# Introduction to statistics TODO subtitle

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# Summary:

- Probability concepts
- Discrete distributions.
- Continuous distributions.
- Calculations on the Normal distribution.
- Convergence
- Inference

#### Motivation



Figure 1: Dados apontam  $\dots$  (data shows  $\dots$ )

#### Sample space $\Omega$

It's the set of all the possible outcomes of a experiment, denoted by S or  $\Omega$ 

#### **Event**

It's a subset of the sample space.

#### Properties needed:

Given a sample sample  $\Omega$  the class of events denoted by  ${\mathcal A}$  need to satisfy the following properties:

- $\emptyset \in \mathcal{A}$ :

## Probability (Definition):

Given a experiment with a sample space  $\Omega$  and a class of events  $\mathcal{A}$ , the probability denoted by  $\mathbb{P}$  is a function which has  $\mathcal{A}$  as domain and associate a numerical value between [0,1] as image.

#### Probability properties:

- lacksquare  $\mathbb{P}(\Omega)=1$  and  $\mathbb{P}(\emptyset)=0$
- $0 \leq \mathbb{P}(A) \leq 1$ , for every event A
- § For any sequence of mutually exclusive events  $A_1, A_2, ...$  that's events that  $A_i \cap A_j$  when  $i \neq j$  we have that:

$$\mathbb{P}\left(\bigcup_{i=1}^{\infty}A_i\right)=\sum_{i=1}^{\infty}\mathbb{P}(A_i)$$

#### Event independence:

Two events are independent when the occurrence of the first does not influence the second.

Two events A and B are independent if:

$$\mathbb{P}(A \cap B) = \mathbb{P}(A)\mathbb{P}(B)$$

#### Conditional Events:

The probability of a event A to occur given that the event B occurred is:

$$\mathbb{P}(A|B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)}$$

#### Bayes theorem:

$$\mathbb{P}(A|B) = \frac{\mathbb{P}(B|A)\mathbb{P}(A)}{\mathbb{P}(B)}$$

General case:

$$\mathbb{P}(A_i|B) = \frac{\mathbb{P}(B|A_i)\mathbb{P}(A_i)}{\sum_{j=1}^n \mathbb{P}(B|A_j)\mathbb{P}(A_j)}$$

## Bayes example (from Veritasium):

You are felling sick, so you go to the doctor, there you run a battery of tests. After getting the results you tested positive for a rare disease (affects 0.1% of the population), the test will correctly identify that you have 99% of the times.

What's the chances that you actually have the disease? 99%?

#### Bayes example Solution

Let's denote the event of you have the disease H (stands for hypothesis, the prior) and the test been positive denoted by E (stands for evidence), so we have:  $\mathbb{P}(H) = 0.001$  and  $\mathbb{P}(E|H) = 0.99$ 

$$\mathbb{P}(H|E) = \frac{\mathbb{P}(E|H)\mathbb{P}(H)}{\mathbb{P}(E)} = \frac{\mathbb{P}(E|H)\mathbb{P}(H)}{\mathbb{P}(H)\mathbb{P}(E|H) + \mathbb{P}(H^C)\mathbb{P}(E|H^C)} = \frac{0.99 \cdot 0.001}{0.001 \cdot 0.99 + 0.999 \cdot 0.01} = 0.09 = 9\%$$

What if you test again and it's also positive? You can just take the posterior probability we just calculated and use as a prior:

$$= \frac{0.99 \cdot 0.09}{0.001 \cdot 0.99 + 0.999 \cdot 0.01} = 0.907 \approx 91\%$$

• Awesome video: A visual guide to Bayesian thinking

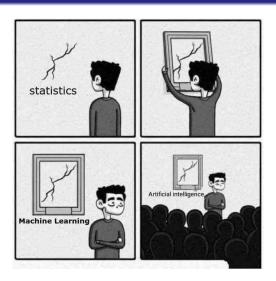


Figure 2: Credits: sandserifcomics

## Random Variable (RV)

Consider a experiment with a sample sample  $\Omega$  associated with it. A function that maps each element  $\omega \in \Omega$  to a Real number it's called random variable (RV)  $(X : \Omega \to \mathbb{R})$ 

• Example: Imagine a experiment that consist of 3 consecutive fair coin tosses, so the sample space of this experiment is:  $S = \{(H,H,H), (H,H,T), \dots (T,T,T)\}$ . Now we want to create a random variable X that counts the number of heads in

each outcome, so X((H,H,H)) = 3 and X((H,H,T)) = 2.

## Random Variable:

## Probability Mass Function (PMF):

$$f_X(x) = \mathbb{P}[X = x] = \mathbb{P}[\{\omega \in \Omega : X(\omega) = x\}]$$

## Probability Density Function (PDF)

$$\mathbb{P}[a \le X \le b] = \int_a^b f(x) dx$$

## Cumulative Distribution Function (CDF)

$$F_X(x) = \mathbb{P}[X \leq x]$$

#### Expectation:

- Discrete :  $\mathbb{E}[X] = \sum x \mathbb{P}(X = x)$ 
  - Continuous:  $\mathbb{E}[X] = \int_{-\infty}^{\infty} xf(x)dx$

# Variance:

$$\mathbb{V}[X] = \sigma_X^2 = \mathbb{E}[X^2] - \mathbb{E}^2[X]$$

# Sample mean:

$$\overline{X_n} = \frac{1}{n} \sum_{i=1}^n X_i$$

$$s^{2} = \frac{1}{n-1} \sum_{i=1}^{n} (X_{i} - \overline{X})^{2}$$

# Discrete distributions

#### Bernoulli:

Consider a experiment with has two possible outcomes: success (X=1, with probability p) or failure (X=0), this random variable is called Bernoulli, the PMF is:

$$\mathbb{P}(X=k)=p^k(1-p)^{1-k}$$

#### Binomial:

Now consider a Bernoulli experiment conducted n times, let X be the random variable that represents the number of successes, X is called Binomial, the PMF is:

$$\mathbb{P}(X=k) = \binom{n}{k} p^k (1-p)^{n-k}$$

## Discrete distributions

#### Geometric:

Again consider a Bernoulli experiment conducted n times, but the first n-1 are failures and the last nth is a success. Let X be number of tries, which is called Geometric, the PMF is:

$$\mathbb{P}(X=k)=(1-p)^kp$$

 A important property is that Geometric distribution is memoryless (TODO definir)

#### Poisson:

A random variable which value can assume 0,1,2 . . . is called Poisson with  $\lambda > 0$  parameter if your PMF is:

$$\mathbb{P}(X=k) = \frac{e^{-\lambda}\lambda^k}{k!}$$

#### Continuous distributions

- Normal
- Exponential memoryless, sunk costs (https://youarenotsosmart.com/2011/03/25/the-sunk-cost-fallacy/)
- Pareto

meme know distributions

# Calculations on the Normal distribution tabela e calcular python, excel, normalizar

## order statitics

defs, min, max, median, q1,q3, IQR, pq? estat robusta, boxplot

# Convergence

defs, lei dos grandes numeros, teorema do limite central

## Inference

metodo da maxima verosimilhanca, e grafico qxq

#### Further reading:

- Portal action (pt)
- stat cookbook
- havard youtube
- (https://www.youtube.com/playlist?list=PL2SOU6wwxB0uwwH80KT oross, barry james, meyer
- khan academy
- http://www.randomservices.org/random/