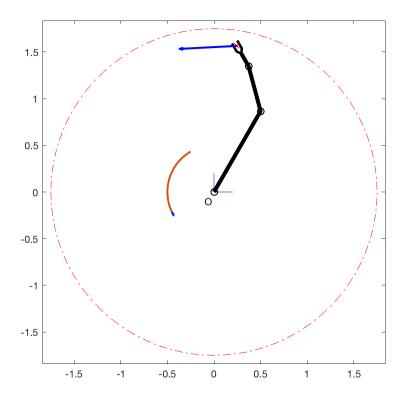
```
% ECE 4560 - Homework 11.1
% Caitlyn Caggia
11 = 1; 12 = 0.5; 13 = 0.25;
1 = [11;12;13];
a = [pi/3; pi/4; pi/12];
adot = [pi/12; pi/8; 0];
%part a
syms 11 12 13 a1 a2 a3;
a = [a1; a2; a3];
ge = [11*cos(a(1)) + 12*cos(a(1)+a(2)) + 13*cos(a(1)+a(2)+a(3));
      11*\sin(a(1)) + 12*\sin(a(1)+a(2)) + 13*\sin(a(1)+a(2)+a(3));
      a(1) + a(2) + a(3);
Jac = jacobian(ge, a)
%part b
adot = [pi/12; pi/8; 0];
11 = 1; 12 = 0.5; 13 = 0.25;
a1 = pi/3; a2 = pi/4; a3 = pi/12;
J11 = -12*sin(a1+a2) - 11*sin(a1) - 13*sin(a1+a2+a3);
J12 = -12*sin(a1+a2) - 13*sin(a1+a2+a3);
J13 = -13*sin(a1+a2+a3);
J21 = 12*\cos(a1 + a2) + 11*\cos(a1) + 13*\cos(a1 + a2 + a3);
J22 = 12*\cos(a1 + a2) + 13*\cos(a1 + a2 + a3);
J23 = 13*cos(a1 + a2 + a3);
J31 = 1;
J32 = 1;
J33 = 1;
Jac = [J11 J12 J13; J21 J22 J23; J31 J32 J33];
v = Jac * adot
disp('theta(v(3))) is positive so CCW rotation')
%part c
ge = [11*cos(a1) + 12*cos(a1+a2) + 13*cos(a1+a2+a3);
      11*\sin(a1) + 12*\sin(a1+a2) + 13*\sin(a1+a2+a3);
      a1 + a2 + a3;
gc = SE2([ge(1); ge(2)], ge(3));
planarR3_display([a1; a2; a3], [11; 12; 13])
velocityPlot(gc, v)
Jac =
[-12*sin(a1 + a2) - 11*sin(a1) - 13*sin(a1 + a2 + a3), -12*sin(a1 + a2)]
a2) - 13*sin(a1 + a2 + a3), -13*sin(a1 + a2 + a3)]
   12*cos(a1 + a2) + 11*cos(a1) + 13*cos(a1 + a2 + a3),
                                                            12*cos(a1 +
a2) + 13*cos(a1 + a2 + a3),  13*cos(a1 + a2 + a3)]
[
                                                       1,
                          1,
                                                  1]
```

```
-0.6845
  -0.0356
    0.6545
theta (v(3)) is positive so CCW rotation
    AlignVertexCenters: 'off'
            Annotation: [1x1 matlab.graphics.eventdata.Annotation]
             AutoScale: 'off'
       AutoScaleFactor: 0.9000
          BeingDeleted: 'off'
            BusyAction: 'queue'
         ButtonDownFcn: ''
              Children: [0×0 GraphicsPlaceholder]
              Clipping: 'on'
                 Color: [0 0 1]
             CreateFcn: ''
             DeleteFcn: ''
           DisplayName: ''
      HandleVisibility: 'on'
               HitTest: 'on'
         Interruptible: 'on'
             LineStyle: '-'
             LineWidth: 2
                Marker: 'none'
       MarkerEdgeColor: 'auto'
      MarkerFaceColor: 'none'
           MarkerSize: 6
           MaxHeadSize: 20
                Parent: [1×1 Axes]
         PickableParts: 'visible'
              Selected: 'off'
   SelectionHighlight: 'on'
         ShowArrowHead: 'on'
                   Taq: ''
                  Type: 'quiver'
                 UData: 0.0192
           UDataSource: ''
         UIContextMenu: [0x0 GraphicsPlaceholder]
              UserData: []
                 VData: -0.0366
           VDataSource: ''
               Visible: 'on'
                 WData: []
           WDataSource: ''
                 XData: -0.4522
             XDataMode: 'manual'
           XDataSource: ''
                 YData: -0.2134
             YDataMode: 'manual'
           YDataSource: ''
                 ZData: []
```

v =

ZDataSource: ''



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