```
1
     # taking a picture to test the camera
 2
 3
     import cv2
 4
     import numpy as np
 5
     import RPi.GPIO as GPIO
 6
 7
     # initalize variables
 8
     code_running=True
9
     # quit button
10
     GPIO.setmode(GPIO.BCM)
11
12
     GPIO.setup(17, GPIO.IN, pull_up_down=GPIO.PUD_UP)
13
     def GPI017_call_back(channel):
14
15
         global code_running
         code_running=False
16
17
     cap = cv2.VideoCapture(0) #video capture source camera
18
19
     n=255
20
     while(code_running):
21
22
         # capture current frame
23
         ret,frame = cap.read()
24
25
         # display captured frame
26
27
         cv2.imshow('img1', frame)
28
         # convert RBG to HSV
29
30
         hsv=cv2.cvtColor(frame,cv2.COLOR_BGR2HSV)
31
         # red: [0-20&340-360,60-100,50-100]
32
33
         light_red1=np.array([255,85,0])
         dark_red1=np.array([128,51,51])
34
         light_red2=np.array([255,0,4])
35
         dark_red2=np.array([128,51,76])
36
37
         # white: [any,0-10,95-100]
38
         light_white=np.array([242,242,242])
39
         dark_white=np.array([255,230,230])
40
41
         # darks:[any,any,0-60] & [230-360,50-100,60-100]
42
         light_dark1=np.array([153,0,3])
43
44
         dark_dark_1=np.array([0,0,0])
         light_dark2=np.array([255,0,4])
45
```

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46
         dark_dark2=np.array([77,89,153])
47
         # lights: [any, 0-50, 60-100]
48
49
         light_light=np.array([153,153,153])
50
         dark_light=np.array([255,128,130])
51
         # colors: [0-230,50-100,60-100]
52
         light_color=np.array([0,42,255])
53
         dark_color=np.array([153,77,77])
54
55
         # find red
56
         mask_red1=cv2.inRange(hsv, light_red1, dark_red1)
57
         mask_red2=cv2.inRange(hsv, light_red2, dark_red2)
58
         mask_white=cv2.inRange(hsv, light_white, dark_white)
59
60
         mask_dark1=cv2.inRange(hsv, light_dark1, dark_dark1)
         mask_dark2=cv2.inRange(hsv, light_dark2, dark_dark2)
61
62
         mask_light=cv2.inRange(hsv,light_light,dark_light)
         mask_color=cv2.inRange(hsv, light_color, dark_color)
63
64
         # output
65
         red1=cv2.bitwise_and(frame, frame, mask=mask_red1)
66
         red2=cv2.bitwise_and(frame, frame, mask=mask_red2)
67
         white=cv2.bitwise_and(frame, frame, mask=mask_white)
68
         dark1=cv2.bitwise_and(frame, frame, mask=mask_dark1)
69
         dark2=cv2.bitwise_and(frame, frame, mask=mask_dark2)
70
71
         light=cv2.bitwise_and(frame, frame, mask=mask_light)
         color=cv2.bitwise_and(frame, frame, mask=mask_color)
72
         cv2.imshow("red1", red1)
73
         cv2.imshow("red2", red2)
74
         cv2.imshow("white", white)
75
         cv2.imshow("dark1", dark1)
76
77
         cv2.imshow("dark2", dark2)
         cv2.imshow("light", light)
78
         cv2.imshow("color", color)
79
80
81
82
         # release video and close windows
         cv2.waitKey(0)
83
         cap.release()
84
         cv2.destroyAllWindows()
85
86
87
```