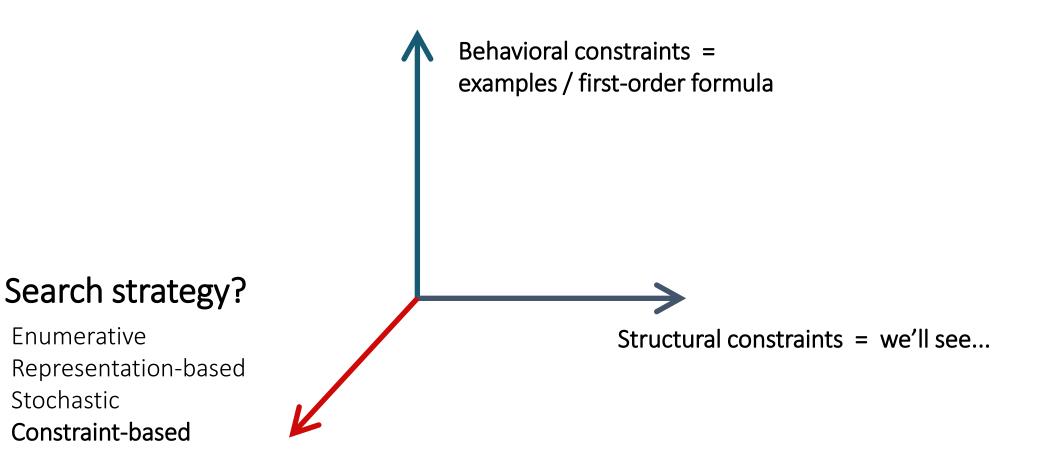
Lecture 8 Constraint-based search

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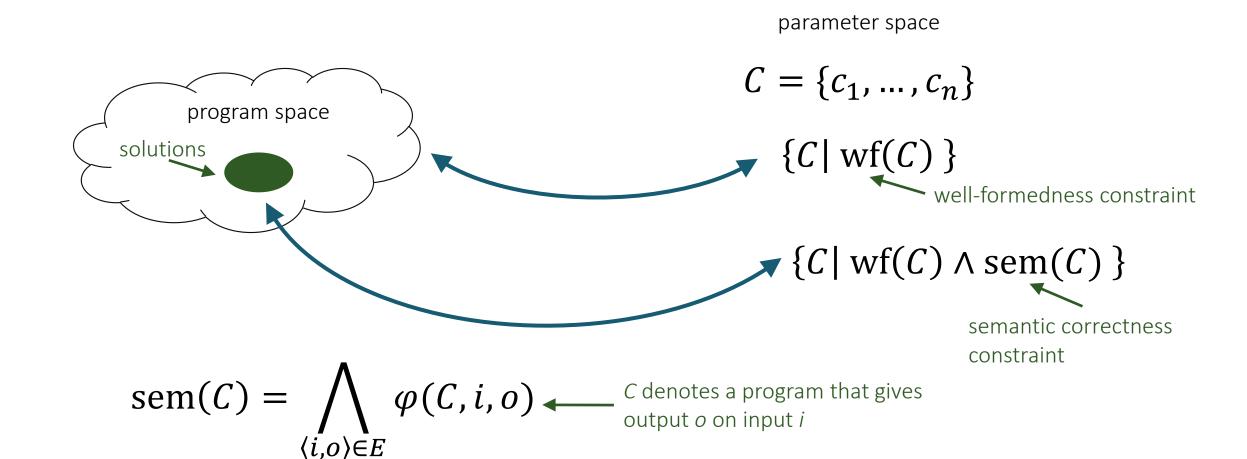
The problem statement



Constraint-based search

Idea: encode the synthesis problem as a SAT/SMT problem and let a solver deal with it

What is an encoding?



How to define an encoding

```
Define the parameter space C = \{c_1, \dots, c_n\}
```

• decode : C → Prog (might not be defined for all C)

Define a formula $wf(c_1, ..., c_n)$

• that holds iff decode[C] is defined

Define a formula $\varphi(c_1, ..., c_n, i, o)$

• that holds iff (decode[C])(i) = o

Constraint-based search

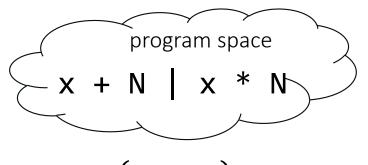
```
constraint-based (wf, \varphi, E = [i \rightarrow o]) {
    match SAT(wf(\mathcal{C}) \land \land_{(i,o) \in E} \varphi(\mathcal{C},i,o)) with \longleftarrow for c_1, \ldots, c_n
    Unsat -> return "No solution" (i and o are fixed)

Model C* -> return decode[C*]
```

SAT encoding: example

```
x is a two-bit word
                                                                         parameter space
      program space
                                     (x = x_h x_1)
                                                                      C = \{c : Bool\}
                                     E = [11 \rightarrow 01]
                                                                       decode[0] \rightarrow x
                                                                       decode[1] \rightarrow x \& 1
wf(c) \equiv T
\varphi(c, i_h, i_l, o_h, o_l) \equiv (\neg c \Rightarrow o_h = i_h \land o_l = i_l)
\wedge (c \Rightarrow o_h = 0 \wedge o_l = i_l)
SAT(\varphi(c, 1, 1, 0, 1))
                                                                                     SAT solver
SAT((\neg c \Rightarrow 0 = 1 \land 1 = 1) \land (c \Rightarrow 0 = 0 \land 1 = 1))
                                                                                                      Model \{c \rightarrow 1\}
                                     return decode[1] i.e. x & 1
```

SMT encoding: example



$$\operatorname{wf}(c_{op}, c_N) \equiv \mathsf{T}$$

N is an in integer literal x is an integer input

$$E = [2 \rightarrow 9]$$

parameter space

$$C = \{c_{op} : Bool, c_N : Int\}$$

$$decode[0,N] \rightarrow x + N$$

$$decode[1,N] \rightarrow x * N$$

$$\varphi(c_{op}, c_N, i, o) \equiv (\neg c_{op} \Rightarrow o = i + c_N) \wedge (c_{op} \Rightarrow o = i * c_N)$$

SAT(
$$\phi(c_{op}, c_N, 2, 9)$$
)

SAT($(\neg c_{op} \Rightarrow 9 = 2 + c_N) \land (c_{op} \Rightarrow 9 = 2 * c_N)$)

SMT solver

return decode[0,7] i.e. x + 7

What is a good encoding?

Sound

• if $wf(C) \land sem(C)$ then decode[C] is a solution

Complete

• if decode[C] is a solution then $wf(C) \wedge sem(C)$

Small parameter space

avoid symmetries

Solver-friendly

• decidable logic, compact constraint

DSL limitations

Program space can be parameterized with a finite set of parameters

Program semantics $\varphi(\mathcal{C},i,o)$ is expressible as a (decidable) SAT/SMT formula

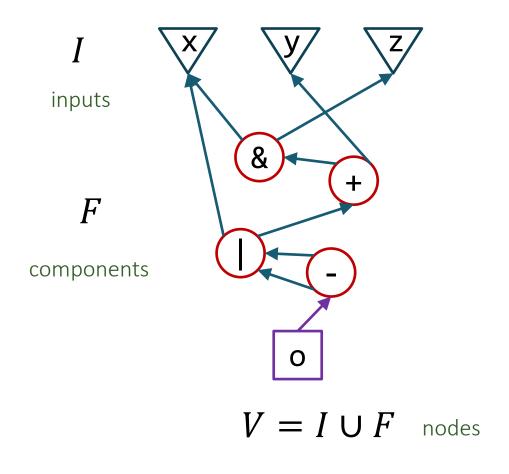
Counterexample

Brahma

Idea: encode the space of loop-free (bit-vector) programs as an SMT constraint

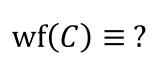
Brahma encoding: take 1

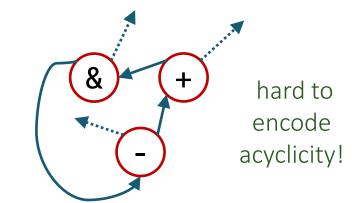
program = DAG



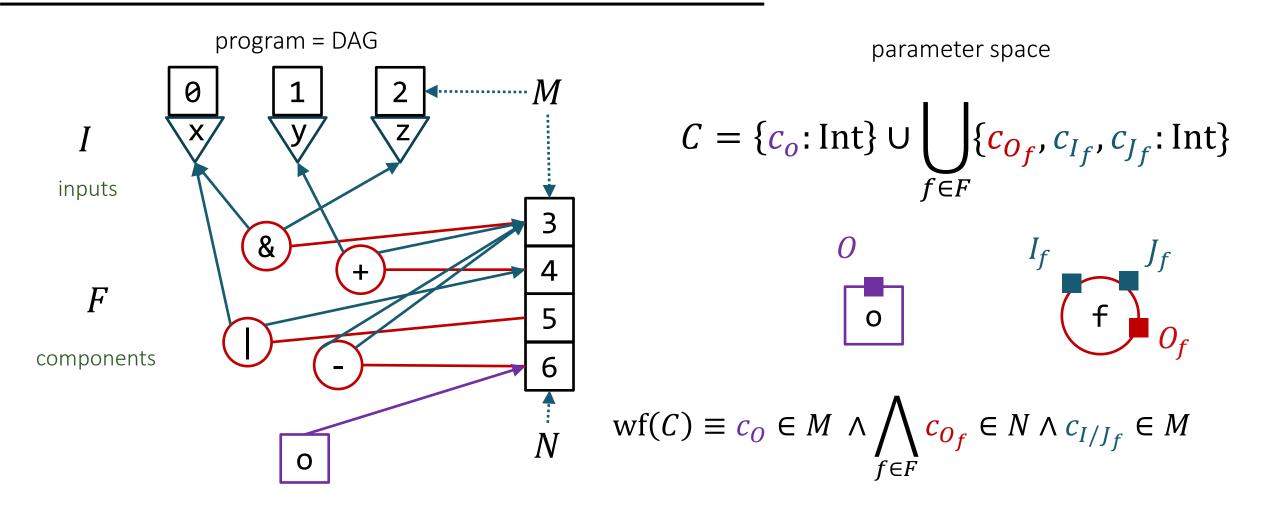
parameter space

$$C = \{c_o: V\} \cup \bigcup_{f \in F} \{c_1^f, c_2^f: V\}$$

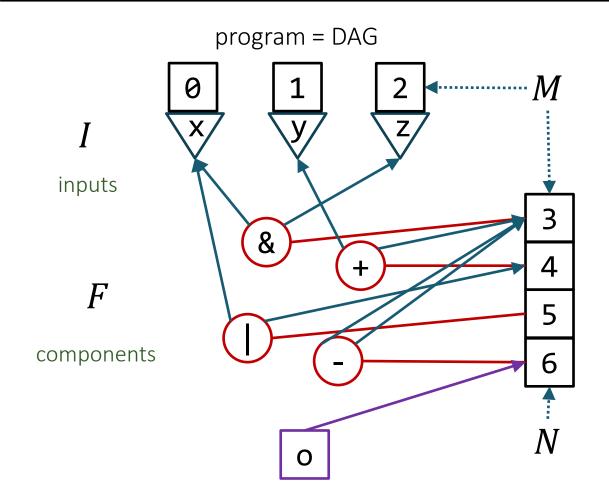




Brahma encoding: take 2



Brahma encoding: take 2



parameter space

$$C = \{c_o: Int\} \cup \bigcup_{f \in F} \{c_{O_f}, c_{I_f}, c_{J_f}: Int\}$$

$$T = \bigcup_{f \in F} \{l_f, J_f, O_f\}$$

$$\varphi(C, I, O) \equiv \exists T. \bigwedge_{f \in F} O_f = F(I_f, J_f)$$

$$\wedge \bigwedge_{x, y \in T \cup I \cup \{O\}} c_x = c_y \Rightarrow x = y$$

Brahma: contributions

SMT encoding of program space

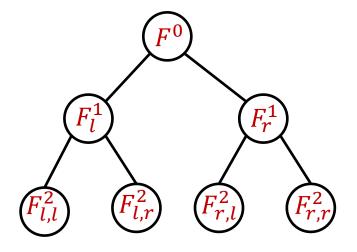
- sound? complete? solver-friendly?
- more compact than alternatives*

SMT solver can guess constants

• e.g. 0x5555555 in P23

Alternative encodings

Tree encoding



Linear encoding

$$t_0 = F_0(t_{I0}, t_{J0})$$
 $t_1 = F_1(t_{I1}, t_{J1})$
...
 $t_N = F_N(t_{IN}, t_{JN})$

Brahma: limitations

Requires component multiplicities

- If we didn't have multiplicities, where would their encoding break? How could we fix it?
- What happens if user provides too many? too few?
- What's the alternative to including dead code?

Requires *precise* SMT specs for components

What happens if we give an over-approximate spec?

No loops, no types, no ranking

Brahma: questions

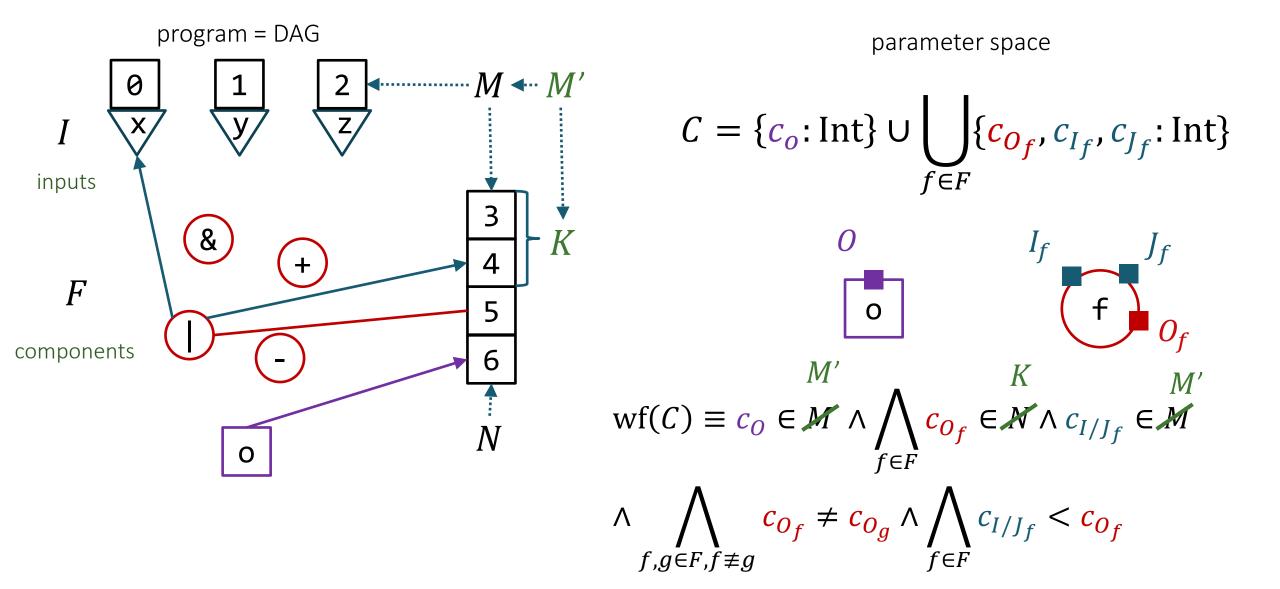
Behavioral Constraints? Structural Constraints? Search Strategy?

- First-order formula
- A multiset of components + straight-line program
- Constraint based + CEGIS

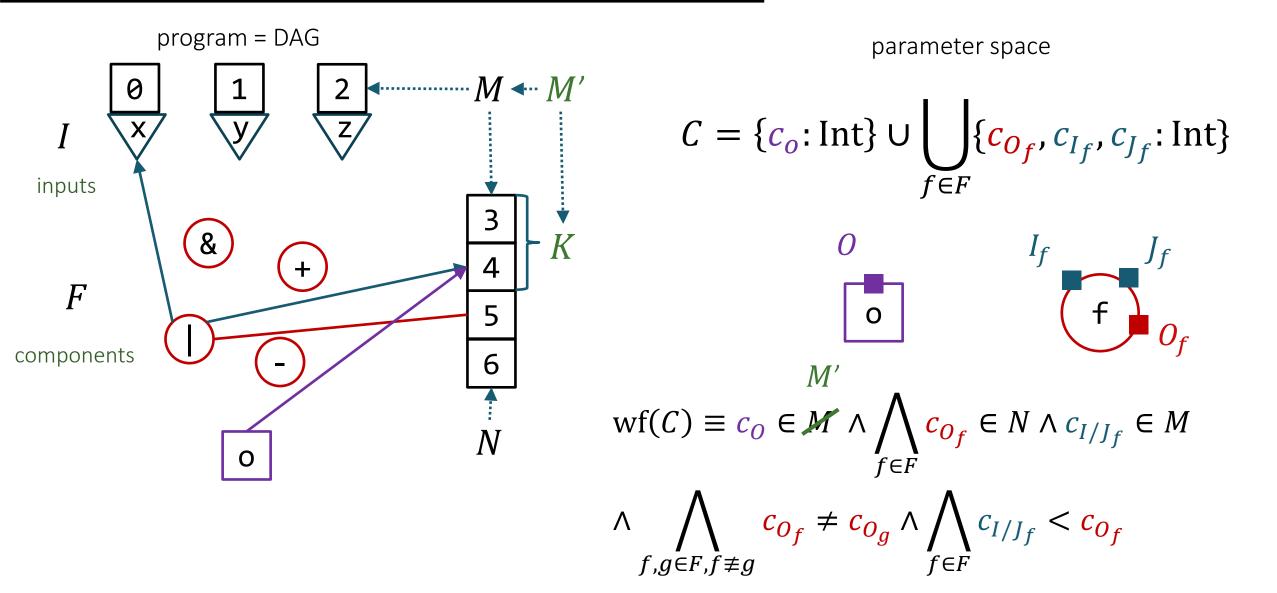
Can we represent these structural constraints as a grammar?

- Yes and no
- No because grammars cannot encode multiplicities
 - also: you can have let-bindings in SyGus but CFG cannot encode well-formedness
- Yes because the set is finite, so we can simply enumerate all possible programs
 - but this is not useful for synthesis

Limit #components to K?



Limit #components to K?



Comparison of search strategies

