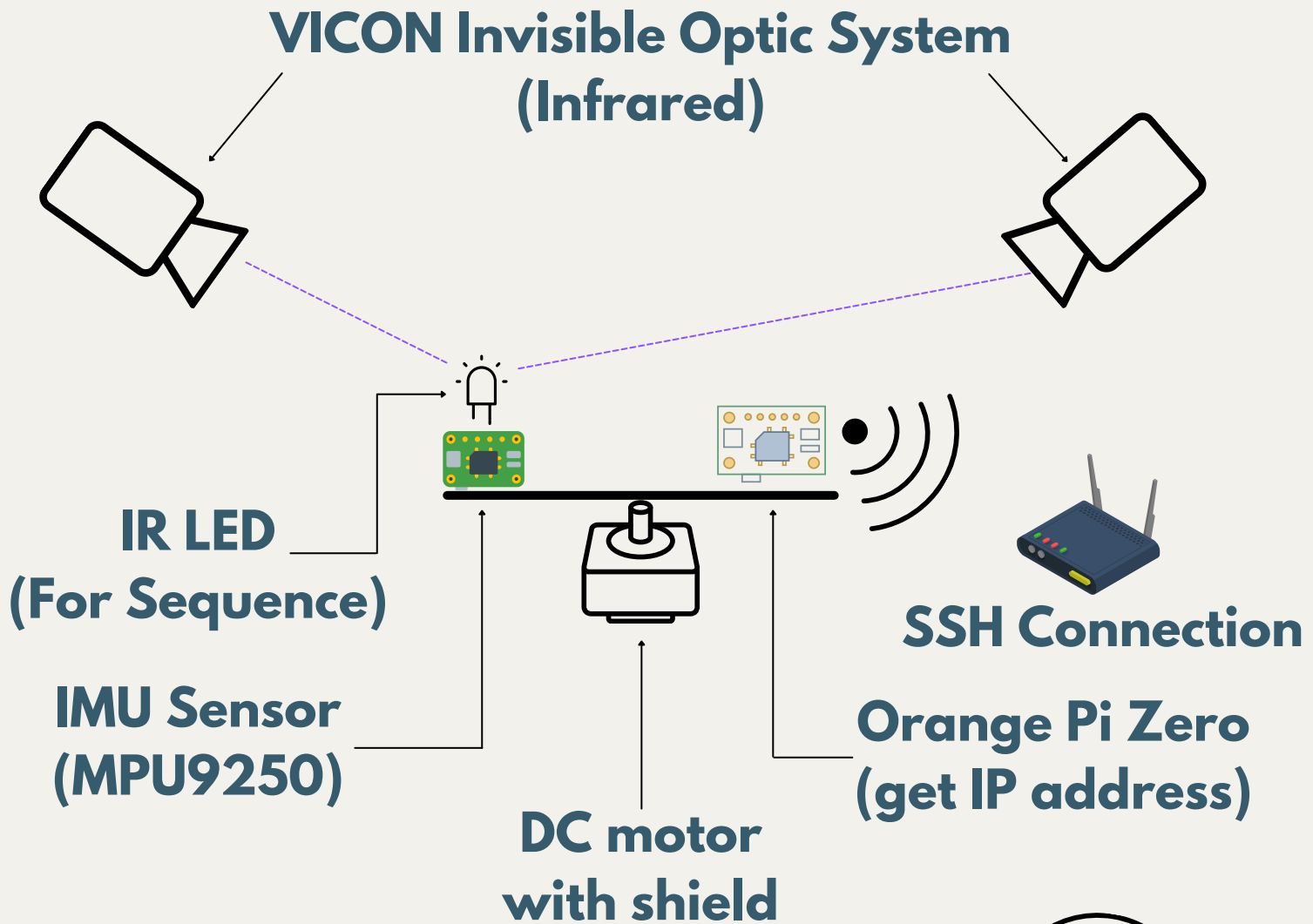


# Experiment Info



## Prospective Results

Comparison between VICON & IMU

- Angular Velocity
- Tangential Velocity
- Position

Determination of Filter Values

\*VICON position data is assumed as Golden Reference

Used



LINUX  
DEBIAN  
& Samba

I2C  
BUS

