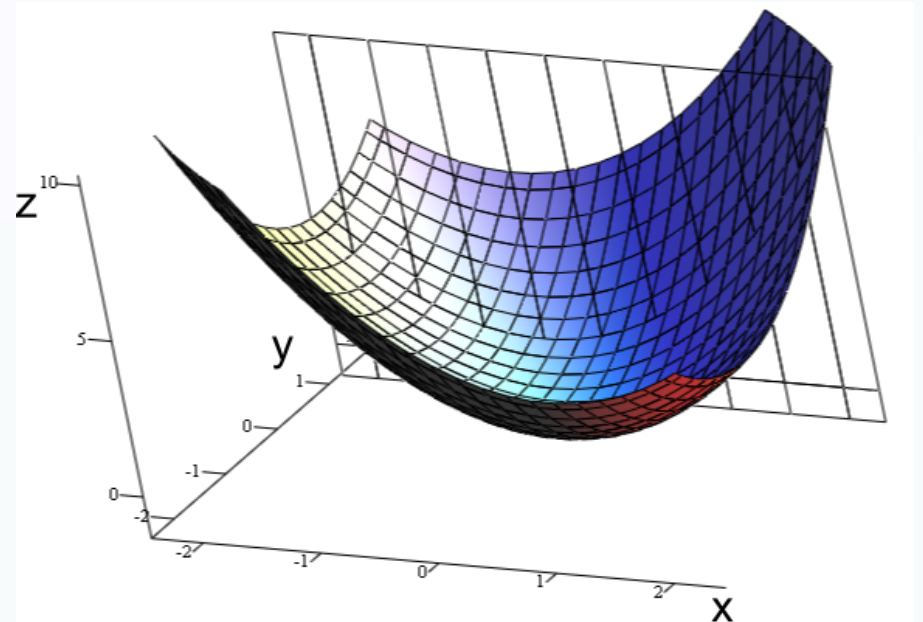
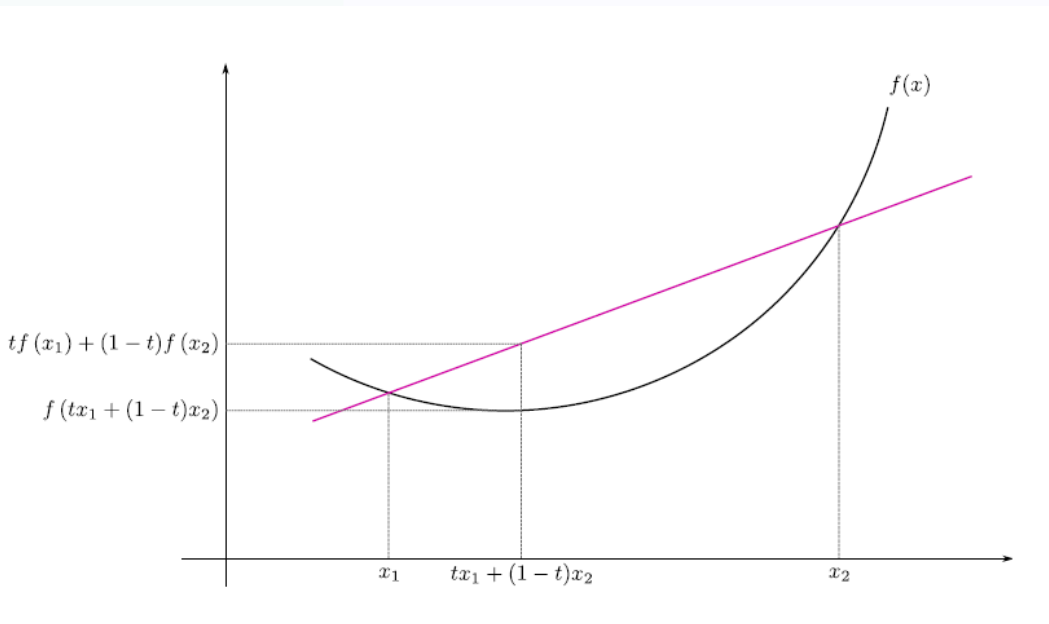
- Quadratic programming (QP):
  - Definition: The objective function is quadratic, and the constraints are linear
  - Solving QP problems is simple under certain conditions
  - [https://en.wikipedia.org/wiki/Quadratic\\_programming](https://en.wikipedia.org/wiki/Quadratic_programming)
- Convex optimization:
  - Definition:  $f(x)$  is a convex function, and  $X$  is a convex set.
  - Property: if a local minimum exists, then it is a global minimum.
  - [https://en.wikipedia.org/wiki/Convex\\_optimization](https://en.wikipedia.org/wiki/Convex_optimization)

# Convex set



A **set**  $C$  is said to be **convex** if, for all  $x$  and  $y$  in  $C$  and all  $t$  in the **interval**  $(0, 1)$ , the point  $(1 - t)x + ty$  also belongs to  $C$

# Convex function



Let  $X$  be a convex set in a real vector space and let  $f : X \rightarrow \mathbb{R}$  be a function.

- $f$  is called **convex** if:

$$\forall x_1, x_2 \in X, \forall t \in [0, 1] : \quad f(tx_1 + (1-t)x_2) \leq tf(x_1) + (1-t)f(x_2).$$

- $f$  is called **strictly convex** if:

$$\forall x_1 \neq x_2 \in X, \forall t \in (0, 1) : \quad f(tx_1 + (1-t)x_2) < tf(x_1) + (1-t)f(x_2).$$



# Terms

- A solution is the assignment of values to all the decision variables
- A solution is called feasible if it satisfies all the constraints.
- The set of all the feasible solutions forms a feasible region.
- A feasible solution is called optimal if  $f(x)$  attains the optimal value at the solution.

- If a problem has no feasible solution, the problem itself is called infeasible.
- If the value of the objective function can be infinitely large, the problem is called unbounded.

# Linear programming

# Linear Programming

- The linear programming method was first developed by Leonid Kantorovich in late 1930s.
- Main applications: diet problem, supply problem
- A primary method for solving LP is the simplex method.
- LP problems can be solved in polynomial time.

# An example

Suppose that a farmer has a piece of farm land, say  $L$  km<sup>2</sup>, to be planted with either wheat or barley or some combination of the two. The farmer has a limited amount of fertilizer,  $F$  kilograms, and pesticide,  $P$  kilograms. Every square kilometer of wheat requires  $F_1$  kilograms of fertilizer and  $P_1$  kilograms of pesticide, while every square kilometer of barley requires  $F_2$  kilograms of fertilizer and  $P_2$  kilograms of pesticide. Let  $S_1$  be the selling price of wheat per square kilometer, and  $S_2$  the selling price of barley. If we denote the area of land planted with wheat and barley by  $x_1$  and  $x_2$  respectively, then profit can be maximized by choosing optimal values for  $x_1$  and  $x_2$ . This problem can be expressed with the following linear programming problem in the standard form:

$$\begin{aligned} \text{Maximize: } & S_1 \cdot x_1 + S_2 \cdot x_2 && \text{(maximize the revenue—revenue is the "objective function")} \\ \text{Subject to: } & x_1 + x_2 \leq L && \text{(limit on total area)} \\ & F_1 \cdot x_1 + F_2 \cdot x_2 \leq F && \text{(limit on fertilizer)} \\ & P_1 \cdot x_1 + P_2 \cdot x_2 \leq P && \text{(limit on pesticide)} \\ & x_1 \geq 0, x_2 \geq 0 && \text{(cannot plant a negative area).} \end{aligned}$$

# Property of LP

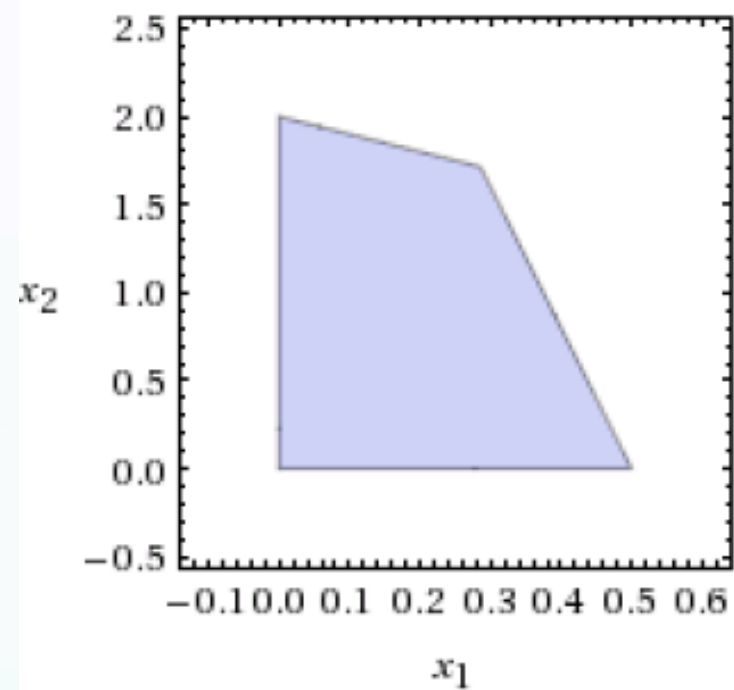
- The feasible region is convex
- If the feasible region is non-empty and bounded, then
  - optimal solutions exist, and
  - there is an optimal solution that is a corner point
    - ➔ We only need to check the corner points
- The most well-known method is called the simplex method.

maximize  $z = x_1 - 3x_2$

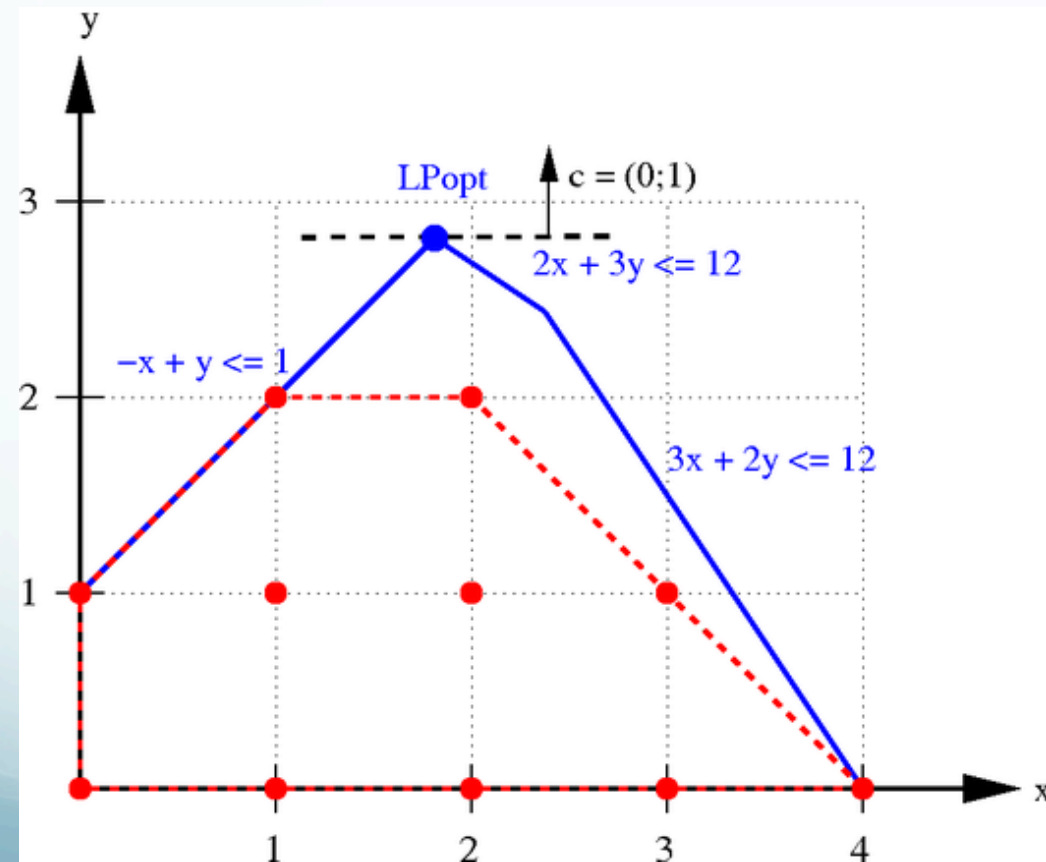
subject to  $x_1 + x_2 \leq 2$

$8x_1 + x_2 \leq 4$

$x_1, x_2 \geq 0$



# Feasible region and simplex method



Simplex method:

- Start with a feasible solution, move to another one to increase  $f(x)$



# Integer linear programming

# Integer programming

- IP is an active research area and there are still many unsolved problems.
- IP is more difficult to solve than LP.
- Methods:
  - Branch and Bound
  - Use LP relaxation

<b>Tournament</b>	<b>Assigned Number (<i>i</i>)</b>	<b>Chance of bidding (<i>c</i>)<sup>1</sup></b>	<b>Cost (<i>m</i>)<sup>2</sup></b>	<b>Time needed (<i>t</i>)<sup>3</sup></b>	<b>Date<sup>4</sup></b>
Greenhill	1	0.4	\$500	3	9/20-9/21
Yale	2	0.3	\$700	4	9/19-9/21
Valley	3	0.5	\$500	3	9/27-9/29
Cypress Bay*	4	0.4	\$600	4	10/10-10/12
Presentation	5	0.5	\$350	3	10/11-10/13
Bronx Science	6	0.3	\$600	3	10/17-10/19
St. Mark's	7	0.5	\$500	3	10/18-10/20
Meadows	8	0.6	\$450	4	10/31-11/2
Apple Valley*	9	0.3	\$300	2	11/7-11/8
Glenbrooks*	10	0.5	\$400	3	11/22-11/24
Alta*	11	0.4	\$500	4	12/4-12/6
Blake	12	0.5	\$450	4	12/19-12/21
College Prep	13	0.4	\$350	3	12/20-12/21
Harvard Westlake	14	0.5	\$400	3	1/3-1/5
Sunvitational	15	0.3	\$600	3	1/11-1/12
Lexington	16	0.4	\$500	3	1/17-1/18
Emory	17	0.5	\$600	4	1/23-1/25
Stanford	18	0.6	\$350	4	2/7-2/9
Berkeley	19	0.4	\$350	3	2/14-2/16
Harvard	20	0.5	\$500	4	2/14-2/16

Decision variables:  $x_i = \begin{cases} 1 & \text{if decided to compete at the } i^{\text{th}} \text{ tournament} \\ 0 & \text{otherwise} \end{cases}$

Objective function: 
$$Z = \sum_{i=1}^n c_i x_i$$

Constraints: 
$$\sum_{i=1}^n m_i x_i \leq M$$
$$\sum_{i=1}^n t_i x_i \leq T$$

$$x_1 + x_2, x_4 + x_5, x_6 + x_7, x_{12} + x_{13}, x_{19} + x_{20} \leq 1$$

$$\text{maximize } z = \sum_{i=1}^n c_i x_i$$

$$\text{subject to } \sum_{i=1}^n m_i x_i \leq M$$

$$\sum_{i=1}^n t_i x_i \leq T$$

$$0 \leq x_i \leq 1 \text{ for every } i$$

$$x_i \text{ is an integer for every } i$$

$$x_1 + x_2 \leq 1$$

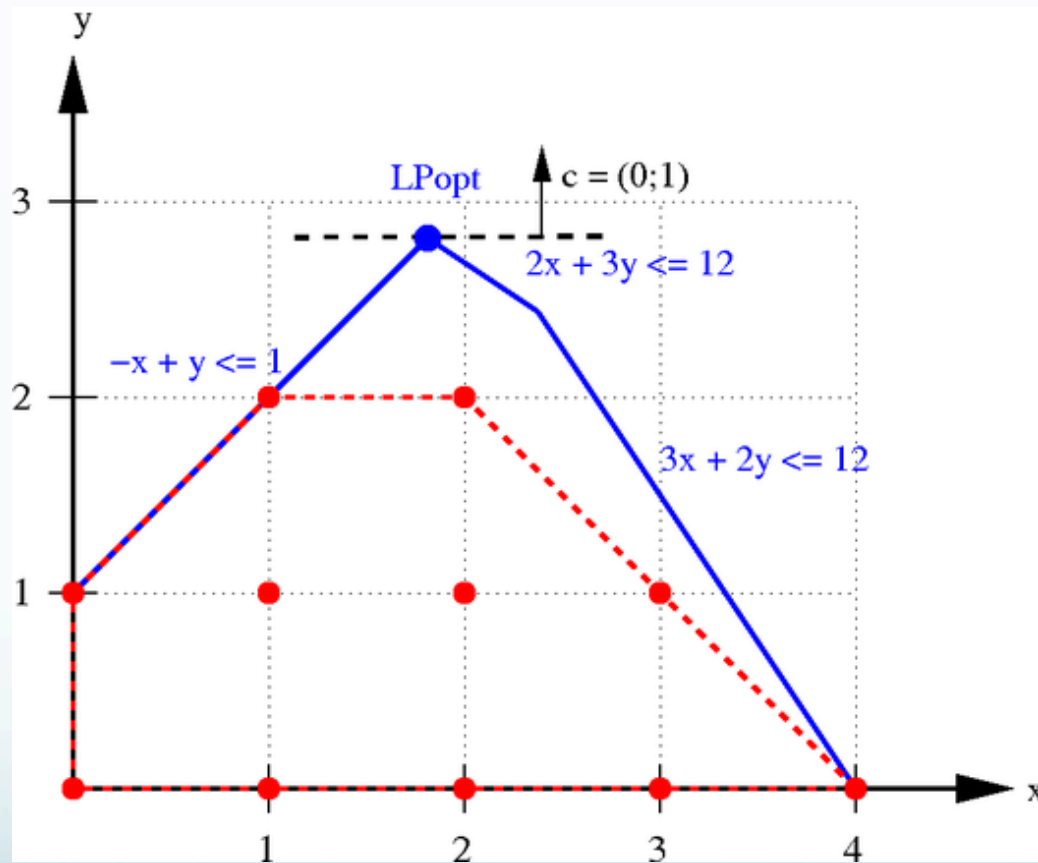
$$x_4 + x_5 \leq 1$$

$$x_6 + x_7 \leq 1$$

$$x_{12} + x_{13} \leq 1$$

$$x_{19} + x_{20} \leq 1$$

# LP vs. ILP



# Summary

- Optimization problems have many real-life applications.
- Common types: LP, IP, ILP, QP, Convex optimization problem
- LP is easy to solve; the most well-known method is the simplex method.
- IP is hard to resolve.
- QP and Convex optimization are used the most in our field.