

Solving Laplace Problems with Corner Singularities

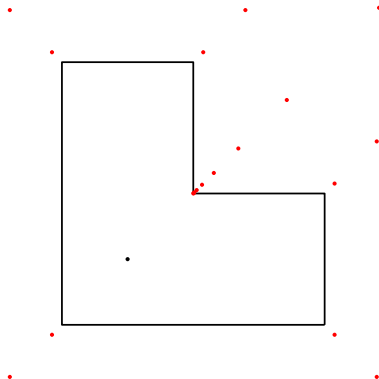
Caelen Feller

Supervised by: Prof. Kirk M. Soodhalter

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Approximation Scheme

$$r(z) = \sum_{j=1}^{N_1} \underbrace{\frac{a_j}{z - z_j}}_{\text{Newman}} + \sum_{j=0}^{N_2} \underbrace{b_j (z - z_*)^j}_{\text{Runge}}$$



A short timeline of results used

- 1885 - Carl Runge proves Runge's theorem, allowing uniform convergence using polynomials within the bulk.
- 1964 - D.J. Newman proves root-exponential convergence for $|x|$ using rational approximations.
- 2003 - Herbert Stahl proves root-exp for $|x|^\alpha$
- 2019 - Trefethen et. al show root-exp. convergence for this.

Definition (Root-Exponential Convergence)

Given a sequence $\{x_n\}$, converging to a true value x . Convergence of the sequence is root-exponential iff

$$\epsilon_n = |x_n - x| = O\left(\exp\left(-C\sqrt{N}\right)\right), \quad N \rightarrow \infty, \quad C > 0$$

- Investigation and implementation of Trefefthen's results.
- Extension of theory and/or implementation completed for:
 - Non-continuous boundary conditions.
 - Non-Dirichlet boundary conditions.
 - Curved domains.
- Verification of Trefefthen's results vs traditional methods

Root-Convergence Theorem

Theorem

Let Ω be a convex polygonal domain with corners $\omega_1 \dots, \omega_m$, $f \in \mathcal{O}(\Omega)$, with holom. continuation to $\Delta_{\epsilon_k}(\omega_k) \setminus$ the exterior bisector of domain at ω_k .

If $\exists \delta > 0$ s.t. $|f(z) - f(\omega_k)| = O(|z - \omega_k|^\delta)$, $z \rightarrow \omega_k \implies$
 \exists degree n rational functions $\{r_i\}$, $i > 0$ s.t. $|f - r|_\Omega =$
 $O(\exp(-C\sqrt{n})), C > 0, n \rightarrow \infty$, with the finite poles of each
 r_n clustered exponentially along the exterior bisectors of
the domain such that the number of poles near a corner grows
in proportion to n , as $n \rightarrow \infty$

Harmonic Functions

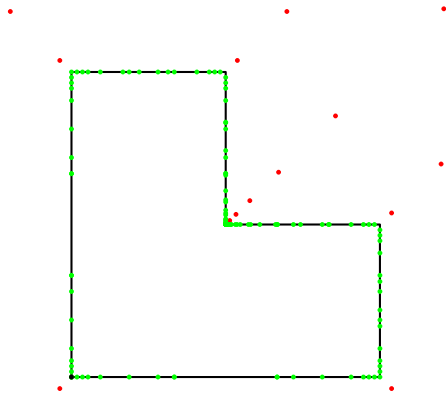
Harmonic Functions

- Harmonic functions can be associated with holomorphic ones using Hilbert transform.
- Imaginary part of transformed function can also be extended across boundaries and about slits with correct behaviour.
- Previous theorem thus holds for harmonic functions
- Laplace solutions are harmonic
- Extensions for other functions in early days

For boundary Γ , with corners $\omega_1, \dots, \omega_m$, boundary function h and error ϵ , with increasing values of n .

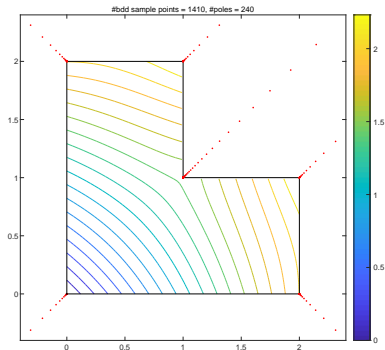
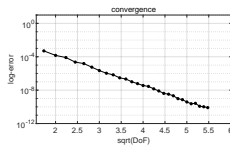
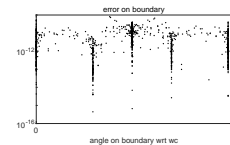
- 1 Fix $N_1 = O(mn)$ poles clustered outside corners.
- 2 Fix $N_2 + 1 = O(n)$ monomials, $1, \dots, (z - z_*)^{N_2}$, and set $N = N_1 + N_2 + 1$
- 3 $M \approx 3N$ sample points on the boundary clustered near the corners.
- 4 Evaluate at sample points to form $M \times N$ matrix A and M -vector b
- 5 **Solve the least-squares problem**, $Ac \approx b$ for c .
- 6 Exit loop if $\|Ax - b\|_\infty < \epsilon$.

Boundary Sampling Method



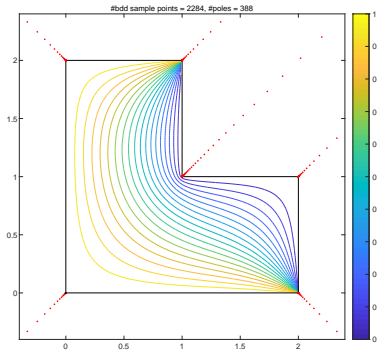
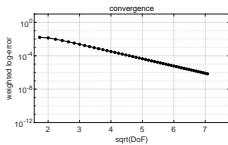
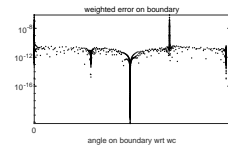
Boundary Sampling points in green

Full Solution



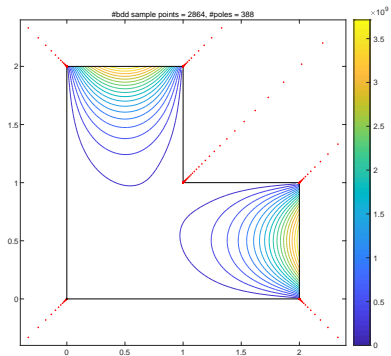
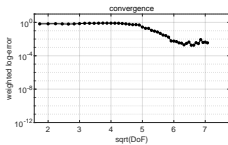
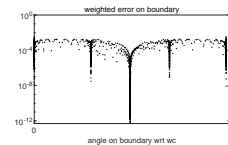
L-Shaped domain with solution

Demonstration



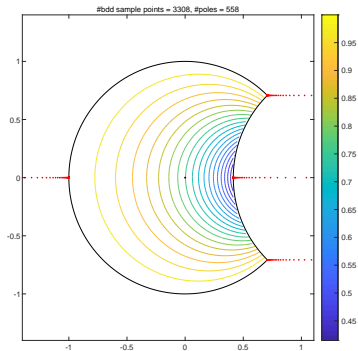
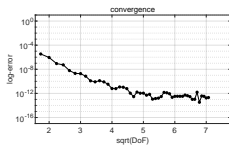
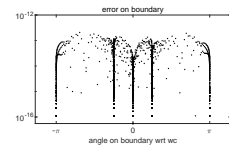
Discontinuous Boundary Conditions

Demonstration



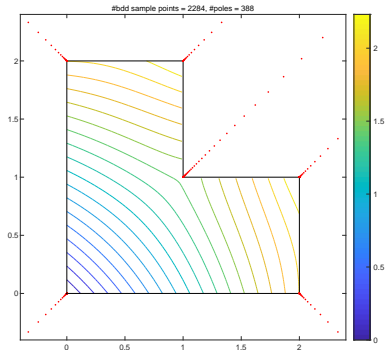
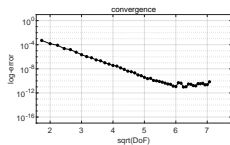
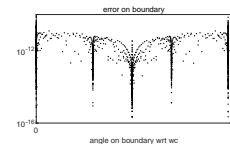
Robin Boundary Conditions

Demonstration



Curved boundaries

Limit to Accuracy



Upper bound to accuracy $1e^{-10}$

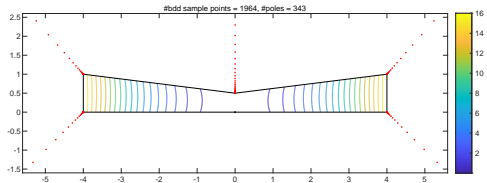
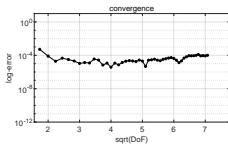
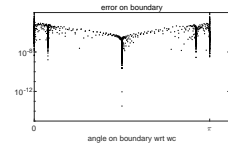
In the remainder of the time allocated for this project, I wish to extend this method to cover at least the following cases:

- Elongated domains
- Domains with slits & multiply connected domains
- Non-convex domains & more complex curved domains
- Transmission problems

I wish to address the lack of stability in the solution for high precision, whether is a software or analytic issue, and understand where this cap in accuracy comes from.

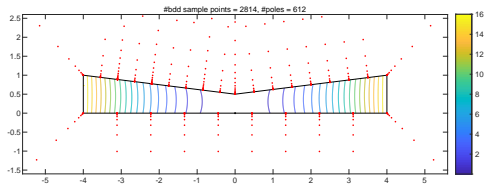
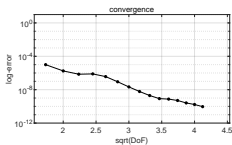
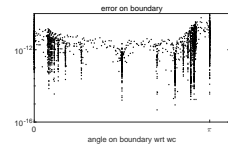
Thank you!

Elongated Domain



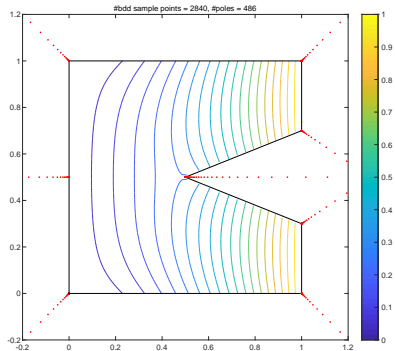
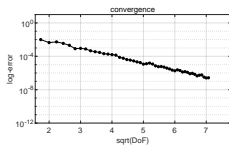
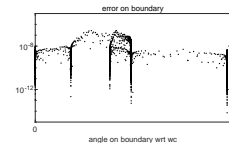
No convergence in case of elongated domain

Elongated Domain



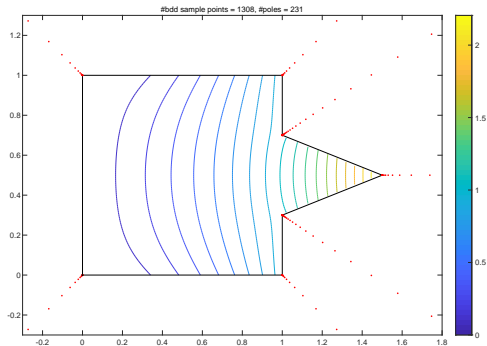
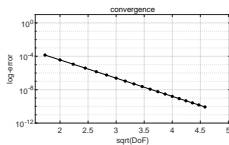
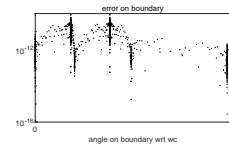
Potential fix to domain

Re-Entrant Spike



Re-Entrant Spike converges slowly

Salient Spike



Salient Spike converges faster