

Acceleration and Stochastic Gradient Descent

Hanchao Zhang

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QUIZ

Momentum Gradient Descent

$$w^{k+1} = w^k - \alpha z^{k+1}$$

$$z^{k+1} = \beta z^k + \nabla f(w^k)$$

1. Each step of momentum gradient descent should be closer to the optimal point compared to the gradient descent method with the same step size.
 - TRUE
 - FALSE
2. In the setting of $f(w) = \frac{1}{2}w^T A w - b^T w$, $A \succ 0$, only the largest eigenvalue of A controls the convergence rate of momentum gradient descent.
 - TRUE
 - FALSE

Overview

1. Stochastic Gradient Descent

2. Momentum Acceleration

Stochastic Gradient Descent

Motivation

- no access to full gradient
- too expensive to compute the full gradient

Solution

- use the noisy (stochastic) version of the gradient
 - stochastic gradient descent
 - random coordinate descent

Quick Peek – Stochastic Gradient Descent

Gradient Descent

$$x^{k+1} = x^k - \eta \nabla f(x^k)$$

Noisy Gradient

$$\tilde{g}(x) = \nabla f(x) + \epsilon$$

where ϵ is zero mean, and

$$E[\tilde{g}(x)] = \nabla f(x)$$

Stochastic Optimization

Original Optimization Problem

$$\begin{aligned} \min f(x) \\ \text{subject to } x \in \mathcal{X} \end{aligned}$$

Stochastic Optimization

$$\begin{aligned} \min_x E_{\xi}[f(x; \xi)] \\ \text{subject to } x \in \mathcal{X} \end{aligned}$$

Example – Regression Problem

$$\begin{aligned} \min_x E_{\xi}[(y - \xi^T x)^2] \\ \text{subject to } x \in \mathcal{X} \end{aligned}$$

Example – Regression Setting

$$\begin{aligned} & \min_x E_{\xi}[(y - \xi^T x)^2] \\ &= \min_x \frac{1}{n} \sum_{i=1}^n (y_i - \xi_i^T x)^2 \\ &= \min_x f(x) = \frac{1}{n} \sum_{i=1}^n f_i(x) \\ & \text{subject to } x \in \mathcal{X} \end{aligned}$$

Gradient Descent

$$x_{t+1} = x_t - \eta \nabla \left(\frac{1}{n} \sum_{i=1}^n f_i(x) \right)$$

Very Expensive! Require Full pass over the data.

Example – Stochastic Optimization

1. Stochastic Gradient

$$x \implies \square \implies \cancel{\nabla f(x)} \implies \tilde{g}(x) = \nabla f_l(x)$$

$$l \sim \text{uniform}(1, 2, \dots, n)$$

Q: is \tilde{g} stochastic gradient?

$$E_l[\nabla f_l(x)] = \sum_{i=1}^n \nabla f_i(x) \cdot \frac{1}{n} = \nabla f(x)$$

Example – Stochastic Optimization

2. Random Coordinate Descent

$$x \Rightarrow \square \Rightarrow \cancel{\nabla f(x)} \Rightarrow \tilde{g}(x) = d \nabla f_J(x) = d \cdot \begin{bmatrix} 0 \\ \vdots \\ \frac{\partial f}{\partial x_j} \\ \vdots \\ 0 \end{bmatrix}$$

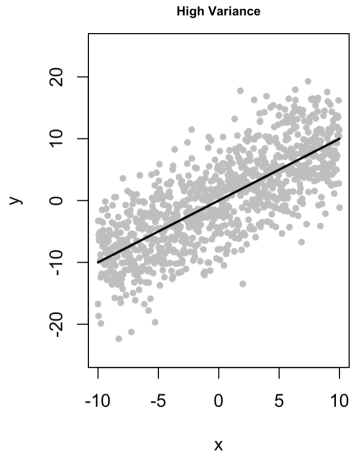
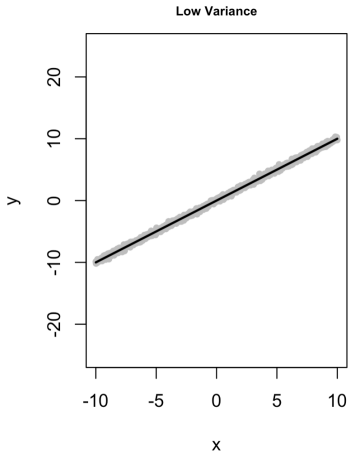
$$J \sim \text{uniform}(1, \dots, d)$$

Q: is \tilde{g} stochastic gradient?

$$E_J[\tilde{g}(x)] = \sum_{j=1}^n d \cdot \nabla f_j(x) \cdot \frac{1}{d} = \nabla f(x)$$

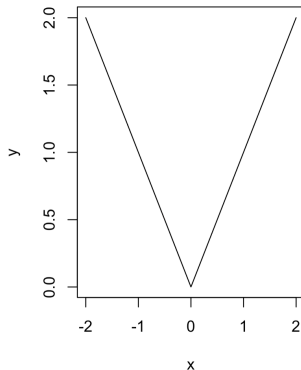
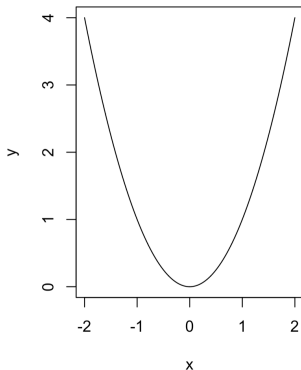
SGD – Role of Variance

Regression Setting



SGD – Why Variance Matters

Self-tuning



When Polyak-Lojasiewicz Inequality hold, $x \rightarrow x^*$, $\nabla f(x) \rightarrow 0$

SGD

Theorem: Convergence Rate

Suppose x^* exists, and $E_{\xi}[\|\tilde{g}(x)\|^2] \leq G^2 \quad \forall x$.

$$x_{t+1} = x_t - \eta \tilde{g}(x)$$

then

$$E_{\xi}[f(\frac{1}{T} \sum_{t=1}^T x_t)] - f(x^*) \leq \frac{RG^2}{\sqrt{T}}$$

$$R^2 \geq \|x_1 - x^*\|_2^2$$

SGD

Theorem: Convergence Rate

Suppose x^* exists, and $E[\|\tilde{g}(x)\|^2] \leq G^2 \quad \forall x$, and f is μ strongly convex, may not be smooth, then SGD with decreasing step size $\eta_t = \frac{2}{\mu(t+1)}$

$$x_{t+1} = x_t - \eta_t \tilde{g}(x)$$

then

$$E[f(\frac{2t}{T(T+1)} \sum_{t=1}^T x_t)] - f(x^*) \leq \frac{2G^2}{\mu} \frac{1}{T+1} = \mathcal{O}(\frac{1}{T})$$

Quick Summary

- convergence rate = $\mathcal{O}(\frac{1}{\sqrt{T}})$ when $E[\|\tilde{g}\|_2^2] \leq G^2$

Question: Can we go a little bit better, what's the key?

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- convergence rate = $\mathcal{O}(\frac{1}{\sqrt{T}})$ when $E[\|\tilde{g}\|_2^2] \leq G^2$
- convergence rate = $\mathcal{O}(\frac{1}{T})$ when we have strong convexity

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Question: Can we go a little bit better, what's the key?

self-tuning property

Two Ways To Reduce Variance

- Mini-Batch
- Recentering

Convergence Rate of SGD

$$x_{t+1} = x_t - \eta \nabla f_l(x_t)$$

$$E\left(\frac{1}{T} \sum_{i=1}^T x_t\right) - f(x^*) \leq \frac{RG^2}{\sqrt{T}} \leq \frac{\|x_1 - x^*\|}{\sqrt{T}} \sqrt{E[\|\nabla f_l(x)\|_2^2]}$$

Recall that $R \leq \|x_1 - x^*\|$, and $E[\|\nabla f_l(x)\|_2^2] \leq G^2$

Convergence Rate of SGD

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Recall that $R \leq \|x_1 - x^*\|$, and $E[\|\nabla f_l(x)\|_2^2] \leq G^2$

Question: Can we control $\sqrt{E[\|\nabla f_l(x)\|_2^2]}$?

Mini-Batch SGD

$$x \Rightarrow \square \Rightarrow \cancel{\nabla f(x)} \Rightarrow \tilde{g}(x) = \frac{1}{B} \sum_{j=1}^B \nabla f_{l_j}(x)$$
$$l_j \sim \text{uniform}(1, 2, \dots, n)$$

Question: is $\tilde{g}(x)$ stochastic gradient?

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$$l_j \sim \text{uniform}(1, 2, \dots, n)$$

Question: is $\tilde{g}(x)$ stochastic gradient?

check:

$$E_l \left[\frac{1}{B} \sum_{j=1}^B \nabla f_{l_j}(x) \right] = \frac{1}{B} \sum_{j=1}^B \nabla f(x) = \nabla f(x)$$

Does it help?

assume variance is independent,

$$\text{Var} \left(\frac{1}{B} \sum_{j=1}^B \nabla f_{l_j}(x) \right) = \frac{1}{B^2} \sum_{j=1}^B \text{Var}(\nabla f_{l_j}(x)) = \frac{1}{B} \text{Var}(\nabla f(x))$$

Mini-Batch SGD

Advantages

- reduce variance
- mini-batch is parallelizable

Disadvantages

- more work per iteration
- no self-tuning when the f is smooth

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- no self-tuning when the f is smooth

Question: can we do better?

We need self-tuning when f smooth and strongly convex

Reduce Variance by Recentering

For x and y

$$x, y \Rightarrow \square \Rightarrow \cancel{\nabla f(x)} \Rightarrow \tilde{g}(x) = \nabla f_l(x) - (\nabla f_l(y) - \nabla f(y))$$

$$l \sim \text{uniform}(1, 2, \dots, n)$$

$$E_l[\tilde{g}(x)] = E_l[\nabla f_l(x) - (\nabla f_l(y) - \nabla f(y))]$$

$$= \nabla f(x) - \cancel{(\nabla f(y) - \nabla f(y))} \xrightarrow{0}$$

Stochastic Variance Reduced Gradient Descent Algorithm (SVRG)

Outer Loop:

On the k^{th} iteration

$$x_1 = y_k$$

Inner Loop:

for $t = 1, 2, \dots T$

$$x_{t+1} = x_t - \eta \left(\nabla f_l(x_t) - (\nabla f_l(y_k) - \nabla f(y_k)) \right)$$

update $y_{k+1} = \frac{1}{T} \sum_{i=1}^T x_t$, and compute $\nabla f(y_{k+1})$

- inner loop only compute $\nabla f_l(x_t)$
- outer loop compute full gradient $\nabla f(y_{k+1})$

Variance Reduction Lemma

Variance Reduction Lemma

Let $f_1 \dots f_n$ be L -smooth, $I \sim \text{uniform}(1, \dots, n)$. Then

$$E_I \left[\|\nabla f_I(x) - \nabla f_I(x^*)\|_2^2 \right] \leq 2L(f(x) - f(x^*))$$

Note: $\nabla f_I(x)$ may not be small when $x \rightarrow x^*$

Proof of Variance Reduction Lemma

Let $g_i(x) = f_i(x) - [f_i(x^*) + \nabla f_i(x^*)^T(x - x^*)] \geq 0$ by convexity

If h is convex and L -smooth, $h(x - \frac{1}{L}\nabla h(x)) \leq h(x) - \frac{1}{2L}\|\nabla h(x)\|_2^2$ and applies this to g

$$0 \leq g_i(x - \frac{1}{L}\nabla g_i(x)) \leq g_i(x) - \frac{1}{2L}\|\nabla g_i(x)\|_2^2$$

\downarrow

$$-g_i(x) \leq -\frac{1}{2L}\|\nabla g_i(x)\|_2^2$$

\downarrow

$$\|\nabla g_i(x)\|_2^2 \leq 2Lg_i(x)$$

Proof of Variance Reduction Lemma – Continuous

$$g_i(x) = f_i(x) - [f_i(x^*) + \nabla f_i(x^*)^T (x - x^*)] \geq 0$$

$$\|\nabla g_i(x)\|_2^2 = \|\nabla f_i(x) - \nabla f_i(x^*)\|_2^2 \leq 2L \left(f_i(x) - f_i(x^*) + \nabla f_i(x^*)^T (x - x^*) \right)$$

$$\begin{aligned} E_l \left[\|\nabla f_l(x) - \nabla f_l(x^*)\| \right] &\leq 2LE \left[f_l(x) - f_l(x^*) + \nabla f_l(x^*)^T (x - x^*) \right] \\ &\leq 2L \left(f(x) - f(x^*) + \cancel{\nabla f(x^*)^T}^0 (x - x^*) \right) \end{aligned}$$

The recentered gradient $E_l \left[\|\nabla f_l(x) - \nabla f_l(x^*)\| \right] \rightarrow 0$, when $x \rightarrow x^*$

Stochastic Variance Reduction Gradient Descent

SVRG Theorem

Let $f = \frac{1}{n} \sum_{i=1}^n f_i(x)$, f_i is L -smooth, and f is μ strongly convex. SVRG algorithm with step size $\eta = \frac{1}{10 \cdot L}$, and inner loop size $T = 10 \cdot (\frac{L}{\mu})$.

Then after $s + 1$ iterations of the outer loop

$$E[f(y^{s+1})] - f(x^*) \leq 0.9^s (f(y^1) - f(x^*))$$

Key Feature:

- linear convergence
- L/μ does not appear in the convergence rate

Proof of SVRG Algorithm

good enough to prove $E[f(y^{s+1})] - f(x^*) \leq 0.9(f(y^s) - f(x^*))$

Recall: $y^{s+1} = \frac{1}{T} \sum x_t$, where x_t is provided in s^{th} inner loop

$$\begin{aligned} \|x_{t+1} - x^*\|_2^2 &= \left\| x_t - \eta \left(\nabla f_t(x_t) - (\nabla f_t(y) - \nabla f(y)) \right) - x^* \right\|_2^2 \\ &= \|x_t - x^*\|_2^2 - 2\eta \underbrace{\left(\nabla f_t(x_t) - \nabla f_t(y) + \nabla f(y) \right)^T}_{V_t} (x_t - x^*) + \eta^2 \|V_t\|_2^2 \\ &\quad \text{variance term} \\ &= \underbrace{\|x_t - x^*\|_2^2}_a - \underbrace{2\eta V_t^T (x_t - x^*)}_b + \underbrace{\eta^2 \|V_t\|_2^2}_c \end{aligned}$$

$a \rightarrow 0$ and $b \rightarrow 0$ when $x_t \rightarrow x^*$, we want the term c goes to 0 as well

Proof of SVRG Algorithm

Let's just look at the term c

$$\begin{aligned} E\left[\|V_t\|_2^2\right] &= E\left[\|\nabla f_{l_t}(x_t) - \nabla f_{l_t}(y) + \nabla f(y)\|_2^2\right] \\ &= E\left[\|\nabla f_{l_t}(x_t) - \nabla f_{l_t}(x^*) + \nabla f_{l_t}(x^*) - \nabla f_{l_t}(y) + \nabla f(y)\|_2^2\right] \\ &\leq 2E\left[\|\nabla f_{l_t}(x_t) - \nabla f_{l_t}(x^*)\|_2^2\right] + \underbrace{2E\left[\|\nabla f_{l_t}(x^*) - \nabla f_{l_t}(y) + \nabla f(y)\|_2^2\right]}_{=0} \\ &\leq 2E\left[\|\nabla f_{l_t}(x_t) - \nabla f_{l_t}(x^*)\|_2^2\right] + 2E\left[\|\nabla f_{l_t}(y) - \nabla f_{l_t}(x^*)\|_2^2\right] \\ &\leq 4L(f(x_t) - f(x^*) + f(y) - f(x^*)) \quad \text{by variance reduction lemma twice} \end{aligned}$$

Proof of SVRG Algorithm

Let's just look at the term c

$$\begin{aligned} E[||V_t||_2^2] &= E[||\nabla f_{l_t}(x_t) - \nabla f_{l_t}(y) + \nabla f(y)||_2^2] \\ &= E[||\nabla f_{l_t}(x_t) - \nabla f_{l_t}(x^*) + \nabla f_{l_t}(x^*) - \nabla f_{l_t}(y) + \nabla f(y)||_2^2] \\ &\leq 2E[||\nabla f_{l_t}(x_t) - \nabla f_{l_t}(x^*)||_2^2] + \underbrace{2E[||\nabla f_{l_t}(x^*) - \nabla f_{l_t}(y) + \nabla f(y)||_2^2]}_{=0} \\ &\leq 2E[||\nabla f_{l_t}(x_t) - \nabla f_{l_t}(x^*)||_2^2] + 2E[||\nabla f_{l_t}(y) - \nabla f_{l_t}(x^*)||_2^2] \\ &\leq 4L(f(x_t) - f(x^*) + f(y) - f(x^*)) \quad \text{by variance reduction lemma twice} \end{aligned}$$

ps $E[(Y - E(Y))^2] \leq E[Y^2]$

Proof of SVRG Algorithm

term b

$$\begin{aligned} E \left[2\eta V_t^T (x_t - x^*) \right] &= 2\eta E[V_t]^T (x_t - x^*) \\ &= 2\eta \nabla f(x_t)^T (x_t - x^*) \\ &\geq 2\eta (f(x_t) - f(x^*)) \quad \text{by convexity} \end{aligned}$$

Then, we have

$$\begin{aligned} E \left[\|x_{t+1} - x^*\|_2^2 \right] &= E[a + b + c] \\ &\leq \|x_t - x^*\|_2^2 - 2\eta (f(x_t) - f(x^*)) + 4\eta^2 L (f(x_t) - f(x^*) + f(y) - f(x^*)) \\ &= \|x_t - x^*\|_2^2 - 2\eta (1 - 2\eta L) (f(x_t) - f(x^*)) + 4\eta^2 L (f(y) - f(x^*)) \\ &\quad \downarrow \text{iterating} \\ &= \|x_1 - x^*\|_2^2 - 2\eta (1 - 2\eta L) \cdot E \left[\sum_{k=1}^t (f(x_k) - f(x^*)) \right] + 4\eta^2 L \cdot t (f(y) - f(x^*)) \end{aligned}$$

Proof of SVRG Algorithm

Recall:

- $x_1 = y^k$
- $\|y - x^*\|_2^2 \leq \frac{2}{\mu}(f(y) - f(x^*))$

$$E\left[\|x_{t+1} - x^*\|_2^2\right] \leq \|x_1 - x^*\|_2^2 - 2\eta(1 - 2\eta)L \cdot E\left[\sum_{k=1}^t (f(x_k) - f(x^*))\right] + 4\eta^2 L \cdot t(f(y) - f(x^*))$$

$$2\eta(1 - 2\eta)L \cdot E\left[f\left(\frac{1}{T} \sum x_t\right) - f(x^*)\right] \leq \left(\frac{2}{\mu} + \eta^2 4LT\right) \frac{1}{T} E(f(y) - f(x^*))$$

$$E[f(y^{s+1})] - f(x^*) \leq 0.9(E[f(y^s)] - f(x^*))$$

Accelerate Gradient Descent

Key Idea: use gradient computed at previous step to accelerate the algorithm

Methods:

- Momentum
- Nesterov

Momentum Acceleration

Momentum Method:

$$\begin{aligned}x_{k+1} &= x_k - \eta z_k \\z_k &= \nabla f(x_k) + \beta z_{k-1}\end{aligned}$$

Nesterov Method:

$$\begin{aligned}x_{t+1} &= x_t + d_t - \eta \nabla f(x_t + d_t) \\d_t &= \gamma_t (x_t - x_{t-1})\end{aligned}$$

Theorem

Let f to be L -smooth and μ -convex.

$$f(z_t) - f(x^*) \leq \frac{L + \mu}{2} \|x_1 - x^*\|_2^2 \cdot \exp\left\{\frac{(t+1)}{\sqrt{k}}\right\}$$

Summary

- gradient descent: $\mathcal{O}(n \frac{L}{\mu} \log(\frac{1}{\epsilon}))$ iterations for ϵ -accuracy
- momentum acceleration: $\mathcal{O}(n \sqrt{\frac{L}{\mu}} \log(\frac{1}{\epsilon}))$ iterations for ϵ -accuracy
- stochastic gradient descent: $\mathcal{O}(\frac{1}{\mu \epsilon})$ for ϵ -accuracy
- SVRG: $\mathcal{O}((n + \frac{L}{\mu}) \log(\frac{1}{\epsilon}))$ for ϵ -accuracy

The End