

# AU Mic Research Notes

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## 6/22/18: Calculating Stirring Body Mass

Calculating the size of the largest possible body, assuming Earth density  $w$   $(1.5 M_{\text{earth}} / (4/3 * \pi * 5.5 \text{ g/cm}^3))^{1/3}$  in earth radii

Calculating stirring extent for a single stirring body:  $w 5*40 \text{ au} * (1.5 M_{\text{earth}} / (3*0.5 M_{\text{sun}}))^{1/3}$

Calculating stirring extent for a Neptune

$w 5*35 \text{ au} * (15 M_{\text{earth}} / (3*0.5 M_{\text{sun}}))^{1/3}$

$w 5*47 \text{ au} * (15 M_{\text{earth}} / (3*0.5 M_{\text{sun}}))^{1/3}$

- average of 5 and 7  $\Rightarrow$  6 au

Calculating number of bodes of size 340 km:

$w 1.5 M_{\text{earth}} / (4/3*\pi*(340\text{km})^3 * 2 \text{ g/cm}^3)$

```
import astropy.units as u; import astropy.constants as c
```

```
from uncertainties import ufloat, umath
```

```
import numpy as np
```

```
h = ufloat(0.032, 0.005)
```

```
rho = 2 * u.g / u.cm**3
```

```
print(h*40 * 2.355 / 2)
```

```
v_Kep = np.sqrt(c.G * 0.5*u.M_sun / (40*u.au) ).to(u.m / u.s)
```

```
v_rel = v_esc = v_Kep * 2.355 * np.sqrt(3) * h; print(v_rel.value) # 430+/-70 m/s
```

```
# v_esc = umath.sqrt(2 * c.G * (4/3*np.pi * s_big**3 * rho) / s_big)
```

```
s_big = (v_esc / np.sqrt(8*np.pi * c.G * rho / 3) ).decompose()
```

```
print(s_big.value * 1e-3) # 410+/-60 km
```

```
M_big = ( 4/3 * np.pi * s_big**3 * rho ).decompose()
```

```
print(M_big.value) # (5.8+/-2.7)e+20 kg
```

```
print(M_big.value * u.kg.to(u.M_earth))
```

### 6/22/18: Dust mass uncertainty propagation

```
from uncertainties import ufloat, umath
import astropy.units as u
log_M_dust = ufloat(-7.564297, 0.006)
M_dust = 10**log_M_dust * u.Msun.to(u.M_earth)
print(M_dust) # 0.00908+/-0.00013

old_log_M_dust = ufloat(-7.540, 0.006)
old_M_dust = 10**old_log_M_dust * u.Msun.to(u.M_earth)
print(old_M_dust) # 0.00960+/-0.00013
scaling_factor.n * old_M_dust
```

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### 6/20/18: Beam projections for Boccaletti plots

```
b_FWHM_maj = 0.5179142951964; b_semimaj = b_FWHM_maj / 2
b_FWHM_min = 0.39400133490576; b_semimin = b_FWHM_min / 2
b_PA = 77.9047088623

# scipy rotate function rotates clockwise; we want the disk to be
# horizontal, so we need to rotate by the disk PA +/- 90
disk_PA = 128.49
rotate_angle = disk_PA - 90
# 38.49 degrees clockwise (negative in terms of PA)

rotated_b_PA = b_PA - rotate_angle
# 39.4147 from north-- longer in vertical direction

# rotate angle is defined counterclockwise to the semi-major axis
# thus y component is just -rotated_b_PA (negative to go counterclockwise to
# PA=0)
# and x is -rotated_b_PA - 90 (rotates to PA = -90)
b_FWHM_y = 2* b_semimin * b_semimaj / np.sqrt(
    (b_semimin * np.cos( np.radians(-rotated_b_PA) ) )**2 +
    (b_semimaj * np.sin( np.radians(-rotated_b_PA) ) )**2) # 0.455
b_FWHM_x = 2* b_semimin * b_semimaj / np.sqrt(
    (b_semimin * np.cos( np.radians(-rotated_b_PA - 90)) )**2 +
    (b_semimaj * np.sin( np.radians(-rotated_b_PA - 90) ) )**2) # 0.432
```

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### 6/20/18: Phase noise notes

- August
  - Test quasar beam : 0.33 arcsec, 0.29 arcsec, 63.6 deg

- imfit gives 0.39 x 0.31, 83.16
- June
  - test quasar beam: 0.48 x .31, 75.5 deg
  - imfit gives 0.54 x 0.32, 71.7 deg
- My note to John Carpenter:

So far we’ve imaged the test quasars for the two long-baseline observations and compared their image-domain FWHM (derived from imfit) to the beam size. The test quasar FWHM is slightly larger than the beam, by 12~18% along the major axis and 3~7% along the minor axis. Also, the deconvolved quasar FWHM (~0.23 x 0.07 arcsec) is smaller than the (beam-subtracted) vertical disk FWHM of 0.28 arcsec that we measure from both image-domain and MCMC analysis of the disk. That being said, it’s difficult to make a direct comparison between the quasar and disk due to the positional offset between the two objects and the shorter integration times used for the test quasar.

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## 6/18/18: Flare analysis

I’ve created a new folder called `stellar_analysis` in the `band6` directory. `flare_scripts` contains all the code, from creating measurement sets to extracting imfit fluxes and positions.

1. Flare position:

```
import numpy as np
from uncertainties import ufloat, umath
# imfit positions in arcseconds:
noflare_ra = ufloat(-0.8501300867444864 * 180/np.pi * 3600, 0.021112856077985704)
noflare_dec = ufloat(-0.5470290355107761 * 180/np.pi * 3600, 0.013264360833506577)
flare_ra = ufloat(-0.8501304916334924 * 180/np.pi * 3600, 0.003768824116591783)
flare_dec = ufloat(-0.5470294258139349 * 180/np.pi * 3600, 0.0023169999050442177)
noflare_ra2 = ufloat(-0.85013027 * 180/np.pi * 3600, 0.021112856077985704)

sep_ra = noflare_ra - flare_ra
sep_dec = noflare_dec - flare_dec
sep_tot = umath.sqrt( sep_ra**2 + sep_dec**2) # 0.118+/-0.019 arcsec
print(sep_tot * 9.725) # 1.13+/-0.18 au
print(sep_tot.n / (0.5 * (0.31 + 0.47))) # 29.74 % of beam

noflare_pos_uncertainty = 0.5 * (0.31 + 0.47) / (0.0009263625278999798 / 2.09217450873e-05)
flare_pos_uncertainty = 0.5 * (0.31 + 0.47) / (0.014884268480064874 / 4.47719756884e-05)
alt_noflare_ra = ufloat(-0.8501300574337373 * 180/np.pi * 3600, noflare_pos_uncertainty)
alt_noflare_dec = ufloat(-0.5470290568647891 * 180/np.pi * 3600, noflare_pos_uncertainty)
```

```
alt_flare_ra    = ufloat(-0.8501304925293767 * 180/np.pi * 3600, flare_pos_uncertainty)
alt_flare_dec   = ufloat(-0.5470294252558661 * 180/np.pi * 3600, flare_pos_uncertainty)
```

```
alt_sep_ra = alt_noflare_ra - alt_flare_ra
alt_sep_dec = alt_noflare_dec - alt_flare_dec
alt_sep_tot = umath.sqrt( alt_sep_ra**2 + alt_sep_dec**2) # 0.118+/-0.0088 arcsec
alt_sep_tot
```

2. Verifying flare fluxes derived by calling imstat on the clean image from each 1-minute timebind

```
from uncertainties import ufloat, umath
MCMC_starflux = ufloat(0.23, 0.02) #mJy
MCMC_diskflux = ufloat(4.81, 0.05) #mJy
cgcurs_flux = ufloat(4.97, 0.08) #mJy
imfit_flux = ufloat(0.26, 0.02)

print(imfit_flux - MCMC_starflux) # 0.030+/-0.028
print(imfit_flux - (cgcurs_flux - MCMC_diskflux)) # 0.10+/-0.10

Everything agrees to within ~1-sigma!
```

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## 6/8/18: scaling values in the literature by Gaia distance

```
from uncertainties import ufloat
import numpy as np
dist_old = ufloat(9.9, 0.10)
gaia_parallax = ufloat(102.82949372268861, 0.04856132557548943)
dist_gaia = 1000. / gaia_parallax
scaling_factor = (dist_gaia / dist_old).n**2

# Results
M_gas = np.array([1.79e-7, 9.06e-7]) * scaling_factor; M_gas # 1.7e-07, 8.7e-07])

# Discussion
M_dust = 0.010*scaling_factor; print(M_dust)# 0.009649264599090284
M_dust_Liu = 0.011*scaling_factor; print(M_dust_Liu) # 0.010614191058999311

macgregor_r_in_lower = ufloat(8.8, 1) * scaling_factor
macgregor_r_in_upper = ufloat(8.8, 11) * scaling_factor
print(macgregor_r_in_lower, macgregor_r_in_upper) # 8.5+/-1.0 8+/-11
macgregor_r_in_3sigma = 21 * scaling_factor; print(macgregor_r_in_3sigma)
45*scaling_factor

macgregor_r_out = ufloat(40.3, 0.4) * scaling_factor
```

```
print(macgregor_r_out) # 38.9+/-0.4

# Vertical Structure
Krist_FWHM = np.array([2.5, 3.5]) * scaling_factor; Krist_FWHM # 2.4, 3.37
```

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## 6/7/18: Notes on Eugene's Email

Quillen (2006):

We denote the free eccentricity dispersion,  $u_e^2 = \langle e_{proper}^2 \rangle$ . The slope of Fomalhaut's disc edge  $h_r/r \leq 0.026$  so the free eccentricities in the disc edge are  $u_e \leq 0.026$ .

this seems to contradict Quillen (2007), where  $e = 2i = 2\sqrt{2}h \dots$

Quillen & Faber (2006) has eccentricity dependence

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## 6/5/18: Plavchan Luminosity Recalculation

From Plavchan et al. (2009):

PHOENIX NextGen models are used to fit the observed optical and near-IR photometry rather than a blackbody, since the stellar SEDs are very different from that of a blackbody at optical and near-IR wavelengths (Hauschildt et al. 1999a, 1999b; Gray 1992; Mullan et al. 1989). To fit the NextGen spectra to the available photometry, we compute a  $\chi^2$  minimization as a function of effective temperature and normalization. We integrate model photospheres as a function of wavelength across effective bandpasses to compare to observed photometry for a given band. Radii are fitted to the nearest 0.5% and the uncertainty is dominated by the uncertainty in the trigonometric parallax.

I don't think calculating  $R_\star$  from a magnitude will work, due to the first sentence above..

$$L = 4\pi R_\star^2 \sigma T_{eff}^4$$

$$f = \frac{L}{4\pi d^2} \implies L = f \cdot 4\pi d^2$$

- Plavchan recalculations:

```
import numpy as np
from uncertainties import ufloat
import astropy.units as u
```

```
import astropy.constants as c
```

```
R_plav = 0.84*u.Rsun
L_plav = 0.09*u.Lsun
T_plav = ufloat(3500, 100) * (1*u.K) # K
L_calc_plav = (4 * np.pi * R_plav.si**2 * c.sigma_sb.to(u.Lsun / (u.m**2 * u.K**4)) * T_plav
L_calc_plav #0.09489585020444333+/-0.010845240023364951
```

Recalculating Plavchan's luminosity (and propagating errors on  $T_{eff}$ ) yields a consistent result, when rounded.

- Accounting for new Gaia distance by simply scaling Plavchan's quoted result:

```
dist_old = ufloat(9.9, 0.10) * (1*u.pc)
gaia_parallax = ufloat(102.82949372268861, 0.04856132557548943)
dist_gaia = 1000. / gaia_parallax * (1*u.pc); #9.724836365496536+/-0.004592563162732345

L_gaia = L_plav * (dist_gaia / dist_old)**2; L_gaia #0.08684338139181255+/-0.00175632812013
```

- By scaling recalculated Plavchan Luminosity:

```
L_gaia_scaled_L = L_calc_plav * (dist_gaia / dist_old)**2; L_gaia_scaled_L #0.0915675167978
```

In sum, when the quoted luminosity of 0.09 is scaled by the new Gaia distance, we find a new luminosity of 0.0868. Rounding to one sig fig, this doesn't change anything. Furthermore, I think Plavchan calculated a luminosity of 0.0948 but rounded it to 0.09 in the table. Scaling the recalculated luminosity of 0.0948 by the new Gaia distance yields 0.0916, which is actually still larger than the quoted value of 0.09. So on both accounts, I think we are justified in keeping the model stellar luminosity at 0.09.

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### 3/31/18: Local Intensity Maxima Offset

- NW: 7.3
  - SE: 10.5
- 

### 3/31/18: Questions for Zach re: AU Mic Gas

1. for the AU Mic standard keplerian model, which model parameters are fixed and which are free parameters?
-

### 3/31/18: New Gaia distance

```
from uncertainties import ufloat
gaia_parallax = ufloat(102.82949372268861, 0.04856132557548943)
gaia_dist = 1000. / gaia_parallax; #9.724836365496536+/-0.004592563162732345
print(gaia_dist)
```

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### 4/16/18: Annulus residual reduction

from ds9 region statistics: - upper right: 56  $\mu$ Jy reduced to 39  $\mu$ Jy - star: 46  $\mu$ Jy reduced to 40  $\mu$ Jy - lower left: 45  $\mu$ Jy reduced to 36  $\mu$ Jy

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### 4/15/18: Smallest spatial scale

```
import numpy as np
import astropy.units as u
longest_baseline= 1320.*u.m / (1.4*u.mm)

angular_scale = np.degrees(1 / longest_baseline.decompose().value)*3600
angular_scale # 0.21876570359540523
spatial_scale = angular_scale * 9.725; spatial_scale # 2.1274964674653156
```

---

### 4/14/18: Macgregor flux density comparison

```
from uncertainties import ufloat, umath
import astropy.units as u; import astropy.constants as c

# calculate scaling factor
mac_mean_freq = 235e9 * u.Hz
mac_mean_wav = np.round((c.c / mac_mean_freq).to(u.mm), 2);
mac_mean_wav.value # 1.28 mm

our_mean_freq = 222.1e9 * u.Hz
our_mean_wav = np.round((c.c / our_mean_freq).to(u.mm), 3)
our_mean_wav.value # 1.350 mm

# have to pick a temperature for scaling factor; MacGregor uses 25 K ("for 35-45
# au") when calculating a dust mass. by my calculations, T(37 au) ~ 25 K
T = 25*u.K
peak_wav = (c.b_wien / T).to(u.mm) # 0.115910916 mm
# because peak wavelength is smaller than observing wavelength by a factor of ten,
```

```

# the scaling factor between MacGregor's 1.28mm flux and our value of 1.350 mm
# flux should be < 1.

scaling_factor = (our_mean_freq / mac_mean_freq)**3 \
    * (np.exp( c.h * mac_mean_freq / (c.k_B * T) ) - 1) \
    / (np.exp( c.h * our_mean_freq / (c.k_B * T) ) - 1) # 0.9051713845664854

# scale disk flux
mac_disk_flux_lower = ufloat(7.14,0.25) * (1*u.mJy)
mac_disk_flux_upper = ufloat(7.14,0.12) * (1*u.mJy)
print(scaling_factor*mac_disk_flux_lower) # 6.46+/-0.23 mJy
print(scaling_factor*mac_disk_flux_upper) # 6.46+/-0.11 mJy
# compare to our value of 4.80 +/- 0.17 mJy

# scale star flux using Plavchan's effective temperature
T_plav = ufloat(3500, 100) * (1*u.K) # K
scaling_factor = (our_mean_freq / mac_mean_freq)**3 \
    * (umath.exp( (c.h * mac_mean_freq / (c.k_B * T_plav)).value ) - 1) \
    / (umath.exp( (c.h * our_mean_freq / (c.k_B * T_plav)).value ) - 1)
# 0.8933051+/-0.0000023

mac_star_flux = ufloat(0.32, 0.06) * (1*u.mJy)
print(mac_star_flux*scaling_factor) # 0.29+/-0.05 mJy

```

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#### 4/14/18: M star flare notes

~ 6.4 % M stars are active; periods of activity up to 10 days? <https://www.sciencedirect.com/science/article/pii/S1538435715384357/aaa59f/pdf>

modeling of M star radio emission seems to predict / fit data with variability from 0.5 to 1 mJy over a 0.44 day rotation period <http://iopscience.iop.org/article/10.3847/1538-4357/aaa59f/pdf>

The emission from the Algol system is known to be highly variable and of very high brightness temperature (~109 K) (Lestrade et al. 1988). More specifically, it has been identified as gyrosynchrotron emission from mildly relativistic electrons accelerated by magnetic reconnections in its stellar chromosphere (as also known for Sun and other stars). The spectrum of such emission peaks at a few centimetres, and may extend into the millimetre wavelength domain (Dulk 1985). The flux observed at 850  $\mu\text{m}$  therefore might be such a tail, rather than thermal emission from a debris disc. The recently measured variability of the millimetre flux density observed at the SMA strengthens this interpretation (Wyatt/Wilner, private communication)... Hence, although it may be possible for a debris disc to exist around Algol, evidence from longer wavelengths points to the emission at 850  $\mu\text{m}$  being due to radio variability rather than a debris disc. <https://ui.adsabs.harvard.edu/#abs/2017MNRAS.470.3606H/abstract>



radio variability on timescales of days, even weeks to months? <http://iopscience.iop.org/article/10.3847/1538-4357/aa7aa4/pdf>

more (14) radio variable sources, some M stars; minutes-days timescales  
<http://iopscience.iop.org/article/10.1088/1674-4527/17/10/105/meta>

paper about variability in debris disks <http://iopscience.iop.org/article/10.1088/2041-8205/765/2/L44/pdf>

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#### 4/11/18: Metchev PA

```
from uncertainties import ufloat
```

```
NW = ufloat(130.1, 0.2)
SE = ufloat(129.5, 0.4)
(NW + SE) / 2
- ufloat(128.49, 0.07)
```

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#### 4/10/18: Discussion calculations

Calculating the size of the largest possible body, assuming Earth density  $w$  ( $1.5 M_{\text{earth}} / (4/3 * \pi * 5.5 \text{ g/cm}^3)$ )<sup>(1/3)</sup> in earth radii

Calculating stirring extent for a single stirring body:  $w 5*40 \text{ au} * (1.5 M_{\text{earth}} / (3*0.5 M_{\text{sun}}))^{(1/3)}$

Calculating stirring extent for a Neptune

```
w 5*35 au * (15 M_earth / (3*0.5 M_sun))^(1/3)
w 5*47 au * (15 M_earth / (3*0.5 M_sun))^(1/3)
- average of 5 and 7  $\Rightarrow$  6 au
```

Calculating number of bodies of size 340 km:

```
w 1.5 M_earth / (4/3*pi*(340km)^3 * 2 g/cm^3)
```

---

#### 3/31/18: Scale height detectability

```
import numpy as np; import matplotlib.pyplot as plt
```

```
H = 1.2 # au
```

```
au_s = np.arange(-3,3,0.01)
```

```
gauss = 23 * np.exp(-1. * (au_s / H)**2)
```

```
SNR_3_FW_au = np.abs(au_s[np.where(gauss < 3)]).min() * 2 #
```

```
SNR_3_FW_au # 3.4399999999997988 full width of >3 sigma emission
```

```
SNR_3_FW_arcsec = SNR_3_FW_au / 9.725 # 0.35372750642671452
```

---

### 3/31/18: Distance uncertainty propagation

```
from uncertainties import ufloat
parallax = ufloat(100.91, 1.06)
dist = 1000 / parallax;
dist = 9.909820632246557+/-0.10409681766109753

gaia_parallax = ufloat(102.82949372268861, 0.04856132557548943)
gaia_dist = 1000 / parallax;
gaia_dist
```

---

### 3/1/18: All calculations in one place

1. Aspect ratio  $\rightarrow$  escape velocity:

- $\bullet < v_{rel} > \sim h \sqrt{\frac{12GM_*}{r}} \sim v_{esc}(s_{big}) \approx 357.6 \text{ m/s}$   
– w  $0.031 * \text{sqrt}(12 * G * 0.5 \text{ M\_sun} / (40 \text{ au}))$

- $\sigma = \sigma_h \sqrt{\frac{12GM_*}{r}} = 57.68 \text{ m/s}$   
\* w  $0.005 * \text{sqrt}(12 * G * 0.5 \text{ M\_sun} / (40 \text{ au}))$

2. Escape velocity can be related to the particle's mass and size, assuming a density:

$$v_{esc}(s_{big}) = \sqrt{\frac{2GM_{big}}{s_{big}}} = s_{big} \sqrt{\frac{8\pi G\rho}{3}}$$

- $\bullet s_{big} = v_{esc} \sqrt{\frac{3}{8\pi G\rho}} = 338.2 \text{ km}$   
– w  $357.6 \text{ m/s} * \text{sqrt}(3 / (8 * \text{pi} * G * 2 \text{ g/cm}^3)) \text{ in km}$

- $\sigma = \sigma_v \sqrt{\frac{3}{8\pi G\rho}} = 54.55 \text{ km}$   
\* w  $57.68 \text{ m/s} * \text{sqrt}(3 / (8 * \text{pi} * G * 2 \text{ g/cm}^3)) \text{ in km}$

- $\bullet M_{big} = \frac{v_{esc}^2 s_{big}}{2G} \approx 3.24 \times 10^{20} \text{ kg}$   
– w  $(357.6 \text{ m/s})^2 * 338.2 \text{ km} / (2 * G)$   
–  $\sigma = \sqrt{\left(\frac{\partial M}{\partial v}\right)^2 \sigma_v^2 + \left(\frac{\partial M}{\partial s}\right)^2 \sigma_s^2} = 1.098 \times 10^{20} \text{ kg}$   
\* w  $\text{sqrt}((54.55 \text{ m/s} * 2 * 357.6 \text{ m/s} * 338.2 \text{ km} / (2 * G))^2 + (50 \text{ km} * (357.6 \text{ m/s})^2 / (2 * G))^2)$

3. Stirring zone of influence is 6 Hill radii:

$$\Delta r \sim 6r_H \approx 6a \sqrt[3]{\frac{m}{3M}}$$

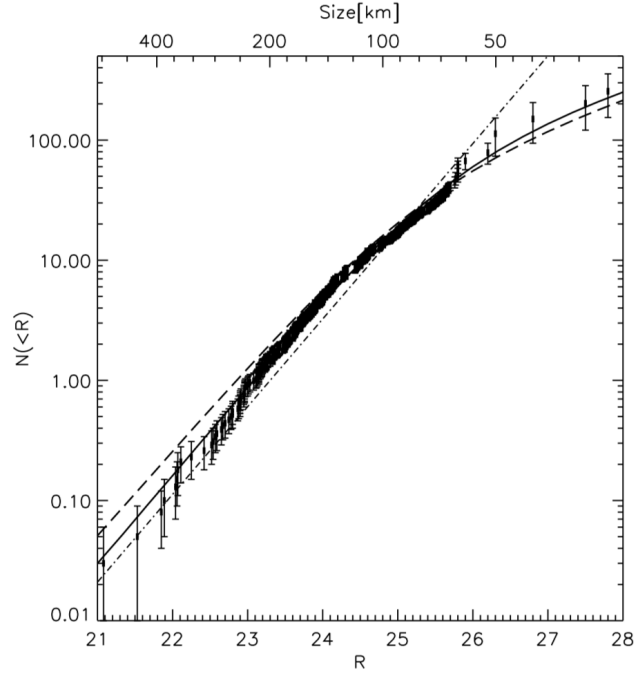
All calculations @ 40 au

- Lower limit  $m = M_{big} \Rightarrow \Delta r = 0.1145$  au.  
– w  $6 * 40 \text{ au} * (3.24e20 \text{ kg} / (3 * 0.5 * M_{\text{sun}}))^{1/3}$
- Upper limit  $m = 2.3M_{\oplus} \Rightarrow \Delta r = 3.993$  au.  
– w  $6 * 40 \text{ au} * (2.3 M_{\text{earth}} / (3 * 0.5 * M_{\text{sun}}))^{1/3}$

4. Number of Kuiper Belt Objects:

1. Fuentes & Holman 2008:

- Bias corrected, etc.; should be representative of total population of TNOs.
- Covers a solid angle of  $\Omega = 21,600$  square degrees
- *Cumulative density plot:* (I think this is surface density?)



**Figure 12.** The cumulative number density for all surveys in Table 2. The best previous model is plotted in the black dashed line. Our most likely DPL is plotted in the long-dashed line. The most likely DPL (see Figure 13) considering all surveys is plotted as a full line. The apparent bump in density at around  $R \sim 25.8$  corresponds to five objects in Gladman et al. (2001).

- $\Rightarrow \Omega N(100 \text{ km}) \sim 361,600$
- $\Rightarrow \Omega N(340 \text{ km}) \sim 4520$

2. Assuming 100,000 KBOs from [archived New Horizon's blog](#) and

[NASA's Kuiper belt page](#) and  $q = 4$ :

$$N(100 \text{ km}) = \beta 100^{-3} \sim 100,000 \implies \beta = 1e11 N(340 \text{ km}) = \beta 340^{-3} \sim 2544$$

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## 2/23/18: Meeting with Margaret & Hilke

- Questions

- How do we go from  $M_{dust}$  and  $H$  to a total dynamical mass? Without knowledge about  $p$  and  $q$ ?
  - \* because there's essentially no damping, the disk becomes more and more dynamically hot over time. Because of this we can mostly make
  - \* this is the mass ABOVE the collisional cascade
- Can we make a more accurate estimate if we use Evan's  $p$  and  $q$  values?
- What went into the plot from the Band 6 proposal?
  - \* assume equipartition, **if** eccentricities/inclinations are less than their Hill eccentricities/inclinations
    - this comes from finding Hill radius of particles and... keplerian shear
  - \* Gravitational stirring, collisional damping; bigger things stir faster
  - \* typical velocity  $\rightarrow$  combination of stirring and damping rates  $\rightarrow$  size of biggest bodies
  - \* assume how effective collisional damping is
    - when total mass of collided bodies equals mass of colliding body, body is effectively damped.
  - \* assume planet is embedded in disks
    - 6 hill radii; dependent on disk velocity?
- Because  $\Delta p \sim 0$ , damping is very effective; like Kuiper Belt
- Original assumption (single-velocity collisional cascade), damping is negligible
- $q$  tells us about how the bodies are held together; probably not gravity dominated
- low  $q$  implies that not much KE is lost in collisions
- particles may not be circular at mm sizes; this makes the internal strengths even weaker  $\rightarrow$  porous grains held together by molecular bonds
- generally, strength are predicted to increase as  $a \rightarrow 0$ ; we're finding the opposite.
-

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## 2/11/18: Making a Plan

### Conventions:

- $a_d$  is grain size traced by observations
- $a_{top}$  is size of largest body in cascade
- $a_{max}$  is size of largest body in disk
- $v_{rel}$  is encounter velocity dispersion or impact velocity
- $v(r)$  is velocity dispersion function

### Known Quantities:

- $h(a_d)$
- $M_{dust}$
- $\bar{\tau}(\lambda) \rightarrow \tau_d$  (or the latter can be determined from modeling?)
- $\Sigma_d$ , either directly from modeling or using Eq. 4 in Quillen

### Derivable Quantities

- $h(a_d) \rightarrow v(a_d) \rightarrow v(r)$  with an assumed value for  $p$
- $M_{dust} \rightarrow N(a = \lambda) \rightarrow N(a)$  with an assumed value for  $q$ 
  - this gives us mass, but doesn't use scale height information.
  - also tricky because  $q$  isn't well constrained for  $a > a_{top}$
- $\{\tau_d, v(a_d), \text{assumed value for } q\} \rightarrow a_{top}$ 
  - or can be inferred directly from  $v(a_d)$  if  $\sim v_{esc}(a_{top})$
- $\Sigma_d, a_d \rightarrow \Sigma(a) \rightarrow \Sigma(a)m(a)$ 
  - $\rightarrow \Sigma(a_{top})$
- $\Sigma(a_{max})m(a_{max})$ : puts constraint on surface density of largest bodies, and thus on  $q$  for  $a > a_{top}$ ?

### Other Ideas

- Incorporating Pan & Schlichting
    - make a guess about where the strength/velocity regimes lie to choose a better value of  $q$ ? or a series of values for  $q$ ?
    - Quillen neglects dynamical friction from smaller particles... combine with Pan & Schlichting? this sounds awful
-

## 2/8/18: Ruminations on Theory

### Thebault:

- Impact velocity or ‘encounter velocity dispersion’ of the observed grains is approximately the same as the escape velocity of the bodies at the top of the cascade:

$$v_{rel}(a_d) = v_{esc}(a_{top})$$

- Equipartition between in-plane and vertical motions:

$$\langle i \rangle = \frac{\langle e \rangle}{2} \implies \langle e \rangle^2 = 4 \langle i \rangle^2$$

- velocity imparted by dynamical interactions  $\rightarrow$  eccentricity is divided equally between the disk plane and vertical direction (inclination  $\langle i \rangle \approx \sqrt{2}h$ )

- Relating observed aspect ratio  $h(a_d)$  to escape velocity of largest bodies  $v_{esc}(s_{big})$ :

$$\langle v_{rel}(a_d) \rangle \sim v_{Kep}(r) \cdot \sqrt{\langle i^2 \rangle + 1.25 \langle e^2 \rangle} \sim v_{esc}(s_{big})$$

which can be rewritten as

$$\langle v_{rel}(a_d) \rangle \sim \sqrt{\frac{GM_\star}{r}} \cdot \sqrt{\langle i^2 \rangle + 5 \langle i \rangle^2} \sim v_{esc}(s_{big}) \langle v_{rel}(a_d) \rangle \sim \sqrt{\frac{12GM_\star}{r}} \cdot h(a_d) \sim v_{esc}(s_{big})$$

or, in terms of velocity dispersion function:

$$v(a_d) \sim \sqrt{\frac{6GM_\star}{r}} \cdot h(a_d) \sim v_{esc}(s_{big})$$

Escape velocity can be related to the particless mass and size, assuming a density:

$$\begin{aligned} - v_{esc}(s_{big}) &= \sqrt{\frac{2GM_{big}}{s_{big}}} = s_{big} \sqrt{\frac{8\pi G\rho}{3}} = \\ - s_{big} &= v_{esc} \cdot \sqrt{\frac{3}{8\pi G\rho}} = j \\ - M_{big} &= \frac{v_{esc}^2 s_{big}}{2G} \approx 3.301 \times 10^{20} \text{ kg} \\ &\quad * \text{ w } (360 \text{ m/s})^2 * 340 \text{ km} / (2 * G) \\ * \sigma_M &= \sqrt{\left(\frac{\partial M}{\partial v}\right)^2 \sigma_v^2 + \left(\frac{\partial M}{\partial s}\right)^2 \sigma_s^2} = 1.203 \times 10^{20} \text{ kg} \\ &\quad \cdot \text{ w } \text{sqrt}((60 \text{ m/s} * 2 * 360 \text{ m/s} * 340 \text{ km} / (2 * G))^2 \\ &\quad + (50 \text{ km} * (360 \text{ m/s})^2 / (2 * G))^2) \end{aligned}$$

### Quillen:

- $H \rightarrow$  inclination dispersion  $\rightarrow$  velocity dispersion  $\rightarrow$  collisional energy  $\rightarrow$  dust production rate
- “Because the absorption or the emissivity coefficient of a dust grain with radius  $a$  is reduced for  $\lambda > a$ , and there are more dust grains with smaller radii, we expect the optical depth to be related to the number density of particles of radius  $a \sim \lambda$ ”
- Scale height to inclination:

$$\langle z^2 \rangle \approx \frac{r^2 \langle i^2 \rangle}{2} \implies \bar{i} \sim \sqrt{2}h$$

where  $\bar{i} = \sqrt{\langle i^2 \rangle}$  and  $\langle i^2 \rangle$  is the inclination dispersion

- Number-size scaling relation:

$$N(a) = N_d \left( \frac{a}{a_d} \right)^{1-q}$$

- Interparticle velocity dispersion is twice the particle velocity dispersion  
duh!

$$v(r)^2 = \frac{1}{2} v_{rel}(r)^2$$

- *Observables to Theory*
  - $h(a_d) \rightarrow v(a_d)$
  - observed normal optical depth  $\bar{\tau}(\lambda) \rightarrow \tau(a_d = \lambda) = \tau_d$ , the optical depth of grains of size  $a_d$
  - $v(a_d), \tau_d, q, \Omega, t_{age} \rightarrow a_{top}$
  - $\Sigma_d, a_d \rightarrow \Sigma(a_{top})$  (really for any  $a \leq a_{top}$ )
- $\Sigma(a_{max})m(a_{max})$  (puts constraint on top of size spectrum?)

### Pan & Schlichting:

- Differential body size spectrum:

$$\frac{dN}{da} \propto a^{-q} \implies N(a) \propto a^{1-q}$$

- “number of bodies with radius  $\geq a$ ”
- “number of bodies in logarithmic size interval about  $a$ ”
- Velocity dispersion function:

$$v(a) \propto a^p$$

- ‘scale height is of order  $v_{rel}/\Omega$ ’

$$v_{rel}(a) \sim h(a) \cdot r \cdot \Omega v_{rel}(a) \sim h(a) \cdot r \cdot \sqrt{\frac{GM_\star}{r^3}} v_{rel}(a) \sim h(a) \cdot \sqrt{\frac{GM_\star}{r}}$$

- same as Thebault derivation above (factor of  $\sqrt{12}$  aside)

### 10/15/17: Visible/infrared scale heights

- schneider14 (optical): 1.5 au (had to measure read off image; compare to the value read off by schuppler, assuming they represent the opening angle radians??!)
  - metchev05 (infrared): ‘FWHM ~4’
  - krist05 (optical): 1.9 au (elsewhere quoted as 2.5-3.5 AU)
- 

### 10/15/17: 3 sigma extent

To find the 3 sigma extent, in `boccaletti_plots.py` print the separations corresponding to fit flux < 3\*rms. SE extent = 4.59” NW extent = 4.32”

---

### 10/10/17: Fixing Model Grid Resolution

We’ve been working on a run to investigate the limits of our spatial resolution, to certify that we have in fact resolve the disk scale height. We fix the scale factor to 0.003 (~1/15 of the beam size). The model image had a bunch of grid resolution problems—it looked like a bunch of superimposed bowties, because the size of the sky plane azimuthal grid elements was too large. ~~I’m setting the number of azimuthal grid points (‘nphi’) to 251; this corresponds a grid element size of 1 au (~1/4-1/5 the beam size) at 40 au.~~ This wasn’t fine enough, had to crank it up to 351.

---

### 10/10/17: Total Disk Flux

```
cgcurs in=3sigma_image.im slev=a,1.49e-05 levs1=-3,3,6,9 device=/xs op-
tions=stats type=con region=arcsec,box'(-5,-5,5,5)'
Sum = 1.27731E+00 Flux density = 4.97180E-03 Jy
Minimum = 9.87927E-07 Maximum = 4.47913E-04 Jy/beam
Mean = 1.51681E-04 sigma = 8.36131E-05 from 8421 valid pixels
Data minimum at 231.00 pixels, 217.00 pixels
Data maximum at 256.00 pixels, 257.00 pixels
Data minimum at 20:45:09.903, -31:20:33.57
Data maximum at 20:45:09.845, -31:20:32.37
```

---

### 10/7/17: Final RMS for Journal figures

In response to concerns that the rms noise estimate from the journal-quality CASA cleans may be biased due to sidelobes/AU Mic’s shape, I’m getting the



rms from the residual clean maps. I'm calling imstat on the *entire* region, since the noise actually goes down when I define the region as a box in the lower third of the image. Might as well use all the information we have!

weighting	CASA clean rms	residual clean rms
natural (no taper)	1.48e-05	1.49e-05
natural (taper)	1.92e-05	2.83e-05

Residual clean and dirty rms values were essentially identical. CASA and miriad may implement a taper differently; to test this I compare the off-source clean rms of the disk image in CASA and miriad: | weighting | CASA clean rms | miriad clean rms | |-----|-----|-----| | natural (taper) | 1.92e-05 | 3.51e-05 | Pretty different! I'm just going to use the CASA clean rmses.

Noting that the residual rms values are higher, one would not be surprised to discover that using this rms value reduces the noise contours even more in the journal-quality image—in fact, there are no noise contours.

**10/6/17:**

- imstat on  $3\sigma$  region of band6\_star\_all.natural\_clean.fits:

Frequency	Velocity	Stokes	BrightnessUnit	BeamArea
2.21987e+11Hz	0km/s	I	Jy/beam	256.908
Npts	Sum	FluxDensity	Mean	Rms
9986	1.334832e+00	5.195759e-03	1.336703e-04	1.605511e-04
Std dev	Minimum	Maximum	region count	
8.893642e-05	-1.100369e-06	4.490895e-04	1	

Total flux = Sum / (Npts/BeamArea) = 34.341mJy?

- star:
  - flux density  $\rightarrow$  4.490895e-04
  - coords  $\rightarrow$  20:45:09.845 -31.20.32.369
  - in degrees: 311.2910208 -31.3423247
- NW ansa:
  - flux density  $\rightarrow$  3.291588e-04
  - coords  $\rightarrow$  20:45:09.693 -31.20.30.834
  - in degrees: 311.2903875 -31.3418983
    - \*  $\Delta\alpha * \cos\delta = 0.152$  seconds  $\cos(-31.3418983) = 1.95''$
    - \*  $\Delta\delta = 1.535''$

```

from uncertainties import ufloat, unumpy
import numpy as np
flux_density = ufloat(3.291588e-04, 1.5e-05)
# uncertainty in position is beam size / SNR
sigma_ra = 0.52 / (flux_density.n / flux_density.std_dev)
sigma_dec = 0.32 / (flux_density.n / flux_density.std_dev)
delta_ra = ufloat(1.95, sigma_ra); delta_dec = ufloat(1.535, sigma_dec)
sep_au_NW = (delta_ra**2 + delta_dec**2)**(1/2) * 9.725
pa_NW = - unumpy.arctan(delta_ra / delta_dec) * 180 / np.pi + 180
print(sep_au_NW, pa_NW) # 24.13+/-0.20, 128.2+/-0.4

```

- SE ansa:
  - flux density -> 3.440531e-04
  - coords -> 20:45:10.021 -31.20:34.179
  - in degrees: 311.2917542 -31.3428275
    - \*  $\Delta\alpha = -0.176$  seconds  $\cos(-31.3423247) = -2.26''$
    - \*  $\Delta\delta = -1.81''$
    - \* PA = 128.69
    - \* 2.896" separation

```

flux_density = ufloat(3.440531e-04, 1.5e-05)
# uncertainty in position is beam size / SNR
sigma_ra = 0.52 / (flux_density.n / flux_density.std_dev)
sigma_dec = 0.32 / (flux_density.n / flux_density.std_dev)
delta_ra = ufloat(-2.26, sigma_ra); delta_dec = ufloat(-1.81, sigma_dec)
sep_au_SE = (delta_ra**2 + delta_dec**2)**(1/2) * 10
pa_SE = - unumpy.arctan(delta_ra / delta_dec) * 180 / np.pi + 180
print(sep_au_SE, pa_SE) # 28.95+/-0.20, 128.69+/-0.35
print(pa_SE - pa_NW) # 0.5+/-0.6

```

---

7/27/17:

**Pomodoros:** 1. Get CASA script going

Need to figure out a way to easily access observation rms for cleaning model images.. - Hard code them into file? - Supply pathname to image for rms?

---

7/27/17:

**Pomodoros:** 1. Make best fit function output visibilities ready for uvcat 2. Get uvcat up and running 3. Make residuals as well as convolved images, and start on casa script

---

**7/27/17:**

‘run5\_26walkers\_10params’ went a little wrong—the first june spw was actually a duplicate of an august spw, so I’m starting run 6 to better describe things.

---

**7/16/17:**

1000 step run with 16 walkers takes ~57 hours

In `run4_16walkers_7params`, `r_in` seems to prefer a very high value—about 25. Meredith pointed out this may be because we are oversubtracting the stellar flux, so we’ve decided to use the unsubtracted visibilities and make the stellar flux a free parameter for each observation (so, three more free parameters).

---

**6/30/17:**

We have to treat each spectral window separately, as `uvmodel` can’t handle spectral windows. Thus, splitting out each spw and weighting separately.

---

**6/16/17: Reweighting**

**note:** I changed the June visibilities name from `aumic_jun_noflare_allspws` to simply `aumic_jun_allspws` since we’re certainly not using the flare anymore.

Now that I’ve (more or less) finished processing the visibilities, I need to reweight them using Kevin’s code. There are three important factors for determining good weights: 1. `uvwidth`: the size of the box within which to search for neighboring visibilities in order to calculate standard deviation/weight. This value is determined using the time smearing equation (3.194) from Essential Radio Astronomy:

$$\Delta t \ll \frac{\theta_s}{\Delta\theta} \frac{1}{2\pi} \implies \text{uvwidth} = 2\pi d_{uv} \Delta t$$

where  $\theta_s$  is the synthesized beam,  $\Delta\theta$  is the largest phasecenter offset of concern, and  $d_{uv}$  is the median  $uv$  distance. 2. `nclose`: the number of points used to calculate the standard deviation/weight. If there are not `nclose` visibilities within `uvwidth`, the weight is set to zero. 3. `acceptance fraction`: the fraction of points for which weights are successfully calculated.

I start by setting `nclose` to 50, and then increase/decrease `nclose` by 1 (while holding `uvwidth` fixed) until the acceptance fraction is just above 0.99.

The procedure to go from CASA `.ms` to correctly weighted visibilities of all file formats is as follows:

```

#CASA
from glob import glob
mses = glob('*.uvsub.ms')
for ms in mses:
    exportuvfits(vis=ms, fitsfile = ms[:-3] + '.uvf')

#put at bottom of var_vis, then run:
uvfs = glob('*.uvsub.uvf')
for uvf in uvfs:
    final_name = uvf[:17] + '_FINAL'
    var_vis(uvf[:-4], final_name)
    create_vis(final_name)

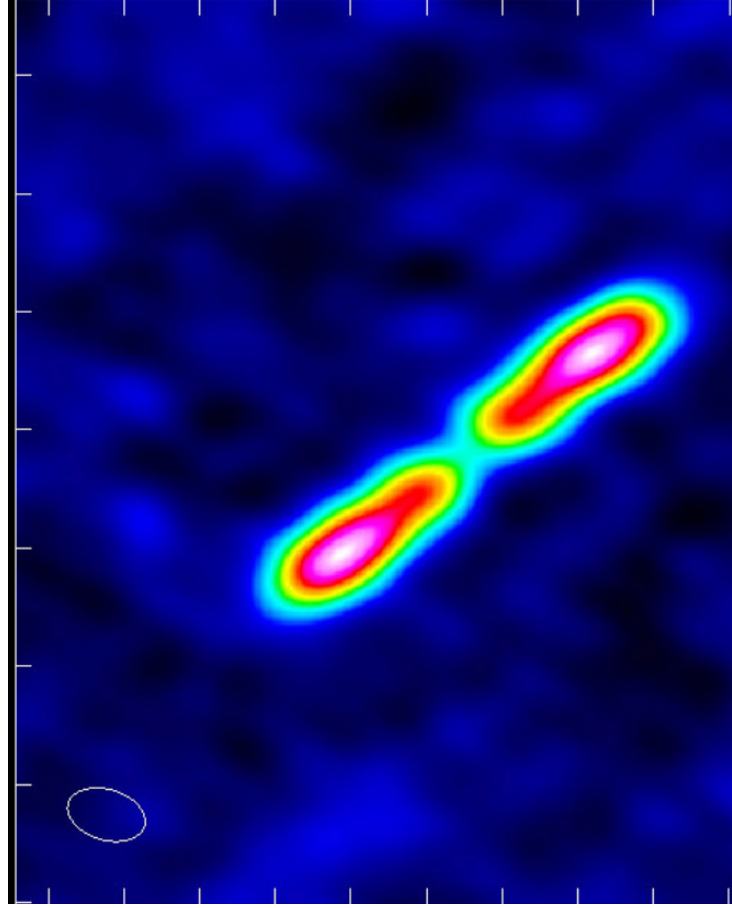
#back to casa
from glob import glob
uvfs = glob('*FINAL.uvf')
for uvf in uvfs:
    importuvfits(fitsfile=uvf, vis=uvf[:-4]+'.ms')

```

---

## 6/16/17: Fixing March

Although I previously said that the March date seemed fine, visual inspection indi-



cates that we are oversubtracting the stellar flux:

Because the March baselines are so short (450 m), we are not able to obtain the star flux by fitting a point source to the longest baselines; the flux of the disk is present at even the longest baselines. As such, I am employing an image-domain approach. I fit a 24th order polynomial to the radial surface brightness profile of the disk, excluding the inner radii where stellar emission is present. Using the fit, I am able to derive an estimate of the disk flux at the location of the star, and thus find the star flux. Derived values can be found below.

Component	Flux ( $\mu\text{Jy}$ )
Disk	781
Star	367

I use the following procedure to subtract the stellar flux from the March visibilities:

```
fixvis(vis = 'aumic_mar_allspws.concat.ms',
```

```

    phasecenter = 'J2000 20:45:09.84238 -31.20.32.35898',
    outputvis = 'aumic_mar_allspws.fixvis.ms')
os.system('rm -rf point_fit.cl')
cl.addcomponent(flux=0.000367, fluxunit='Jy', shape='point',
    dir='J2000 20:45:09.84238 -31.20.32.35898')
cl.rename('point_fit.cl')
cl.close()
ft(vis='aumic_mar_allspws.fixvis.ms', complist='point_fit.cl')
uvsub(vis='aumic_mar_allspws.fixvis.ms')
os.system('rm -rf aumic_mar_allspws.fixvis.uvsub.ms')
split(vis='aumic_mar_allspws.fixvis.ms',
    outputvis='aumic_mar_allspws.fixvis.uvsub.ms',
    datacolumn='corrected')

```

The resulting visibilities appear very slightly oversubtracted, but it's good enough for now.

---

## 6/14/17: Final corrections on visibility files, and exclusion of flare

Now that we have a more reliable result for the June star position, Meredith and I have decided that it would be a good idea to re-subtract the stellar component from the actual star position, rather than the flare position. I apply `uvmodelfit` to the I used the following code to fit a point source to several different baseline ranges; the point source flux should converge to the stellar flux as the shorter baselines are excluded.

```

I = []
for i in range(0, 701, 50):
    uvmodelfit(junvis, uvrage='{}~1400'.format(i))
    flux = input("Flux? ")
    I.append(flux)

```

After visual inspection, I've decided that `uvrange='350~1400'` provides the best balance between excluding disk flux and including as many data points as possible. This yields a stellar flux of  $I = 0.000262055 \pm 9.40667 \times 10^{-9}$  Jy.

The procedure for June is as follows:

1. Fix phasecenter:

```

fixvis(vis = 'aumic_jun_noflare_allspws.concat.ms',
    phasecenter = 'J2000 20:45:09.871593 -31.20.32.838199',
    outputvis = 'aumic_jun_noflare_allspws.fixvis.ms')

```

2. Subtract stellar component, and split out corrected data:

```

cl.addcomponent(flux=0.000262055, fluxunit='Jy', shape='point',
    dir='J2000 20:45:09.871593 -31.20.32.838199')

```

```

cl.rename('point_fit.cl')
cl.close()
ft(vis='aumic_jun_noflare_allspws.fixvis.ms', complist='point_fit.cl')
uvsub(vis='aumic_jun_noflare_allspws.fixvis.ms')
split(vis='aumic_jun_noflare_allspws.fixvis.ms',
      outputvis='aumic_jun_noflare_allspws.fixvis.uvsub.ms',
      datacolumn='corrected')

```

3. Now, pull all files from the 24jun2015\_flare\_main, which contains all flare-subtracted visibilities, and concatenate into single file:

```

import subprocess
from glob import glob
files = glob("../24jun2015_flare_reduced/*.uvsub")
concat(vis=files, concatvis='aumic_jun_flare_allspws.fixvis.uvsub.ms')

```

When the output vis is cleaned, some stellar emission clearly remains. This is weird, because I haven't seen stellar emission in any of the previously made clean images...

*Given the difficulties that I experienced with the bad spectral window during the flare timewindow, the persistent flare/stellar flux in the supposedly corrected flare visibilities, and general uncertainty about how we fit the point sources to the star/flare the first time around, I'm deciding to fully eliminate the flare timewindow (4:23:38-4:29:58) from the data we use for imaging and modeling.*

---

**Other dates:** I went back to re-check March and August using a for loop similar to that above—March seems fine, but I'm redoing August. I went with `uvrange='500~1200'`, which yields  $I = 0.00012281 \pm 1.17063e-08$  Jy. The procedure is as follows:

1. Fix phasecenter:

```

fixvis(vis = 'aumic_aug_allspws.concat.ms',
      phasecenter = 'J2000 20:45:09.85274 -31.20.32.50258',
      outputvis = 'aumic_aug_allspws.fixvis.ms')

```

2. Subtract stellar component, and split out corrected data:

```

cl.addcomponent(flux=0.00012281, fluxunit='Jy', shape='point',
               dir='J2000 20:45:09.85274 -31.20.32.50258')
cl.rename('point_fit.cl')
cl.close()
ft(vis='aumic_aug_allspws.fixvis.ms', complist='point_fit.cl')
uvsub(vis='aumic_aug_allspws.fixvis.ms')
split(vis='aumic_aug_allspws.fixvis.ms',
      outputvis='aumic_aug_allspws.fixvis.uvsub.ms',
      datacolumn='corrected')

```

For **March**, all we have to do is phase shift:

```
fixvis(vis = 'aumic_mar_allspws.concat.ms',  
       phasecenter = 'J2000 20:45:09.84238 -31.20.32.35898',  
       outputvis = 'aumic_mar_allspws.fixvis.ms')
```

For consistency, I'm also creating a copy called `aumic_mar_allspws.fixvis.uvsub.ms`

---

### **6/13/17: Position fixing: imfit on non-flare component of June date**

A different method to fix the June flare offset problem: if the flare is indeed asymmetric and pulled the imfit position away from the true star position, this can be remedied by calling imfit on the non-flare part of the June observation. First, I will use March and August as controls.

*Methods:* Concatenate all four pre-fixvis and -uvsub spws (i.e. before phase shifting and stellar component subtraction), use this to fit. Make sure region around star is a very small circle, so that any irregularities at the edges of the smeared point source don't affect fit position

#### **March:**

ra: 20:45:09.84238 +/- 0.00033 s (0.00426 arcsec along great circle)  
dec: -31.20.32.35898 +/- 0.00223 arcsec  
Peak: 771.3 +/- 4.7 uJy/beam

Compare to previously used imfit values:

All times

ra: 20:45:09.843230 +/- 0.000062 s (0.000800 arcsec along great circle)  
dec: -31.20.32.358302 +/- 0.000378 arcsec  
Peak: 755.40 +/- 0.82 uJy/beam

Fixvis phase center:

J2000 20h45m09.8443s -031d20m32.36s

#### **August:**

ra: 20:45:09.85274 +/- 0.00016 s (0.00200 arcsec along great circle)  
dec: -31.20.32.50258 +/- 0.00182 arcsec  
Peak: 226.5 +/- 2.5 uJy/beam

Compare to previously used imfit values:

ra: 20:45:09.85471 +/- 0.00077 s (0.00984 arcsec along great circle)  
dec: -31.20.32.52039 +/- 0.00717 arcsec



Peak: 225.1 +/- 10.0 uJy/beam

Fixvis phase center:  
J2000 20h45m09.85471s -031d20m32.52034s

**June:**

ra: 20:45:09.871593 +/- 0.000061 s (0.000778 arcsec along great circle)  
dec: -31.20.32.838199 +/- 0.000479 arcsec  
Peak: 378.9 +/- 1.3 uJy/beam  
in degrees: 311.2911313 -31.3424550

Compare to previously used imfit values:

All times  
ra: 20:45:09.86765 +/- 0.00016 s (0.00203 arcsec along great circle)  
dec: -31.20.32.88803 +/- 0.00128 arcsec  
Peak: 862.3 +/- 7.7 uJy/beam  
in degrees: 311.2911154 -31.3424689

Fixvis phase center:  
J2000 20h45m09.8677s -031d20m32.89s

Now, to calculate the shift caused by excluding the flare:

```
from uncertainties import ufloat, unumpy as unp
dec_flare = ufloat( -( 31 + 20/60. + 32.838199/60**2 ), 0.000479/60**2 )
ra_flare = ufloat( 9.871593, 0.000061 )
dec_noflare = ufloat( -( 31 + 20/60. + 32.88803 /60**2 ), 0.00128 /60**2 )
ra_noflare = ufloat( 09.86765, 0.00016 )
# when converted to an angle, errors match with "arcsec along great circle"

d_ra_arcsec = 15 * (
    ra_flare * unp.cos( unp.radians( dec_flare ) )
    - ra_noflare * unp.cos( unp.radians( dec_noflare ) ) )
d_dec_arcsec = 60**2 * (dec_flare - dec_noflare)

angular_sep = unp.sqrt( d_ra_arcsec**2 + d_dec_arcsec**2 );
print(angular_sep) # 0.0710+/-0.0018
print(angular_sep*9.725) # 0.690+/-0.018
```

For all dates, the imfit coordinates are just about exactly at the stellar emission (by visual inspection). For June, the previously used coordinates are significantly below and to the right of the star position. Separation: 0.069956821"

---

**5/31/17: First day of summer research**

- Relative position uncertainty (per synthesized beam) =  $\frac{\theta_{sb}}{SNR}$
  - → Fixvis phasecenter
- 

## 5/28/17: Star position

Sooo it's been a while since I've written any notes. In the last month and a half, I have:

1. Cutting out the last observation window for (**just spw3? all spws?**) fixed the flare date.
2. While concatenating the different dates before cleaning may have helped with the star offset from the image center, this effect remains. Meredith and I wonder if the flare could have been asymmetric, so that the point source fit to the flaring star that defines the image center is offset from the star itself. This would also explain the asymmetric gap/hole by the star in the June observation.
3. To fix this issue, I hope to find some metric of determining the center/star position of the disk that gives good agreement with august and march dates and apply it to the June date.

## Approaches:

- **pixel\_mean**: take the mean position of all pixels with values above  $6.2 \sigma$ 
  - mar offset from image center: (0.0, 0.03)
  - aug offset from image center: (0.0, 0.0)
  - jun offset from image center: (0.06, -0.18)
    - \* visual inspection shows that this is on the wrong side of the disk...
- **single\_gauss**: fit a Gaussian to the whole disk
  - mar offset from image center: (-0.04, 0.02)
  - aug offset from image center: (0.07, -0.03)
  - jun offset from image center: (0.25, -0.10)
- **double\_gauss**: fit a Gaussian to each side of the disk
  - mar offset from image center: (0.01, -0.06)
  - aug offset from image center: (0, 0.06)
  - jun offset from image center: (0.13, 0.09)
- **clean\_pixels**: run clean with a low number of iterations, select the brightest pixel on each side of the disk from the clean component map
  - March:
    - \* NW side: 20:45:09.682 -31.20.30.767, ( $6.77 \times 10^{-5}$ ) Jy
    - \* SE side: 20:45:10.012 -31.20.34.047, ( $6.78 \times 10^{-5}$ ) Jy
    - \* Mean: → 20:45:9.847 -31.20.32.407;
    - \* Pointing center: 20:45:09.84 -31:20:32.36
    - \* Offset: 0.01 -0.05 arcsec

- August:
  - \* NW side: 20:45:09.68   -31.20.30.75, ( $3.69 \times 10^{-5}$ ) Jy
  - \* SE side: 20:45:10.03   -31.20.34.29, ( $3.24 \times 10^{-5}$ ) Jy
  - \* Mean:  $\rightarrow$  20:45:9.855   -31.20.32.52;
  - \* Pointing center: 20:45:09.85   -31:20:32.52
  - \* Offset: 0.01 0.00 arcsec
- June:
  - \* NW side: 20:45:09.702   -31.20.31.099, ( $1.03 \times 10^{-4}$ ) Jy
  - \* SE side: 20:45:10.036   -31.20.34.504, ( $6.70 \times 10^{-4}$ ) Jy
  - \* Mean:  $\rightarrow$  20:45:09.869   -31.20.32.802;
  - \* Pointing center: 20:45:09.87   -31:20:32.89
  - \* Offset: 0.00 0.09 arcsec

The ‘clean pixel’ method gives the best agreement for the March and August dates, and we will use this method going forward. The coordinates calculated above will be used as the new phasecenters (`fixvis` will be applied to all three dates for consistency).

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#### 4/8/17: Final iteration of data files?

Aug $\chi^2$	Jun $\chi^2$	Mar $\chi^2$
0.96209719	2.77836548	1.9568517
0.96680418	2.52863844	1.96150345
0.97191927	2.59185666	1.97182168
1.02544892	<b>1.74236074</b>	1.97257757

Aug $\chi^2$	Jun $\chi^2$	Mar $\chi^2$
0.96209719	2.77836548	1.9568517
0.96680418	2.52863844	1.96150345
0.97191927	2.59185666	1.97182168
1.02544892	<b>2.29280139</b>	1.97257757

#### 3/21/17: Pixel location:

- `ctrpix` remains the same if I make image 257 pixels
- `interpolate.rotate` works on arrays, and does not mention a rotation centroid—I assume it must choose the float center point of the array

CRPIXn from FITS standard:

The value field shall contain a floating point number, identifying the location of a reference point along axis n, in units of the axis index. This value is based

upon a counter that runs from 1 to NAXISn with an increment of 1 per pixel. The reference point value need not be that for the center of a pixel nor lie within the actual data array. Use comments to indicate the location of the index point relative to the pixel.

From STSCI:

When the data matrix represents a digital image, transformation between the data matrix and the physical picture requires knowledge of where in the pixel – center or corner – the data point is. Historically, astronomers have generally assumed that the index point in a FITS file represents the center of a pixel. This interpretation is endorsed by GC. It differs from the common practice in computer graphics of treating the center of a pixel as a half-integral point. GC note that the pixel in a FITS file is commonly regarded as a volume element in physical space, which might be viewed from different perspectives via transposition and rotation. Under such operations, only the center of an element remains invariant. Pending adoption of a standard convention by the astronomical community, FITS writers should use appropriate comments in the comment field of the card image or the COMMENT keyword to inform readers of the file which convention is being used. Once the community has accepted a convention, a single comment noting that the convention is being used will be sufficient.

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### 3/21/17: Flare date and bad spws

Recently I realized that the time window we split out to fix the bad spw in the June date was exactly the time window of the flare. This makes me somewhat suspicious, and Meredith and I decided I should do some more digging, especially considering all the work we put into making the flare data useable.

The `plotms` of amp vs. time for spw3 (the bad one) and spw1 (well behaved) are roughly the same—both show a huge spike in the last (flare) time window. This leads me to believe that it's not the flare itself that's messing up spw3; if this were the case, we should see the same thing for spw1.

- Antenna 1 and 2 are almost constantly 'on' in last time window, as opposed to dashed in previous windows?
- same for baseline, phase
- weights get very low for in flare window for both spws
- everything I tried seems to match for both spws...

This is a little confusing, since spw1 had a pretty nice  $\chi^2$ ; but we did remove that flare time window for *all* spws...

## 2/26/17—3/20/17: Image Centering

While comparing images made with different date combinations (i.e. removing August date because of poor quality), I noticed that the disk was offset from the image center for certain combinations. We have decided that this is caused by the non-homogeneous pointing centers (due to proper motion) of the three datasets. When `tclean` is called on a collection of datasets with different pointing centers, the pointing center of the first of the datasets is chosen as the origin of the image, and all datasets are combined in the *uv*-domain, with their phase offsets preserved. The resulting sky-domain image is both offset from the image center and a false representation of the disk.

To fix this issue, I tried using `concat` with its *dirtol* parameter set to a high value (2"). As long as the pointing/phase centers of the datasets do not differ from each other by more than *dirtol*, the datasets are combined as if they all share the pointing center of the first dataset and all is well. A quick test indicates that this method is succesful.

However, I ran into another problem while attempting the `concat` method. The `26mar2014_aumic_spw0.corrected_weights.ms` dataset is missing `table.f8_TSM1` (all other datasets have this table), and because of this `concat` fails when applied to this dataset. However, recreating the `.ms` file from the corresponding `.uvf` file seems to have fixed this problem. I'm starting over with a `cleans` directory, and have added the suffix `_old` to the originals.

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### *My troubleshooting notes:*

**Fixvis:** If the phase center is changed, the corresponding modifications are applied to the visibility columns given by the parameter "datacolumn" which is by default set to "all" (DATA, CORRECTED, and MODEL).

- All dates have 257, 257 CRPIX
  - 24 June: 311.291115417 -31.3424694444
- 24 June fixvis: `phasecenter = J2000 20h45m09.8677s -031d20m32.89s`
  - not many precision points?
  - 311.2911154166666 -31.342469444444443 in deg... essentially the same as the image center
- Center pixel info for all dates:
  - `aumic_18aug_usermask_natural`:
    - \* 311.2910612917 -31.34236676111
  - `aumic_26mar_usermask_natural`
    - \* 311.2910179167 -31.34232222222

- aumic\_24jun\_usermask\_natural
  - \* 311.291115417 -31.3424694444
- aumic\_usermask\_natural
  - \* 311.2910612917 -31.34236676111
- aumic\_marjune\_usermask\_natural
  - \* 311.291115417 -31.3424694444 March + June (the culprit):
- 311.291115417 -31.3424694444
- 257 257 center pixel