

EE 503
HW #5
Due: Dec. 29th, 2009

We examine the noise cancellation application of Wiener filtering in this homework. Please read *Section 7.2.3 Noise Cancellation* of Hayes before starting the homework.

In the following figure, $w[n]$ is white noise with zero mean and unit variance. The sequences $w_1[n]$ and $w_2[n]$ are correlated random processes with zero mean and with variances of $\sigma_{w_1}^2$ and 1 respectively. In the set-up shown in the figure, the desired sequence $d[n]$ is corrupted by the noise $w_1[n]$. Our goal is to estimate $w_1[n]$ from the auxiliary information $w_2[n]$ and cancel it as shown in the figure.

Part A:

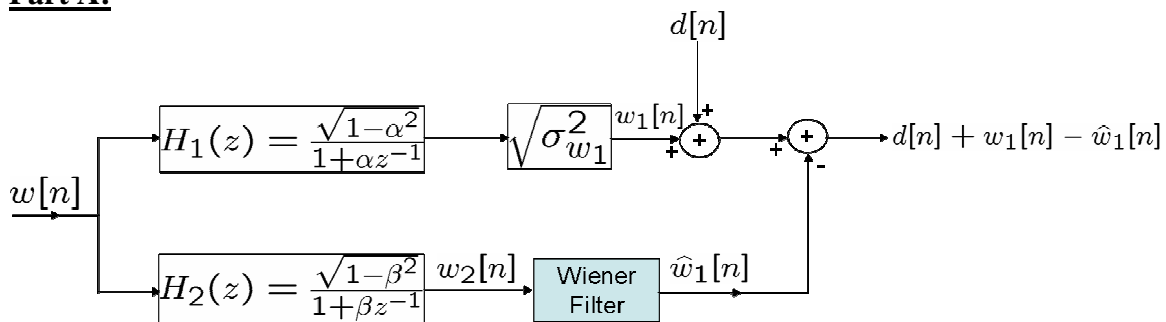


Figure 1: Noise Cancellation Configuration

A1. Execute the following in Matlab command line

```
>> load handel
```

In the work place, you should see “y” and “Fs” as Matlab variables. After adjusting the volume of your speakers to a comfortable level, execute the following:

```
>> sound (y,Fs);
```

You should hear the famous movement of Handel. In this homework, we use Handel sequence for noise cancellation experiment.

Now, execute the following

```
>> yzm = y - mean(y);
```

and plot yzm sequence and visually observe that it is a zero mean sequence. Now listen yzm using the sound command, there should not any noticeable difference. The desired sequence shown as $d[n]$ in Figure 1 is the “yzm” sequence.

Calculate the variance of yzm sequence, call this variance as σ_d^2 . The following is the definition of sample SNR for noise corrupted signal, $d[n] + w_1[n]$:

$$SNR = \frac{\sigma_d^2}{\sigma_{w_1}^2}$$

- A2. Analytically calculate the auto-correlation of $w_2[n]$ and the cross-correlation of $w_1[n]$ and $w_2[n]$ in terms of α and β . (Report your calculations.)
- A3. Set $\sigma_{w_1}^2$ such that sample SNR is 5 dB. Set $\alpha = -0.8$ and $\beta = -0.5$ and let the Wiener filter have $P=5$ taps (4th order filter).
- Listen $d[n] + w_1[n]$ at this SNR level.
 - Estimate the auto-correlation of $w_2[n]$ and the cross-correlation of $w_1[n]$ and $w_2[n]$ using xcorr command of Matlab. Compare your estimates with the ones you have found in step A2.
 - Implement the P tap Wiener filter using estimated coefficients. Examine the variance of the noise term effecting $d[n]$ before and after noise cancellation, that is compare the variance of $w_1[n]$ and $w_1[n] - \hat{w}_1[n]$.
 - Listen the noise cancelled signal.
- A4. Repeat part A3 for $\alpha = -0.8$, $\beta = \{0.9, 0.85, 0.5, 0.25, -0.25, -0.5, -0.85, -0.9\}$. (Present the results of part A3d in your report). How can you explain the change in error with β ?
- A5. Repeat part A3 for $\alpha = -0.8$, $\beta = 0.25$, for $P = \{2, 4, 8, 16, 32\}$. (Present the results of part A3d in your report).
- A6. Repeat part A3 for $\alpha = -0.8$, $\beta = 0.25$, $P=8$ and $SNR = \{5, 0, -5, -10\}$ dB. (Present the results of part A3d in your report).

Everything should work fine up to this point. But, in practice, we face a more difficult problem.

Part B:

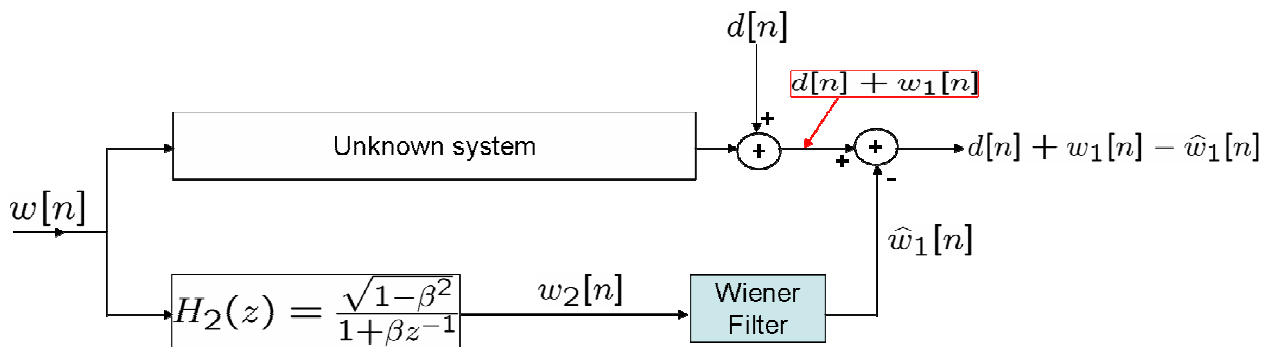


Figure 2: Practical Scheme

In practice, it is not possible to observe $w_1[n]$ directly, but we can only observe $d[n] + w_1[n]$. If we could have observed $w_1[n]$ and $d[n] + w_1[n]$ individually,

then we can subtract $w_1[n]$ from the observation, so there is no need to estimate $\hat{w}_1[n]$!!!

Figure 2 shows the more practical scheme for noise cancellation. In this scheme different from the earlier one, we can only observe $d[n] + w_1[n]$, not $w_1[n]$.

B1. Let the unknown system be the $H_1[z]$ given part A. Set $\alpha = -0.8$ and $\sigma_{w_1}^2$ such that sample SNR is 5 dB. Set $\beta = -0.5$. Let the Wiener filter have $P=5$ taps (4th order filter).

- Estimate the auto-correlation of $w_2[n]$ and the cross-correlation of $(d[n] + w_1[n])$ and $w_2[n]$. Compare the cross-correlation estimate with the one found in part A. Do you expect a similar result ? Why ?
- Implement P tap Wiener filter and examine the variance of the noise term effecting $d[n]$ before and after noise cancellation, that is compare the variance of $w_1[n]$ and $w_1[n] - \hat{w}_1[n]$.
- Compare the result of part b with the corresponding result when $w_1[n]$ is available instead of $d[n] + w_1[n]$.

B2. Repeat part A6 and report your results.

Yet there is another difficulty that we face in practice.

Part C:

In practice, it is not possible to observe $w_2[n]$ alone that is without the presence $d[n]$. Even though by a sufficient isolation of the desired source from the second receiver (auxiliary channel), the leakage of $d[n]$ into the auxiliary signal (signal at the input of the Wiener filter) is in many scenarios unavoidable.

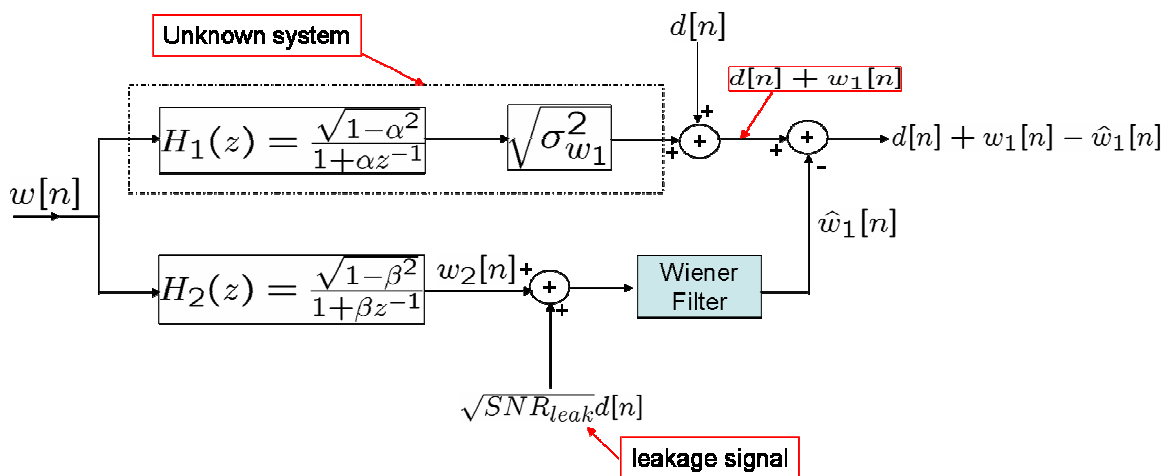


Figure 3: Practical scheme with leakage term

Note that when SNR_{leak} is 0 (that is, $SNR_{leak} = -\infty$ dB), Figure 3 is the same as Figure 2 given before.

C1. Let the unknown system be $H_1[z]$ given part A. Set $\alpha = -0.8$ and $\sigma_{w_1}^2$ be such that the sample SNR is 5 dB. Let $SNR_{leak} = -10$ dB and the Wiener filter have $P=5$ taps (4th order filter).

- a. Estimate the auto-correlation of $(w_2[n] + \sqrt{SNR_{leak}} d[n])$ and the cross-correlation of $(d[n] + w_1[n])$ and $(w_2[n] + \sqrt{SNR_{leak}} d[n])$. Compare the cross-correlation estimate with the one found in part A. Do you expect a similar result?
- b. Implement P tap Wiener filter and examine the variance of the noise term effecting $d[n]$ before and after noise cancellation, that is compare the variance of $w_1[n]$ and $w_1[n] - \hat{w}_1[n]$.
- c. Compare the result of part b with the corresponding result given in Part A.

C2. Repeat part C1 for $SNR_{leak} = \{-5, 0, 5\}$ dB. Compare your results with the corresponding results given in Part A. Report your comparisons.