



**IEEE**  
IEEE  
Signal Processing Society

# Perception Preserving Decolorization

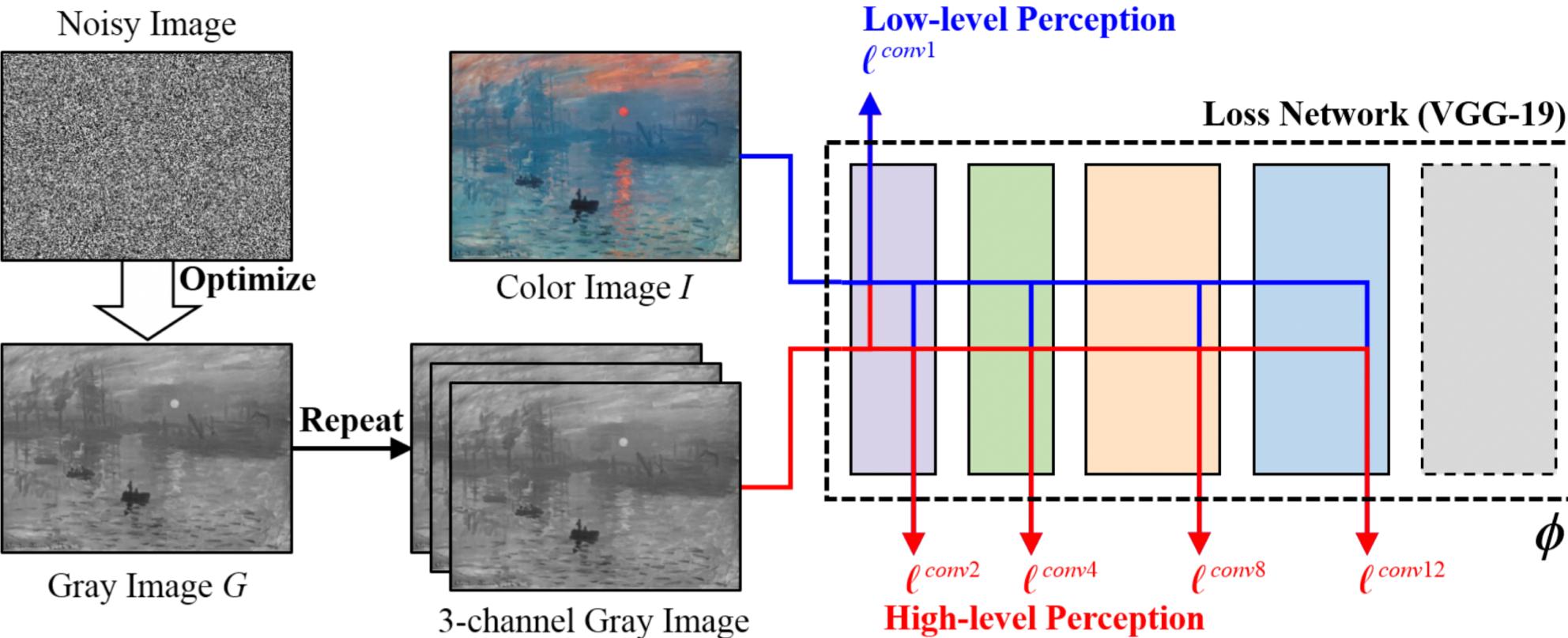
Bolun Cai, Xiangmin Xu, Xiaofen Xing  
South China University of Technology  
caibolun@gmail.com



## Abstract

Decolorization is a basic tool to transform a color image into a grayscale image. In this paper, we explore how to use **deep neural networks** for **decolorization**, and propose an optimization approach aiming at **perception preserving**. The system uses deep representations to extract content information based on human visual perception, and automatically selects suitable grayscale for decolorization. The evaluation experiments show the effectiveness of the proposed method.

**Index Terms** — Color-to-gray conversion, perception preserving, deep neural networks.



## Perception Preserving Decolorization

### ➤ Deep Perceptual Loss

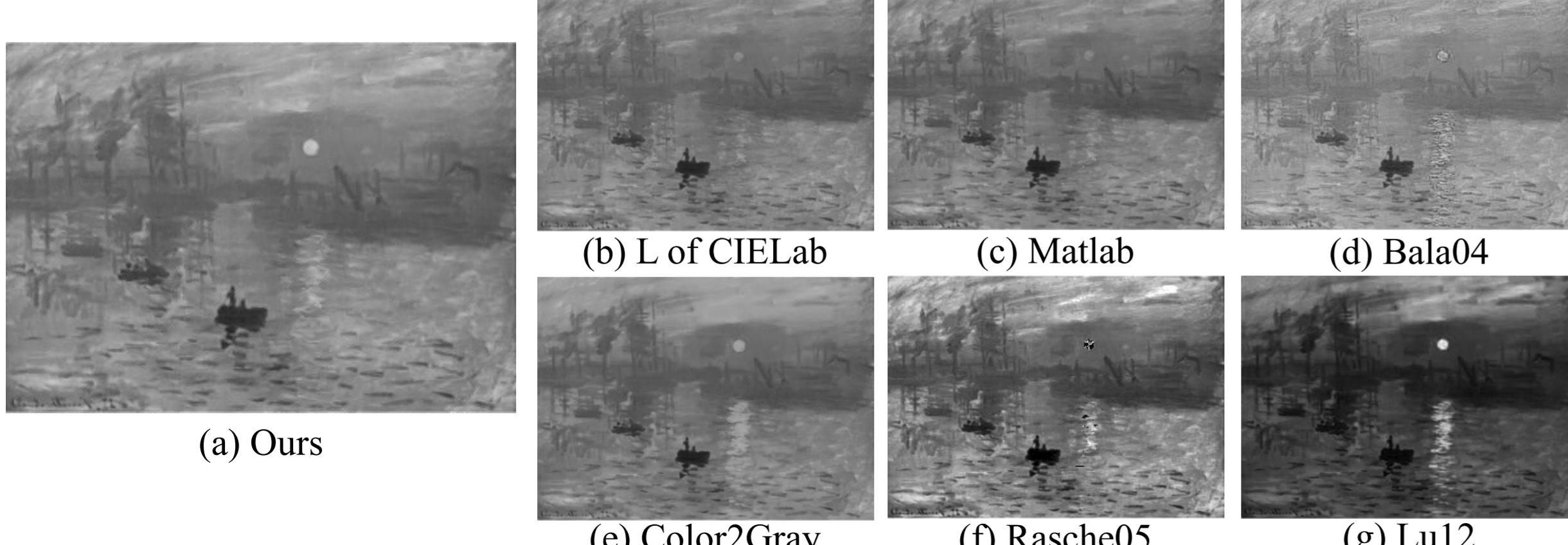
A perceptual loss measures low/high-level between color and gray images. In CNNs, **linear filter (conv)** and **non-linear activation (relu)** correspond to:  
**Dense perception** describes the convolutional output for high-order cognition  
**Sparse perception** describes the convolutional input for feature selection

$$\ell^j(G, I) = \frac{1}{C_j H_j W_j} \left( \|\phi_{conv}^j(G) - \phi_{conv}^j(I)\|_2^2 + \|\phi_{relu}^j(G) - \phi_{relu}^j(I)\|_2^2 \right)$$

### ➤ Color-to-Gray Conversion

Given a color image  $I$ , a grayscale image  $G$  is initialized with white noise and optimized by solving the problem

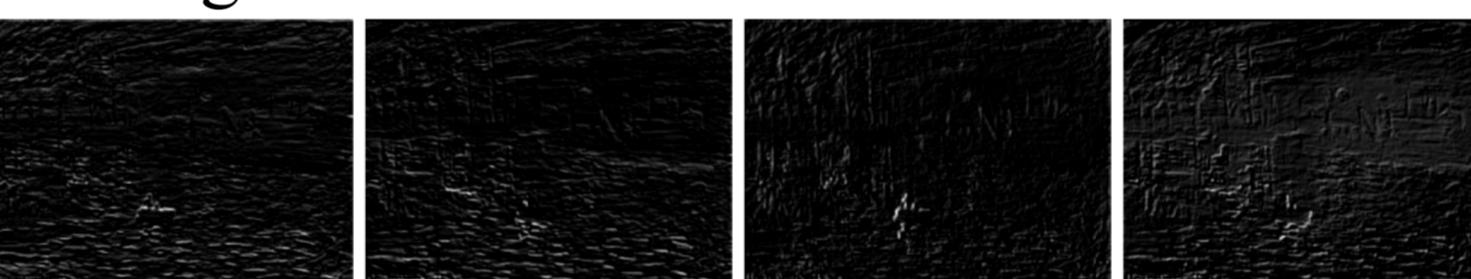
$$\arg \min_G \sum_{j \in J} \lambda_j \ell^j(G, I)$$



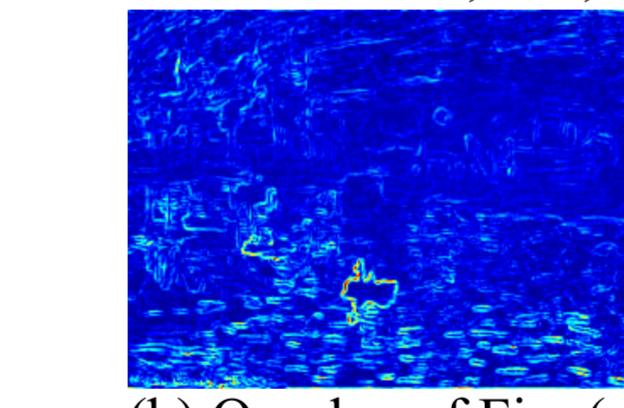
## Analysis

### ➤ Low-level Perception & Edge Preserving

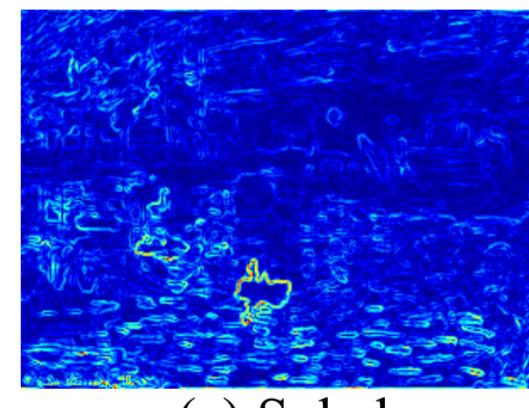
The low-level perception effectively extracts high-frequency components of the chrominance edges.



(a) Representative low-level features, #11, #27, #52 and #24 feature extracted by VGG-19 conv1



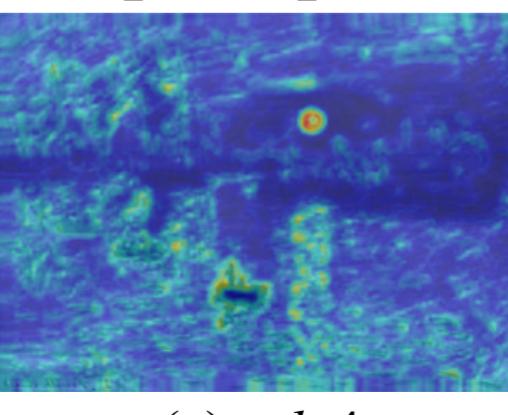
(b) Overlay of Fig. (a)



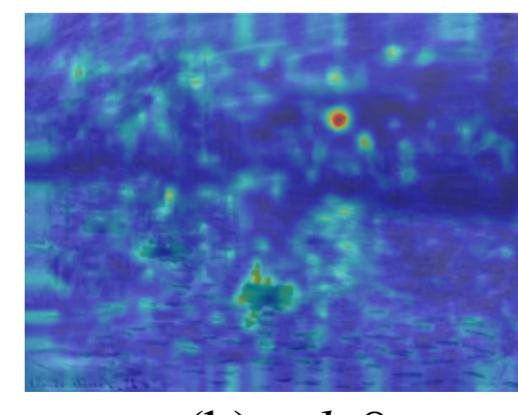
(c) Sobel

### ➤ High-level Perception & Saliency Preserving

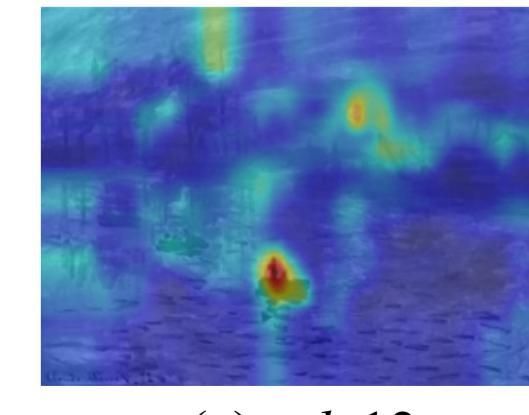
Based on the saliency of visual attention, the sun and boats are located by the high-level perception.



(a) relu4



(b) relu8



(c) relu12