Mixtures of Gaussians and Expectation Maximization algorithm

The following manuscript from PRML derives the EM algorithm for Mixtures of Gaussians. You can refer to PRML 9.2 for more details.

Recall that the Gaussian mixture distribution can be written as a linear superposition of Gaussians,

$$p(\mathbf{x}) = \sum_{k=1}^K \pi_k \mathcal{N}\left(\mathbf{x} \mid oldsymbol{\mu}_k, oldsymbol{\Sigma}_k
ight).$$

Let us introduce a K-dimensional binary random variable \mathbf{z} having a 1 -of- K representation in which a particular element z_k is equal to 1 and all other elements are equal to 0 . The values of z_k therefore satisfy $z_k \in \{0,1\}$ and $\sum_k z_k = 1$, and we see that there are K possible states for the vector \mathbf{z} according to which element is nonzero. We shall define the joint distribution $p(\mathbf{x},\mathbf{z})$ in terms of a marginal distribution $p(\mathbf{z})$ and a conditional distribution $p(\mathbf{x} \mid \mathbf{z})$. The marginal distribution over \mathbf{z} is specified in terms of the mixing coefficients π_k , such that

$$p\left(z_{k}=1
ight)=\pi_{k}$$

where the parameters $\{\pi_k\}$ must satisfy

$$0 \leqslant \pi_k \leqslant 1$$

together with

$$\sum_{k=1}^K \pi_k = 1$$

in order to be valid probabilities. Because ${\bf z}$ uses a 1 -of- K representation, we can also write this distribution in the form

$$p(\mathbf{z}) = \prod_{k=1}^K \pi_k^{z_k}.$$

Similarly, the conditional distribution of x given a particular value for z is a Gaussian

$$p\left(\mathbf{x} \mid z_k = 1\right) = \mathcal{N}\left(\mathbf{x} \mid \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k\right)$$

which can also be written in the form

$$p(\mathbf{x} \mid \mathbf{z}) = \prod_{k=1}^K \mathcal{N}(\mathbf{x} \mid oldsymbol{\mu}_k, oldsymbol{\Sigma}_k)^{z_k}.$$

The joint distribution is given by $p(\mathbf{z})p(\mathbf{x} \mid \mathbf{z})$, and the marginal distribution of \mathbf{x} is then obtained by summing the joint distribution over all possible states of \mathbf{z} to give

$$p(\mathbf{x}) = \sum_{\mathbf{z}} p(\mathbf{z}) p(\mathbf{x} \mid \mathbf{z}) = \sum_{k=1}^K \pi_k \mathcal{N}\left(\mathbf{x} \mid oldsymbol{\mu}_k, oldsymbol{\Sigma}_k
ight).$$

Thus the marginal distribution of \mathbf{x} is a Gaussian mixture of the form (9.7). If we have several observations $\mathbf{x}_1, \dots, \mathbf{x}_N$, then, because we have represented the marginal distribution in the form $p(\mathbf{x}) = \sum_{\mathbf{z}} p(\mathbf{x}, \mathbf{z})$, it follows that for every observed data point \mathbf{x}_n there is a corresponding latent variable \mathbf{z}_n .

We shall use $\gamma\left(z_{k}\right)$ to denote $p\left(z_{k}=1\mid\mathbf{x}\right)$, whose value can be found using Bayes' theorem

$$egin{aligned} \gamma\left(z_{k}
ight) &\equiv p\left(z_{k}=1\mid\mathbf{x}
ight) = rac{p\left(z_{k}=1
ight)p\left(\mathbf{x}\mid z_{k}=1
ight)}{\sum_{j=1}^{K}p\left(z_{j}=1
ight)p\left(\mathbf{x}\mid z_{j}=1
ight)} \ &= rac{\pi_{k}\mathcal{N}\left(\mathbf{x}\midoldsymbol{\mu}_{k},oldsymbol{\Sigma}_{k}
ight)}{\sum_{j=1}^{K}\pi_{j}\mathcal{N}\left(\mathbf{x}\midoldsymbol{\mu}_{j},oldsymbol{\Sigma}_{j}
ight)} \end{aligned}$$

The log of the likelihood function is given by

$$\log p(\mathbf{X}) = \sum_{n=1}^N \log \Biggl\{ \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}_n | oldsymbol{\mu}_k, oldsymbol{\Sigma}_k) \Biggr\}.$$

Let us begin by writing down the conditions that must be satisfied at a maximum of the likelihood function. Setting the derivatives of $\ln p(\mathbf{X} \mid \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Sigma})$ with respect to the means $\boldsymbol{\mu}_k$ of the Gaussian components to zero, we obtain

$$0 = -\sum_{n=1}^{N} rac{\pi_{k} \mathcal{N}\left(\mathbf{x}_{n} \mid oldsymbol{\mu}_{k}, oldsymbol{\Sigma}_{k}
ight)}{\sum_{j} \pi_{j} \mathcal{N}\left(\mathbf{x}_{n} \mid oldsymbol{\mu}_{j}, oldsymbol{\Sigma}_{j}
ight)} oldsymbol{\Sigma}_{k}\left(\mathbf{x}_{n} - oldsymbol{\mu}_{k}
ight)$$

where we have made use of the form (2.43) for the Gaussian distribution. Note that the posterior probabilities, or responsibilities, given by (9.13) appear naturally on the right-hand side. Multiplying by Σ_k^{-1} (which we assume to be nonsingular) and rearranging we obtain

$$oldsymbol{\mu}_k = rac{1}{N_k} \sum_{n=1}^N \gamma\left(z_{nk}
ight) \mathbf{x}_n$$

where we have defined

$$N_k = \sum_{n=1}^N \gamma\left(z_{nk}
ight)$$

If we set the derivative of $\ln p(\mathbf{X} \mid \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Sigma})$ with respect to $\boldsymbol{\Sigma}_k$ to zero, and follow a similar line of reasoning, making use of the result for the maximum likelihood solution for the covariance matrix of a single Gaussian, we obtain

$$oldsymbol{\Sigma}_k = rac{1}{N_k} \sum_{n=1}^N \gamma\left(z_{nk}
ight) \left(\mathbf{x}_n - oldsymbol{\mu}_k
ight) \left(\mathbf{x}_n - oldsymbol{\mu}_k
ight)^{\mathrm{T}}$$

which has the same form as the corresponding result for a single Gaussian fitted to the data set, but again with each data point weighted by the corresponding posterior probability and with the denominator given by the effective number of points associated with the corresponding component.

Finally, we maximize $\ln p(\mathbf{X} \mid \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Sigma})$ with respect to the mixing coefficients π_k . Here we must take account of the constraint (9.9), which requires the mixing coefficients to sum to one. This can be achieved using a Lagrange multiplier and maximizing the following quantity

$$\ln p(\mathbf{X} \mid oldsymbol{\pi}, oldsymbol{\mu}, oldsymbol{\Sigma}) + \lambda \left(\sum_{k=1}^K \pi_k - 1
ight)$$

which gives

$$0 = \sum_{n=1}^{N} rac{\mathcal{N}\left(\mathbf{x}_{n} \mid oldsymbol{\mu}_{k}, oldsymbol{\Sigma}_{k}
ight)}{\sum_{j} \pi_{j} \mathcal{N}\left(\mathbf{x}_{n} \mid oldsymbol{\mu}_{j}, oldsymbol{\Sigma}_{j}
ight)} + \lambda$$

where again we see the appearance of the responsibilities. If we now multiply both sides by π_k and sum over k making use of the constraint (9.9), we find $\lambda=-N$. Using this to eliminate λ and rearranging we obtain

$$\pi_k = rac{N_k}{N}$$

so that the mixing coefficient for the $k^{\rm th}$ component is given by the average responsibility which that component takes for explaining the data points.

EM for Gaussian Mixtures

Given a Gaussian mixture model, the goal is to maximize the likelihood function with respect to the parameters (comprising the means and covariances of the components and the mixing coefficients).

- 1. Initialize the means μ_k , covariances Σ_k and mixing coefficients π_k , and evaluate the initial value of the log likelihood.
- 2. E step. Evaluate the responsibilities using the current parameter values

$$\gamma\left(z_{nk}
ight) = rac{\pi_{k}\mathcal{N}\left(\mathbf{x}_{n} \mid oldsymbol{\mu}_{k}, oldsymbol{\Sigma}_{k}
ight)}{\sum_{j=1}^{K}\pi_{j}\mathcal{N}\left(\mathbf{x}_{n} \mid oldsymbol{\mu}_{j}, oldsymbol{\Sigma}_{j}
ight)}.$$

3. M step. Re-estimate the parameters using the current responsibilities

$$oldsymbol{\mu}_k^{ ext{new}} = rac{1}{N_k} \sum_{n=1}^N \gamma\left(z_{nk}
ight) \mathbf{x}_n \ oldsymbol{\Sigma}_k^{ ext{new}} = rac{1}{N_k} \sum_{n=1}^N \gamma\left(z_{nk}
ight) \left(\mathbf{x}_n - oldsymbol{\mu}_k^{ ext{new}}
ight) \left(\mathbf{x}_n - oldsymbol{\mu}_k^{ ext{new}}
ight)^{ ext{T}} \ \pi_k^{ ext{new}} = rac{N_k}{N}$$

where

$$N_{k}=\sum_{n=1}^{N}\gamma\left(z_{nk}
ight) .$$

4. Evaluate the log likelihood

$$\ln p(\mathbf{X} \mid oldsymbol{\mu}, oldsymbol{\Sigma}, oldsymbol{\pi}) = \sum_{n=1}^N \ln \Biggl\{ \sum_{k=1}^K \pi_k \mathcal{N} \left(\mathbf{x}_n \mid oldsymbol{\mu}_k, oldsymbol{\Sigma}_k
ight) \Biggr\}$$

and check for convergence of either the parameters or the log likelihood. If the convergence criterion is not satisfied return to step 2.

```
In [ ]: !pip install numpy
        !pip install scipy
        !pip install matplotlib
        Requirement already satisfied: numpy in d:\anaconda\envs\cs182\lib\site-packages (1.
        Requirement already satisfied: scipy in d:\anaconda\envs\cs182\lib\site-packages (1.
        7.3)
        Requirement already satisfied: numpy < 1.23.0, >= 1.16.5 in d:\anaconda\envs\cs182\lib\s
        ite-packages (from scipy) (1.21.5)
        s (3.5.2)
        Requirement already satisfied: kiwisolver>=1.0.1 in d:\anaconda\envs\cs182\lib\site-
        packages (from matplotlib) (1.4.2)
        Requirement already satisfied: pillow>=6.2.0 in d:\anaconda\envs\cs182\lib\site-pack
        ages (from matplotlib) (9.2.0)
        Requirement already satisfied: python-dateutil>=2.7 in d:\anaconda\envs\cs182\lib\si
        te-packages (from matplotlib) (2.8.2)
        Requirement already satisfied: fonttools>=4.22.0 in d:\anaconda\envs\cs182\lib\site-
        packages (from matplotlib) (4.25.0)
        Requirement already satisfied: numpy>=1.17 in d:\anaconda\envs\cs182\lib\site-packag
        es (from matplotlib) (1.21.5)
        Requirement already satisfied: pyparsing>=2.2.1 in d:\anaconda\envs\cs182\lib\site-p
        ackages (from matplotlib) (3.0.9)
        Requirement already satisfied: packaging>=20.0 in d:\anaconda\envs\cs182\lib\site-pa
        ckages (from matplotlib) (21.3)
        Requirement already satisfied: cycler>=0.10 in d:\anaconda\envs\cs182\lib\site-packa
        ges (from matplotlib) (0.11.0)
        Requirement already satisfied: typing-extensions in d:\anaconda\envs\cs182\lib\site-
        packages (from kiwisolver>=1.0.1->matplotlib) (4.3.0)
        Requirement already satisfied: six>=1.5 in d:\anaconda\envs\cs182\lib\site-packages
        (from python-dateutil>=2.7->matplotlib) (1.16.0)
In [ ]: import numpy as np
        import matplotlib.pyplot as plt
        from matplotlib.patches import Ellipse
        from scipy.stats import multivariate_normal
        # The seed is fixed for reproducibility.
        np. random. seed (42)
In [ ]: def log_likelihood(X, pi, mu, sigma):
           n, d = X. shape
           k = 1en(pi)
           11 = 0
           # Calculate the log-likelihood (while this is not essential for vanilla EM)
```

```
# Draw color points according to their cluster using pyplot, you should not edit this
In [ ]:
         def draw(X, pi, mu, sigma, iter):
             n, d = X. shape
             k = 1en(mu)
             #print(mu) 5*2
             gamma = np. zeros((n, k))
             for i in range(n):
                 for j in range(k):
                     gamma[i, j] = pi[j] * multivariate_normal(mean=mu[j], cov=sigma[j]).pdf(
                 gamma[i] /= np. sum(gamma[i])
             # y is n*1
             y = np. argmax(gamma, axis=1)
             plt. scatter(X[:, 0], X[:, 1], c=y, s=1)
             # plot the mean of each cluster with striking points
             plt. scatter(mu[:, 0], mu[:, 1], c='black', s=50)
             plt. axis ('equal')
             plt. title('iter: {}'. format(iter))
             plt. show()
```

Implementation of EM algorithm

```
In [ ]: def EM(X, k, max_iter=10, plot=True):
            n, d = X. shape
            pi = np. ones(k) / k
            # pi [0.2 0.2 0.2 0.2 0.2]
            \# k-means++ initialization
            mu = np. zeros((k, d))
            #mu [[0. 0.][0. 0.][0. 0.][0. 0.][0. 0.]
            mu[0] = X[np. random. choice(n)]
            for j in range(1, k):
                dist = np. zeros(n)
                for i in range(n):
                    #求出各点到mu的距离(最近的mu)
                    dist[i] = np. min(np. sum((X[i] - mu[:j]) ** 2, axis=1))
                #倾向选择离mu远的点
                mu[j] = X[np. random. choice(n, p=dist / np. sum(dist))]
            sigma = np. array([np. eye(d) for in range(k)])
            #print(sigma) 5*2*2
            11 = log_likelihood(X, pi, mu, sigma)
            draw(X, pi, mu, sigma, '-1')
            for iter in range (max_iter):
                # E-step
                gamma = np. zeros((n, k))
```

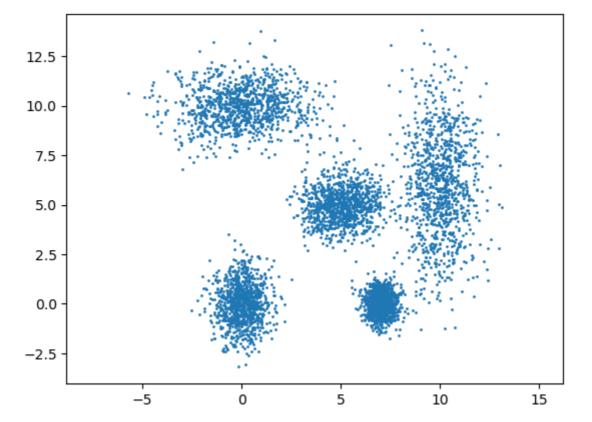
```
# TODO:
# Do the E-step, update p(z_k=1|X). (a.k.a gamma, or the responsibility)
# Hint: Refer to the above mentioned algorithm; try use multivariate normal.
# *****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE) ****
# the same with draw
for i in range(n):
   for j in range(k):
      gamma[i, j] = pi[j] * multivariate normal(mean=mu[j], cov=sigma[j]).
   gamma[i] /= np. sum(gamma[i])
# ****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE) ****
# M-step
# TODO:
# Do the M-step, update pi, mu, and sigma.
# Hint: Refer to the above mentioned algorithm.
# ****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE) ****
#Nk is 1*k
Nk = np. zeros(k)
for i in range (k):
   for j in range(n):
      Nk[i] += gamma[j][i]
#pi is 1*k
for i in range(k):
   pi[i] = Nk[i]/n
#mu is k*d
mu = np. zeros((k, d))
for i in range(k):
   for j in range(d):
      for num in range(n):
          mu[i][j] += gamma[num][i]*X[num][j]
      mu[i][j] = mu[i][j]/Nk[i]
#sigma is 5*2*2
for i in range(k):
   my_sigma = np.zeros((d, d))
   for num in range(n):
      minus = X[num] - mu[i]
      temp = np. outer (minus, minus)
      my_sigma = np. add(gamma[num][i]*temp, my_sigma)
   my sigma = my sigma / Nk[i]
   sigma[i] = my_sigma
# *****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE) ****
11 new = log likelihood(X, pi, mu, sigma)
if np. abs (11 new - 11) < 1e-5:
   break
11 = 11 \text{ new}
# plot the current cluster
if iter % 1 == 0:
   print('Iteration: {}, log-likelihood: {}'.format(iter, 11))
      draw(X, pi, mu, sigma, iter)
```

```
return pi, mu, sigma
```

1. Unsupervised Clustering [40 points]

Let's validate our implementation on synthetic data of 2D Gaussian mixture with 5 components.

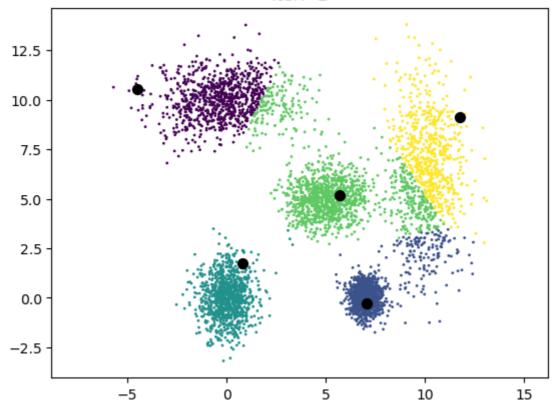
```
In []: # The data is geneated from 5 gaussians with different means, different covariance makes k=5
X=np.\ loadtxt('synthetic.csv', delimiter=',')
plt.\ scatter(X[:, 0], X[:, 1], s=1)
plt.\ axis('equal')
plt.\ show()
```



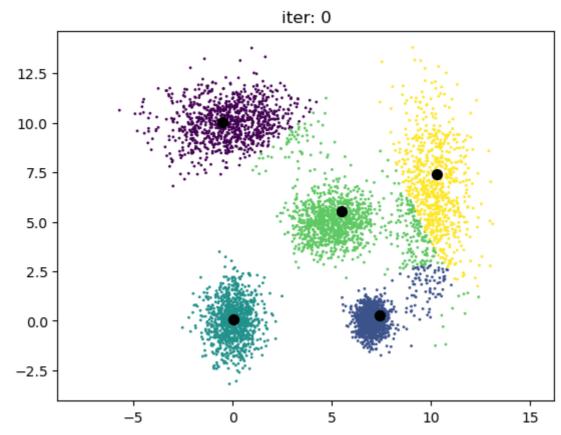
```
In []: # run EM algorithm
pi, mu, sigma = EM(X, k)

## A quick validation of your implementation:
## log-likelihood should increase after each iteration, and is around ~-20000.
```



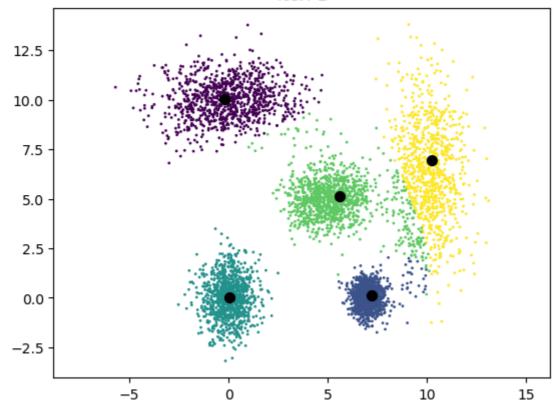


Iteration: 0, log-likelihood: -23110.476800635297

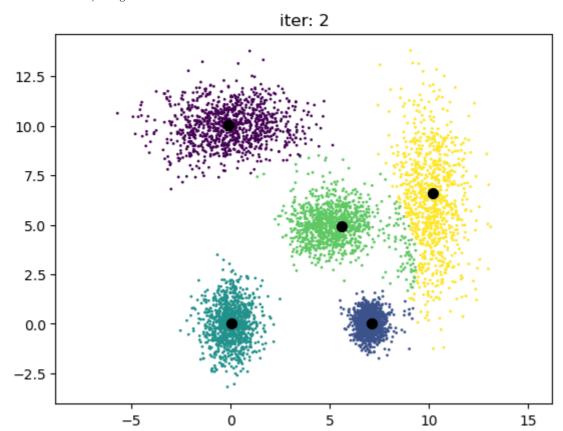


Iteration: 1, log-likelihood: -22611.1946969844



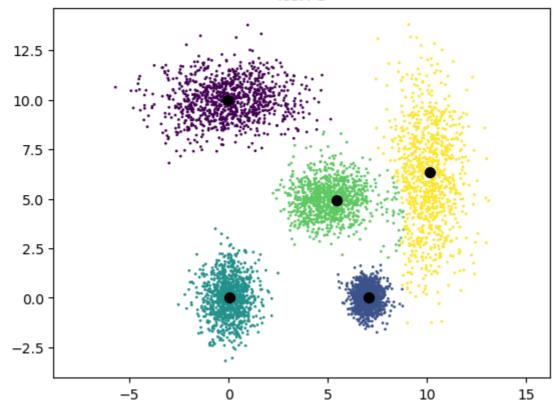


Iteration: 2, log-likelihood: -22178.01890358943

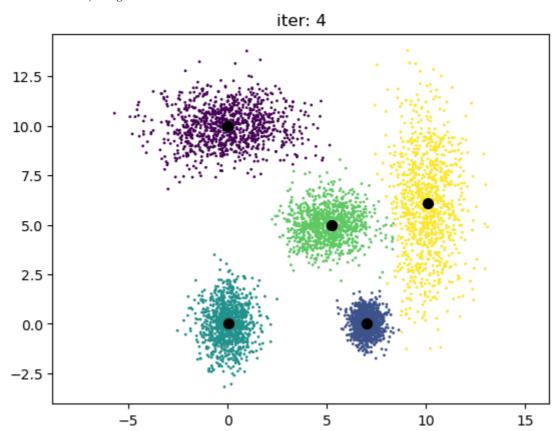


Iteration: 3, log-likelihood: -21952.19247197296



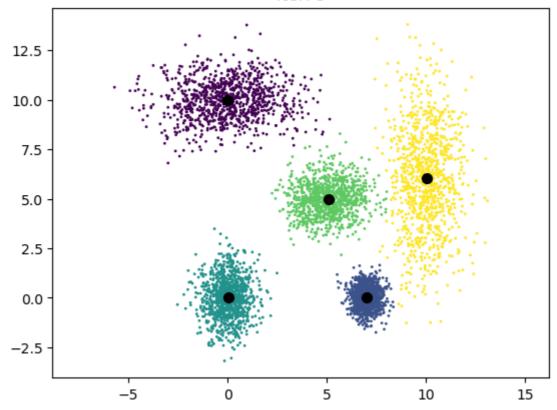


Iteration: 4, log-likelihood: -21804.825654169905

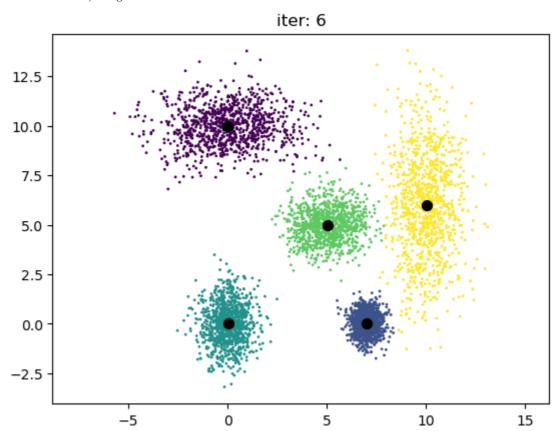


Iteration: 5, log-likelihood: -21736.666532626863



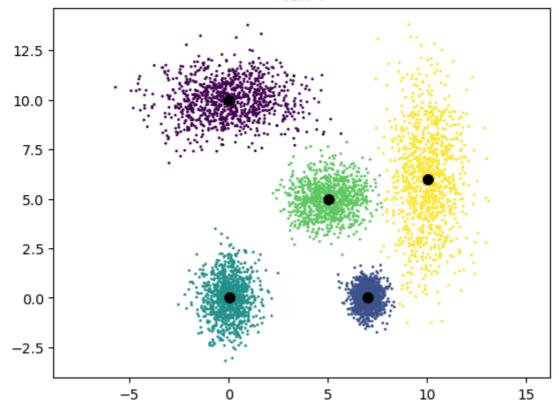


Iteration: 6, log-likelihood: -21726.158133836998

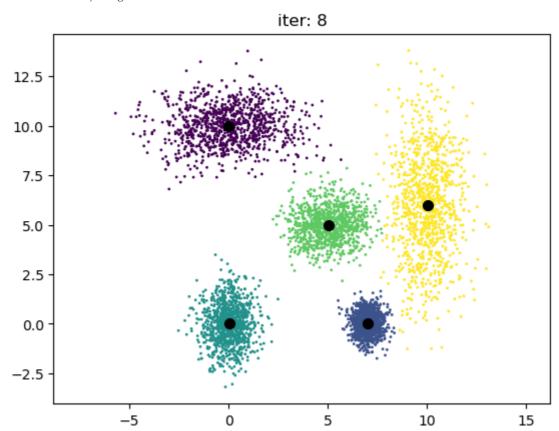


Iteration: 7, log-likelihood: -21725.32599697582



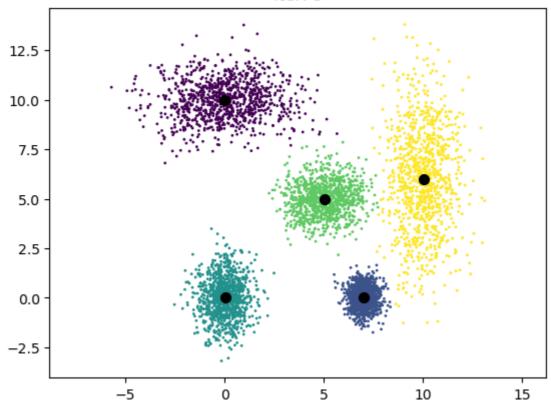


Iteration: 8, log-likelihood: -21725.263882574305

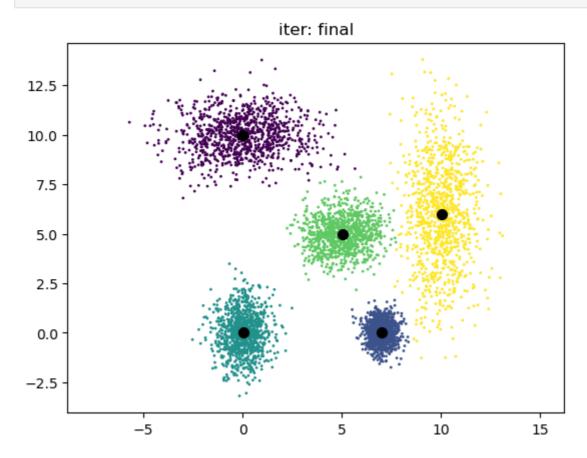


Iteration: 9, log-likelihood: -21725.25909289951

iter: 9

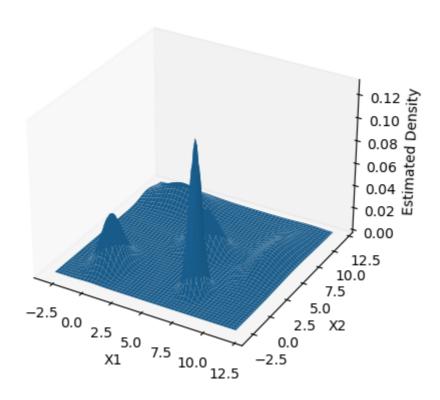


In []: # The following draws the means and clusters of the final result.
draw(X, pi, mu, sigma, 'final')



```
# The following plots the estimated density on a 3D grid.
x1 = np. linspace(-3, 12, 100)
x2 = np. linspace(-3, 12, 100)
X1, X2 = np. meshgrid(x1, x2)
Z = np. zeros(X1. shape)
for j in range(k):
```

```
Z += pi[j] * multivariate_normal(mean=mu[j], cov=sigma[j]).pdf(np.dstack((X1, X2))
fig = plt.figure()
ax = fig.add_subplot(projection='3d')
ax.grid(False)
ax.plot_surface(X1, X2, Z)
ax.set_xlabel('X1')
ax.set_ylabel('X2')
ax.set_zlabel('Estimated Density')
plt.show()
```



2. Image Compression [20 points]

Now let's explore the application of Gaussian mixture model to image compression. We will use the GMM from sklearn package to compress the image as it provides much more stable and faster implementation! The GMM will be trained on the pixels of the image and the cluster assignment for each pixel will be used to replace the original pixel value. The number of clusters is a hyperparameter that can be tuned to control the compression rate. The higher the number of clusters, the higher the compression rate.

```
In [ ]: !pip install scikit-learn from sklearn.mixture import GaussianMixture
```

Requirement already satisfied: scikit-learn in d:\anaconda\envs\cs182\lib\site-packa ges (1.0.2)

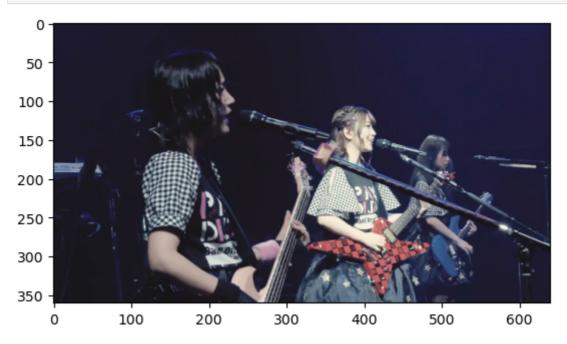
Requirement already satisfied: numpy>=1.14.6 in d:\anaconda\envs\cs182\lib\site-pack ages (from scikit-learn) (1.21.5)

Requirement already satisfied: joblib>=0.11 in d:\anaconda\envs\cs182\lib\site-packa ges (from scikit-learn) (1.1.0)

Requirement already satisfied: threadpoolct1>=2.0.0 in d:\anaconda\envs\cs182\lib\site-packages (from scikit-learn) (2.2.0)

Requirement already satisfied: scipy >= 1.1.0 in d:\anaconda\envs\cs182\lib\site-packa ges (from scikit-learn) (1.7.3)

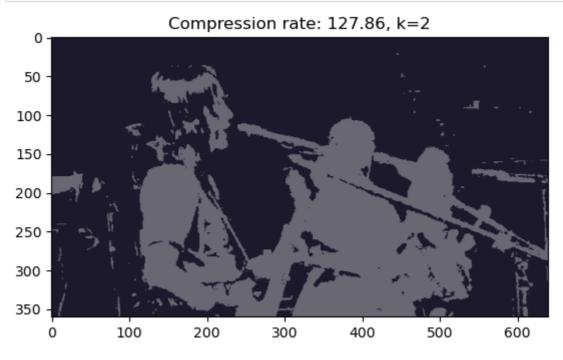
```
In [ ]: image = plt. imread('compression.png')
    plt. imshow(image)
    plt. show()
```

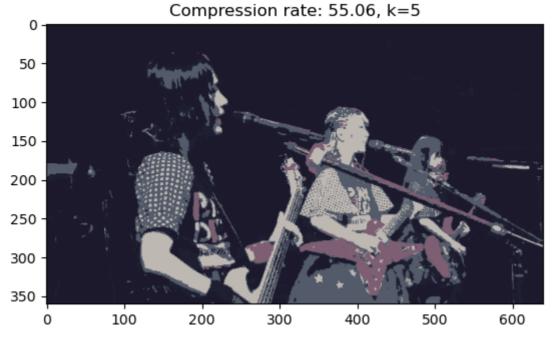


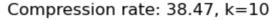
```
# image compression using EM in sklearn
In [ ]:
        def GMM compression(image, k):
           #print(image.shape) (360, 640, 4)
           X = image. reshape(-1, image. shape[2])
           \#X = X. \text{ reshape}([360, 640, 4])
           #plt.imshow(X)
           #plt.show()
           image_compressed = np. zeros(X. shape)
           #print(X. shape) (230400, 4)
           # TODO:
           # Refer to https://scikit-learn.org/stable/modules/generated/sklearn.mixture.Gau
           # Create a GaussianMixture object with k components and fit the image data (X).
           # Then, predict the cluster label of each pixel(像素) and replace each pixel by
           # Finally, reshape the compressed image to the original image shape.
           # ****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE) ****
           gm = GaussianMixture (n components=k, random state=0). fit (X)
           my_predict = gm. predict(X)
           my_mean = gm. means_
           for i in range(X. shape[0]):
               image_compressed[i] = my_mean[my_predict[i]]
           image_compressed = image_compressed.reshape([image.shape[0], image.shape[1], image
           # ****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE) ****
           original size = image. shape[0] * image. shape[1] * image. shape[2] * 32
           # the compressed image stores the label of each pixel, which can be represented
           \# and the mean of each cluster, which can be represented by 4*32 bits
           compressed_size = image_compressed.shape[0] * image_compressed.shape[1] * np. log
           compression_rate = original_size / compressed_size
           plt. title(f'Compression rate: {compression_rate:.2f}, k={k}')
           plt.imshow(image compressed)
           plt. show()
```

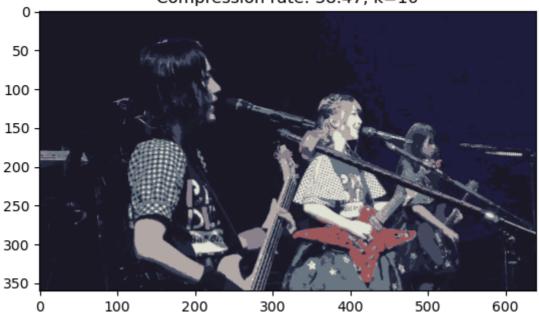
Now let's see how the image looks like after compression under different number of clusters. Here Compression rate is defined as the theoeretical number of bits required to represent the image divided by the number of bits required to represent the compressed image.

In []: for k in [2, 5, 10, 20, 30]:
 GMM_compression(image, k)

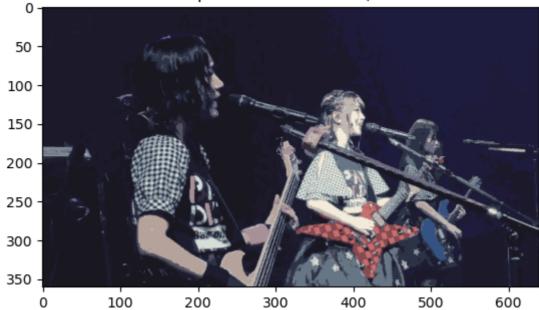








Compression rate: 29.54, k=20



Compression rate: 26.00, k=30

