

# Joey Carpinelli | Technical Portfolio



+1 202.660.2578



joey@carpinelli.email

## Professional Experience

### GN&C Engineer @ NASA Johnson Space Center (JSC)

July 2021 — Present

- Supports Orion's Launch Abort System development, analysis, and verification
- Reduced, analyzed, and implemented flexible structure model (MATLAB, C++)
- Uses monte-carlo simulations for parameter tuning; improved performance
- Uses linear analysis to analyze vehicle performance, verify stability margins
- Serves as backup regression data approver for Orion Launch Abort System
- Led development for polarity tests through novel kinematics simulation (Julia, Python); represented Orion GN&C at multiple lab tests

### Research Assistant @ Space Systems Laboratory (SSL)

August 2019 — May 2021

- Graduate Assistant under Dr. Dave Akin; led manipulator software development
- Developed novel Julia package to generate symbolic manipulator kinematics models; implemented and merged required changes to ModelingToolkit.jl
- Created C++ templates, and implementations, for multiple manipulator kinematic controllers, including force/torque control and Cartesian control
- Maintained operator GUI for all manipulators; primary operator for neutral-buoyancy testing; maintained facility as diver; received open water certification

### Inertial & Viscous Friction Compensation Project

January 2017 — August 2017

- Independent study to implement Dr. Carignan's inertial and viscous friction compensation for Maryland-Georgetown-Army (MGA) exoskeleton within SSL; used Galil, Python, ROS, UART

### Intern @ Harris Corporation

May 2016 — August 2016

- Automated Excel task with VBA; 20 worker hours → 2 minute runtime
- Worked with one other intern to implement rain attenuation ITU Propagation Model; MATLAB functions written to implement model calculations, C# used to gather terrain data

### Intern @ SRI International

May 2015 — December 2015

- Collected and annotated data to train deep-learning algorithms
- Designed LED Array and circuit layouts for gaze tracking project using Eagle CAD

## Education

### M.S. in Aerospace Engineering @ University of Maryland

- Research assistant under Dr. Akin; space robotics (manipulator) software lead, primary operator
- Halo orbit & invariant-manifold research project with Professor Barbee; released as open source tools
- Emphasis in space systems, prioritized dynamics & controls in coursework

### B.S. in Electrical Engineering @ University of Maryland

- Emphasis in control theory, prioritized software in coursework through four computer science classes
- Undergraduate Research Assistant under Dr. Akin at SSL; manipulator software lead as junior

## Technical Skills

### Computer Programming

- Productive in C++, used for robotic manipulator control software
- Experienced with Julia, used for astrodynamics research; hobbyist FOSS
- Experienced with Python, used for post-simulation analysis & scripting at NASA JSC; hobbyist FOSS

### Circuit Design

- Undergraduate digital & analog lab experience, including Verilog, SPICE, PSpice, Xilinx, oscilloscopes
- Internship experience using Eagle CAD to design PCB for gaze-tracking project

### Modeling & Simulation

- Experienced with linear model reduction, linear analysis, and nonlinear analysis methods

## FOSS Projects

### SolarSystemSurrogates.jl

*An experiment that I'm excited about. This package will provide surrogate models for solar system ephemeris data. Fingers crossed!*

### AstrodynamicalModels.jl

*Model generation — with optional state transition matrix dynamics — through ModelingToolkit.jl.*

### GeneralAstrodynamics.jl

*General calculations, visualizations, iterative & analytical periodic orbit solvers, and orbit-manifold solvers.*

### HorizonsAPI.jl

*A word-for-word wrapper for the JPL Horizons REST API. Fetch solar system ephemeris for free!*

### HorizonsEphemeris.jl

*A user-friendly wrapper around the word-for-word wrapper for the JPL Horizons REST API.*

### PolynomialGTM.jl

*Implements publicly available polynomial models for NASA's Generic Transport Model using ModelingToolkit.jl.*

### module-hygiene

*Provides an `__export__` key, and an associated `cleanup` function to reduce namespace clutter.*

### block-scopes

*Provides a single context manager, `only`, which creates block-style scopes within Python. This package isn't unique — it's just for fun!*

### rich-admonitions

*Extends the excellent terminal formatting package `rich` with Julia-style Markdown admonition blocks!*

## Social Media



loopy.software



@cadojo



@cadojo#6211



@code\_typed