```cpp
/*-------------------------------------------------------------*/
/*      5249Z-Ignite                                           */
/*      Version: 1.2.0                                          */
/*      File: RobotMethods.h                                   */
/*      Description: Methods for controlling different parts of */
/*          the robot                                          */
/*-------------------------------------------------------------*/
#include "RobotConfig.h"
void intake(double speed);
void intakeStop(brakeType stopMode = brakeType::coast);
void chassisLeft(double speed);
void chassisRight(double speed);
void arm(double speed);
void armStop(brakeType stopMode = brakeType::coast);
void rampLift(double speed);
void rampLiftStop(brakeType stopMode = brakeType::coast);
bool cubesClear();
void setOriginalLight();

bool liftRamp(bool moveUp, double slow = 50, double fast = 100);
```