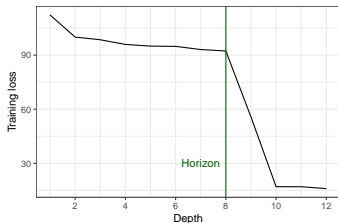


## Stopping Criteria & Pruning



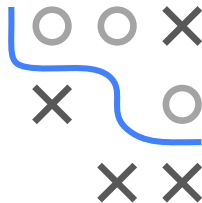
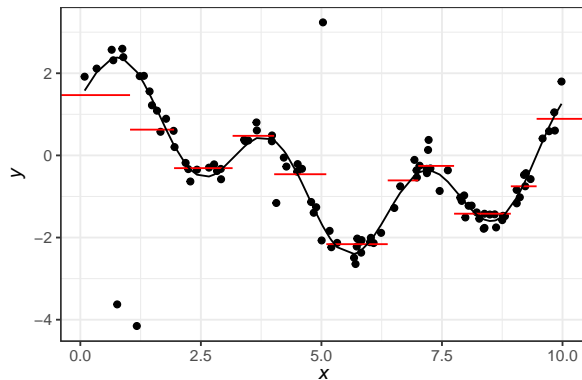
- Understand which problems arise when growing the tree until the end
- Know different stopping criteria
- Understand the idea of pruning





# OVERFITTING TREES

We can reduce overfitting to some extent with a less deep tree:

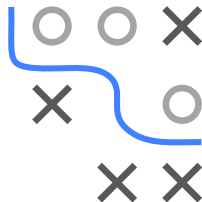


# STOPPING CRITERIA

We can define different **stopping criteria**, e.g.: Don't split a node if

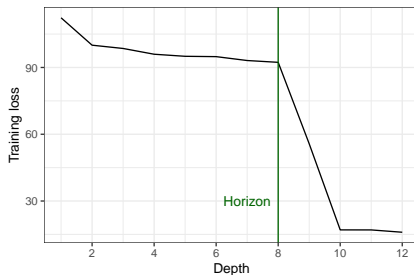
- a certain number of leaves if reached,
- it contains too few observations,
- splitting results in children with too few observations,
- splitting does not achieve a certain minimal improvement of the risk in the children, compared to the risk in the parent node,
- it already has the same target value (**pure node**) or identical feature values for all observations.

Selection of a stopping criterion and its concrete values are hyperparameters of CART.



# HORIZON EFFECT

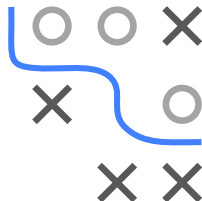
It is hard to tell where we should stop while we're growing the tree:  
Before we have actually tried all possible additional splits further down a branch, we can't know whether any one of them will be able to reduce the risk by a lot (*horizon effect*).



# PRUNING

We try to tackle the horizon effect by **pruning**, a method to select the optimal size of a tree:

- Finding a combination of suitable strict stopping criteria (“pre-pruning”) is a hard problem (see chapter on **tuning**).
- Alternative: Grow a large tree, then remove branches so that the resulting smaller tree has lower risk (“post-pruning”).
- Often, post-pruning is meant when referring to pruning.

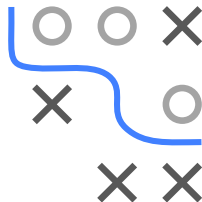


# POST-PRUNING: CCP

- Prominent pruning method: Cost-complexity pruning (CCP)
- Idea: Grow a large tree and remove the least informative leaves
- CCP is steered with a regularization parameter  $\alpha$  that penalizes the number of leaves in a sub tree

$$\mathcal{R}_{\text{reg}}(T) = \sum_{m=1}^{|T|} \sum_{i: x^{(i)} \in Q_m} L(y^{(i)}, c_m) + \alpha |T|,$$

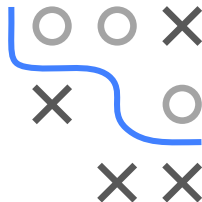
where  $|T|$  is the number of leaves of sub tree  $T$ ,  $Q_m$  is the subset of the feature space related to the  $m$ -th terminal node, with its prediction  $c_m$ , and  $T_0$  is the complete tree.



# CCP

CCP performs a greedy backward search:

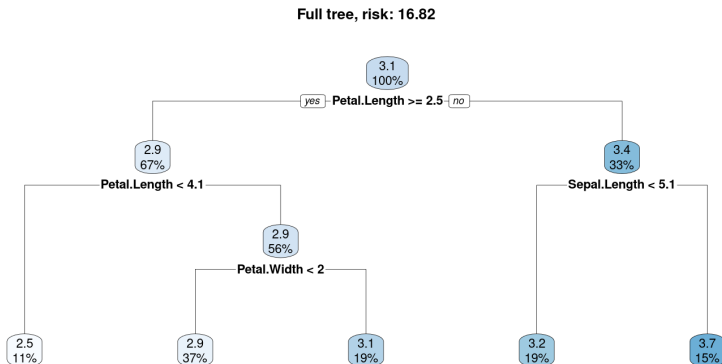
- Computes  $\mathcal{R}_{\text{reg}}(T)$  with a fixed  $\alpha$  for all possible sub trees that can be created by replacing one internal node with a leaf.
- By replacing a node we also eliminate all subsequent nodes.
- We select the sub tree with lowest risk and repeat the procedure.
- We stop if pruning does not further reduce the risk.
- This is proven to result in the pruned tree with the lowest risk.
- For  $\alpha = 0$ , we would obviously select  $T_0$ .
- Hyperparameter  $\alpha$  is typically selected via cross-validation.
- Other prominent post-pruning methods include, e.g., reduced error pruning (REP) or pessimistic error pruning (PEP).





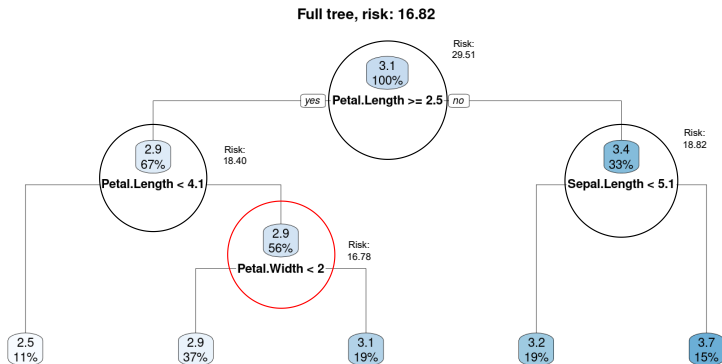
# CCP

We run the CCP algorithm step-by-step with  $\alpha = 1.2$ :



# CCP

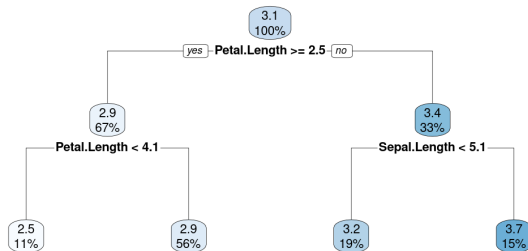
There are four possible nodes that we can eliminate to prune the tree.  
We take the one replacement that results in the lowest risk (red).



# CCP

The first pruned sub tree has a lower risk than the full tree. Thus, we prefer it over the full tree.

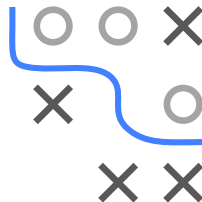
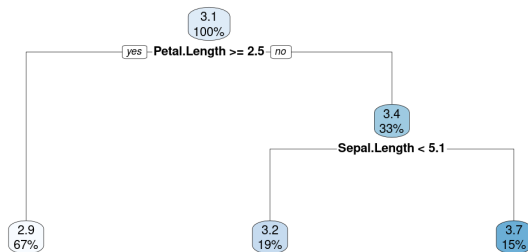
First pruned sub tree, risk: 16.78



# CCP

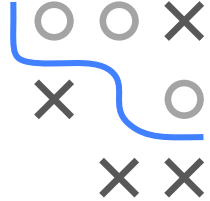
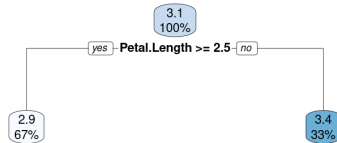
From here on, the risk increases.

Second pruned sub tree, risk: 18.4



# CCP

Third pruned sub tree, risk: 20.4



# CCP

We select the first sub tree as it results in the lowest risk in the complete sequence of sub trees.

Fully pruned sub tree, risk: 29.51

3.1  
100%

