ECON 401 – Tech Session 1 Intro to Stochastic Processes, Time Series, and Matlab

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Stochastic Processes



A stochastic process refers to a family of random variables whose behaviour depends totally or partially on a stochastic or random component.

A variable can take on values **deterministically**, such as x = 3, or x = 2 + 3t with $t = 1, 2, \dots, 10$

Or **randomly** such as x: number displayed after rolling a dice.

We know such values can be 1, 2, 3, 4, 5, or 6. But we can't know with certainty which will be the actual value if we roll it once.

These latter type are denoted as **random variables**, and their already observed values are **realizations**.

In macroeconomics, we will form an expectation on variables whose actual future value is unknown. But we can form an idea on its expected value if we study its features as an **stochastic process**.

As in the case of the dice, sometimes we know the probability of each value the random variable can take.

In that case, the **expected value** of a random variable (let X be such variable) is:

$$E(X) = \sum_{i} x_{i} Pr(x_{i})$$

Where $Pr(x_i)$ is the probability that X takes on the value x_i .

In the case of the dice, where each value may appear with probability $\frac{1}{6}$ the expected value is $\frac{1}{6}(1) + \frac{1}{6}(2) + \frac{1}{6}(3) + \frac{1}{6}(4) + \frac{1}{6}(5) + \frac{1}{6}(6) = 3.5$.

For the case in which X is continuous, the expected value will be $E[X] = \int_{-\infty}^{\infty} x f(x) dx$ where f(x) is the PDF or probability density function.

Properties of the Expected Value

- 1. The expected value of a constant is the constant itself: Let a be a constant, then E[a] = a
- 2. Expected value of a constant times a random variable: E[aX] = aE[X]3. The expected value is a linear operator: E[aX + b] = aE[X] + E[b] \longrightarrow $E_{b-1} m_b = E_{b-1} m_b$
- Mixing these properties we get the expectation of a weighted sum of random variables: E[aX + bY] = aE[X] + bE[Y]
- 5. The expected value cannot pass through non-linear functions: let g be a non-linear function, then $E[g(X)] \neq g(E[X])$ E[VX] + VECX] VECX

But we know this result for concave/convex functions (Jensen's Inequality, used a lot in statistics and economics)

$$E[g(X)] = \begin{cases} > g[E(X)] & \text{if g is convex} \\ = g[E(X)] & \text{if g is linear} \\ < g[E(X)] & \text{if g is concave} \end{cases}$$

Conditional Expectation

We can also think of the **joint probability for pairs of events** or for several random variables. That is, we will consider a joint probability function Pr(x,y) = Pr(X = x, Y = y). In that case we say that X and Y are jointly distributed.

Given, *X* and *Y* are jointly distributed by knowing about one variable we can get information about the other. The following definitions will be useful for that end:

- ► Conditional Probability: $Pr(y|x) = Pr(y|X = x) = \frac{Pr(x,y)}{Pr(x)}$
- Conditional Expectations: $E[Y|X=x] \equiv E[Y|X] = \sum_y y \left(Pr(y|X=x) \right)$ Moreover, evaluating this expectation over the possible values of X would yield E[Y]:

$$E_X[E[Y|X=x]] = E[Y]$$

In macroeconomics, this concept is useful to the denote the expectation **conditional on an information set**. Notation-wise we will have:

$$E_{t-1}[Y_t] = E[Y_t|I_{t-1}]$$

Where I_{t-1} is the information set available at time t-1.

A useful property of these expectations is the **Law of Iterated Expectations**:

- 1. E[E[Y|X]|X] = E[Y|X], then $E_{t-j}[E_{t-j}[Y_t]] = E_{t-j}[Y_t]$
- 2. $E[E[Y|I_1]|I_2] = E[Y|I_2]$, where I_1 and I_2 are two information sets such that $I_2 \subseteq I_1$ (I_1 has at least all the information contained in I_2). Then,

$$E_{t-j-k}[E_{t-j}[Y_t]] = E_{t-j-k}[Y_t]$$

This property implies that when we conditioned on several information sets, the smaller dominates (i.e. the less complete).

Intuitively (read this part slowly), the expectation about a future variable we were able to form conditional on the info today, conditional (again) on the information we had a day before is just the expectation of the variable of interest conditional on the info available yesterday.

Higher order expectations

We can also consider expectations of higher orders:

$$E(X^j) = \sum_i x_i^j Pr(x_i), \quad \text{for } j = 2, \dots$$

We will use j = 2 to obtain the variance of our random variables.

 $Var(\xi_b) = E[\xi_b^2] - [E[\xi_b]]$ $= E[\xi_b^2] = C^2$

The **variance** of *X* is defined as:

$$Var(X) = \sigma_X^2 = E[(X - E(X))^2] = E[X^2] - (E[X])^2$$

The last line implies, that if we already now the expected value (E[X]), then we just need to get the expected value of the squared variable $E[X^2]$ to determine the variance.

Similarly, a more general concept is the **covariance**, it measures the linear comovement between two variables:

$$\underbrace{Cov(X,Y)}_{} = E[(X - E[X])(Y - E[Y])] = \underbrace{E[XY] - E[X]E[Y]}_{}$$

Notice the variance is just the covariance of a variable with itself.

We will use this last formula repeatedly, particularly whenever we want to substitute for the expectation of the product of random variables (E[XY] = Cov(X, Y) + E[X]E[Y]).

ELYX = GV (X, y) - ELY) EOX)

Properties

For the variance:

- 1. $Var(X) \ge 0$
- 2. The variance of a constant is zero.
- 3. Let a, b be constants, then: $Var(aX + b) = a^2 Var(X)$
- 4. $Var(X) = E[X^2] (E[X])^2$

For the covariance:

1.
$$Var(X + Y) = Var(X) + Var(Y) + 2Cov(X, Y)$$

$$2. Cov(X, Y) = E[XY] - E[X]E[Y]$$

Independent and Uncorrelated variables

- ▶ If two variables X and Y are independent, then they are uncorrelated (Cov(X,Y) = 0) and the expectation of the product is just the product of the individual expectations E[XY] = E[X]E[Y]
- ▶ If two variables are not correlated, we cannot guarantee that they are independent.

Distributions

Some variables take values on (countable and uncountable) an infinite support, so it may be unfeasible to list the probability for each possible realization value.

However, we may know how their probability is defined. That information may be enough to characterize its moments of interest (e.g. expected value and variance). Some examples are:

▶ Uniform Distribution: $X \sim U[a, b]$, and its density function is:

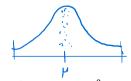
$$f(x) = \begin{cases} \frac{1}{b-a}, & \text{if } a \le x \le b\\ 0, & \text{otherwise} \end{cases}$$

• Exponential Distribution: $X \sim exp(\lambda)$

$$f(x) = \begin{cases} \lambda e^{-\lambda x}, & \text{if } x \ge 0\\ 0, & \text{otherwise} \end{cases}$$

Normal Distribution: $X \sim N(\mu, \sigma^2)$

$$f(x) = \frac{1}{\sigma\sqrt{2\pi}}e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$



From the latter, what we'll use the most is that the expected value of *X* is μ and its variance σ^2 .

Bivariate Normal

We may also know the **joint** distribution of a combination of random variables. A commonly used is the bivariate (or multivariate) Normal distribution:

$$\begin{pmatrix} X \\ Y \end{pmatrix} \sim N \left(\begin{pmatrix} \mu_X \\ \mu_y \end{pmatrix}, \begin{pmatrix} \sigma_X^2 & \sigma_{X,Y} \\ \sigma_{X,Y} & \sigma_Y^2 \end{pmatrix} \right)$$

Where $\sigma_{X,Y} = Cov(X,Y), \sigma_X^2 = Var(X), \sigma_Y^2 = Var(Y).$

A useful property we will use in our analysis of rational expectations is:

$$E[X|Y] = \mu_X + \frac{\sigma_{X,Y}}{\sigma_Y^2}(y - \mu_Y)$$

You can also express this formula in terms of the correlation $\rho_{X,Y}$: $E[X|Y=y] = \mu_X - \rho_{X,Y} \frac{\sigma_X}{\sigma_Y} (y-\mu_Y)$

Log-normal distribution

A random variable X is said to have a log-normal distribution if it's log is normally distributed. Let $log(X) = Z \sim N(\mu, \sigma^2)$. Then, we can find the expected value of X as:

$$E[X] = E[\exp(Z)] = \exp(\mu + \frac{1}{2}\sigma^2)$$

HW1

Autorregressive Processes

Finally, another process widely used in macroeconomics are the autorregresive processes. These refer to time series whose value is given by a deterministic component, which is a (usually linear) function of its previous realizations plus an stochastic component.

The simplest one is the AR(1) model, or autorregressive process of order one: Let y_t be an AR(1) process, then:

$$y_{t} = \alpha_{0} + \alpha_{1}y_{t-1} + \epsilon_{t}$$

$$\epsilon_{t} \stackrel{i.i.d.}{\sim} N(0, \sigma_{\epsilon}^{2})$$
(1)
$$(2)$$

This process will be stationary if $|\alpha_1| < 1$

$$(\gamma < 1)$$

Very related to HW1

Its expected value and variance is given as follow:

$$E[y_t] = E[\alpha_0 + \alpha_1 y_{t-1} + \epsilon_t]$$

$$E[y_b] = D$$

$$E[y_b] = E[y_b] = Hy$$

$$\vdots$$

$$\mu_y = \frac{\alpha_0}{1 - \alpha_1}$$

(filling the steps in the dots is part of your (HW1)

For the variance we just need to find $E[y_t^2]$ and then use: $Var(y_t) = E[y_t^2] - (E[y_t])^2$.

The variance will be:

$$Var(y_t) = rac{\sigma_{\epsilon}^2}{1 - lpha_1^2}$$

(again, for the HW1 you should provide the steps leading to these -or similar- results.)

Summary

We have provided you a very basic toolkit on statistics (stochastic processes and time series).

However, this is just the tip of the iceberg. Some of these topics have their own courses and the cases and applications go well beyond what we just showed.

Yet, this may be just enough for you to understand most of the applications in this course.

Here are some references in case you want to know more:

- Econometric Analysis, by William H. Greene.
- ► *Instroduction to Econometrics*, by Bruce Hansen. (https://www.ssc.wisc.edu/~bhansen/probability/)
- ► Time Series for Macroeconomics and Finance, by John Cochrane, unplublished lecture notes (https://www.johnhcochrane.com/s/time_series_book.pdf).

Introduction to Matlab

MATLAB stands for MATrix LABoratory. It is a software and a programming language designed for numeric computing. It is based mainly in calculations around matrices manipulations. However, there's many more things you could use it for (plots, algorithms, etc.).

MATLAB is widely used in engineering. In economics is also very popular, particular in macroeconomics.

For those familiar with other languages, the code syntax is **very** similar to R.

MATLAB is case sensitive: mean([1 2 3]) will work, whereas Mean([1 2 3]) won't

Why should we use MATLAB and not R, Python, Mathematica, etc? ... just *because*. These and many other options would work too.

But...you wanna work with the same tool used by the people in your field, so that you can benefit from their work (public goods). For Macro that implies knowing your way around MATLAB.

Where to get it

Great news! for UW students MATLAB is free:

https://itconnect.uw.edu/wares/uware/matlab/#students

Licenses for Students

Students may obtain free of charge Matlab license for use on computers they own personally. To register your UW student Mathworks account and download the software go to the <u>UW portal at Mathworks</u>.

Click in 'UW portal at Mathworks'

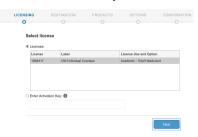
Create a Mathworks account. Make sure to use your UW email.

Download the installing file and follow the instructions.

Make sure to use your UW email:



Use the Student License Option (Not the activation key one)



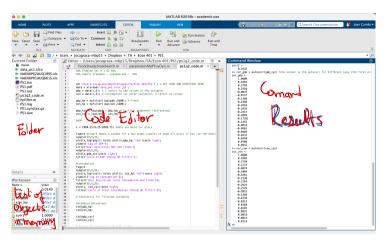
Everything else is standard except: when picking products, select also the Econometrics Toolbox and the Optimization Toolbox.



Then you just confirm:



Layout



Your code goes in an m-file shown in the middle. After running it, the output will show up in the command window.

To the left, you will see what variables you have created in the *workspace*. Above it, you'll see the content of your *working directory*

Usage

You can use matlab as a calculator (type directly on the command window and press Enter):

```
>> 1+2+3+4+5
ans =
15
>> 1*2*(3+4)/5
ans =
2.8000
```

But if you want to keep your code (e.g. for future use) you should use an m-file.

From that file you can run the whole code by typing the name of the file in the command window.

Or you can select a part of the code and run it with Ctrl-click -> "evaluate selection", or Shift+fn+F7 (in Mac).

Usage (cont.)

```
Syntax: name = command;
```

Here we create an object given by the outtut of the command. Also the semicolon prevents the output from showing in the *command window*.

Notice: no need to specify the type of an object (it does it automatically), you can overwrite objects/variables just by creating them again.

Order for mathematical expressions: From left to right + PEMDAS (Parentheses are evaluated first, then Exponents, Multiplications/Divisions, then Additions/Subtractions).

Whenever in doubt, enclose what you want evaluated first in parentheses.

Example:

```
>> 1+2+3*4
ans =
15
>> (1+2+3)*4
ans =
24
```

Most important command: help function-name, e.g., help mean (doc function-name also works)

Functions

- We can use *built-in* functions to make specific calculations.

```
Examples: mean, max, std
```

- But we can also create out own functions:
 - ► Standard way: create a separate m-file named as the function where we set our calculation code in function format (i.e. define inputs and declare a procedure to be executed in order to generate an output). Example: hpfilter.m
 - Less usual: with very small functions we can create *anonymous* functions in the same m-file we're working. Example:

```
>> f1 = @(x) x^2 +2*x + exp(x);
f1(3)
f2 = @(x,a) x^a +a*x + exp(x);
f2(3,2)
ans =
35.0855
ans =
```

Setting your directory and accessing/saving data

You can get the current directory with pwd (print working directory):

```
>> pwd
ans =
'/Users/jocagraca-mbp15/Dropbox/TA/Econ 401/PS1'
if you want to change it use cd(path) (change directory):
cd('/Users/jocagraca-mbp15/Dropbox/TA/Econ 401')
```

Saving results:

Let's say we have our result variables (A, B, C) and want to save them, just use save command:

(Ame of file) (list of variables save)

save example file A B C

Here we specified we want to save A, B, and C. If we want to save everything we have in the current workspace we just use: save exampleFile.

The resulting file (saved in your working directory) is: exampleFile.mat

Loading data:

Matlab Files: Exactly the same, but use load instead (e.g. load exampleFile)

Loading Excel data

```
If your data starts at the cell A1 in the first sheet of your spreadsheet just use:
data = xlsread('data_ps1.xlsx');
More complicated applications:
% Read a specific range of data in the second sheet:
subsetA = xlsread('myExample.xls', 2, 'B2:C3')
% Read from a named worksheet:
B = xlsread('myExample.xls', 'MySheet')
Just as with save/load, you can save your results as excel files with xlswrite
```

Matrices and Vectors

By default, MATLAB is used to work with matrices/vectors. Then, you can create them directly without particular commands:

Create a row vector: \rightarrow A = [1 2 3] \rightarrow D = [1 2 3]

Create a column vector (with semicolon you move down to next row): >> A = [1; 2; 3]

Create a matrix (element by element):

We can extract particular elements from the matrix with (rows, columns):

>> C(2,3) %Displays the element in the 2nd row and 3rd column of C. ans = 6

4 A= [2]

Matrices and Vectors (cont.)

If you want to extract a whole row, or a whole column, then you indicate you want all the elements in the dimension with colon (:):

Similarly, you can extract sequences of rows or columns:

```
>> C(1:2,2:3) %Displays the first two elements of the 2nd and third column
ans =
2     3
5     6
```

Matrices and Vectors (cont.)

Other useful commands:

Extract the diagonal elements of a matrix: >> diag(C)

Delete elements (including whole rows or columns) by setting them equal to []:

Generate a predetermined matrices:

- >> D=zeros(3,3) %displays a 3x3 matrix of zeros
- >> E=eye(4,4) %displays a 4x4 identity matrix
- >> F=ones(3,1) %displays a 3x1 matrix of ones

Operations with matrices

Let's create another matrix: >> A = magic(3) %3x3 matrix w/ rows, cols, diag summing same

Addition: >> A+C

Subtraction: >> A-C

Multiplication: >> A*C

Inverse of a matrix:

Testing if it worked:

Other useful commands: det(), trace(), eig() (determinant, trace and eigenvalues)

Other applications with matrices

Concatenation: if the dimensions are conformable we can concatenate matrices/vectors/

		/					
	>> [A]) = (C])	_			
Λ	D =		\sim	<u>c</u>	· · · · · · · · · · · · · · · · · · ·		
E	8	1	6	1	2	3	1
	3	5	7	4	5	6	
	4	9	2	7	8	9	
	>> E	E = [A]	; C]				J
	E =						
A	8	1	6				
	3	5	7				
	4	9	2				
C	T	2	3				
	4	5	6				
	7	8	9)				

Element-wise operations: sometimes it's useful to perform calculations with (or on) each element of the matrix separately

>>A^2 %Performs the usual matrix multiplication A*A
>>A(...) %Squares each element of the matrix A

Loops

Control structure that affects the flow of the executed program. (took it from CS142).

(=1:10

Saves you time. Use it when you are doing stuff -repeatedly-. Don't do it for one-time applications.

Types: for, while, if-else-elseif

For: executes a set of command a given number of times

```
>> x = zeros(10,1);
for i=1:10
x(i,1) = i;
>> x' % ' transposes a matrix
ans =
1  2  3  4  5  6  7  8  9  10
```

 $=\begin{bmatrix} X_1 \\ X_2 \\ X_3 \\ \vdots \\ X_{10} \end{bmatrix} = \begin{bmatrix} X_1 \\ X_2 \\ X_3 \\ \vdots \\ X_{10} \end{bmatrix}$

While: executes a command until a conditions is no longer met

```
y = 20;
while y >= 18 %the command below will be executed as long as y >= 18
y = y - 1;
end
>> y
y =
17
```

Loops (cont.)

If, else:

```
>> a = 30; b = 11;
>> if a < 20
c = 3+2;
else
c = 4;
end
>> c
c = 4
```

With Else-if:

```
>> if a > 30
c = 12;
elseif b == 11
c = 13;
else
c = 0;
end
>> c
c = 13
```

When writing conditionals, you can also consider the intersection of conditions (Cond 1 AND Cond 2) or the union (Cond 1 OR Cond 2):

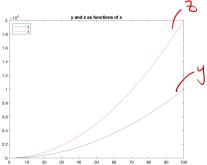
```
>> if 3 > 4 & 3 < 4 & or & refers to AND c = 6; elseif 3 > 4 | 3 < 4 % | or (| refers to OR c = 7; else c = 0; end >> c = c = 0;
```

Plots HW1

To make a plot of a variable x and y use: >> plot(x,y)

To add another variable z to that same plot use hold and then >> plot(x,z)

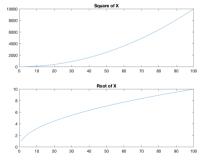
```
x = 1:100; %x will be the numbers from 1 to 100
y = x.^2; z = 2*x.^2;
plot(x,y); hold; plot(x,z)
title('y and z as functions of x')
legend('y','z','Location','NorthWest');
```



Plots(cont)

```
You can also make a matrix of plots in a window with >> subplot(rows,columns,number of plot):

subplot(2,1,1);
plot(x,y);
title('Square of X')
subplot(2,1,2);
plot(x,sqrt(x))
title('Root of X')
```



Deleting, quitting

If you want to delete an element (called A): clear A

If you want to delete everything in your workspace: clear all

To close all the plots' windows: close all

To clear your command window: clc

Finally, you can close MATLAB by typing this in the command window: quit

Conclusion

This is only a tiny glimpse of what you can do in MATLAB.

The best way to learn is by trying it yourself (rather than reading manuals or these slides).

Nobody memorizes the whole code and syntax. You get the gist, then look up the manual or google what you need (e.g. StackOverFlow).

In Canvas you can find an application with a code for the Question 2 of the problem set.