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% ECE 4560 - Homework 6, Problem 5
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%PART A
=====
%extend SE2 leftact to work for point (2x1) or vector (3x1) velocity
ga = SE2([1 1], pi/4);
T = [-2; 3];
v = [9; -3; pi/8];
fprintf('Part A \n\n')

%verify with SE2 * homogeneous matrix translation
disp('Verify leftact works with SE2 * homogeneous matrix
translation:')
parta1 = ga.leftact(T)

%verify with SE2 * velocity vector
disp('Verify leftact works with SE2 * velocity vector:')
parta2 = ga.leftact(v)

%PART B
=====
%amend adjoint to operate on vectors
%show SE2 works with adjoint * vector-velocity problem : HW5prob 3

gCB = SE2([0,3], -pi/6); %given in HW5.2
zBB = [2; -3; pi/9]; %given in HW5.2
gBC = inv(gCB);
disp('Part B')

zCC = adjoint(zBB, gBC)
zCCsoln = [2.3252; -2.127; 0.3491] %from HW5.3

%PART C
=====
%show that (Adgxi)^ = Adg(xi)^ (in vector form) and vice versa with
unhat
%(in homogeneous form)
g = SE2([4;5], pi/3);
disp('Part C')

%verify hat
disp('verify (Adgxi)^ = Adg(xi)^:')
xiVec1 = [4; 6; pi/12];
xiHat1 = SE2.hat(xiVec1);
adj1 = adjoint(xiVec1, g);
left1 = SE2.hat(adj1)
right1 = adjoint(xiHat1, g)

%verify unhat

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disp('verify (Adgxihat)v = Adg(xihat)v:')
xiHat2 = [0      -pi/8   7;
          pi/8   0      -3;
          0      0      0];
xiVec2 = SE2.unhat(xiHat2);
adj2 = adjoint(xiHat2, g);
left2 = SE2.unhat(adj2)
right2 = adjoint(xiVec2, g)

```

Part A

Verify leftact works with SE2 * homogeneous matrix translation:

parta1 =

```

-2.5355
 1.7071
 1.0000

```

Verify leftact works with SE2 * velocity vector:

parta2 =

```

 8.8780
 4.6353
 0.3927

```

Part B

zCC =

```

 2.3252
-2.1217
 0.3491

```

zCCsoln =

```

 2.3252
-2.1270
 0.3491

```

Part C

verify (Adgxi)^ = Adg(xi)^:

left1 =

```

      0   -0.2618   -1.8872
0.2618      0     5.4169
      0      0      0

```

right1 =

-0.0000	-0.2618	-1.8872
0.2618	-0.0000	5.4169
0	0	0

`verify (Adgxihat)v = Adg(xihat)v:`

`left2 =`

8.0616
2.9914
0.3927

`right2 =`

8.0616
2.9914
0.3927

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