```python
# taking a picture to test the camera

import cv2
import numpy as np
import RPi.GPIO as GPIO

# initalize variables
code_running=True

# quit button
GPIO.setmode(GPIO.BCM)
GPIO.setup(17, GPIO.IN, pull_up_down=GPIO.PUD_UP)

def GPIO17_call_back(channel):
    global code_running
    code_running=False

cap = cv2.VideoCapture(0) #video capture source camera


while(code_running):

    # capture current frame
    ret,frame = cap.read()

    # display captured frame
    cv2.imshow('img1',frame)

    # set values for base color
    b=frame[:,:,:1]
    g=frame[:,:,1:2]
    r=frame[:,:,2:]

    # computing mean
    b_mean=np.mean(b)
    g_mean=np.mean(g)
    r_mean=np.mean(r)

    # display prominent color
    if (r_mean > g_mean and r_mean > b_mean):
        print("Red")
    elif (g_mean > r_mean and g_mean > b_mean):
        print("Green")
    else:
        print("Blue")
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48      # release video and close windows
49      cv2.wait+Key(0)
50      cap.release()
51      cv2.destroyAllWindows()
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```