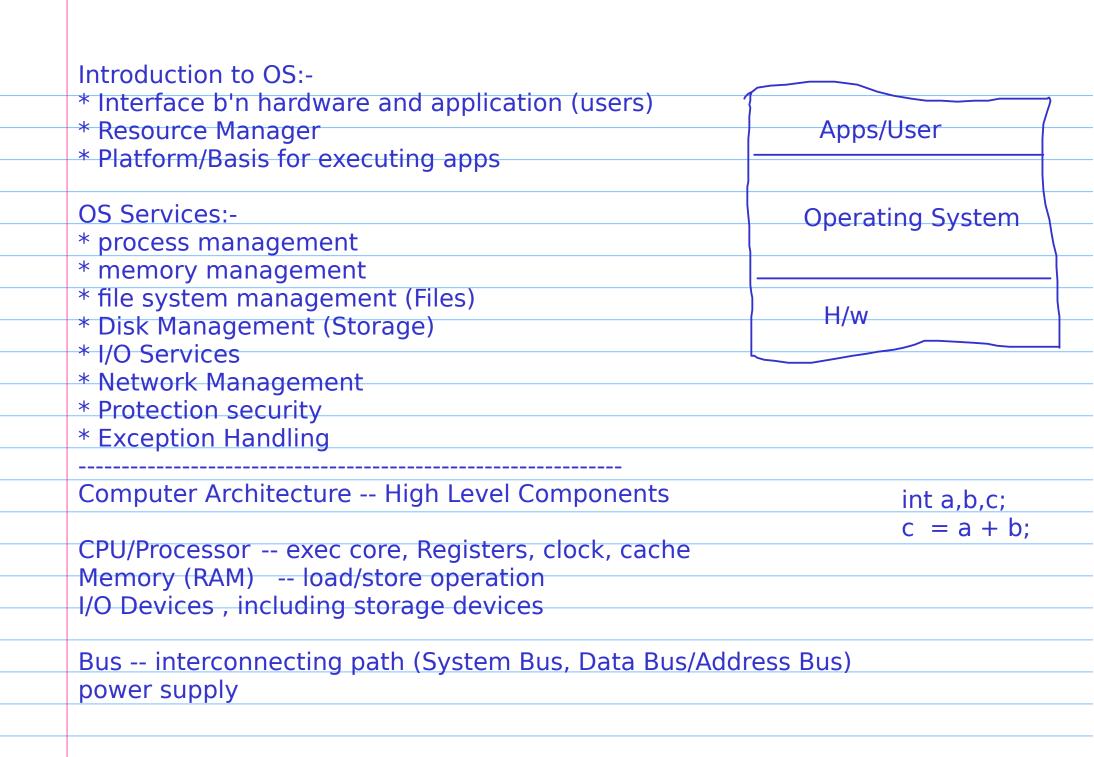
AVL Trees	
Heap Sort	
Hash Tables	
Self-paced:- sorting & searching techniques	
Linux System Programming User Space Programming	
process management	
threading	
scheduling	
signals	
IPC - semaphores, mutex, shared memory, message queues File Systems - pipes,fifos	
Virtual Memory page tables, mmap etc	
i0: 1500	
i1: 1504	
i2: 1508	
i3: 1512	
i4: 1516	



```
Higher cache levels -- lesser cost, lesser performance, increased capacity
               ==> Special purpose - stack pointer, frame/base pointer
CPU Regs
                                program counter(PC)/instruction pointer(IP)
                                FLAGS register / Program Status Word (PSW)
          ==> General Purpose - Accumulator, others
FLAGS/PSW
               ==> status bits, control bits
mode bit ==> 0 or 1
supervisor mode (unlimited/unrestricted/privileged mode)
* Can access hardware
* Can access entire instruction set
* Can access entire memory
normal mode (limited/restricted/unprivileged mode)
* no/minimal hardware access
* can access subset of instruction set (typically ALU,CU operations)
* can access subset of memory
If no mode bit (i.e. low end systems) --> single mode of operations (flat mode)
```

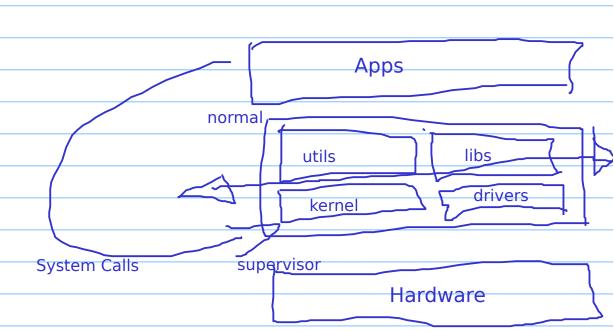
Trap instruction (s/w interrupt) by CPU:normal mode to supervisor mode transition e.g. int 80h / sysenter in INTEL swi / svc in ARM

OS Architecture:-

- * std apps (utils)
- * libraries
- * kernel (core component), minimal h/w access CPU & memory
- * device drivers

Kernel:-

- * Core component of OS (nutshell
- * Provides all services
- * Resides in memory all times
- * Kernel Mode
- * User Mode



```
Memory Partitioning
Kernel Space
                   (Around 1 GB/25%)
User space
                    (Rest of 75%/3 GB)
mode vs space
user mode -- user space access only
kernel mode -- kernel space + user space (entire memory)
Types of Kernel (self - study):-
* Monolithic Kernel
* Micro kernel
* Modular Kernel
Linux Kernel -- Modular Kernel architecture
               -- collection of modules
              -- all modules run in supervisor mode(kernel mode)
               -- static modules vs dynamic modules
Every device driver is a module
```

```
ls /boot/vmlinuz*
                             # compressed kernel image
uname -r
modular kernel:-
                                           /boot/vmlinuz (kernel image)
     core + static modules
                                  ==>
                                           /lib/modules
     dynamic modules
interfacing channel b'n user mode and kernel mode?
                                                     System Calls
In Linux/Unix ==> Everything is a file
dev/psaux ==> PS/2 device
              ==> UART device (Serial interface)
/dev/ttyS0
Device Files -- special files representing I/O devices
char devices
                   -- char by char, arbitrary size of data
block devices
                   -- block size only (chunk by chunk)
Is -I /dev
                        # starting letter -c or b
```

```
I/O Mechanisms:-
* Simple/Direct i/o -- wait until data is ready (1)
* Interrupt Driven I/O -- trigger on event
                                                (2)
* Polling -- periodical checking status
                                                (3)
Multitasking
FLAGS/PSW
               ==> interrupt pending bit (1 when interrupt arrives)
               ==> interrupt enable/masking bit
PC/IP
               ==> check the pending and jump to PC/IP
Interrupts:-
Asynchronous event -- caused by I/O devices, Timers, H/w failures (or CPU)
Utlmost priority -- handle priority
Interrupt Service Routine(ISR) / Handler
ISR Table / Interrupt Vector
TODO:- context saving in case of preemption (emergency save)
```

System Calls:-	A1 requested I/O
	A2 running when
way of consuming kernel service (offerings)	interrupt arrives
communicating with kernel	A3 other
bridge bin user space and kernel space	Cabadular call
bridge b'n user space and kernel space defined in kernel space, executed in kernel mode	Scheduler call
requested/invoked by usespace component	
Tequested/IIIVoked by dsespace component	
system call calling conventions (protocols) ABI	
not identified by name/address	
indentified by unique number (std header files)	
	s—supo(a b).
	c=sum(a,b);
	int sum(int x,int y) {
	int res=x+y;
	return res;
	}
	Accumulator register

```
int fd=4;
char str[]="Hello Linux";
int len=12;
                         //sys call no.for write is 21 (as an example)
write(fd,str,len);
Trap instruction can't carry system call number
System call invocation: (ABI -- Application Binary Application)
identify sys call number (from headers)
sys call number --> designated general purpose register (accumulator)
store arguments in other g.p. regs (in x86 - ebx,ecx,edx,esi,edi,xxx)
trap instruction
if arguments are not primitive -- store base addr in register
How to send more values than available regs .. pack them as struct
Ref:- man 2 syscall , for ABI details
```

```
write(fd,str,len);
                    // system call wrapper in userspace
                                                               0 - stdin
                    // defined in std C library
                                                               1 - stdout
                     // prototyped in unistd.h
                                                               2 - stderr
printf("abcdxyz\n");
char str[]="abcdxyz\n";
write(1, str, 8);
printf (vs) write
TODO:-
     open, read, write, close (git repo --> intro --> code)
     strace
     Library API vs System Calls
     Process Management
     examples - fork etc
```