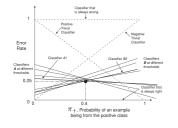
Introduction to Machine Learning

Evaluation: Cost Curves



Learning goals

- Understand cost curves
- As alternative to ROC curves



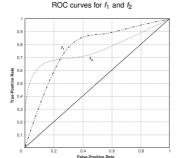
COST CURVES

- Directly plot the misclassif costs / error
- Might be easier to interpret than ROC, especially in case of different misclassif costs or priors

Example:

- f_1 and f_2 with intersecting ROC curves
- f_2 dominates first, then f_1

BUT: Unclear for which thresholds, costs or class distribs f_2 better than f_1



Nathalie Japkowicz (2004): Evaluating Learning Algorithms: A Classification Perspective. (p. 125)



COST CURVES

Simplifying assumption: equal misclassif costs, i.e., $cost_{FN} = cost_{FP}$ \Rightarrow Expected misclassif cost reduces to misclassif error rate With law of total prob, we write error rate as function of π_+ :

$$ho_{MCE}(\pi_{+}) = (1 - \pi_{+}) \cdot \mathbb{P}(\hat{y} = 1|y = 0) + \pi_{+} \cdot \mathbb{P}(\hat{y} = 0|y = 1)$$

$$= (1 - \pi_{+}) \cdot FPR + \pi_{+} \cdot FNR$$

$$= (FNR - FPR) \cdot \pi_{+} + FPR$$

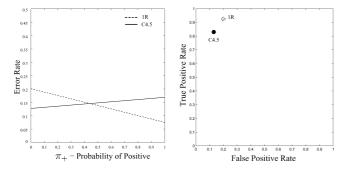
Confusion matrix True class				
	y = 1	y=0		
$Pred\hat{y} = 1$	TP	FP		
$class\hat{y} = 0$	FN	TN		

	Cost matrix		
	True class		
	<i>y</i> = 1	y = 0	
$Pred \hat{y} = 1$	0	$cost_{FP}$	
$class\hat{y} = 0$	cost _{FN}	0	



COST CURVES

- Expected misclassif costs (or error rate if $cost_{FN} = cost_{FP}$) is plotted as function of proportion of positive instances, $\pi_+ = \mathbb{P}(y = 1)$
- Cost curves are point-line duals of ROC curves, i.e., a single classifier is represented by a point in the ROC space and by a line in cost space



Chris Drummond and Robert C. Holte (2006): Cost curves: An improved method for visualizing classifier performance.

Machine Learning, 65, 95-130 (<u>URL</u>).



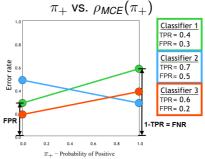
COST LINES

Cost line of a classifier with slope (FNR - FPR) and intercept FPR:

$$\rho_{MCE}(\pi_+) = (FNR - FPR) \cdot \pi_+ + FPR$$

- Hard classifiers are points (TPR, FPR) in ROC space
- The cost line of a classifier connects (π₊, ρ_{MCE})-points at (0, FPR) and (1, 1 – TPR)
- Classifier 3 always dominates classifier 1
- Classifier 3 is better than classifier 2 when $\pi_+ < 0.7$

Cost lines plot different values of

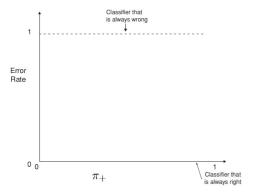


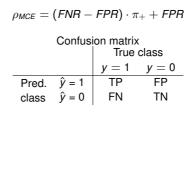


COST LINES - EXAMPLE

- Horizontal dashed line: worst classifier (100% error rate for all π_+) \Rightarrow FNR = FPR = 1
- x-axis: perfect classifier (0% error rate for all π_+) \Rightarrow FNR = FPR = 0



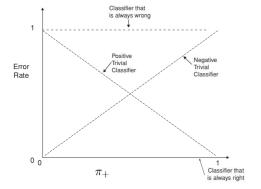




COST LINES - EXAMPLE

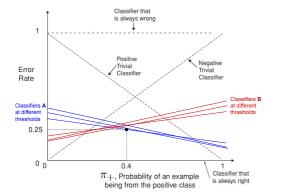
- Horizontal dashed line: worst classifier (100% error rate for all π_+) \Rightarrow *FNR* = *FPR* = 1
- x-axis: perfect classifier (0% error rate for all π_+) \Rightarrow FNR = FPR = 0
- Dashed diagonal lines: trivial classifiers, i.e., ascending diagonal always predicts negative instances (\$\Rightarrow\$ FNR = 1 and FPR = 0) and vice versa

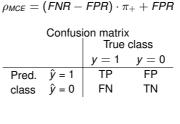




COST LINES - EXAMPLE

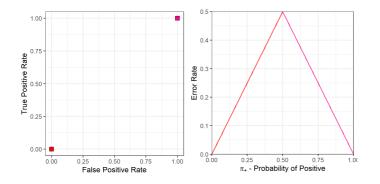
- Horizontal dashed line: worst classifier (100% error rate for all π_+) \Rightarrow FNR = FPR = 1
- x-axis: perfect classifier (0% error rate for all π_+) \Rightarrow FNR = FPR = 0
- Dashed diagonal lines: trivial classifiers, i.e., ascending diagonal always predicts negative instances (\$\Rightarrow\$ FNR = 1 and FPR = 0) and vice versa
- Descending/ascending bold lines: two families of classifiers A and B (represented by points in their respective ROC curves)





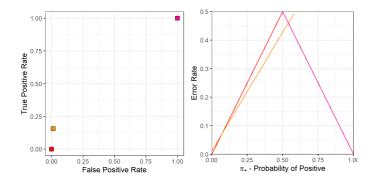


- Left: TPR & FPR of a classifier for different prob thresholds
- Right: Corresponding cost lines



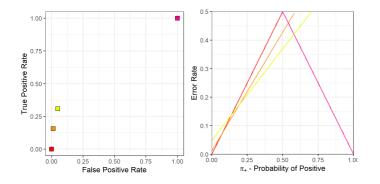


- Left: TPR & FPR of a classifier for different prob thresholds
- Right: Corresponding cost lines



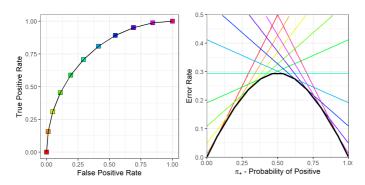


- Left: TPR & FPR of a classifier for different prob thresholds
- Right: Corresponding cost lines





- Left: TPR & FPR of a classifier for different prob thresholds
- Right: Corresponding cost lines
- Cost curve (right: black line) is lower envelope of cost lines $\hat{=}$ pointwise minimum of error rate (as function of π_+)





CONSIDER COSTS

Now: Assume unequal misclassif costs, i.e., $cost_{FN} \neq cost_{FP}$ and generalize error rate to **expected costs** (as function of π_+):

$$\textit{Costs}(\pi_+) = (1 - \pi_+) \cdot \textit{FPR} \cdot \textit{cost}_{\textit{FP}} + \pi_+ \cdot \textit{FNR} \cdot \textit{cost}_{\textit{FN}}$$

Maximum of expected costs happens when

$$FPR = FNR = 1 \Rightarrow Costs_{max} = (1 - \pi_{+}) \cdot cost_{FP} + \pi_{+} \cdot cost_{FN}$$

Consider **normalized costs** (as function of π_+):

$$\begin{aligned} \textit{Costs}_{\textit{norm}}(\pi_{+}) &= \frac{(1-\pi_{+}) \cdot \textit{FPR} \cdot \textit{cost}_\textit{FP} + \pi_{+} \cdot \textit{FNR} \cdot \textit{cost}_\textit{FN}}{(1-\pi_{+}) \cdot \textit{cost}_\textit{FP} + \pi_{+} \cdot \textit{cost}_\textit{FN}} \\ &= \frac{(1-\pi_{+}) \cdot \textit{cost}_\textit{FP} \cdot \textit{FPR}}{(1-\pi_{+}) \cdot \textit{cost}_\textit{FP} + \pi_{+} \cdot \textit{cost}_\textit{FN}} + \frac{\pi_{+} \cdot \textit{cost}_\textit{FN} \cdot \textit{FNR}}{(1-\pi_{+}) \cdot \textit{cost}_\textit{FP} + \pi_{+} \cdot \textit{cost}_\textit{FN}} \end{aligned}$$

Let "probability times cost" PC(+) be normalized version of $\pi_+ \cdot cost_{FN}$:

$$PC(+) = \frac{\pi_+ \cdot cost_{FN}}{(1-\pi_+) \cdot cost_{FP} + \pi_+ \cdot cost_{FN}}$$
 and $1 - PC(+) = \frac{(1-\pi_+) \cdot cost_{FP}}{(1-\pi_+) \cdot cost_{FP} + \pi_+ \cdot cost_{FN}}$



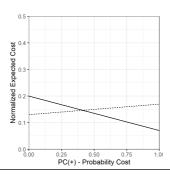
CONSIDER COSTS / 2

To obtain cost lines, we need a function with slope (FNR - FPR) and intercept $FPR \Rightarrow \text{Rewrite } Costs_{norm}(\pi_+)$ as function of PC(+):

$$\begin{aligned} \textit{Costs}_{\textit{norm}}(\textit{PC}(+)) &= (1 - \textit{PC}(+)) \cdot \textit{FPR} + \textit{PC}(+) \cdot \textit{FNR} \\ &= (\textit{FNR} - \textit{FPR}) \cdot \textit{PC}(+) + \textit{FPR} \\ &= \begin{cases} \textit{FPR}, \textit{if } \textit{PC}(+) = 0 \\ \textit{FNR}, \textit{if } \textit{PC}(+) = 1 \end{cases} \end{aligned}$$



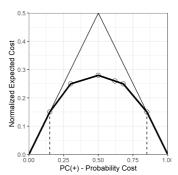
- Plot is similar to simplified case with cost_{FN} = cost_{FP}
- Axes' labels and their interpretation have changed
- Normalized cost vs. "probability times cost"



COMPARE WITH TRIVIAL CLASSIFIERS

- Operating range of a classifier is a set of PC(+) values (operating points) where classifier performs better than both trivial classifiers
- Intersection of cost curves and trivial classifiers' diagonals determine operating range
- At any PC(+) value, the vertical distance of trivial diagonal to a classifer's cost curve within operating range shows advantage in performance (normalized costs) of classifier

Example: Dotted lines are operating range of a classifier (here: [0.14, 0.85])

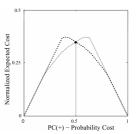




COMPARING CLASSIFIERS

- If classifier C1's expected cost is lower than classifier C2's at a PC(+) value, C1 outperforms C2 at that operating point
- The two cost curves of C1 and C2 may cross, which indicates C1 outperforms C2 for a certain operating range and vice versa
- The vertical distance between the two cost curves of C1 and C2 at any PC(+) value directly indicates the performance difference between them at that operating point

Example: Dotted cost curve has lower expected cost as dashed cost curve for PC(+) < 0.5 and hence outperforms dashed one in this operating range and vice versa



Chris Drummond and Robert C. Holte (2006): Cost curves: An improved method for visualizing classifier performance. Machine Learning, 65, 95-130 (URL)



ROC CURVES VS. COST CURVES

- A point/line in ROC space is represented by a line/point in cost space, and vice versa
- Area under an ROC curve is a ranking measure while area under a cost curve is the expected cost of the classifier (assuming that all possible PC(+) values are equally likely)
- ROC curves do not indicate for which prob threshold classifier A is superior to another classifier B, cost curves can do exactly that!
 Cost curves practically more useful than ROC curves
- Cost curves allows users to measure quantitative performance difference between multiple classifiers at any given operating point
 Not so easy to do that with ROC curve

