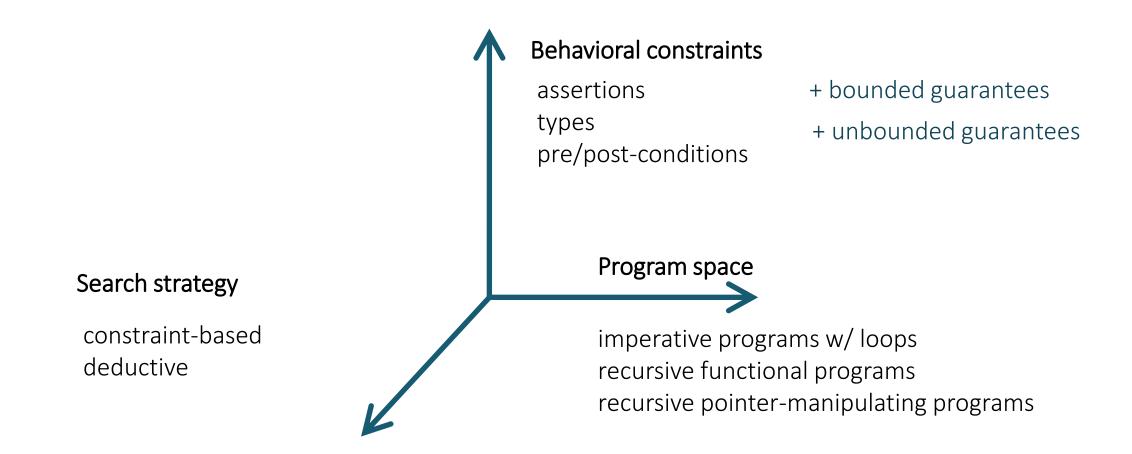
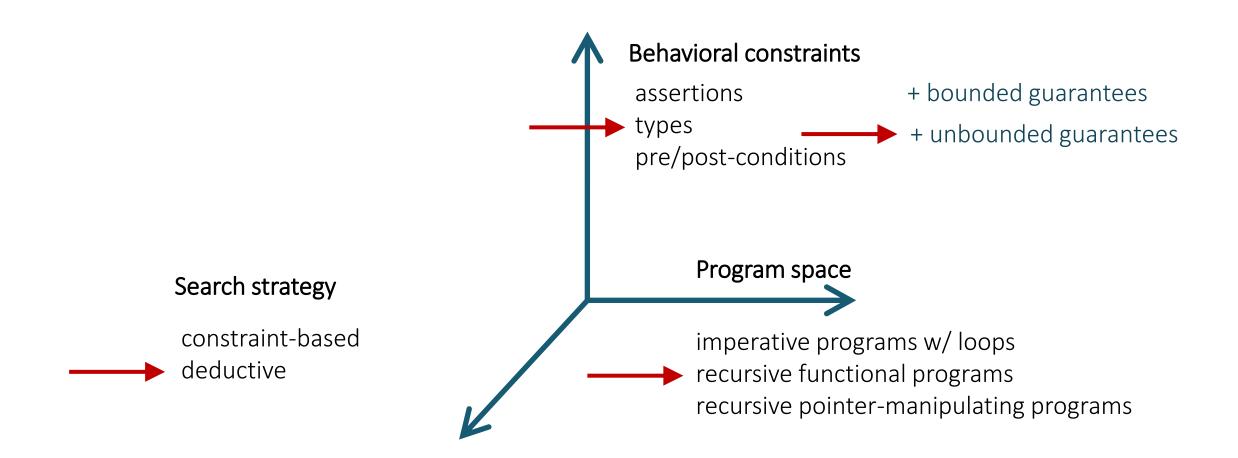
# Lecture 12 Hoare Logic

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#### Module II



#### Last week



#### This week

Behavioral constraints + bounded guarantees assertions types + unbounded guarantees pre/post-conditions Program space imperative programs w/ loops recursive functional programs recursive pointer-manipulating programs

Search strategy

constraint-based deductive

#### Constraint-based synthesis

Behavioral constraints = assertions, reference implementation, pre/post

encoding

Structural constraints

 $\exists c . \forall x . Q(c, x)$ 

## Why is this hard?

```
Euclid (int a, int b) returns (int x)
                                                              infinitely many inputs
  requires a > 0 \land b > 0
  ensures x = \gcd(a, b)
  int x , y := a, b;
                                                               infinitely many paths!
  while (x != y) {
    if (x > y) x := ??*x + ??*y + ??;
else y := ??*x + ??*y + ??;
}}
```

#### Loop unrolling

```
Euclid (int a, int b) returns (int x)
  requires a > 0 \land b > 0
  ensures x = \gcd(a, b)
                                                      if (x != y) {
  int x , y := a, b;
                                                        if (x > y)
 while (x != y) {
                                                          x := ??*x + ??*y + ??;
                                           Unroll with
    if (x > y) x := ??*x + ??*y + ??;
                                                        else
                                           depth = 1
                                                          y := ??*x + ??*y + ??;
    else y := ??*x + ??*y + ??;
                                                        assert !(x != y);
}}
```

#### What's wrong with unrolling?

```
Euclid (int a, int b) returns (int x)
  requires a > 0 \land b > 0
  ensures x = \gcd(a, b)
                                                       if (x != y) {
  int x , y := a, b;
  while (x != y) {
                                           Unroll with
    if (x > y) x := ??*x + ??*y + ??;
                                                         else
                                            depth = 1
    else y := ??*x + ??*y + ??;
}}
```

Unsatisfiable sketch

```
if (x != y) {
  if (x > y)
    x := ??*x + ??*y + ??;
  else
    y := ??*x + ??*y + ??;
  assert !(x != y);
}
```

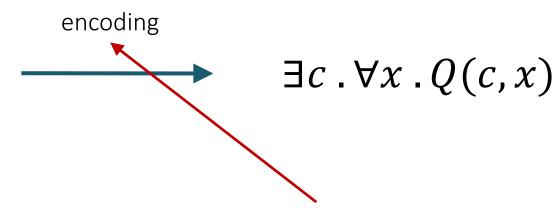
### What's wrong with unrolling?

What if we restrict inputs to [0, 1, 2]? Euclid (int a, int b) returns (int x) Unsound solution! requires  $a > 0 \land b > 0$ ensures  $x = \gcd(a, b)$ **if** (x != y) { **int** x , y := a, b; if (x > y)**while** (x != y) { x := 0 \*x + 0 \*y + 1;Unroll with if (x > y) x := ??\*x + ??\*y + ??;else depth = 1y := 0 \* x + 0 \* y + 1; else y := ??\*x + ??\*y + ??; **assert** !(x != y); }}

### Constraint-based synthesis

Behavioral constraints = assertions, reference implementation, pre/post

Structural constraints



If we want to synthesize programs that are correct on all inputs, we need a better way to deal with loops!

#### Solution

Hoare logic = a program logic for simple imperative programs

• in particular: loop invariants

#### The Imp language

### Hoare triples

Properties of programs are specified as judgments

$$\{P\} c \{Q\}$$

where c is a command and P,  $Q: \sigma \to Bool$  are predicates

• e.g. if  $\sigma = [x \mapsto 2]$  and  $P \equiv x > 0$  then  $P \sigma = T$ 

#### **Terminology**

- Judgments of this kind are called (Hoare) triples
- *P* is called precondition
- Q is called postcondition

## Meaning of triples

#### The meaning of $\{P\}$ c $\{Q\}$ is:

- if P holds in the initial state  $\sigma$ , and
- if the execution of c from  $\sigma$  terminates in a state  $\sigma'$
- then Q holds in  $\sigma'$

#### This interpretation is called *partial correctness*

termination is not essential

#### Another possible interpretation: total correctness

- if P holds in the initial state  $\sigma$
- then the execution of c from  $\sigma$  terminates in a state (call it  $\sigma'$ )
- and Q holds in  $\sigma'$

### Example: swap

```
{T}

x := x + y; y := x - y; x := x - y

{x = y \land y = x}
```

We have to express that y in the final state is equal to x in the initial state!

#### Logical variables

```
\{x = N \land y = M\}
x := x + y; y := x - y; x := x - y
\{x = M \land y = N\}
```

#### Assertions can contain *logical variables*

- may occur only in pre- and postconditions, not in programs
- the state maps logical variables to their values, just like normal variables

## Inference system

We formalize the semantics of a language by describing which judgments are valid about a program

An inference system

 a set of axioms and inference rules that describe how to derive a valid judgment

We combine axioms and inference rules to build *inference trees* (derivations)

## Semantics of skip

**skip** does not modify the state

```
{ P } skip { P }
```

### Semantics of assignment

x := e assigns the value of e to variable x

$$\{P[x \mapsto e]\} \quad x \coloneqq e \quad \{P\}$$

- Let  $\sigma$  be the initial state
- Precondition:  $(P[x \mapsto e])\sigma$ , i.e.,  $P(\sigma[x \mapsto \mathcal{A}[e]\sigma])$
- Final state:  $\sigma' = \sigma[x \mapsto \mathcal{A}[e]\sigma]$
- Consequently, P holds in the final state

## Semantics of composition

Sequential composition **c1**; **c2** executes **c1** to produce an intermediate state and from there executes **c2** 

$$\frac{\{P\}\;c_1\;\{R\}\;\;\{R\}\;c_2\;\{Q\}}{\{P\}\;c_1;\,c_2\;\{Q\}}$$

#### Example: swap

#### inference tree

#### leaves = axioms

assign 
$$\overline{\{\mathbf{x} = N + M \land \mathbf{y} = N\}} \quad \mathbf{x} := \mathbf{x} - \mathbf{y} \quad \{\mathbf{x} = M \land \mathbf{y} = N\}$$

assign 
$$\overline{\{x = N + M \land y = M\}}$$
  $y := x - y \{x = N + M \land y = N\}$ 

edges = rules

$$\{x = N + M \land y = M\} y := x - y; x := x - y \{x = M \land y = N\}$$

$$\{x = N \land y = M\} \ x := x + y \ \{x = N + M \land y = M\}$$

comp

$$\{x = N \land y = M\}$$
 x := x + y; y := x - y; x := x - y  $\{x = M \land y = N\}$ 

root = triple to prove

#### **Proof outline**

An alternative (more compact) representation of inference trees

$$\{x = N \land y = M\}$$

$$\Rightarrow$$

$$\{(x + y) - ((x + y) - y) = M \land (x + y) - y = N\}$$

$$x = x + y;$$

$$\{x - (x - y) = M \land x - y = N\}$$

$$y = x - y;$$

$$\{x - y = M \land y = N\}$$

$$x = x - y$$

$$\{x = M \land y = N\}$$

#### Rule of consequence

$$\frac{\{P'\}\ c\ \{Q'\}}{\{P\}\ c\ \{Q\}} \quad \text{if} \quad P \Rightarrow P' \land Q' \Rightarrow Q$$

Corresponds to adding  $\Rightarrow$  steps in a proof outline Here  $R \Rightarrow S$  should be read as

• "We can prove for all states  $\sigma$ , that R  $\sigma$  implies S  $\sigma$ "

#### Semantics of conditionals

$$\frac{\{P \land e\} c_1 \{Q\}}{\{P\} \text{ if } e \text{ then } c_1 \text{ else } c_2 \{Q\}}$$

#### Example: absolute value

```
\{T\}
     if x < 0 then
       {x < 0}
        \{-x \ge 0\}
        X := -X
        \{x \ge 0\}
     else
     \Rightarrow^{\{\neg(x<0)\}}
        \{x \ge 0\}
         skip
         \{x \ge 0\}
\{x \ge 0\}
```

$$\frac{\{P \land e\} c_1 \{Q\} \qquad \{P \land \neg e\} c_2 \{Q\}}{\{P\} \text{ if } e \text{ then } c_1 \text{ else } c_2 \{Q\}}$$

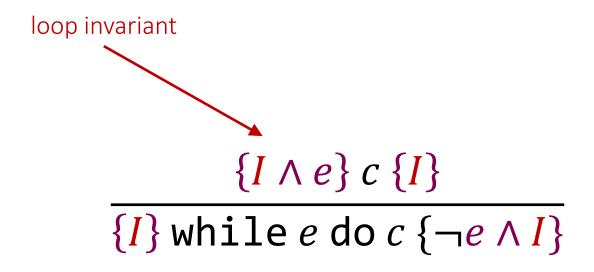
### Semantics of loops

#### We want to say:

- P holds initially
- after executing *c* 
  - if *e* still holds, we execute it *c* again
  - otherwise, Q holds

```
\frac{\{?\} c \{?\}}{\{P\} \text{ while } e \text{ do } c \{Q\}}
```

## Semantics of loops



#### **Example: GCD**

```
\{x = N \land y = M \land N > 0 \land M > 0\}
{I}
    while x != y do
      {I \land x \neq y}
         if x > y then
            x := x - y
         else
            y := y - x
       \{I\}
{I \land x = y}
\{x = \gcd(N, M)\}
```

Guessing the loop invariant:

$$I \equiv \gcd(x, y) = \gcd(N, M)$$

#### **Example: GCD**

```
\{x = N \land y = M \land N > 0 \land M > 0\}
 \Rightarrow
\{\gcd(x,y)=\gcd(N,M)\land x,y>0\}
    while x != y do
      \{\gcd(x,y)=\gcd(N,M)\land x,y>0\land x\neq y\}
         if x > y then
           \{\gcd(x,y)=\gcd(N,M)\land x\neq y\land x>y\}
           \{\gcd(x-y,y)=\gcd(N,M)\land x-y,y>0\}
              X := X - y
           \{\gcd(x,y)=\gcd(N,M)\land x,y>0\}
         else
              y := y - x
      \{\gcd(x,y)=\gcd(N,M)\land x,y>0\}
\{\gcd(x,y) = \gcd(N,M) \land x, y > 0 \land x = y\}
 \Rightarrow
\{x = \gcd(N, M)\}
```

#### **Termination**

## **Example: GCD**

#### **Example: GCD**

```
\{x = N \land y = M \land N > 0 \land M > 0\}
  \Rightarrow
\{\gcd(x,y)=\gcd(N,M)\land x,y>0\}
    while x != y do
       \{\gcd(x,y) = \gcd(N,M) \land x, y > 0 \land x + y = R \land x \neq y\}
         if x > y then
               x := x - y
         else
               y := y - x
       \{\gcd(x,y) = \gcd(N,M) \land x, y > 0 \land x + y < R \land x + y \ge 0\}
\{\gcd(x,y)=\gcd(N,M)\land x,y>0\land x=y\}
  \Rightarrow
\{x = \gcd(N, M)\}
```

### Program verifiers

Dafny demo

https://rise4fun.com/Dafny/29sh

#### Verification

```
method Euclid (a: int, b: int) returns (gcd: int)
  requires a > 0 && b > 0
  ensures x == gcd(a,b)
  var x, y := a, b;
 while (x != y)
    invariant y > 0 & x > 0 & gcd(x,y) == gcd(a,b)
                                                                                 correct!
    decreases x + y
    if (x > y) {
                                                                                 can't proof
     x := x - y;
                                                                                 correctness
    } else {
     y := y - x;
```

#### Program synthesis

found a correct program!

```
var x, y := a, b;
while (x != y)
  invariant y > 0 && x > 0 && gcd(x,y) == gcd(a,b)
  decreases x + y
{
  if (x > y) {
    x := x - y;
  } else {
    y := y - x;
  }
}
```



can't find a (program, invariant) pair that I can prove correct

### Verification → synthesis

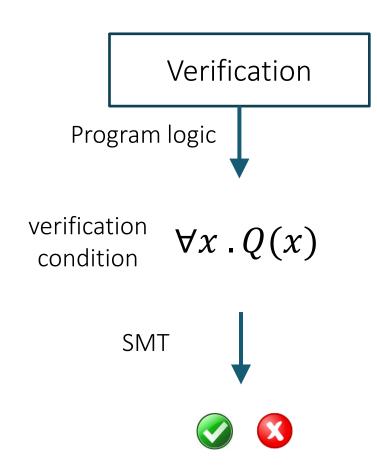
Srivastava, Gulwani, Foster: <u>From program verification to</u> program synthesis. POPL'10

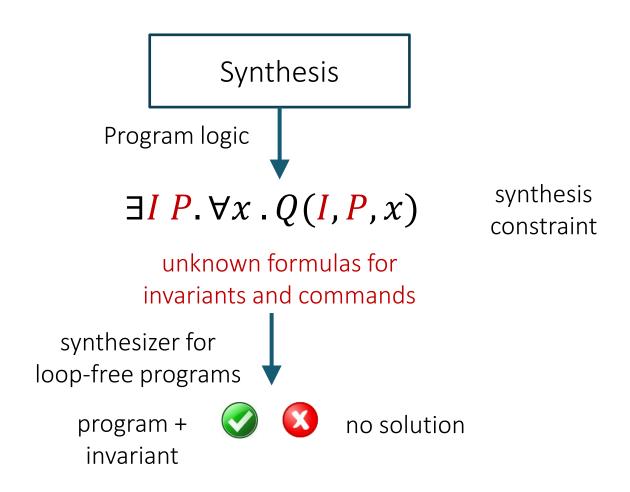
- idea: make constraint-based synthesis unbounded by synthesizing loop invariants alongside programs
- synthesized some looping programs with integers, including Bresenheim algorithm
- won "Most Influential Paper" at POPL'20!

Qiu, Solar-Lezama: <u>Natural Synthesis of Provably-Correct Data-</u> Structure Manipulations. OOPSLA'17

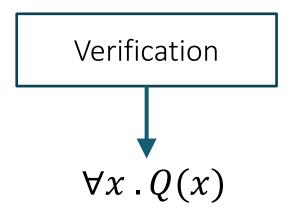
same approach for pointer-manipulating programs

## Verification → synthesis





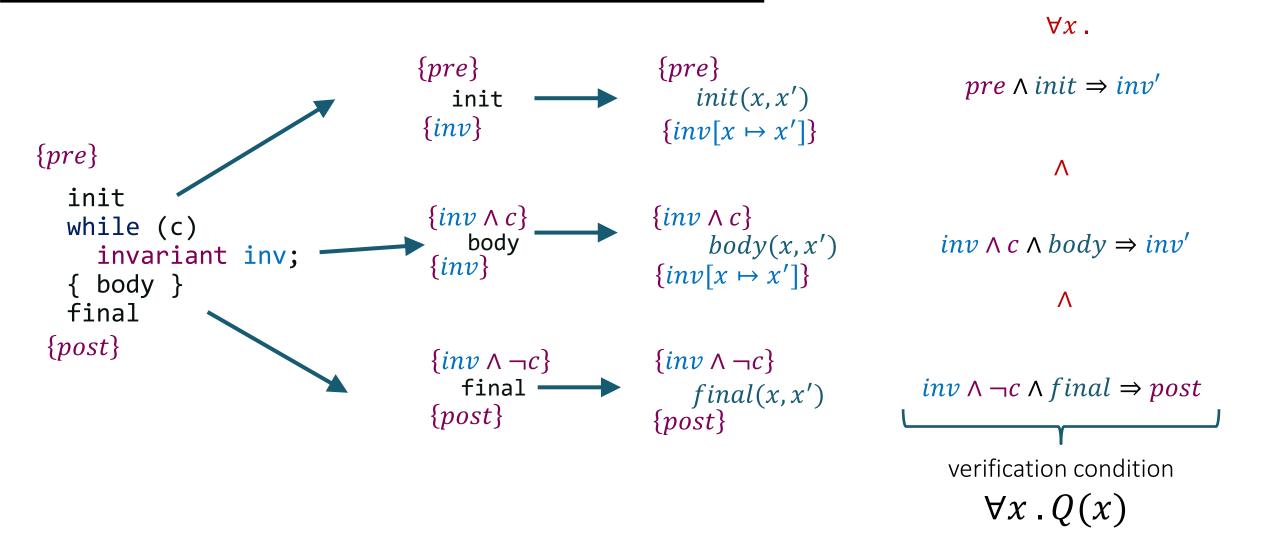
#### How verification works



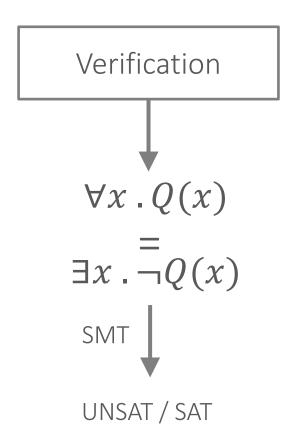
### Step 1: eliminate loops

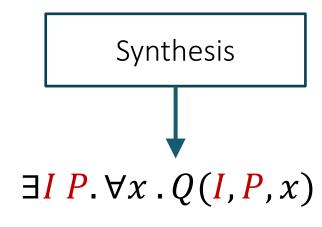
```
\{pre\}
                                                     init;
                                                   {inv }
{pre}
                                                              \{inv \land cond \}
    init;
    while (c)
                                                                 body;
      invariant inv
                                                              \{inv\}
    { body; }
    final;
{post}
                                                   \{inv \land \neg(cond)\}
                                                     final;
                                                   {post}
```

#### Step 2: generate VCs

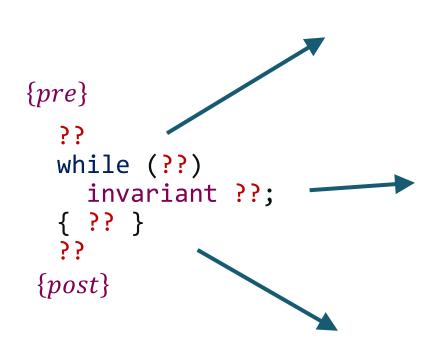


## From verification to synthesis





#### Program synthesis



```
\{pre\}
S_{i}(x, x')
\{I[x \mapsto x']\}
\{I \land G_{0}\}
G_{1} \rightarrow S_{1}(x, x')
G_{2} \rightarrow S_{2}(x, x')
\{I[x \mapsto x']\}
```

$$\begin{cases} I \land \neg G_0 \\ S_f(x, x') \\ \{post \} \end{cases}$$

```
\exists S \ G \ I. \ \forall x.
   pre \land S_i \Rightarrow I'
  I \wedge G_0 \wedge G_1 \wedge S_1 \Rightarrow I'
  I \wedge G_0 \wedge G_2 \wedge S_2 \Rightarrow I'
       T \Rightarrow G_1 \vee G_2
I \land \neg G_0 \land S_f \Rightarrow post
synthesis constraint
```

 $\exists I P. \forall x . Q(I, P, x)$ 

### Synthesis constraints

$$I \wedge G_i \wedge S_i \wedge \psi \Rightarrow I'$$

$$I \wedge G_i \wedge S_i \Rightarrow \omega$$

$$T \Rightarrow G_i \vee G_j$$

Domain for I,  $G_i$ : formulas over program variables

Domain for 
$$S_i = \{x' = e_x \land y' = e_y \land \cdots \mid e_x, e_y, \dots \in Expr\}$$

• conjunction of equalities, one per variables

#### Solving synthesis constraints

$$I \wedge G_i \wedge S_i \wedge \psi \Rightarrow I'$$

$$I \wedge G_i \wedge S_i \Rightarrow \omega$$

$$T \Rightarrow G_i \vee G_j$$

#### Can be solved this with...

- SyGuS solvers
- Sketch
  - Look we made an unbounded synthesizer out of Sketch!
- VS3 uses Lattice search
  - More efficient for predicates