

Part I

$$1.) \text{ Pf: } E_{\text{avg}}(x) = E \left[E \left[\frac{1}{n} \sum_{i=1}^n h_i(x) - f(x) \right]^2 \right]$$

$$= E \left[\frac{1}{n^2} \left[\sum_{i=1}^n h_i(x) - f(x) \right]^2 \right]$$

since $E[ax+b] = aE[x] + b$ we can say:

$$= \frac{1}{n^2} \cdot E \left[\left[\sum_{i=1}^n (h_i(x) - f(x)) \right]^2 \right]$$

Now since $E[x_1 + x_2 + \dots + x_n] = E[x_1] + E[x_2] + \dots + E[x_n]$

$$= \sum_{i=1}^n E[x_i]$$

we can say:

$$= \frac{1}{n^2} \cdot \sum_{i=1}^n E \left[-(f(x) - h_i(x))^2 \right] \text{ and due to given assumptions.}$$

$$= \frac{1}{n^2} \cdot \sum_{i=1}^n E \left[f(x) - h_i(x) \right]^2 \rightarrow e_i = f(x) - h_i$$

$$= \frac{1}{n^2} \cdot \sum_{i=1}^n E \left[e_i(x)^2 \right] = \frac{1}{n} \cdot \left[\frac{1}{n} \cdot \sum_{i=1}^n E \left[e_i(x)^2 \right] \right] \text{ note dotted box}$$

the dotted box is E_{avg} , substitute to get

$$E_{\text{avg}}(x) = \frac{1}{n} E_{\text{avg}} \quad \blacksquare$$

2.) If " f " convex function on (a, b) and x is r.v. then

$$f(E(x)) \leq E[f(x)]$$

Then using Jensen's Inequality we get:

$$E[f(x)] = \lambda(x_1) f(x_1) + \sum_{i=2}^m \lambda(x_i) f(x_i)$$

$$= \lambda(x_1) f(x_1) + (1 - \lambda(x_1)) \cdot \frac{\sum_{i=2}^m \lambda(x_i) f(x_i)}{(1 - \lambda(x_1))}$$

$$\leq \lambda(x_1) f(x_1) + (1 - \lambda(x_1)) f\left(\frac{\sum_{i=2}^m \lambda(x_i) x_i}{1 - \lambda(x_1)}\right)$$

$$\leq f(\lambda(x_1) x_1 + (1 - \lambda(x_1)) \left(\frac{\sum_{i=2}^m \lambda(x_i) x_i}{(1 - \lambda(x_1))}\right))$$

Hence

$$E[f(x)] \leq f(E[x]), \text{ Notice:}$$

$E_{avg} \rightarrow E[f(x)], E_{avg} \rightarrow f(E[x])$ so we get

$$E_{avg} \leq E_{avg}$$

3.)

Hypothesis for Boolean Classifier:

$$H(x) = \text{sign} \left(\sum_{t=1}^T \alpha_t h_t(x) \right) \quad (1)$$

weight for point i at $t+1$

$$D_{t+1}(i) = \frac{D_t(i)}{Z_t} \cdot e^{-\alpha_t h_t(i) y(i)} \quad (2)$$

Base case of recurrence:

$$D_1 = \frac{1}{N} \forall i \quad (3)$$

E_t , error for AdaBoost can be measured with relation to D_t

$$E_t = \sum_{i: h_t(i) \neq y(i)} D_t(i) \quad (4)$$

meaning error at t is sum of weights corresponding to all points i which are misclassified by h_t i.e. $h_t(i) \neq y(i)$

we start with (2)

$$D_{t+1}(i) = \frac{D_t(i) e^{-\alpha_t h_t(i) y(i)}}{Z_t}$$

Now notice we can say $h_t(i)$ and $y(i)$ is in $\{1, -1\}$ because this is a boolean classifier

we then expand the recurrence from (4) to its base case (3)

3 (continued)

$$D_{t+1}(i) = D_t(i) \cdot \frac{e^{-\alpha_1 h_1(i) y(i)}}{Z_1} \cdot \frac{e^{-\alpha_2 h_2(i) y(i)}}{Z_2} \cdots \frac{e^{-\alpha_t h_t(i) y(i)}}{Z_t}$$

$$\text{from (3)} \rightarrow = \frac{1}{N} \cdot \frac{e^{-\alpha_1 h_1(i) y(i)}}{Z_1} \cdots \frac{e^{-\alpha_t h_t(i) y(i)}}{Z_t}$$

$$\textcircled{5} = \frac{1}{N} \frac{e^{-y(i) f_t(i)}}{\prod_{j=1}^t Z_j} \quad \text{where } f_t(i) = -\sum_{j=1}^t \alpha_j h_j(i)$$

Let's look at T_H , the total training error for t .

$$T_H = \frac{1}{N} \sum_{i: h(i) \neq y(i)} 1$$

This is average of mis-classified points. Another way to say it is accuracy loss.

$H(i) = \text{sign}(f(i))$, we can say:

$T_H = \frac{1}{N} \sum_{i: y(i) f(i) \leq 0}$ because $y(i)$ and $f(i)$ will have opposite signs when mis-classified.
Hence $y(i) \cdot f(i) \leq 0$,

with this T_H we can say

$$T_H = \frac{1}{N} \sum_{i: y(i) f(i) \leq 0} 1 \leq \frac{1}{N} \sum_i e^{-y(i) f(i)}$$

because $e^{-z} \geq 1$ when $z \leq 0$

$$\text{Hence, } T_H \leq \frac{1}{N} \sum_i e^{-y(i) f(i)}$$

3. continued)

from ⑤ we substitute for

$$T_H \leq \frac{1}{N} \left(\prod_t Z_t \right) \sum_i D_{t+1}(i)$$

$$T_H \leq \left(\prod_t Z_t \right) \underbrace{\left(\sum_i D_{t+1}(i) \right)}_{\text{will be 1 because it's a probability distribution.}}$$

will be 1 because it's a probability distribution.

$$T_H \leq \prod_t Z_t \quad \textcircled{6}$$

$$\text{now } Z_t = \sum_i D_t(i) e^{-\alpha_t h_t(i)} \psi(i)$$

$$= \sum_{i: h_t(i) = \psi(i)} D_t(i) e^{-\alpha_t} + \sum_{i: h_t(i) \neq \psi(i)} D_t(i) e^{\alpha_t}$$

We do this because at a ϵ -1, 1/3 range,

$h_t(i) = \psi(i)$ is for 1 and $h_t(i) \neq \psi(i)$ is for -1.

$$Z_t = e^{-\alpha_t} \sum_{i: h_t(i) = \psi(i)} D_t(i) + e^{\alpha_t} \sum_{i: h_t(i) \neq \psi(i)} D_t(i)$$

from ④

$Z_t = e^{-\alpha_t} (1 - \epsilon_t) + e^{\alpha_t} \epsilon_t$, to minimize we must evaluate α_t roughly comes out to be $\frac{1 - \epsilon_t}{\epsilon_t}$

substitute this and simplify. Due to lengthiness I will provide the simplified answer at:

$$Z_t = 2 \sqrt{\epsilon_t (1 - \epsilon_t)}, \text{ consider the given } \wedge$$

$$\epsilon_t = \frac{1}{2} - Y_t$$

3 continued)

$$Z_t = 2\sqrt{\left(\frac{1}{2} - Y_t\right)\left(\frac{1}{2} + Y_t\right)}, \text{ multiply inside sqrt and simplify} \\ = \frac{2\sqrt{1-4Y_t^2}}{2} = \sqrt{1-4Y_t^2}$$

consider $1+x \leq e^x \quad \forall x \in \mathbb{R}$
thus $1-4Y_t^2 \leq e^{-4Y_t^2} + \{-4Y_t^2\} \in \mathbb{R}$
Notice this inequality gives us:

$$Z_t \leq \sqrt{e^{-4Y_t^2}} = e^{-2Y_t^2}$$

Now substitute this Z_t into (6)

$$T_H \leq \prod_t Z_t \leftarrow$$

$$T_H \leq \prod_t e^{-2Y_t^2} = e^{-2\sum_{t=1}^T Y_t^2}$$

Hence

$$T_H \leq e^{-2\sum_{t=1}^T Y_t^2} \quad \square$$