

Joey Carpinelli

Technical Résumé
Available at resume.loopy.codes



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Professional Experience

NASA Johnson Space Center (JSC)

August 2017 — Present

GN&C Engineer, Pathways Intern, USRA Intern

- Full time as of July 2021; Orion's Launch Abort System GN&C development, analysis, verification
- Reduced, analyzed, and implemented flexible body (structure) model (MATLAB, C++)
- Uses monte-carlo simulations for parameter tuning; improved vehicle performance noticeably
- Uses linear analysis to analyze vehicle performance, verify stability margins; validates linear models
- Serves as backup regression data approver for simulated Orion Launch Abort System performance
- Led development for polarity tests; created novel 6DOF kinematics simulation (Julia, Python); represented Orion GN&C at multiple lab tests in three states: Texas, Colorado, Florida

Space Systems Laboratory (SSL)

August 2016 — May 2021

Graduate Assistant

- Led core robot software development (C++, ROS) as Graduate Assistant under Dr. Dave Akin
- Developed novel Julia package to generate symbolic manipulator kinematics models; implemented and merged required changes to `ModelingToolkit.jl`; intermediate Jacobian performance substantially improved over **Orocos** iterative solvers; implemented fast inverse-kinematics algorithm
- Created C++ interfaces (templates) and implementations for control, including force/torque control
- Maintained operator GUI (Python); diver for Neutral Buoyancy Research Facility Maintenance

Harris Corporation

May 2016 — August 2016

Electrical Engineering Intern

- Automated Excel task with VBA; 20 worker hours → 2 minute runtime
- Worked with one other intern to implement rain attenuation ITU Propagation Model; MATLAB functions written to implement model calculations, C# used to gather terrain data

SRI International

May 2015 — December 2015

Data Annotation Intern

- Collected and annotated data to train deep-learning algorithms; improved process with scripting
- Designed LED Array and circuit layouts for gaze tracking project using Eagle CAD

Education

M.S. Aerospace Engineering

August 2019 — May 2021

University of Maryland, College Park

- Research assistant under Dr. Akin; space robotics (manipulator) software lead, primary operator
- Halo orbit & invariant-manifold research project with Instructor Barbee; released as open source tools
- Emphasis in space systems, prioritized dynamics & controls in coursework

B.S. Electrical Engineering

May 2019

University of Maryland, College Park

- Four control theory courses, four computer science courses; major emphasis in control theory
- Undergraduate Research Assistant under Dr. Akin at SSL; ROS/Orocos software lead in third year
- Implemented inertial and viscous friction compensation for SSL's MGA Exoskeleton (Galil, UART)

Technical Skills

Computer Programming

- Experienced Julia & Python developer; aerospace dynamics, simulation, and analysis applications
- Experienced C/C++ developer; robot core software, kinematics, & control applications
- Currently tutoring student seeking C/C++ certification; student is passing practice tests with margin

Modeling & Simulation

- Utilized linear model reduction, linear analysis, and nonlinear analysis techniques
- Frequent 6DOF monte-carlo simulations (NASA, Trick), stiff differential equation solves (Julia)

FOSS Projects

GeneralAstrodynamics.jl

General calculations, visualizations, and halo & manifold solvers. Presented at **JuliaCon!**

KinematicChains.jl

In-development forward & inverse kinematics, and Jacobian solvers for robotic manipulators.

AstrodynamicalModels.jl

Model generation, with optional state transition matrix dynamics.

SPICEBodies.jl

Simple Julia interface to retrieving ephemeris and physical body data from loaded kernels.

SPICEKernels.jl

All generic kernels provided by NASA, exposed and cached through Julia functions. See also: **SPICEApplications.jl**.

HorizonsEphemeris.jl

Request JPL Horizons ephemeris data from within Julia, with a simplified interface! For a verbatim wrapper, see **HorizonsAPI.jl**.

PolynomialGTM.jl

Implements publicly available polynomial models for NASA's Generic Transport Model using `ModelingToolkit.jl`.

CommonLicenses.jl

Inline any **standard license** into your executable document! For example: `CommonLicenses.MIT()`.

module-hygiene

Provides an `__export__` key for namespace hygiene. See also: **block-scopes**.

rich-admonitions

Extends the excellent terminal formatting package **rich** with Julia-style Markdown admonition blocks!

Personal Media



@cadojo



in/joeycarp



<https://loopy.codes>