Joey Carpinelli | Technical Résumé

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Professional Experience

GN&C Engineer @ NASA Johnson Space Center (JSC) *July 2021 — Present*
- Supports Orion's Launch Abort System GN&C development, analysis, and verification
- Reduced, analyzed, and implemented flexible body (structure) model (MATLAB, C++)
- Uses monte-carlo simulations for parameter tuning; improved vehicle performance noticeably
- Uses linear analysis to analyze vehicle performance, verify stability margins; validates linear models
- Serves as backup regression data approver for simulated Orion Launch Abort System performance
- Led development for polarity tests; created novel 6DOF kinematics simulation (Julia, Python); represented Orion GN&C at multiple lab tests in three states: Texas, Colorado, Florida

Research Assistant @ Space Systems Laboratory (SSL) *August 2019 — May 2021*
- Graduate Assistant under Dr. Dave Akin; led manipulator software development (C++)
- Developed novel Julia package to generate symbolic manipulator kinematics models; implemented and merged required changes to `ModelingToolkit.jl`; intermediate Jacobian performance substantially improved over Orocos iterative solvers; implemented fast inverse-kinematics algorithm
- Created C++ templates, and controller implementations, including force/torque and Cartesian control
- Maintained operator GUI for all manipulators; primary operator for neutral-buoyancy testing
- Maintained neutral buoyance facility as diver; received open water certification in 2017

Inertial & Viscous Friction Compensation Project *January 2017 — August 2017*
- Independent study to implement Dr. Carignan's inertial and viscous friction compensation for Maryland-Georgetown-Army (MGA) exoskeleton within SSL; used Galil, Python, ROS, UART

Intern @ Harris Corporation *May 2016 — August 2016*
- Automated Excel task with VBA; 20 worker hours → 2 minute runtime
- Worked with one other intern to implement rain attenuation ITU Propagation Model; MATLAB functions written to implement model calculations, C# used to gather terrain data

Intern @ SRI International *May 2015 — December 2015*
- Collected and annotated data to train deep-learning algorithms; improved process with scripting
- Designed LED Array and circuit layouts for gaze tracking project using Eagle CAD

Education

M.S. in Aerospace Engineering @ University of Maryland
- Research assistant under Dr. Akin; space robotics (manipulator) software lead, primary operator
- Halo orbit & invariant-manifold research project with Professor Barbee; released as open source tools
- Emphasis in space systems, prioritized dynamics & controls in coursework

B.S. in Electrical Engineering @ University of Maryland
- Emphasis in control theory, prioritized software in coursework through four computer science classes
- Undergraduate Research Assistant under Dr. Akin at SSL; manipulator software lead as junior

Technical Skills

Computer Programming
- Productive in C++, used for robotic manipulator control software
- Experienced with Julia, used for astrodynamics research; hobbyist FOSS
- Experienced with Python, used for post-simulation analysis & scripting at NASA JSC; hobbyist FOSS

Circuit Design
- Undergraduate digital & analog lab experience, including Verilog, SPICE, PSpice, Xilinx, oscilloscopes
- Internship experience using Eagle CAD to design PCB for gaze-tracking project

Modeling & Simulation
- Experienced with linear model reduction, linear analysis, and nonlinear analysis methods

FOSS Projects

`SolarSystemSurrogates.jl`
An experiment that I'm excited about. This package will provide surrogate models for solar system ephemeris data. Fingers crossed!

`AstrodynamicalModels.jl`
Model generation — with optional state transition matrix dynamics — through `ModelingToolkit.jl`.

`GeneralAstrodynamics.jl`
General calculations, visualizations, iterative & analytical periodic orbit solvers, and orbit-manifold solvers.

`HorizonsAPI.jl`
A word-for-word wrapper for the JPL Horizons REST API. Fetch solar system ephemeris for free!

`HorizonsEphemeris.jl`
A user-friendly wrapper around the word-for-word wrapper for the JPL Horizons REST API.

`PolynomialGTM.jl`
Implements publicly available polynomial models for NASA's Generic Transport Model using `ModelingToolkit.jl`.

`module-hygiene`
Provides an `__export__` key, and an associated `cleanup` function to reduce namespace clutter.

`block-scopes`
Provides a single context manager, `only`, which creates block-style copes within Python. This package isn't unique — it's just for fun!

`rich-admonitions`
Extends the excellent terminal formatting package `rich` with Julia-style Markdown admonition blocks!

Social Media

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