# Problem Three

## Michael Cai

## March 2, 2016

## 1

```
Output
     y_t = e^{z_t} k_t^{\alpha}
     Suppose y_t and k_t changes around their steady states y and k
     \hat{y}_t = log(\frac{y_t}{y})
     y_t = ye^{\hat{y}_t} and k_t follows the same form.
     Then ye^{\hat{y}_t} = e^{z_t} (ke^{\hat{k}_t})^{\alpha}
     In the steady-state z_t = 0, thus e^{z_t} = 1
     \therefore y = k^{\alpha}
     Thus dividing both sides by y/k^{\alpha} equivalently, we get:
     =e^{\hat{y_t}}=e^{z_t}(e^{\hat{k_t}})^{\alpha}
     And taking logs we get:
     \hat{y_t} = z_t + \alpha \hat{k_t}
     Capital
     k_{t+1} = (1 - \delta)k_t + se^{z_t}k_t^{\alpha}
     k_t and k_{t+1} changes around its steady state k.
     Therefore:
     ke^{\widehat{k_{t+1}}} = (1-\delta)ke^{\widehat{k_t}} + se^{z_t}(ke^{\widehat{k_t}})^{\alpha}
     Dividing by k we get:
     e^{\widehat{k_{t+1}}} = (1 - \delta)e^{\widehat{k_t}} + \frac{sk^{\alpha}}{k}e^{z_t}(e^{\widehat{k_t}})^{\alpha}
     Recall: k_{t+1} = (1 - \delta)k_t + sy_t
     In the steady-state:
     k = (1 - \delta)k + sy
     k - (1 - \delta)k = sy
     \delta k = sy
     Because y = k^{\alpha}
     \delta k = sk^{\alpha}
     \delta = \frac{sk^{\alpha}}{k}
     Thus replacing \frac{sk^{\alpha}}{k} in our last equation with \delta we get:
```

```
\begin{split} e^{\widehat{k_{t+1}}} &= (1-\delta)e^{\widehat{k_t}} + \delta e^{z_t}(e^{\widehat{k_t}})^{\alpha} \\ \text{Recall from the Taylor Series expansion of } e^x \\ e^x &= 1 + x + \frac{1}{2}x^2 + \dots \\ &\approx 1 + x \\ \text{Thus } e^{\widehat{k_{t+1}}} &\approx 1 + \widehat{k_{t+1}} = (1-\delta)(1+\widehat{k_t}) + \delta(1+z_t + \alpha \widehat{k_t}) \\ &= (1-\delta) + (1-\delta)\widehat{k_t} + \delta + delta(z_t + \alpha \widehat{k_t}) \\ \widehat{k_{t+1}} &= (1-\delta)\widehat{k_t} + \delta z_t + \alpha \delta \widehat{k_t} \\ \widehat{k_{t+1}} &= \delta z_t + (1-\delta + \alpha \delta)\widehat{k_t} \end{split}
```

### $\mathbf{2}$

Expressing as ARMA processes

$$\begin{aligned} \dot{k}_{t+1} &= (1 - \delta - \alpha \delta) \dot{k}_t + \delta z_t \\ \text{Recall:} \\ z_t &= \rho z_{t-1} + w_t \\ &= \rho L z_t + w_t \\ (1 - \rho L) z_t &= w_t \\ z_t &= \frac{1}{1 - \rho L} w_t \end{aligned}$$

Plugging this back into our equation for  $\widehat{k_{t+1}}$ 

$$\widehat{k_{t+1}} = (1 - \delta - \alpha \delta)\widehat{k_t} + \delta(\frac{1}{1 - \rho L}w_t)$$

Then plugging in the lag operator, L

$$\widehat{k_{t+1}} = (1 - \delta - \alpha \delta) L \widehat{k_{t+1}} + \delta(\frac{1}{1 - \rho L} w_t)$$

$$\widehat{k_{t+1}} - (1 - \delta - \alpha \delta) \widehat{Lk_{t+1}} = \delta(\widehat{\frac{1}{1-\rho L}} w_t)$$

$$[1 - (1 - \delta - \alpha \delta)L]\widehat{k_{t+1}} = \delta(\frac{1}{1 - \rho L}w_t)$$

$$\widehat{k_{t+1}} = \delta(\frac{1}{[1 - (1 - \delta - \alpha \delta)L](1 - \rho L)}) w_t$$

Lets denote  $1 - (1 - \delta - \alpha \delta)L$  as  $\rho_1$  and the previous  $\rho$  as  $\rho_2$ , which will make the equation of the form:

$$\widehat{k_{t+1}} = \delta(\frac{1}{[1-\rho_1 L](1-\rho_2 L)})w_t$$

$$= (1-\rho_1 L)(1-\rho_2 L)\widehat{k_{t+1}} = \delta w_t$$

$$[1-(\rho_1+\rho_2)L+\rho_1\rho_2 L^2]\widehat{k_{t+1}} = \delta w_t$$

$$\widehat{k_{t+1}} - (\rho_1+\rho_2)\widehat{k_t} + \rho_1\rho_2 k_{t-1} = \delta w_t$$
Let us denote  $\rho_1+\rho_2$  as  $\phi_1$  and  $\rho_1\rho_2$  as  $\phi_2$ 
Now  $\widehat{k_{t+1}}$  is rewritten as an AR(2) process:
$$\widehat{k_{t+1}} = \phi_1 \widehat{k_t} + \phi_2 \widehat{k_{t-1}} + \delta w_t$$