

**University of Brasília**  
**Electrical Engineering Department**



**Topics in Biomedical Engineering**  
**Exercise 3.28 - Semmlow**

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# 1 Exercises

## 1.1 Exercise 3.28:

The MATLAB's code:

```
1 % exercise 3.28 - Semmlow
2 clc; close all; clear all;
3
4 fs = 1e3; % sampling frequency
5 samples = [64, 512]; % array of samples
6 windows = 'Rectangular Blackman Hamming';
7 windows = string(split(windows)'); % windowed filter
   names
8 pos = 1; % counter used in for loop to plot
9
10 for N = samples
11     [s, t] = sig_noise([200, 300], -4, N); % signal with
        noise
12     filters = [ones(1, N); blackman(N)'; hamming(N)']; %
        filters functions
13     f = (0:N-1)*(fs/N); % frequency axis
14
15     for i = 1:3
16         subplot(2, 3, pos);
17         sf = s.*filters(i,:); % applying filter
18         S_mag = fft(sf); % fft
19         S_mag = (2/N)*abs(S_mag(1:N/2)); % fft
            normalized mag
20         plot(f(1:N/2), S_mag, 'linewidth', 1.1); % only
            positive freqs plot
21         xlabel('Frequency (Hz)');
22         ylabel('Magnitude Spectrum');
23         grid on;
24         title(sprintf('%s | N = %d', windows(i), N));
25         pos = pos + 1; % ++counter to subplot
26     end
27 end
28
29 sgtitle('Comparison of windowed filters w/ N = [64, 512']
```

```

] ', 'Interpreter', 'latex');
30 saveas(gcf, sprintf('%s.png', mfilename)); % save image

```

According to the Figure 1, it's notorious the difference between 64 and 512 samples in the three types of windows applied to the signal. The 512-samples has a better resolution of the signal spectrum and of the existing frequencies than the 64-samples, this better resolution happens because de sampling frequency is constant and only  $N$  changes (Equation 1) and generates a smaller step,  $f_i$ , between the  $N$  points. The difference of the plotted magnitude spectra of the three windowed filters is slightly, there's only a quite difference between the amplitude value and some points, but certainly there's a difference. The windowed filters (Rectangular, Hamming and Blackman) have their own particularities and the most appropriate varies according to the situation.

$$f_{axis} = (0 : N - 1) \cdot f_i, \quad f_i = \frac{f_s}{N} \quad (1)$$

Comparison of windowed filters w/  $N = [64, 512]$

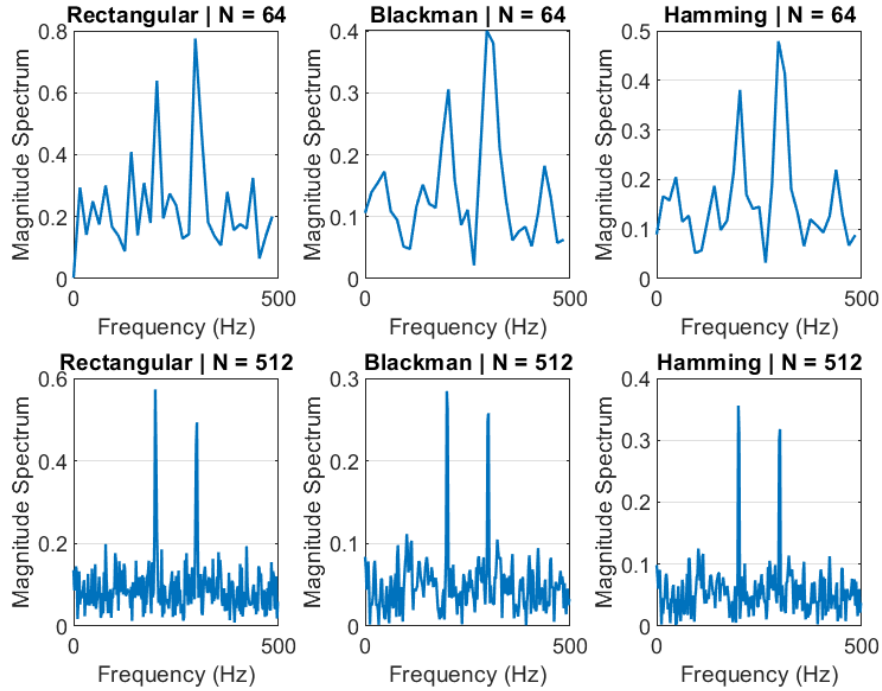


Figure 1: Comparison of windowed filters with different values of  $N$