

Problem Three

Michael Cai

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Output

$$y_t = e^{z_t} k_t^\alpha$$

Suppose y_t and k_t changes around their steady states y and k

$$\hat{y}_t = \log\left(\frac{y_t}{y}\right)$$

$y_t = ye^{\hat{y}_t}$ and k_t follows the same form.

$$\text{Then } ye^{\hat{y}_t} = e^{z_t} (ke^{\hat{k}_t})^\alpha$$

In the steady-state $z_t = 0$, thus $e^{z_t} = 1$

$$\therefore y = k^\alpha$$

Thus dividing both sides by y/k^α equivalently, we get:

$$= e^{\hat{y}_t} = e^{z_t} (e^{\hat{k}_t})^\alpha$$

And taking logs we get:

$$\hat{y}_t = z_t + \alpha \hat{k}_t$$

Capital

$$k_{t+1} = (1 - \delta)k_t + se^{z_t} k_t^\alpha$$

k_t and k_{t+1} changes around its steady state k .

Therefore:

$$ke^{\hat{k}_{t+1}} = (1 - \delta)ke^{\hat{k}_t} + se^{z_t} (ke^{\hat{k}_t})^\alpha$$

Dividing by k we get:

$$e^{\hat{k}_{t+1}} = (1 - \delta)e^{\hat{k}_t} + \frac{sk^\alpha}{k} e^{z_t} (e^{\hat{k}_t})^\alpha$$

$$\text{Recall: } k_{t+1} = (1 - \delta)k_t + sy_t$$

In the steady-state:

$$k = (1 - \delta)k + sy$$

$$k - (1 - \delta)k = sy$$

$$\delta k = sy$$

$$\text{Because } y = k^\alpha$$

$$\delta k = sk^\alpha$$

$$\delta = \frac{sk^\alpha}{k}$$

Thus replacing $\frac{sk^\alpha}{k}$ in our last equation with δ we get:

$$\begin{aligned}
\widehat{e^{k_{t+1}}} &= (1 - \delta)e^{\hat{k}_t} + \delta e^{z_t}(e^{\hat{k}_t})^\alpha \\
\text{Recall from the Taylor Series expansion of } e^x \\
e^x &= 1 + x + \frac{1}{2}x^2 + \dots \\
&\approx 1 + x \\
\text{Thus } \widehat{e^{k_{t+1}}} &\approx 1 + \widehat{k_{t+1}} = (1 - \delta)(1 + \hat{k}_t) + \delta(1 + z_t + \alpha \hat{k}_t) \\
&= (1 - \delta) + (1 - \delta)\hat{k}_t + \delta + \delta z_t + \alpha \delta \hat{k}_t \\
\widehat{k_{t+1}} &= (1 - \delta)\hat{k}_t + \delta z_t + \alpha \delta \hat{k}_t \\
\widehat{k_{t+1}} &= \delta z_t + (1 - \delta + \alpha \delta)\hat{k}_t
\end{aligned}$$

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Expressing as ARMA processes

$$\widehat{k_{t+1}} = (1 - \delta - \alpha \delta)\hat{k}_t + \delta z_t$$

Recall:

$$z_t = \rho z_{t-1} + w_t$$

$$= \rho L z_t + w_t$$

$$(1 - \rho L)z_t = w_t$$

$$z_t = \frac{1}{1 - \rho L} w_t$$

Plugging this back into our equation for $\widehat{k_{t+1}}$

$$\widehat{k_{t+1}} = (1 - \delta - \alpha \delta)\hat{k}_t + \delta\left(\frac{1}{1 - \rho L} w_t\right)$$

Then plugging in the lag operator, L

$$\widehat{k_{t+1}} = (1 - \delta - \alpha \delta)L\widehat{k_{t+1}} + \delta\left(\frac{1}{1 - \rho L} w_t\right)$$

$$\widehat{k_{t+1}} - (1 - \delta - \alpha \delta)L\widehat{k_{t+1}} = \delta\left(\frac{1}{1 - \rho L} w_t\right)$$

$$[1 - (1 - \delta - \alpha \delta)L]\widehat{k_{t+1}} = \delta\left(\frac{1}{1 - \rho L} w_t\right)$$

$$\widehat{k_{t+1}} = \delta\left(\frac{1}{[1 - (1 - \delta - \alpha \delta)L](1 - \rho L)}\right) w_t$$

Lets denote $1 - (1 - \delta - \alpha \delta)L$ as ρ_1 and the previous ρ as ρ_2 , which will make the equation of the form:

$$\widehat{k_{t+1}} = \delta\left(\frac{1}{[1 - \rho_1 L][1 - \rho_2 L]}\right) w_t$$

$$= (1 - \rho_1 L)(1 - \rho_2 L)\widehat{k_{t+1}} = \delta w_t$$

$$[1 - (\rho_1 + \rho_2)L + \rho_1 \rho_2 L^2]\widehat{k_{t+1}} = \delta w_t$$

$$\widehat{k_{t+1}} - (\rho_1 + \rho_2)\hat{k}_t + \rho_1 \rho_2 \widehat{k_{t-1}} = \delta w_t$$

Let us denote $\rho_1 + \rho_2$ as ϕ_1 and $\rho_1 \rho_2$ as ϕ_2

Now $\widehat{k_{t+1}}$ is rewritten as an AR(2) process:

$$\widehat{k_{t+1}} = \phi_1 \hat{k}_t + \phi_2 \widehat{k_{t-1}} + \delta w_t$$

Now to represent output as well.

$$\text{Recall: } \hat{y}_t = z_t + \alpha k_t = \frac{1}{1 - \rho L} w_t + \frac{\alpha \delta}{(1 - (1 - \delta + \alpha \delta)L)(1 - \rho L)} w_t$$

$$\hat{y}_t = \frac{1 + \alpha \delta - (1 - \delta + \alpha \delta)L}{(1 - (1 - \delta + \alpha \delta)L)(1 - \rho L)} w_t$$

$$\hat{y}_t + \phi_1 \widehat{y_{t-1}} + \phi_2 \widehat{y_{t-2}} = [1 + \alpha \delta - (1 - \delta + \alpha \delta)L] w_t$$

$$= (1 + \alpha\delta)w_t - (1 - \delta + \alpha\delta)w_{t-1}$$

$$\hat{y}_t = \phi_1 \widehat{y_{t-1}} + \phi_2 \widehat{y_{t-2}} + (1 + \alpha\delta)w_t - (1 - \delta + \alpha\delta)w_{t-1}$$

Thus output is represented as an ARMA(2,1) process.