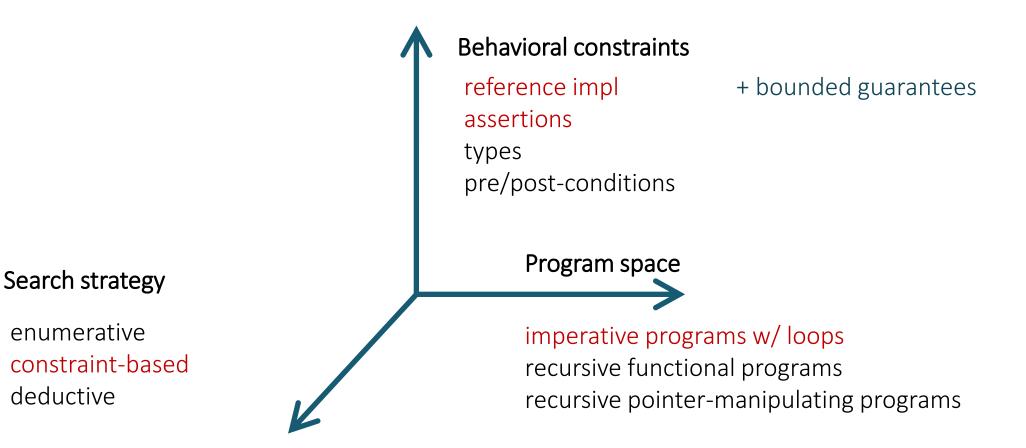
Lecture 10 Program Sketching

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Program Sketching



Constraint-based synthesis

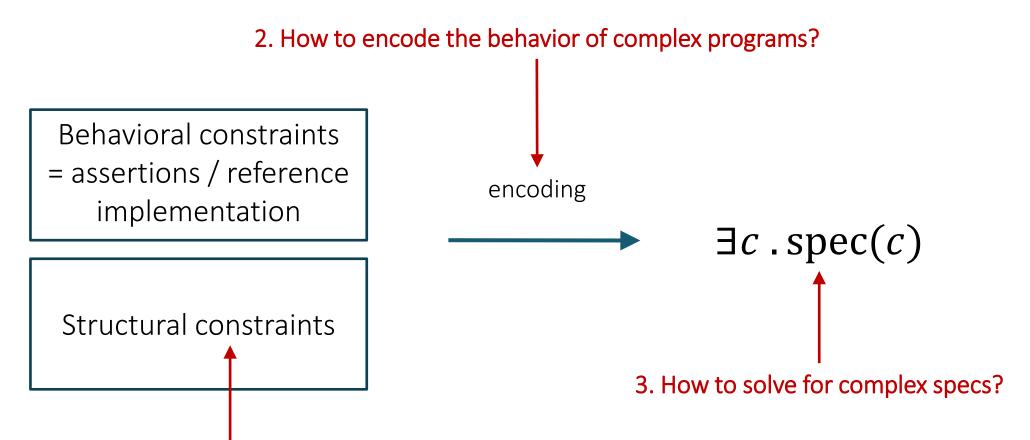
Behavioral constraints

encoding

Structural constraints

 $\exists c . \operatorname{spec}(c)$

CBS for complex programs



1. How to specify for complex programs?

Program Sketching

2. How to encode the behavior of complex programs?

Symbolic execution

Behavioral constraints
= assertions / reference implementation $\exists c . \operatorname{spec}(c)$

Structural constraints

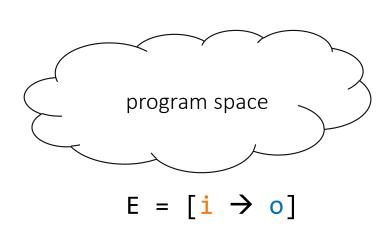
3. How to solve for complex specs?

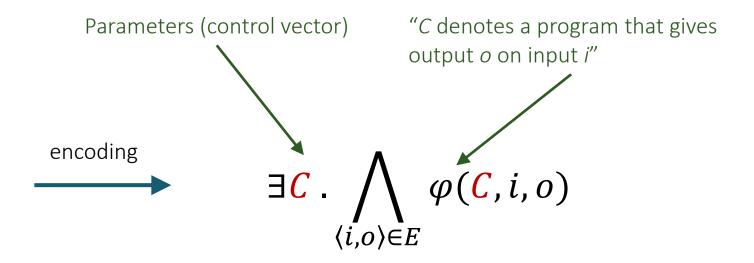
CEGIS

1. How to specify for complex programs?

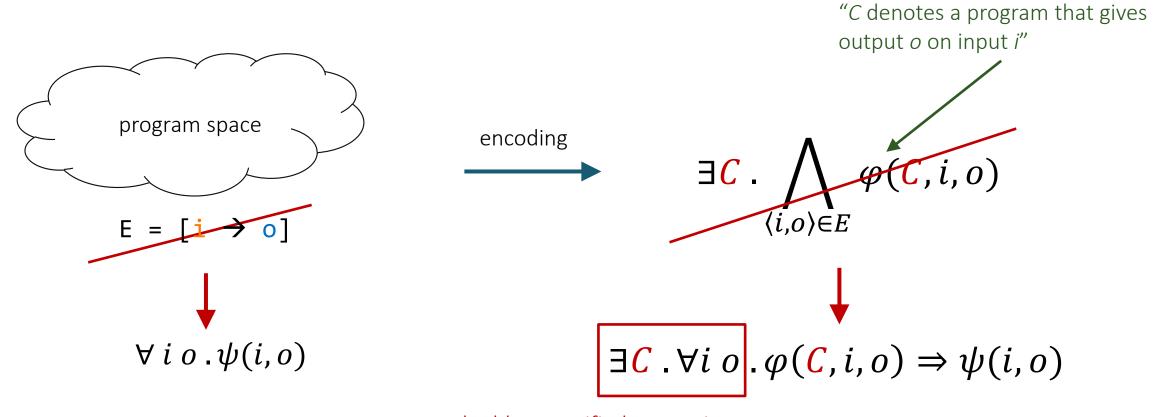
Sketches

CBS from examples





CBS from specifications



doubly-quantified constraint: not solver-friendly

Example

```
\exists C . \forall i o . \varphi(C, i, o) \Rightarrow \psi(i, o)
                                                          \exists c_1 c_2 . \forall x \ y . y = c_1 * x + c_2
harness void main(int x) {
                                          encoding
                                                                          \Rightarrow y - 1 = x + x
  int y := ?? * x + ??;
  assert y - 1 == x + x;
                                                                      simplify
                                                    \exists c_1 c_2 . \forall x . c_1 * x + c_2 - 1 = x + x
```

How do we solve this constraint?

$$\exists c . \forall x . Q(c, x)$$

Idea 1: Bounded Observation Hypothesis

• Assume there exists a small set of inputs $X = \{x_1, x_2, ... x_n\}$ such that

whenever c satisfies

i∈1..*n*

No quantifiers here, can give to SAT / SMT

it also satisfies

 $\forall x. Q(c, x)$

Example

 $\exists c_1 c_2 . \forall x . c_1 * x + c_2 - 1 = x + x$ $Q(c_1, c_2, 0) \equiv c_2 - 1 = 0$ $Q(c_1, c_2, 1) \equiv c_1 + c_2 - 1 = 2$ $\{c_1 \to 2, c_2 \to 1\}$ $\begin{cases} \text{harness void main(int } x) \\ \text{int } y := 2 * x + 1; \\ \text{assert } y - 1 := x + x; \end{cases}$

This is a linear constraint, two

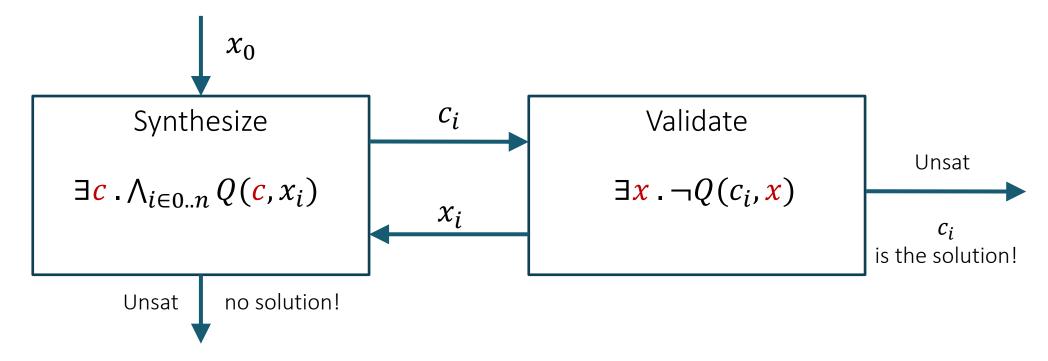
inputs are enough!

How do we find X in a general case?

CEGIS

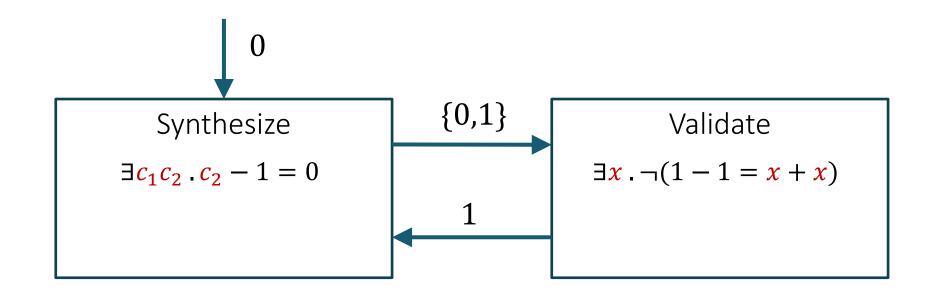
$$\exists c . \forall x . Q(c, x)$$

Idea 2: Rely on a validation oracle to generate counterexamples



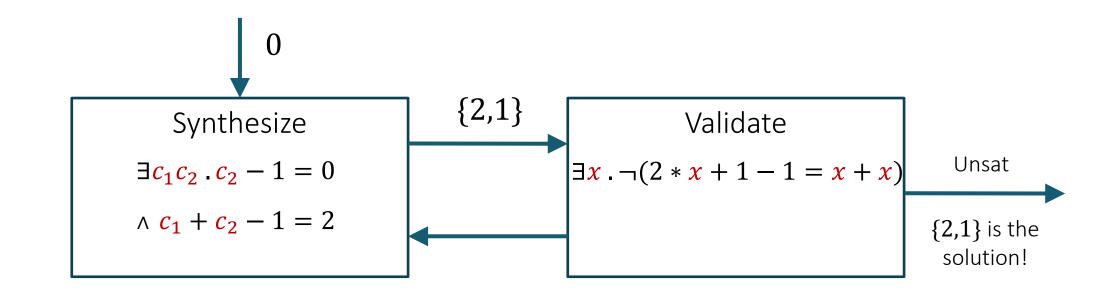
Example

$$\exists c_1 c_2 . \forall x . c_1 * x + c_2 - 1 = x + x$$



Example

$$\exists c_1 c_2 . \forall x . c_1 * x + c_2 - 1 = x + x$$



Program Sketching



Behavioral constraints = assertions / reference implementation

Structural constraints

Symbolic execution encoding

 $\exists c . \forall x . Q(c, x)$

3. How to solve for complex specs?

CEGIS

1. How to specify for complex programs?

Sketches

Structural constraints in Sketch

Different constraints good for different problems

- CFGs
- Components
- Just figure out the constants

Idea: Allow the programmer to encode all kinds of constraints using... programs (duh!)

Language Design Strategy

Extend base language with one construct

Constant hole: ??

```
int bar (int x)
{
   int t = x * ??;
   assert t == x + x;
   return t;
}
int bar (int x)
{
   int t = x * 2;
   assert t == x + x;
   return t;
}
```

Synthesizer replaces ?? with a natural number

Constant holes \rightarrow sets of expressions

Expressions with ?? == sets of expressions

- linear expressions
- polynomials
- sets of variables

```
x*?? + y*??
x*x*?? + x*?? + ??
?? ? x : y
```

Example: swap without a temporary

Swap two integers without an extra temporary

```
void swap(ref int x, ref int y){
    x = ... // sum or difference of x and y
    y = ... // sum or difference of x and y
    x = ... // sum or difference of x and y
}

harness void main(int x, int y){
    int tx = x; int ty = y;
    swap(x, y);
    assert x==ty && y == tx;
}
```

Syntactic sugar

```
{| RegExp |}
```

RegExp supports choice '|' and optional '?'

can be used arbitrarily within an expression

```
    to select operands {| (x | y | z) + 1 |}
    to select operators {| x (+ | -) y |}
    to select fields {| n(.prev | .next)? |}
    to select arguments {| foo( x | y, z) |}
```

Set must respect the type system

- all expressions in the set must type-check
- all must be of the same type

Complex program spaces

Idea: To build complex program spaces from simple program spaces, borrow abstraction devices from programming languages

Function: abstracts expressions

Generator: abstracts set of expressions

- Like a function with holes...
- ...but different invocations → different code

Example: swap without a temporary

```
generator int sign() {
    if ?? {return 1;} else {return -1;}
void swap(ref int x, ref int y){
   x = x + sign()*y; \rightarrow 1
   y = x + sign()*y; \rightarrow -1
   x = x + sign()*y;  \rightarrow -1
harness void main(int x, int y){
    int tx = x; int ty = y;
    swap(x, y);
   assert x==ty && y == tx;
```

Recursive generators

Can generators encode a CFG?

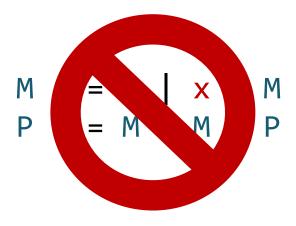
```
M ::= n | x * M
P ::= M | M + P
```

```
generator int mono(int x) {
    if (??) {return ??;}
    else {return x * mono(x);}
}

generator int poly(int x) {
    if (??) {return mono(x);}
    else {return mono(x) + poly(x);}
}
```

Recursive generators

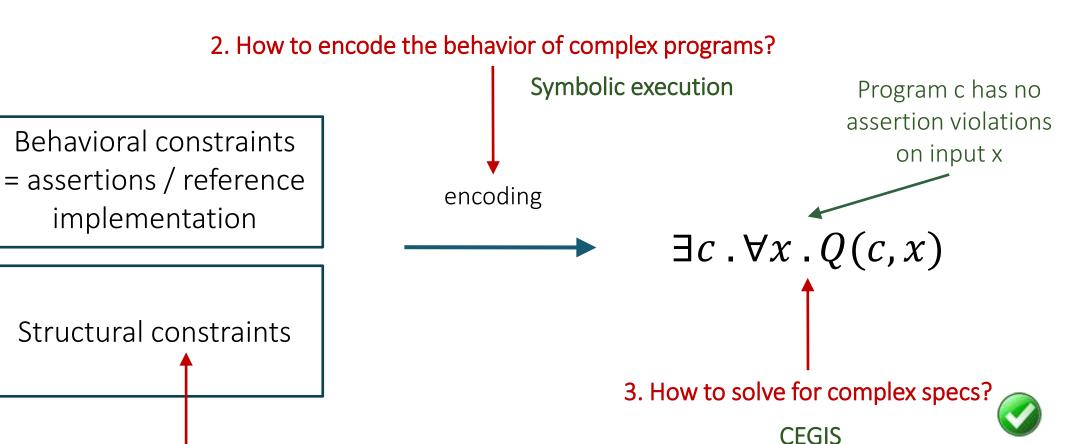
What if monomial of every degree can occur at most once?



```
generator int mono(int x, int n) {
   if (n <= 0) {return ??;}
   else {return x * mono(x, n - 1);}
}

generator int poly(int x, int n) {
   if (n <= 0) {return mono(x,0);}
   else {return mono(x,n) + poly(x, n - 1);}
}</pre>
```

Program Sketching



1. How to specify for complex programs?

Sketches

Symbolic execution

Semantics of a simple imperative language

How to use it for symbolic execution?

Adding while loops

Adding holes

Semantics of a simple language

```
e := n \mid x \mid e_1 + e_2

c := x := e \mid assert e

\mid c_1 ; c_2 \mid if e then c_1 else c_2 \mid while e do c
```

What does an expression mean?

- An expression reads the state and produces a value
- The state is modeled as a map σ from variables to values
- $\mathcal{A}[\![\cdot]\!]:e\to\Sigma\to\mathbb{Z}$

Ex:

- $\mathcal{A}[x] = \lambda \sigma . \sigma[x]$
- $\mathcal{A}[n] = \lambda \sigma. n$
- $\mathcal{A}\llbracket e_1 + e_2 \rrbracket = \lambda \sigma$. $\mathcal{A}\llbracket e_1 \rrbracket \sigma + \mathcal{A}\llbracket e_2 \rrbracket \sigma$

Semantics of a simple language

```
e := n \mid x \mid e_1 + e_2

c := x := e \mid assert e

\mid c_1 ; c_2 \mid if e then c_1 else c_2 \mid while e do c
```

What does a command mean?

- A command modifies the state
- $\mathcal{C}[\![\cdot]\!]:c\to\Sigma\to\Sigma$

Ex:

- $\mathcal{C}[x \coloneqq e] = \lambda \sigma . \sigma[x \to (\mathcal{A}[e]\sigma)]$
- $\mathcal{C}[[c_1; c_2]] = \lambda \sigma \cdot \mathcal{C}[[c_2]] (\mathcal{C}[[c_1]] \sigma)$
- $\mathcal{C}[\![\![ife]] e then c_1 else c_2]\!] = \lambda \sigma. \mathcal{A}[\![\![e]] \sigma ? (\mathcal{C}[\![\![c_1]]] \sigma) : (\mathcal{C}[\![\![c_2]]] \sigma)$

Semantics of a simple language

```
e := n \mid x \mid e_1 + e_2

c := x := e \mid assert e

\mid c_1 ; c_2 \mid if e then c_1 else c_2 \mid while e do c
```

What does a command mean?

- Commands also generate constraints on valid executions
- $\mathcal{C}[\cdot]: c \to \langle \Sigma, \Psi \rangle \to \langle \Sigma, \Psi \rangle$

Constraints on values in initial σ

Ex:

• $\mathcal{C}[[assert\ e]] = \lambda \langle \sigma, \psi \rangle. \langle \sigma, \psi \wedge \mathcal{A}[[e]] \sigma = 1 \rangle$

Symbolic execution

Semantics of a simple imperative language

How to use it for symbolic execution?

Adding while loops

Adding holes

Symbolic execution: example 1

```
harness void main(int x){
                                         \sigma = \{x \to X\}, \psi = T
  int y = 2 * x;
                                       \sigma = \{x \to X, y \to 2X\}
  assert y > x;
                                         \psi = \{ 2X > X \}
           \mathcal{C}[[p]]\langle\{\},\top\rangle = \langle\{x \to X, y \to 2X\}, 2X > X\rangle
                                      SMT solver
                            \forall X. 2X > X
```

Symbolic execution: example 2

 $\psi = \{(U > 0 ? 2X : X + X) = 2X\}$

Symbolic execution

Semantics of a simple imperative language

How to use it for symbolic execution?

Adding while loops

Adding holes

What about loops?

Semantics of a while loop

- Let $W = C[[while \ e \ do \ c]]$
- W satisfies the following equation: $(W \sigma)[x] = \mathcal{A}[e]\sigma \ ? \ (W(\mathcal{C}[c]\sigma))[x] : \sigma[x]$
- One strategy: find a fixpoint (see later in class)
- We'll settle for a simpler strategy: unroll k times and then give up

Symbolic execution: example 3

```
harness void main(int x){
                                             if (i < 2) {
  int y = 0;
                                               y = y + x;
  int i = 0;
                                               i = i + 1;
  while (i < 2) {
                                               if (i < 2) {
                           Step 1: unroll
    y = y + x;
                                                 y = y + x;
                           with depth = 2
    i = i + 1;
                                                 i = i + 1;
                                                 assert !(i < 2);
  assert y == 2 * x;
```

Symbolic execution: example 3

```
→ harness void main(int x){
                                                   \sigma = \{x \to X\}
     int y = 0;
     int i = 0;
                                                   \sigma = \{x \to X, y \to 0, i \to 0\}
     if (i < 2) {
        y = y + x;
    i = i + 1;
                                                        \sigma = \{x \to X, y \to X, i \to 1\}
   if (i < 2) {
          y = y + x;
          i = i + 1;
                                                        \sigma = \{x \to X, y \to X + X, i \to 2\}
       assert !(i < 2);
                                                     \psi = \{ \neg (2 > 2) \}
     assert y == 2*x;
                                                        \sigma = \{x \to X, y \to X + X, i \to 2\}
                                                     \Psi = \{\neg(2 > 2) \land X + X = 2X\}
```

Symbolic execution

Semantics of a simple imperative language

How to use it for symbolic execution?

Adding while loops

Adding holes

Semantics of sketches

```
e := n \mid x \mid e_1 + e_2 \mid ??_i

c := x := e \mid assert e

\mid c_1 ; c_2 \mid if e then c_1 else c_2 \mid while e do c
```

What does an expression mean?

- Like before, but values are "parameterized" by the valuation of the holes
- $\mathcal{A}[\![\cdot]\!]:e\to\Sigma\to(\Phi\to\mathbb{Z})$

Ex:

- $\mathcal{A}[x] = \lambda \sigma. \lambda \phi. \sigma[x]$
- $\mathcal{A}[??_i] = \lambda \sigma. \lambda \phi. \phi[i]$
- $\mathcal{A}\llbracket e_1 + e_2 \rrbracket = \lambda \sigma. \lambda \phi. \mathcal{A}\llbracket e_1 \rrbracket \sigma \phi + \mathcal{A}\llbracket e_2 \rrbracket \sigma \phi$

Symbolic Evaluation of Commands

Commands have two roles

- Modify the symbolic state
- Generate constraints

$$\mathcal{C}[\![\cdot]\!]:c \to \langle \Sigma, \Psi \rangle \to (\Sigma, \Psi)$$
Constraints on ϕ tables, e.g.

 $\lambda \phi. \phi[1] > 3$

Symbolic Evaluation of Commands

Example: assignment and assertion

$$\mathcal{C}[x \coloneqq e] \langle \sigma, \psi \rangle = \langle \sigma[x \mapsto \mathcal{A}[e]\sigma], \psi \rangle$$

$$\mathcal{C}[[assert e]]\langle \sigma, \psi \rangle = \langle \sigma, \lambda \phi, \psi(\phi) \wedge \mathcal{A}[[e]] \sigma \phi = 1 \rangle$$

Symbolic Evaluation of Commands

Example: conditional

$$\mathcal{C}[\text{if } e \text{ then } c_1 \text{ else } c_2] \langle \sigma, \psi \rangle = \\ \langle \lambda x. \mathcal{A}[e] \sigma ? \sigma_1[x] : \sigma_2[x], \\ \langle \lambda \phi. \psi(\phi) \wedge \mathcal{A}[e] \sigma ? \psi_1(\phi) : \psi_2(\phi) \rangle$$

where

$$\langle \sigma_1, \psi_1 \rangle = \mathcal{C} [[c_1]] \langle \sigma, \psi \rangle$$
$$\langle \sigma_2, \psi_2 \rangle = \mathcal{C} [[c_2]] \langle \sigma, \psi \rangle$$

Symbolic execution of sketches: example

```
harness void main(int x){
int z = ??₁ * x;
                                                                 \sigma = \{x \to X\} \psi = \top
       int y = 0;
      int i = 0;
                                                                 \sigma = \{x \to X, z \to \phi_1 * X, y \to 0, i \to 0\}
       if (i < 2) {
       y = y + x;

    i = i + 1;
    if (i < 2) {</pre>
                                                                       \sigma = \{x \to X, z \to \phi_1 * X, y \to X, i \to 1\}
           y = y + x;
           i = i + 1;
                                                                       \sigma = \{x \to X, z \to \phi_1 * X, y \to X + X, i \to 2\}
→ assert !(i < 2);</pre>
→ }
                                                                  \psi = \{ \neg (2 > 2) \}
                          \psi = \{\neg(2 > 2) \land X + X = \phi_1 * X\}
\{\phi_1 \mapsto 2\} \longleftarrow \exists \phi_1. \forall X. X + X = \phi_1 * X
       assert y == z;
```

Controls for generators

```
harness void main(int x, int y){

z = mono(x) + mono(y);
assert z = x + x + 3;

\sigma = \{z \rightarrow (\phi_1? \phi_2: X*\phi_2) + (\phi_1? \phi_2: Y*\phi_2)\}

No solution!

generator int mono(int x) {

if (??<sub>1</sub>) {return ??<sub>2</sub>;}

else {return x * mono(x);}

depth = 1

else {return x * ??<sub>2</sub>;}

\sigma = \{z \rightarrow (\phi_1? \phi_2: X*\phi_2) + (\phi_1? \phi_2: Y*\phi_2)\}
```

We need to map different calls to mono to different controls!

Controls for generators: context

```
harness void main(int x, int y){

z = mono^{1}(x,1) + mono^{2}(y,2);

assert z = x + x + 3;

\sigma = \{z \rightarrow (\phi_{1}^{1}? \phi_{2}^{1}: X * \phi_{2}^{1.3}) + (\phi_{1}^{2}? \phi_{2}^{2}: X * \phi_{2}^{2.3})\}

generator int mono(int x, context \tau) {

if (??\tau_{1}) {return ??\tau_{2};}

else {return x * mono<sup>3</sup>(x, \tau.3);}
}
```

$$\{\phi_1^1 \mapsto 0, \phi_2^{1.3} \mapsto 2, \phi_1^2 \mapsto 1, \phi_2^{1.3} \mapsto 3\}$$

Sketch: contributions

Expressing structural and behavioral constraints as programs

- the only primitive extension is an integer hole ??
- why is it important to keep extensions minimal?

CEGIS

• became extremely popular; now used in most constraint-based synthesizers

Sketch: limitations

Everything is bounded

- loops are unrolled
- integers are bounded
- are any of the above easily fixable?

Unclear if sketching is a good user interaction model

• but: as search gets better, less user input is required

CEGIS relies on the Bounded Observation Hypothesis

Sketches hard to debug

Does not prioritize likely programs

Sketch: questions

Behavioral constraints? structural constraints? search strategy?

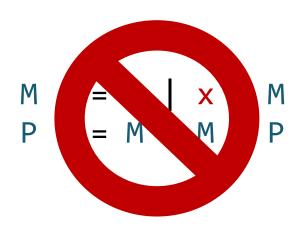
- assertions / reference implementation
- sketches
- constraint-based (CEGIS + SAT)

Sketches vs CFGs? Brahma's components?

- A generator can encode a multiset of components (although it's not very straightforward)
- Can a generator encode a CFG?

Recursive generators

What if monomial of every degree can occur at most once?



```
generator int mono(int x, int n) {
   if (n <= 0) {return ??;}
   else {return x * mono(x, n - 1);}
}

generator int poly(int x, int n) {
   if (n <= 0) {return mono(x,0);}
   else {return mono(x,n) + poly(x, n - 1);}
}</pre>
```

Generators are more expressive than CFGs!

- but unbounded generators cannot be encoded into constraints
- need to bound unrolling depth
- bounded generators less expressive than CFGs (but more convenient)

Semantics of abort

$$\mathcal{C}[[abort]]\langle \sigma, \psi \rangle = \langle \sigma, \lambda \phi, \bot \rangle$$

CEGIS: the worst case

Satisfiable constraint $\exists c. \forall x. Q(c, x)$ that violates the Bounded Observation Hypothesis

$$Q(\mathbf{c}, x) \equiv x \neq \mathbf{c}$$

unsatisfiable

$$Q(\mathbf{c}, x) \equiv \mathbf{c} = 010$$

solved in single iteration

$$Q(\mathbf{c}, x) \equiv x = (x \& \mathbf{c})$$

solved in max n iterations

$$Q(c,x) \equiv x \leq c$$

does not violate BOH, but will require 2^N iterations with worst-case counterexamples

$$Q(c,x) \equiv c \neq x \lor c = 0$$

violates BOH:

no small set of counter-examples exists