

# EZO-PRS™

## Embedded Pressure Sensor

Reads

**Pressure (Absolute)**

**psi (0 - 74.000) Default**

**atm (0 - 5.03)**

**bar (0 - 5.102)**

**kPa (0 - 510.212)**

**inches of water (0 - 2,050.36")**

**cm of water (0 - 5,202.71 cm)**

Response time

**1 reading per second**

Resolution

**0.001**

Accuracy

**+/- 1.35% (1psi)**

Threaded connection

**1/4" NPT**

Cable

**1 meter / 5 lead**

Data protocol

**UART & I<sup>2</sup>C**

Default I<sup>2</sup>C address

**106 (0x6A)**

Data format

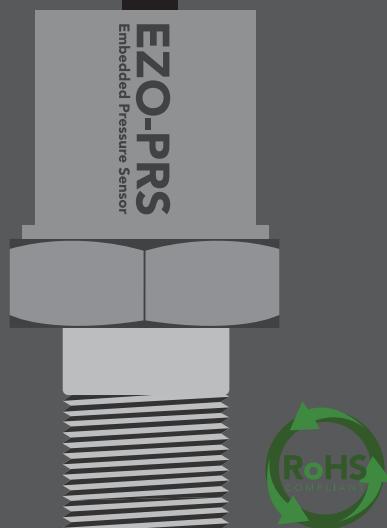
**ASCII**

Operating voltage

**3.3V – 5V**

Water resistant/dust proof

**IP67**



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Absolute pressure			

## UART

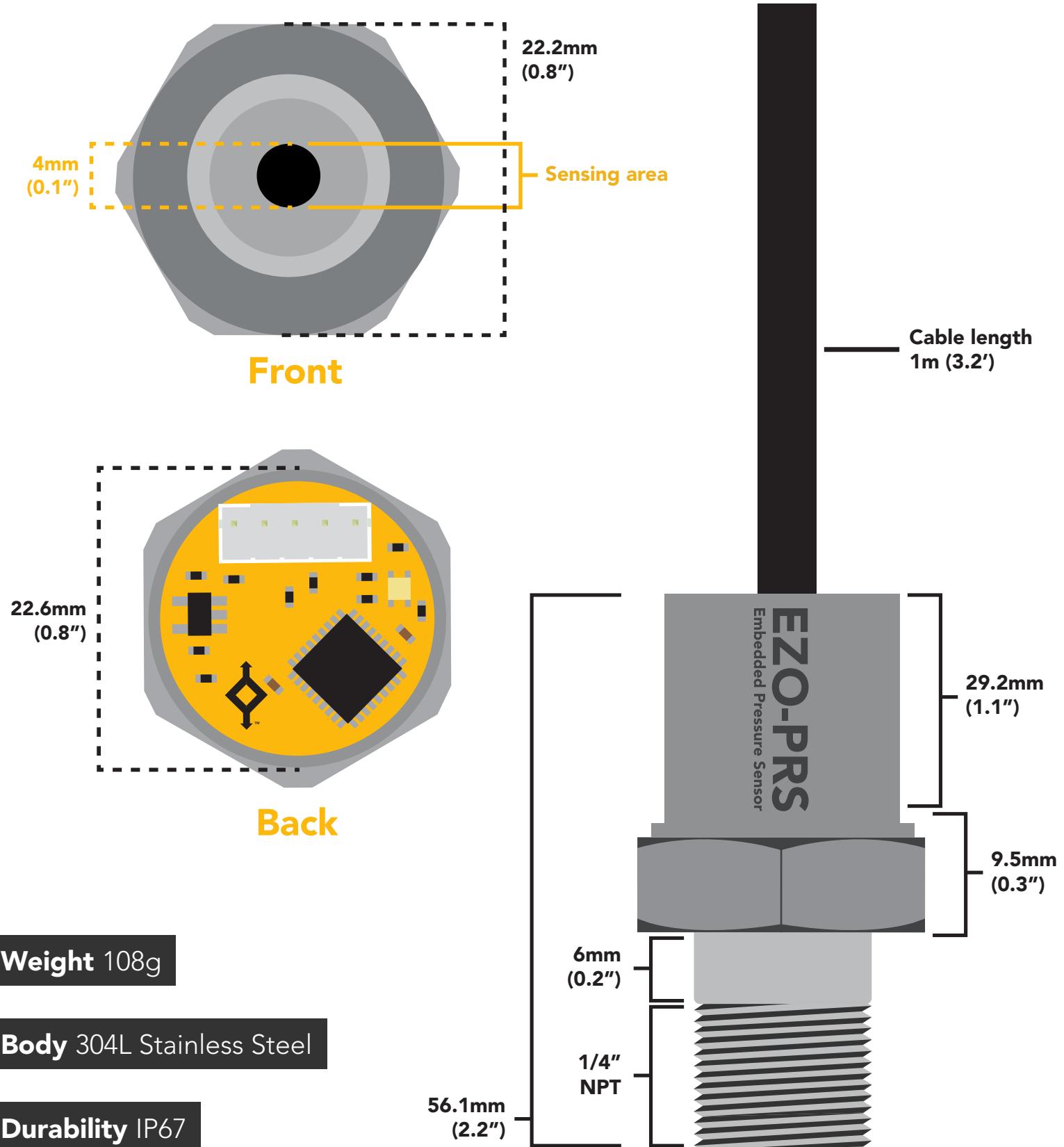
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## I<sup>2</sup>C

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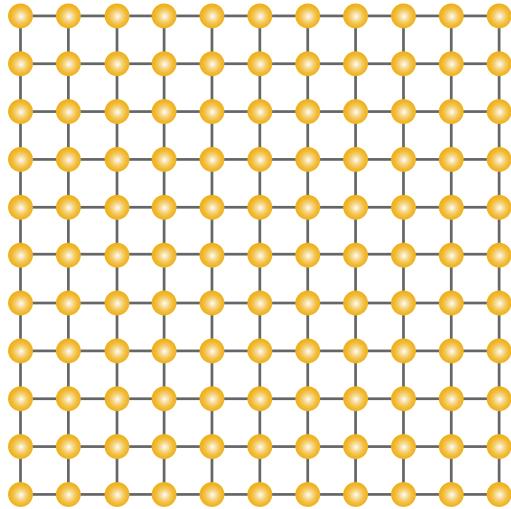
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# EZO-PRS™ dimensions

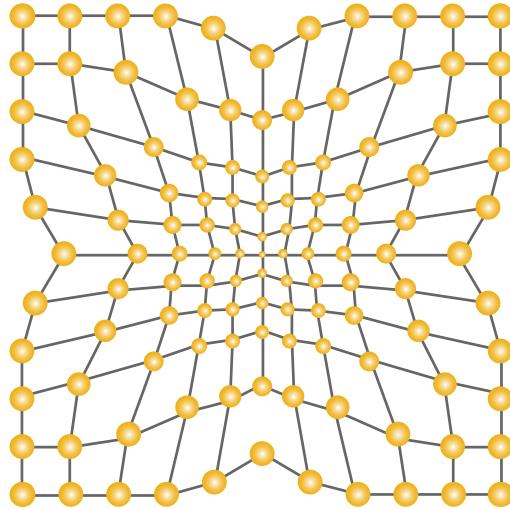


# Operating principle

Internally the pressure sensor uses a piezoresistive semiconducting element. The semiconducting element (a silicon wafer) changes its resistance in proportion to pressure. As the pressure increases the atomic spacing of the silicon atoms decreases, this in turn lowers the resistance of the silicon wafer.



**Atmospheric pressure**



**50 PSI**

## Chemical compatibility

Any gas, liquid or oil compatible with 304L Stainless Steel.

## Power consumption

	LED	MAX	STANDBY	SLEEP
5V	ON	14.25 mA	14.25 mA	1.66 mA
	OFF	14.00 mA	14.00 mA	
3.3V	ON	13.21 mA	13.21 mA	0.85 mA
	OFF	12.95 mA	12.95 mA	

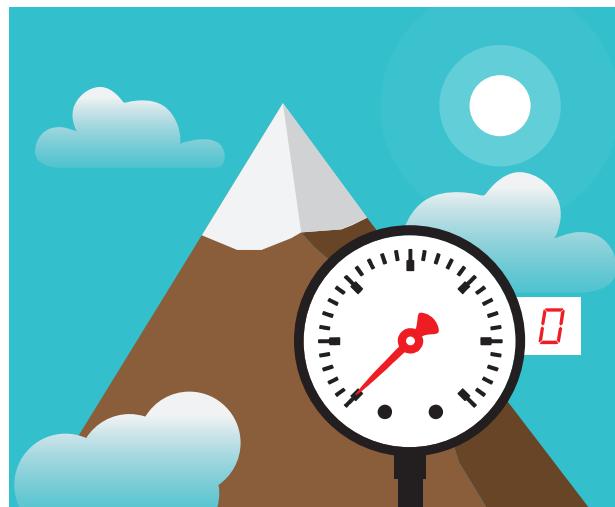
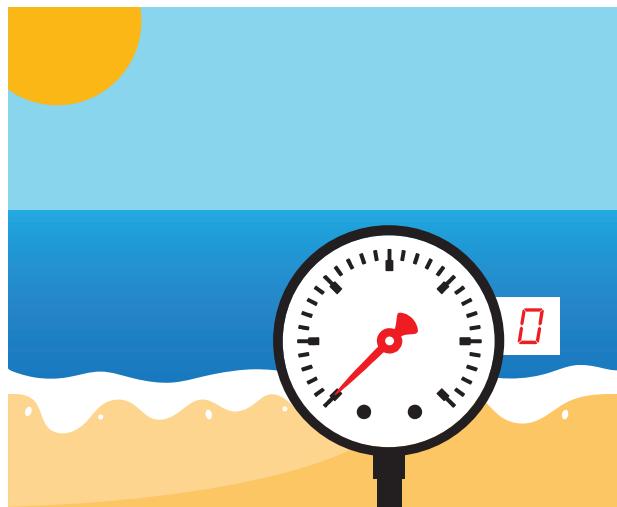
## Absolute max ratings

Parameter	MIN	TYP	MAX
Storage temperature (EZO-Pressure)	-65 °C		125 °C
Operational temperature (EZO-Pressure)	-40 °C	25 °C	105 °C
VCC	3.3V	5V	5.5V
Pressure limit (sensor damage)			~150 psi
Burst Pressure			7,500 psi

# Gauge pressure vs Absolute pressure

## Gauge pressure

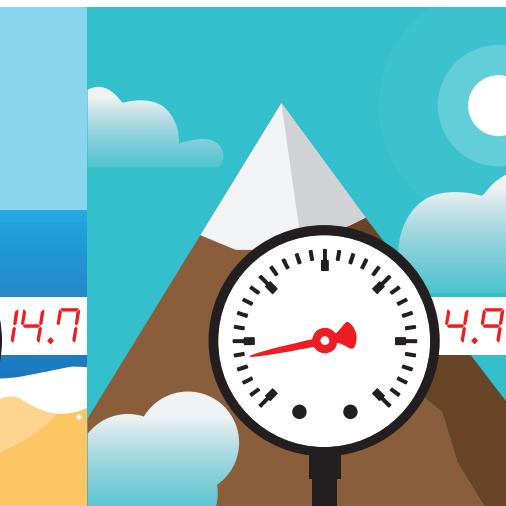
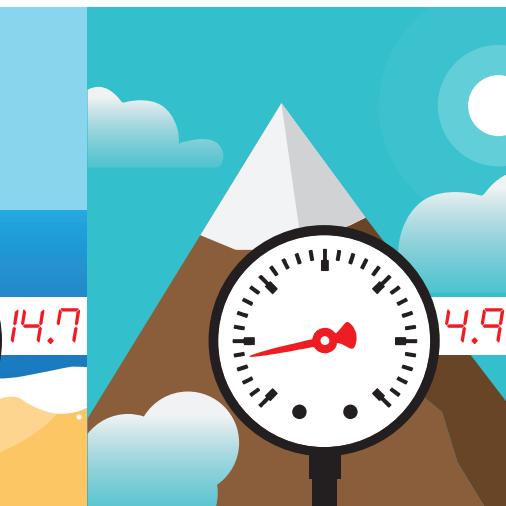
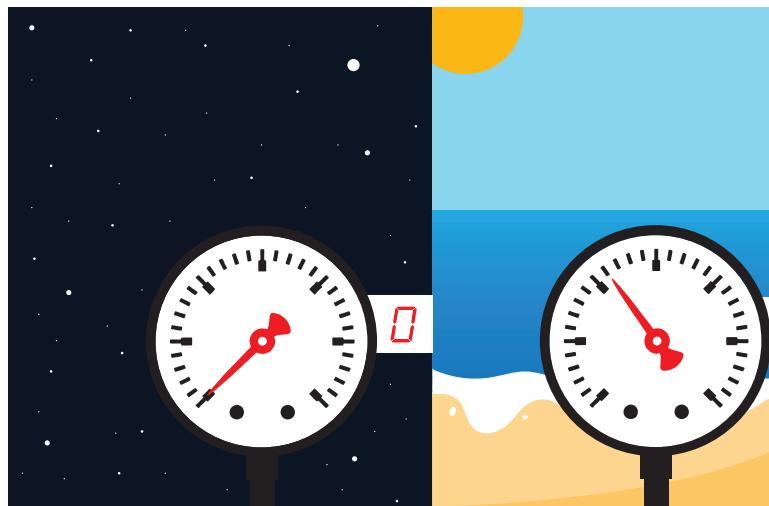
A gauge pressure sensor reads pressure relative to atmospheric pressure.



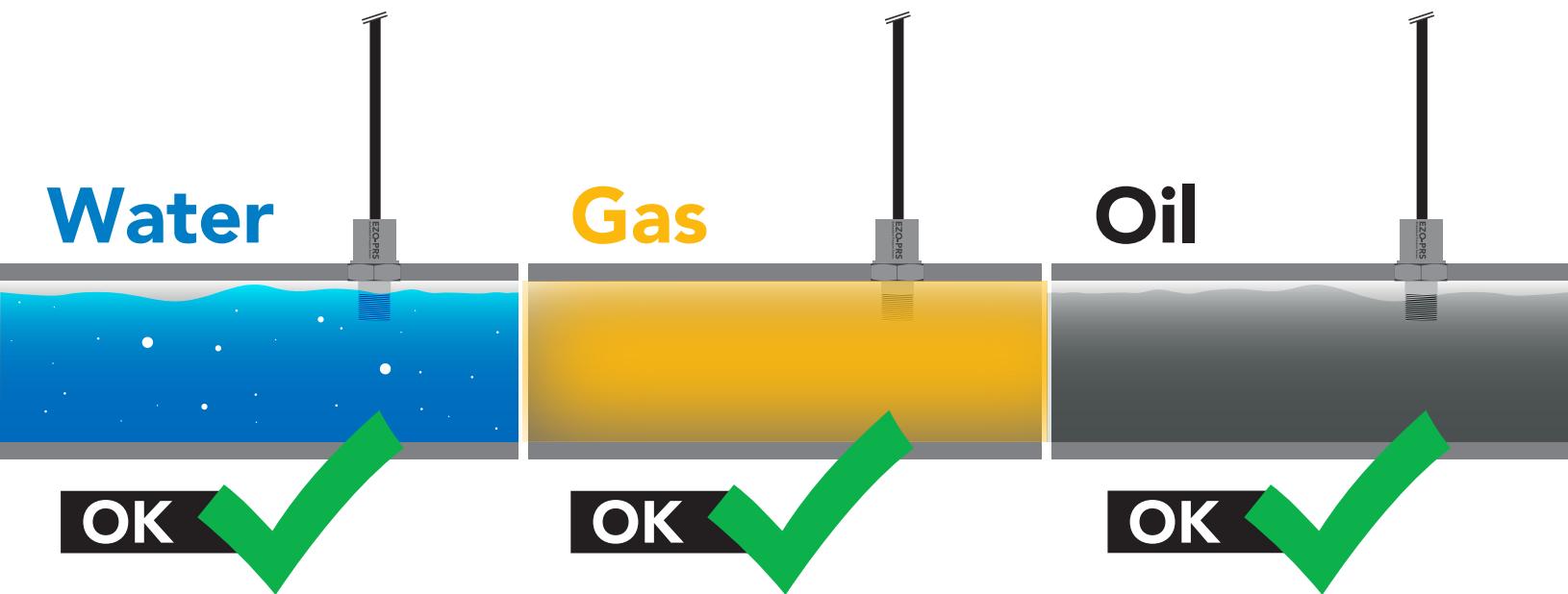
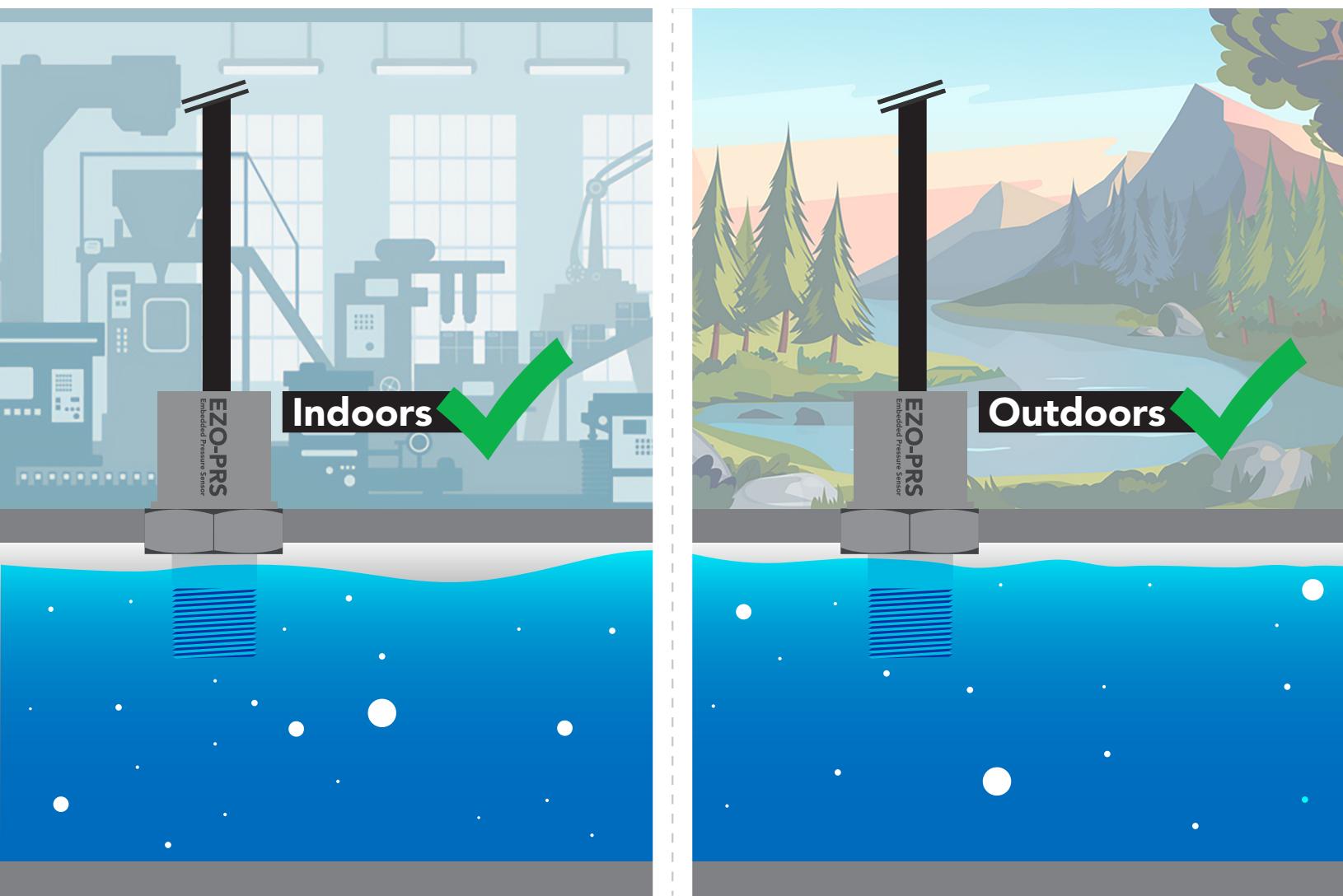
A gauge pressure sensor will always read atmospheric pressure as 0.

## Absolute pressure

An absolute pressure sensor reads pressure relative to the vacuum of space.



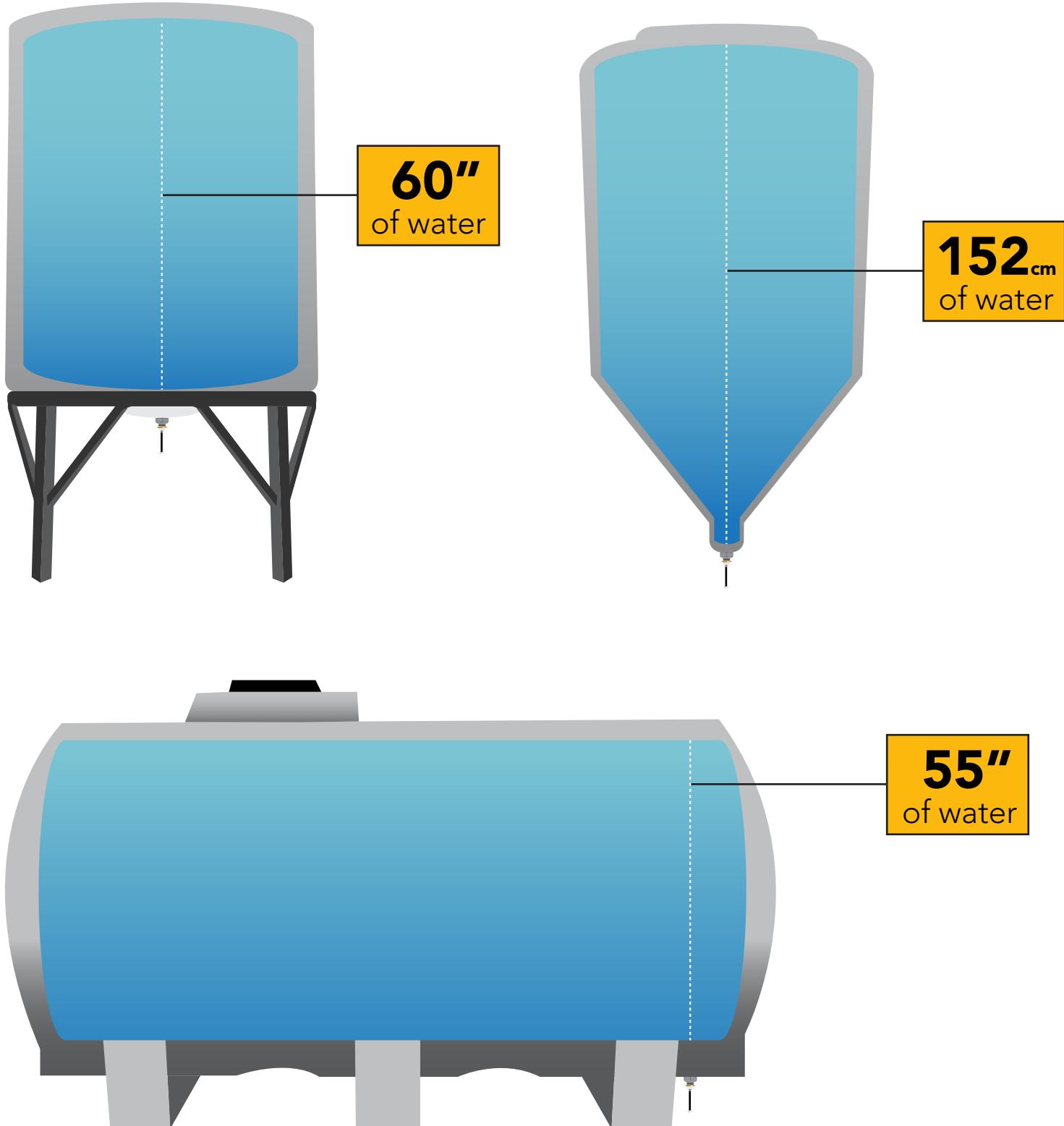
# Typical applications



# Typical applications

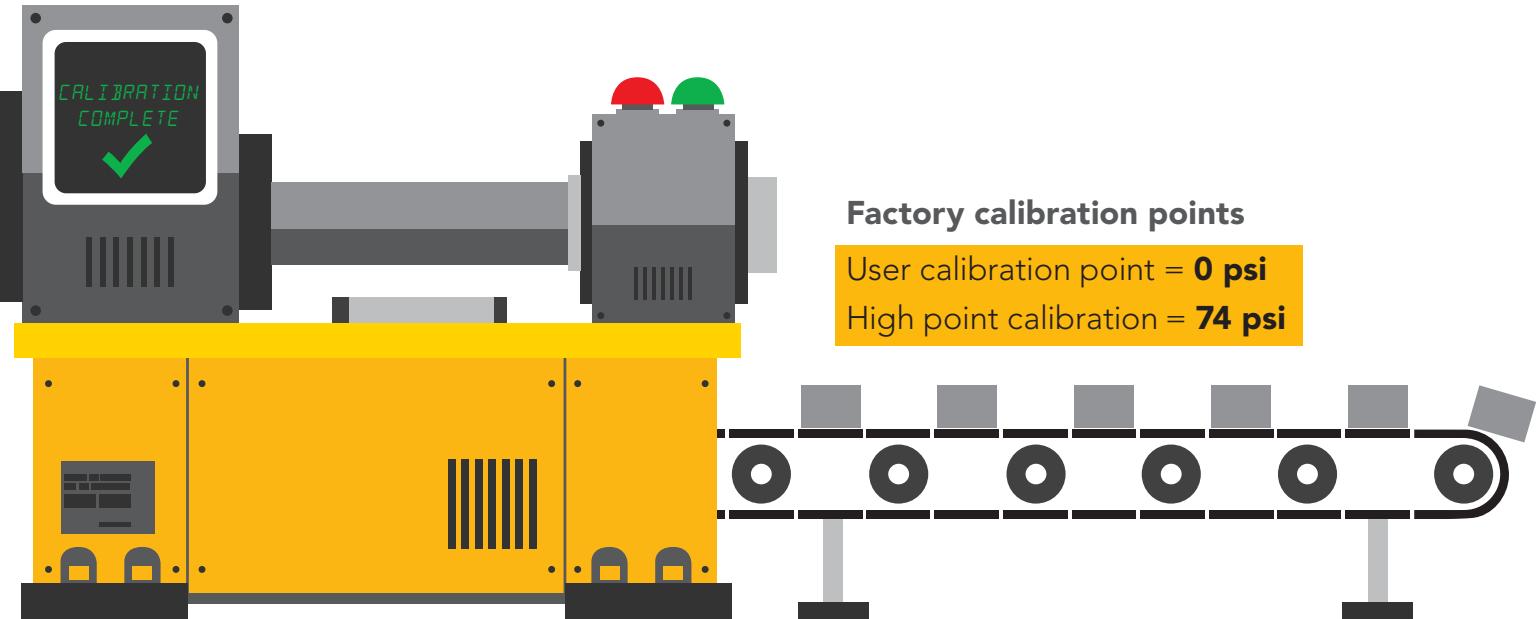
## Measuring the water level in a tank

Setting the EZO-PRS™ to measure the height of water is a great way to measure the volume of a tank. See page [24](#) or [48](#) for more info.



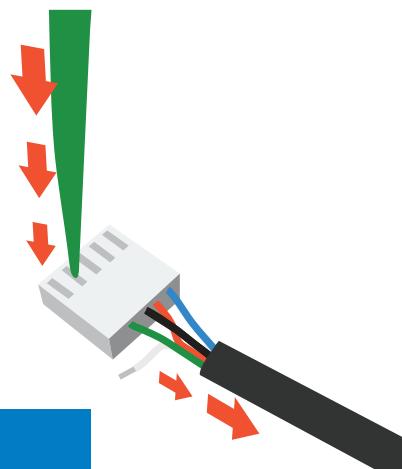
# Calibration theory

The Atlas Scientific EZO-PRS™ Embedded Pressure Sensor comes half-calibrated. When using the sensor for the first time, it is common to see a small pressure reading even though it is not connected to a pressure source. Issue the "Cal,0" command to complete the calibration process.



## Pin out

Data and power cable pinout



Should you need to remove this connector from the data cable, follow the provided illustration.

The alarm pin will go high when a set pressure level has been crossed.



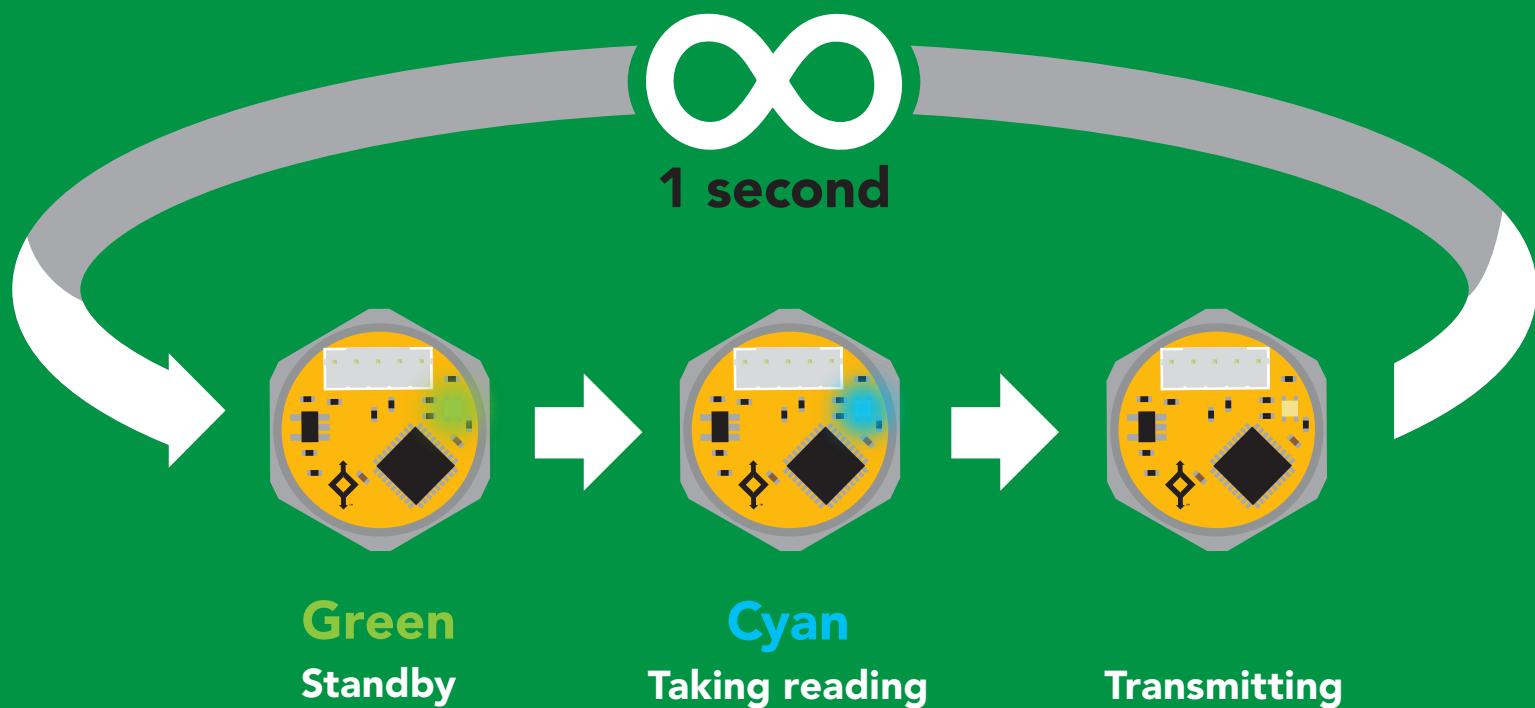
If unused leave **ALM** floating. Do not connect **ALM** to **VCC** or **GND**.

See page **21** or **45** to enable pressure level alarm.

# Default state

# UART mode

Baud	9,600
Readings	continuous
Units	PSI
Speed	1 reading per second
LED	on



 Available data protocols

**UART**

**Default**

**I<sup>2</sup>C**

 Unavailable data protocols

**SPI**

**Analog**

**RS-485**

**Mod Bus**

**4–20mA**

# UART mode

## Settings that are retained if power is cut

Baud rate  
Calibration  
Continuous mode  
Custom calibration  
Device name  
Enable/disable response codes  
Hardware switch to I<sup>2</sup>C mode  
LED control  
Protocol lock  
Software switch to I<sup>2</sup>C mode

## Settings that are **NOT** retained if power is cut

Find  
Sleep mode

# UART mode

8 data bits      no parity  
1 stop bit      no flow control

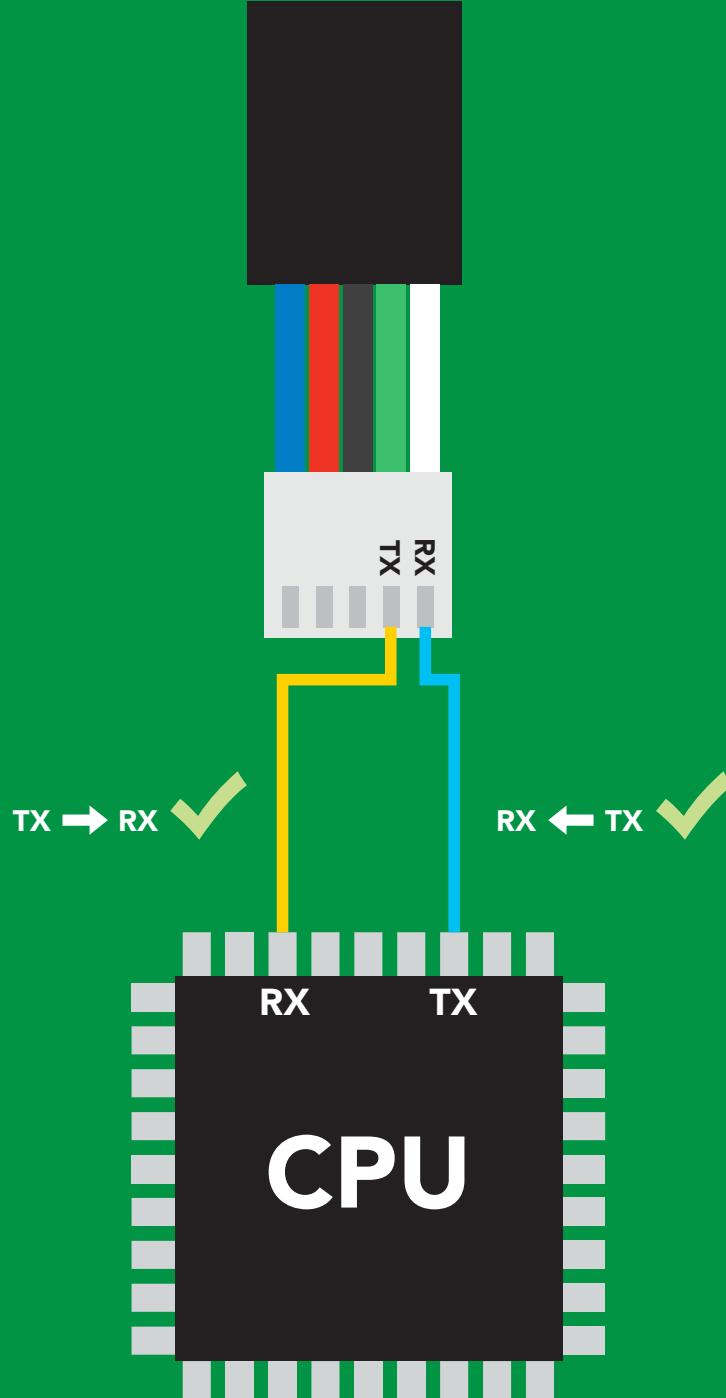
Baud 300  
1,200  
2,400  
**9,600 default**  
19,200  
38,400  
57,600  
115,200

**RX** Data in

**TX** Data out

**Vcc** 3.3V – 5.5V

0V  0V



## Data format

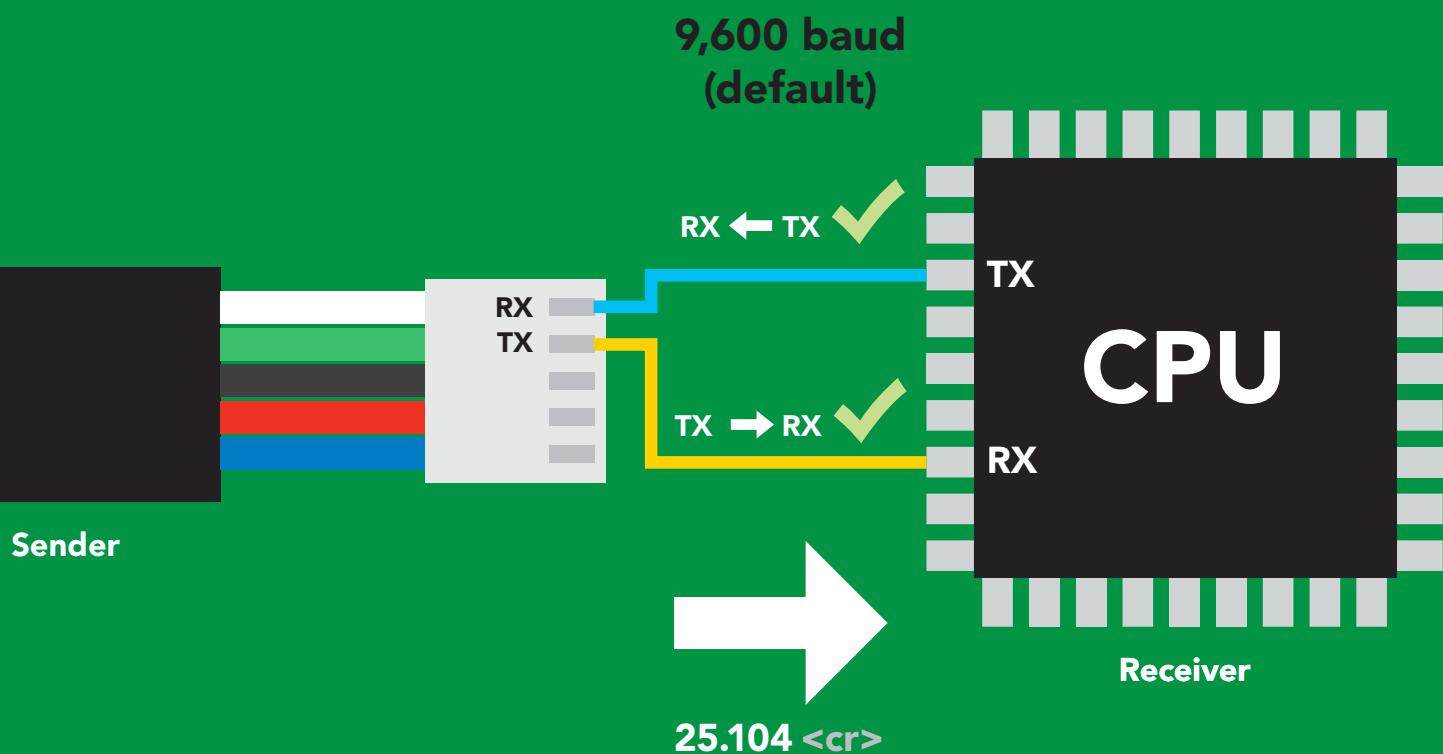
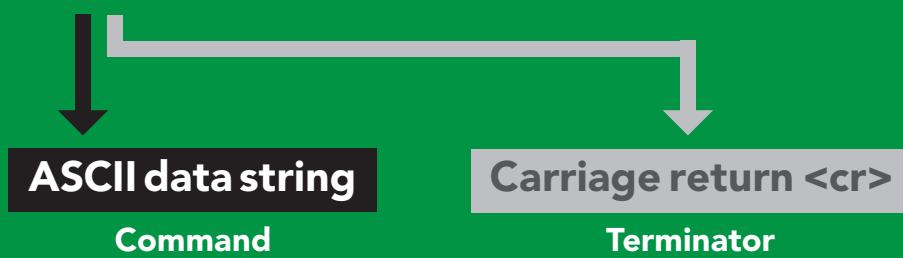
**Output** pressure  
**Units** **PSI** **default**  
(ATM, kPa, bar,  
inch's of water  
cm of water)

**Encoding** ASCII  
**Format** string

**Terminator** carriage return  
**Data type** floating point  
**Decimal places** 3  
**Smallest string** 3 characters  
**Largest string** 39 characters

# Receiving data from device

2 parts



## Advanced

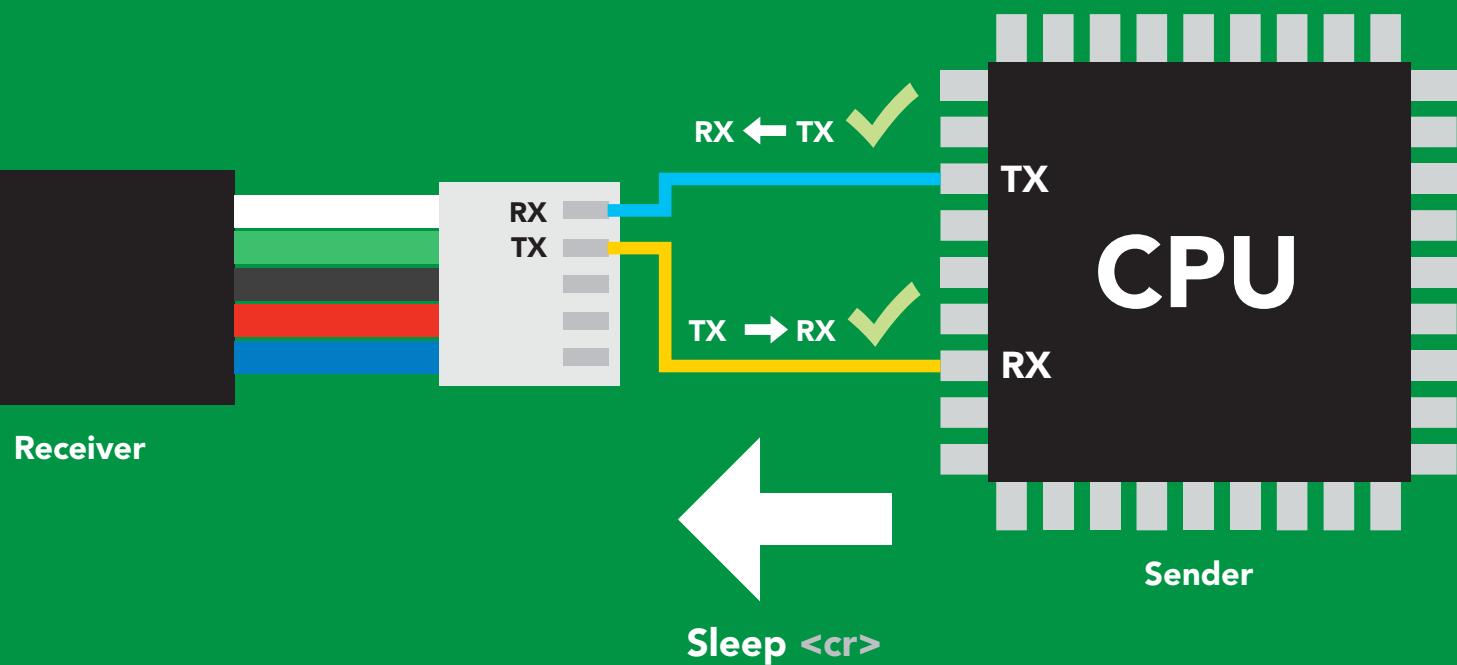
ASCII: 2 5 . 1 0 4 <cr>

Hex: 32 35 2E 31 30 34 0D

Dec: 50 53 46 49 48 52 13

# Sending commands to device

2 parts



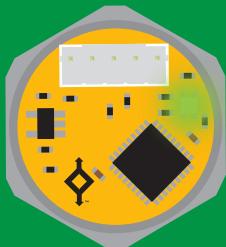
## Advanced

ASCII: S I e e p <cr>

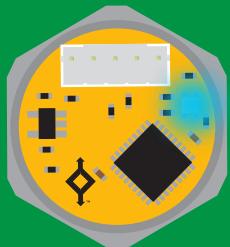
Hex: 53 6C 65 65 70 0D

Dec: 83 108 101 101 112 13

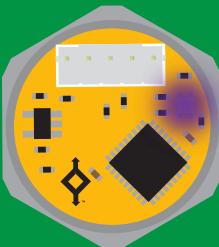
# LED color definition



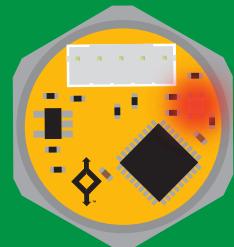
**Green**  
UART standby



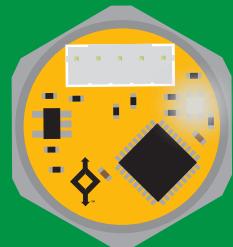
**Cyan**  
Taking reading



**Purple**  
Changing baud rate



**Red**  
Command not understood



**White**  
Find

<b>5V</b>	LED ON <b>+.25 mA</b>
<b>3.3V</b>	<b>+.26 mA</b>

# UART mode

## command quick reference

All commands are ASCII strings or single ASCII characters.

Command	Function	Default state
Alarm	enable/disable alarm	pg. 21 n/a
Baud	change baud rate	pg. 30 9,600
C	enable/disable continuous mode	pg. 19 enabled
Cal	performs custom calibration	pg. 22 n/a
Dec	add/remove decimal places	pg. 23 n/a
Factory	enable factory reset	pg. 32 n/a
Find	finds device with blinking white LED	pg. 18 n/a
i	device information	pg. 26 n/a
I2C	change to I <sup>2</sup> C mode	pg. 33 not set
L	enable/disable LED	pg. 17 enabled
Name	set/show name of device	pg. 25 not set
Plock	enable/disable protocol lock	pg. 31 disabled
R	returns a single reading	pg. 20 n/a
Sleep	enter sleep mode/low power	pg. 29 n/a
Status	retrieve status information	pg. 28 enable
U	pressure units	pg. 24 psi
*OK	enable/disable response codes	pg. 27 enable

# LED control

## Command syntax

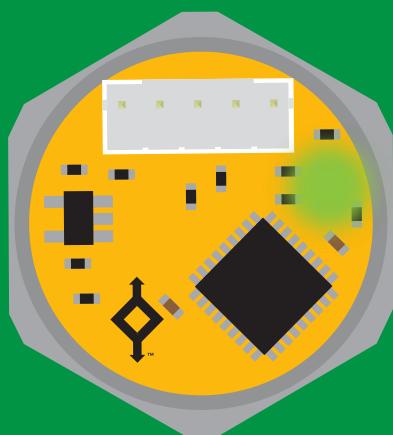
L,1 <cr> LED on **default**

L,0 <cr> LED off

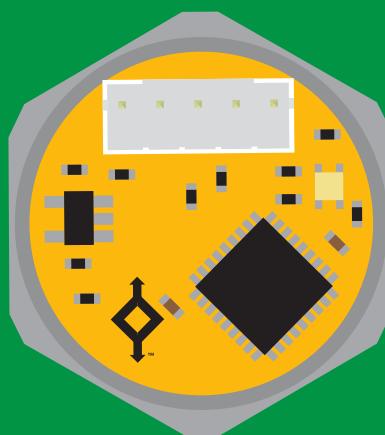
L,? <cr> LED state on/off?

## Example      Response

L,1 <cr>	*OK <cr>
L,0 <cr>	*OK <cr>
L,? <cr>	?L,1 <cr> or ?L,0 <cr> *OK <cr>



L,1



L,0

# Find

## Command syntax

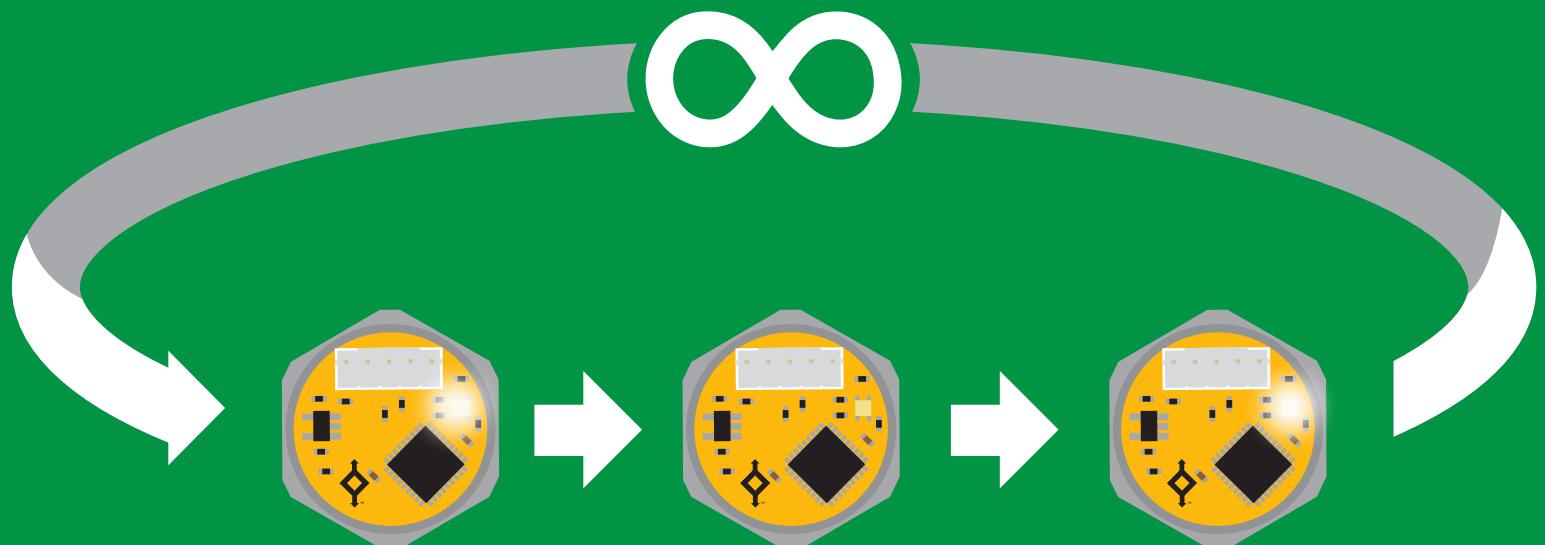
This command will disable continuous mode  
Send any character or command to terminate find.

Find <cr> LED rapidly blinks white, used to help find device

## Example Response

Find <cr>

\*OK <cr>



# Continuous mode

## Command syntax

- C,1 <cr> enable continuous readings once per second **default**
- C,n <cr> continuous readings every n seconds (n = 2 to 99 sec)
- C,0 <cr> disable continuous readings
- C,? <cr> continuous reading mode on/off?

## Example      Response

C,1 <cr>

\*OK <cr>  
pressure (1 sec) <cr>  
pressure (2 sec) <cr>  
pressure (n sec) <cr>

C,30 <cr>

\*OK <cr>  
pressure (30 sec) <cr>  
pressure (60 sec) <cr>  
pressure (90 sec) <cr>

C,0 <cr>

\*OK <cr>

C,? <cr>

?C,1 <cr> or ?C,0 <cr> or ?C,30 <cr>  
\*OK <cr>

# Single reading mode

## Command syntax

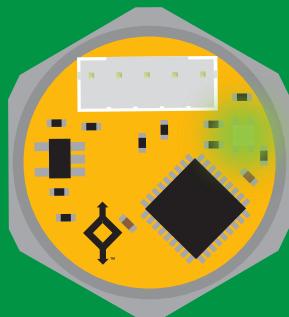
R <cr> takes single reading

### Example      Response

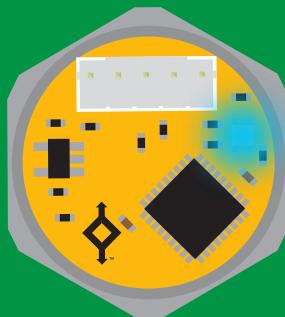
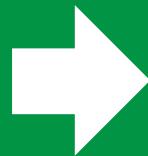
R <cr>

38.462 <cr>

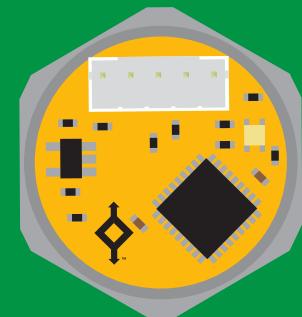
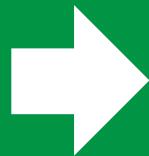
\*OK <cr>



Green  
Standby



Cyan  
Taking reading



Transmitting



# Alarm

## Command syntax

The alarm pin will = 1 when pressure levels are > alarm set point. Alarm tolerance sets how far below the set point pressure levels need to drop before the pin will = 0 again.

**Alarm,en,[1,0]** <cr> enable / disable alarm

**Alarm,n** <cr> sets alarm

**Alarm,tol,n** <cr> sets alarm tolerance

**Alarm,?** <cr> alarm set?

## Example

## Response

**Alarm,en,1** <cr>

\*OK <cr> Enable alarm

**Alarm,35** <cr>

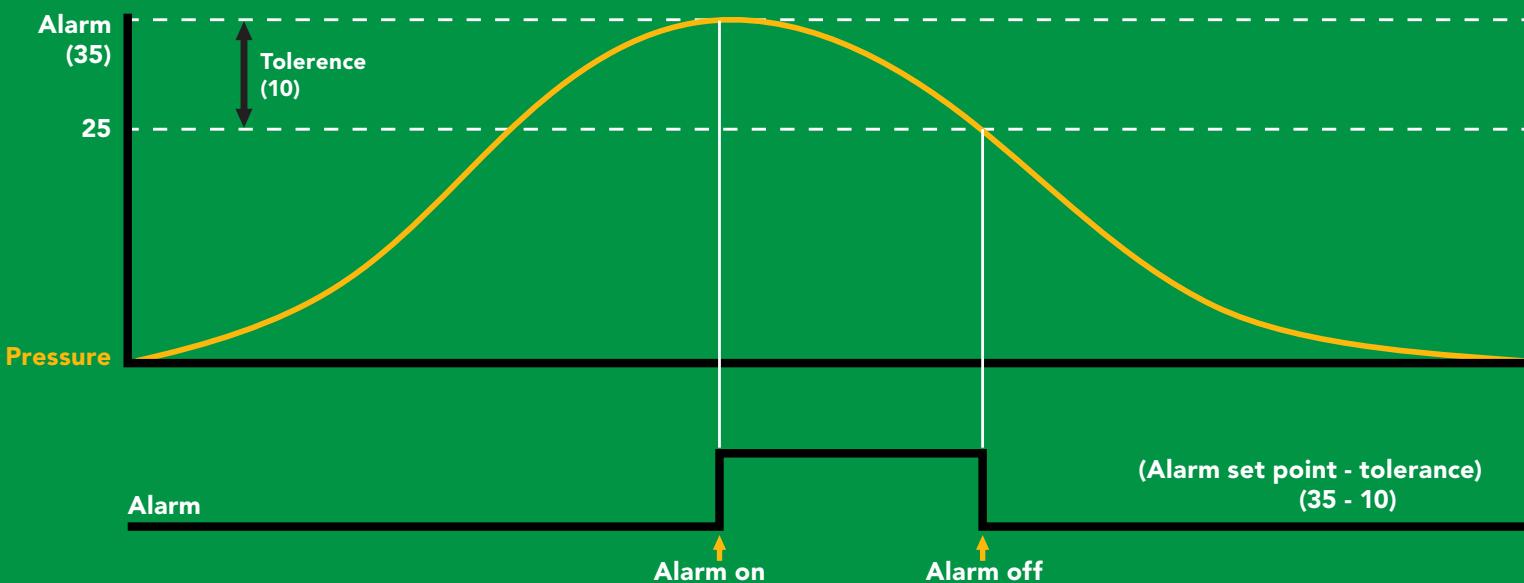
\*OK <cr>

**Alarm,tol,10** <cr>

\*OK <cr> Pressure level must fall 10 units below set point for alarm to reset.

**Alarm,?** <cr>

? ,alarm,35,10,1 <cr> if all are enabled



# Custom calibration

## Command syntax

Although calibration is not required, it may be necessary to adjust your 0 point or perform a custom calibration.

**Cal,n** <cr> calibrates the high point

**Cal,0** <cr> calibrates the zero point

**Cal,clear** <cr> restores calibration to factory settings

**Cal,?** <cr> device calibrated?

## Example

## Response

**Cal,50 <cr>**

\*OK <cr> high point calibration in psi

**Cal,0 <cr>**

\*OK <cr> low point calibration in psi

**Cal,clear <cr>**

\*OK <cr>

**Cal,? <cr>**

?Cal,0 <cr> or ?Cal,1 <cr> or ?Cal,2 <cr> or

no calibration

only zero point calibration

only high point calibration

?Cal,3 <cr> \*OK <cr>

zero and high point calibration

Calibration should be done using the pressure scale you have set the sensor to.

### Example

Readings are set to bar.

High point calibration = 3.44  
(3.44 bar = 50 psi)

# Add/remove decimal places

## Command syntax

Change how many decimal points the reading outputs.

**Dec,n <cr>** n = number of decimal points between 0 and 3

**Dec,? <cr>** number of decimal points the output is set to

## Example

R <cr>

Dec,1 <cr>

R <cr>

Dec,? <cr>

## Response

38.462 <cr>

\*OK <cr>

38.4 <cr>

?Dec,1 <cr>

# Pressure units

(psi, atm, bar, kPa, inch's of water, cm of water)

## Command syntax

U,[1/0]	<cr> 1 will add a unit identifier to the output
U,psi	<cr> output will be in psi <b>default</b>
U,atm	<cr> output will be in atm
U,bar	<cr> output will be in bar
U,kPa	<cr> output will be in kPa
U,inh2o	<cr> output will be in inches of water (Resolution: 0.027")
U,cmh2o	<cr> output will be in cm of water (Resolution: 0.7mm)
U,?	<cr> pressure units?

## Example

## Response

U,bar <cr>

\*OK <cr>

U,1 <cr>

\*OK <cr>  
1.228,bar <cr>

U,? <cr>

?U,bar <cr>

# Naming device

## Command syntax

Name,n <cr> set name

n = 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16

Name, <cr> clears name

Up to 16 ASCII characters

Name,? <cr> show name

Do not use spaces in the name

## Example

Name, <cr>

Name,zzt <cr>

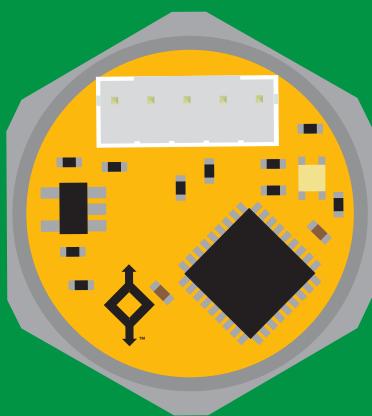
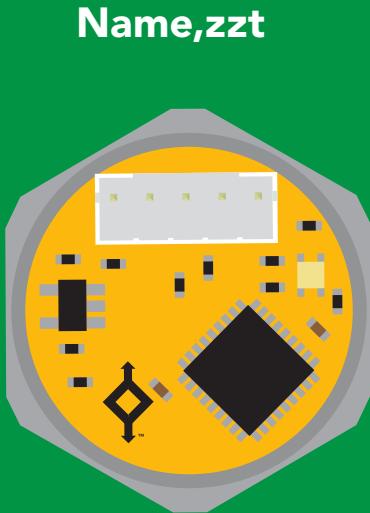
Name,? <cr>

## Response

\*OK <cr> name has been cleared

\*OK <cr>

?Name,zzt <cr>  
\*OK <cr>



Name,zzt  
\*OK <cr>

Name,?  
?Name,zzt <cr>  
\*OK <cr>

# Device information

## Command syntax

i <cr> device information

### Example      Response

i <cr>

?i,PRS,1.0 <cr>  
\*OK <cr>

### Response breakdown

?i,    PRS    1.0  
     ↑           ↑  
Device    Firmware

# Response codes

## Command syntax

\*OK,1 <cr> enable response **default**  
\*OK,0 <cr> disable response  
\*OK,? <cr> response on/off?

### Example

R <cr>

**38.462 <cr>**

**\*OK <cr>**

**\*OK,0 <cr>**

**no response, \*OK disabled**

R <cr>

**38.462 <cr> \*OK disabled**

**\*OK,? <cr>**

**?\*OK,1 <cr> or ?\*OK,0 <cr>**

### Response

### Other response codes

\*ER unknown command  
\*OV over volt (VCC>=5.5V)  
\*UV under volt (VCC<=3.1V)  
\*RS reset  
\*RE boot up complete, ready  
\*SL entering sleep mode  
\*WA wake up

These response codes  
cannot be disabled

# Reading device status

## Command syntax

Status <cr> voltage at Vcc pin and reason for last restart

### Example      Response

Status <cr>

?Status,P,5.038 <cr>

\*OK <cr>

### Response breakdown

?Status, P, 5.038  
↑                    ↑  
Reason for restart      Voltage at Vcc

#### Restart codes

P	powered off
S	software reset
B	brown out
W	watchdog
U	unknown

# Sleep mode/low power

## Command syntax

Send any character or command to awaken device.

**Sleep <cr>** enter sleep mode/low power

### Example

**Sleep <cr>**

### Response

\*OK <cr>  
\*SL <cr>

### Any command

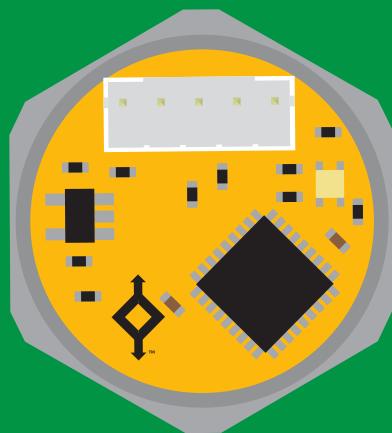
\*WA <cr> wakes up device

**5V**

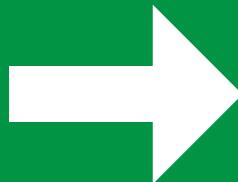
	STANDBY	SLEEP
5V	13.4 mA	0.415 mA

**3.3V**

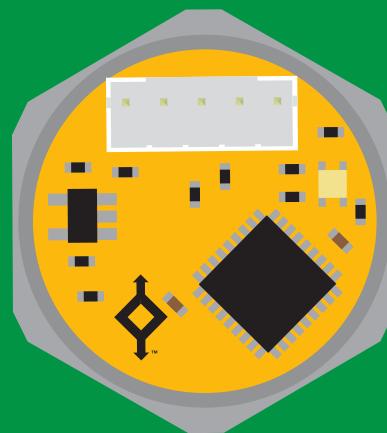
3.3V	12.4 mA	0.13 mA
------	---------	---------



**Standby**  
**13.4 mA**



**Sleep <cr>**



**Sleep**  
**0.415 mA**

# Change baud rate

## Command syntax

Baud,n <cr> change baud rate

### Example      Response

Baud,38400 <cr>

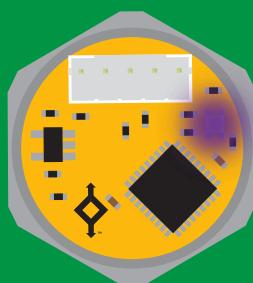
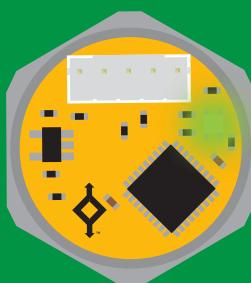
\*OK <cr>

Baud,? <cr>

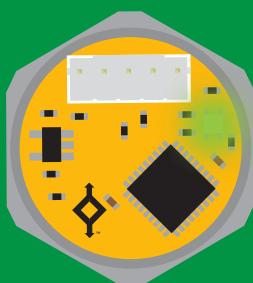
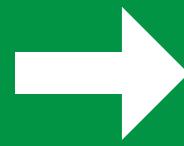
?Baud,38400 <cr>

\*OK <cr>

n = [ 300  
1200  
2400  
**9600 default**  
19200  
38400  
57600  
115200 ]



Baud,38400 <cr>



(reboot)

Standby

Changing  
baud rate

\*OK <cr>

Standby

# Protocol lock

## Command syntax

Locks device to UART mode.

Plock,1 <cr> enable Plock

Plock,0 <cr> disable Plock **default**

Plock,? <cr> Plock on/off?

## Example

Plock,1 <cr>

\*OK <cr>

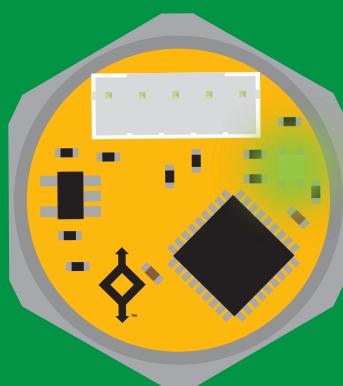
Plock,0 <cr>

\*OK <cr>

Plock,? <cr>

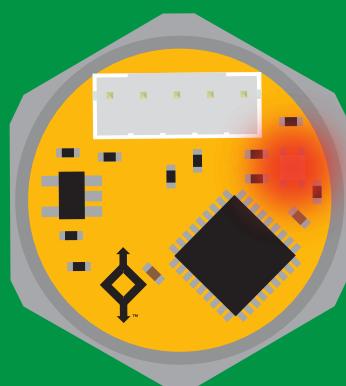
?Plock,1 <cr> or ?Plock,0 <cr>

## Response



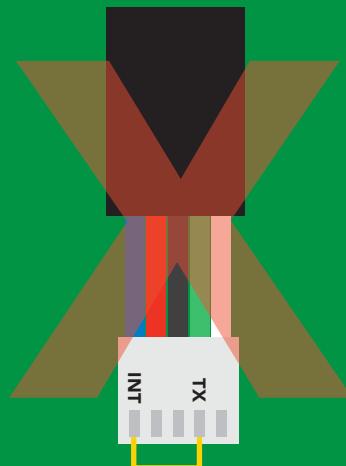
Plock,1

I2C,100



cannot change to I<sup>2</sup>C

\*ER <cr>



cannot change to I<sup>2</sup>C

# Factory reset

## Command syntax

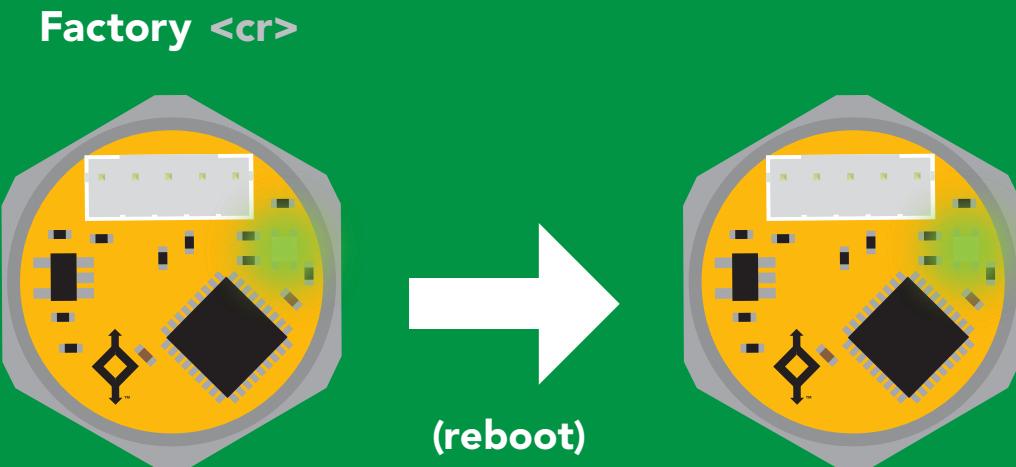
Clears calibration  
LED on  
"\*OK" enabled

Factory <cr> enable factory reset

## Example Response

Factory <cr>

\*OK <cr>



\*OK <cr>

\*RS <cr>  
\*RE <cr>

Baud rate will not change

# Change to I<sup>2</sup>C mode

## Command syntax

Default I<sup>2</sup>C address 106 (0x6A)

I<sup>2</sup>C,n <cr> sets I<sup>2</sup>C address and reboots into I<sup>2</sup>C mode

n = any number 1 – 127

## Example      Response

I<sup>2</sup>C,100 <cr>

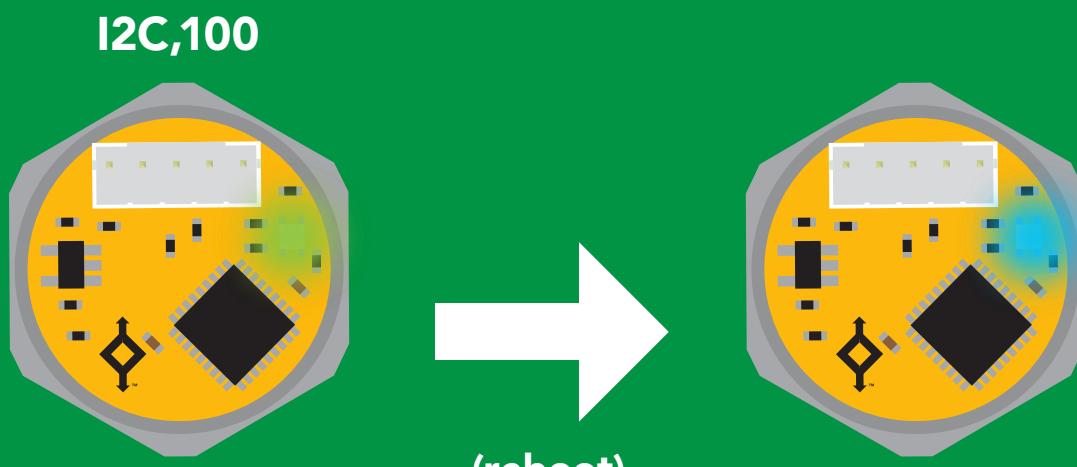
\*OK (reboot in I<sup>2</sup>C mode)

## Wrong example

I<sup>2</sup>C,139 <cr> n > 127

## Response

\*ER <cr>



Green  
\*OK <cr>

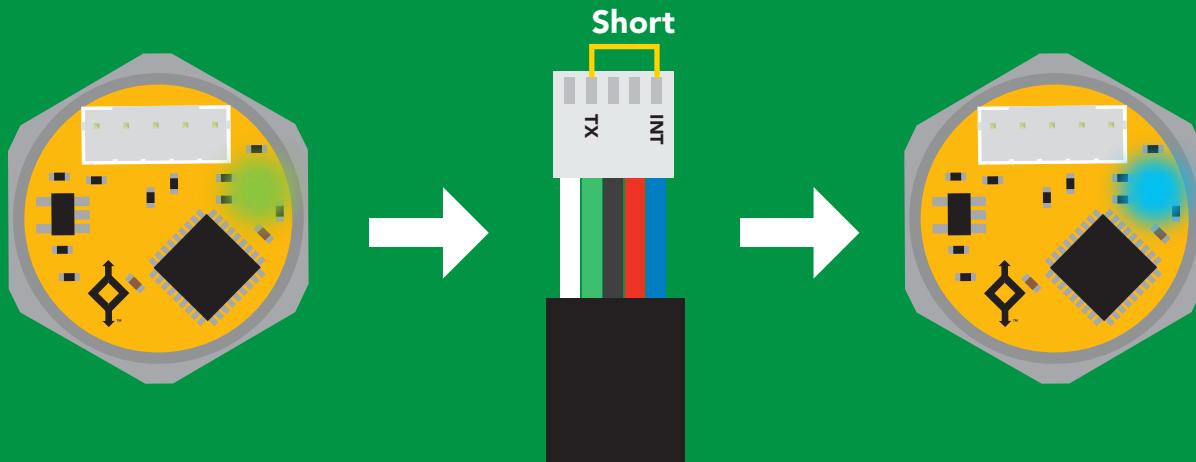
Blue  
now in I<sup>2</sup>C mode

# Manual switching to I<sup>2</sup>C

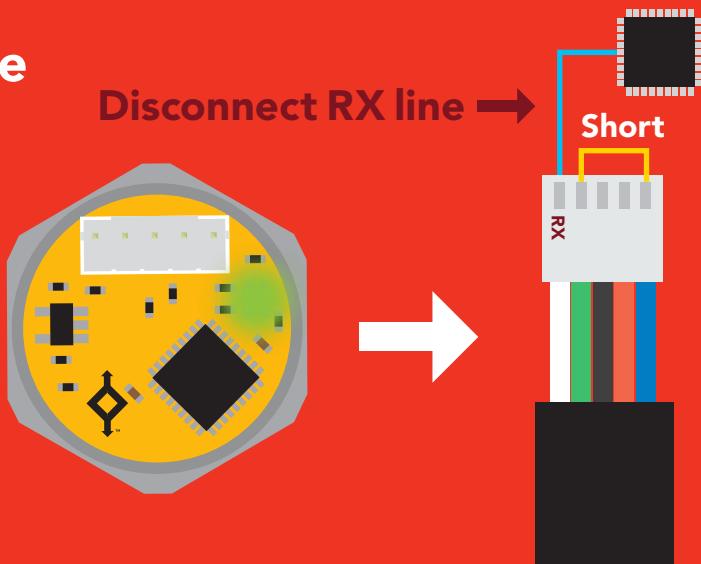
- Disconnect ground (power off)
- Disconnect TX and RX
- Connect TX to INT
- Confirm RX is disconnected
- Connect ground (power on)
- Wait for LED to change from **Green to Blue**
- Disconnect ground (power off)
- Reconnect all data and power

Manually switching to I<sup>2</sup>C will set the I<sup>2</sup>C address to 106 (0x6A)

## Example



## Wrong Example



# I<sup>2</sup>C mode

The I<sup>2</sup>C protocol is **considerably more complex** than the UART (RS-232) protocol. Atlas Scientific assumes the embedded systems engineer understands this protocol.

To set your EZO-PRS™ into I<sup>2</sup>C mode [click here](#)

## Settings that are retained if power is cut

- Calibration
- Change I<sup>2</sup>C address
- Custom calibration
- Hardware switch to UART mode
- LED control
- Protocol lock
- Software switch to UART mode

## Settings that are **NOT** retained if power is cut

- Find
- Sleep mode

# I<sup>2</sup>C mode

I<sup>2</sup>C address (0x01 – 0x7F)  
106 (0x6A) default

V<sub>cc</sub> 3.3V – 5.5V

Clock speed 100 – 400 kHz

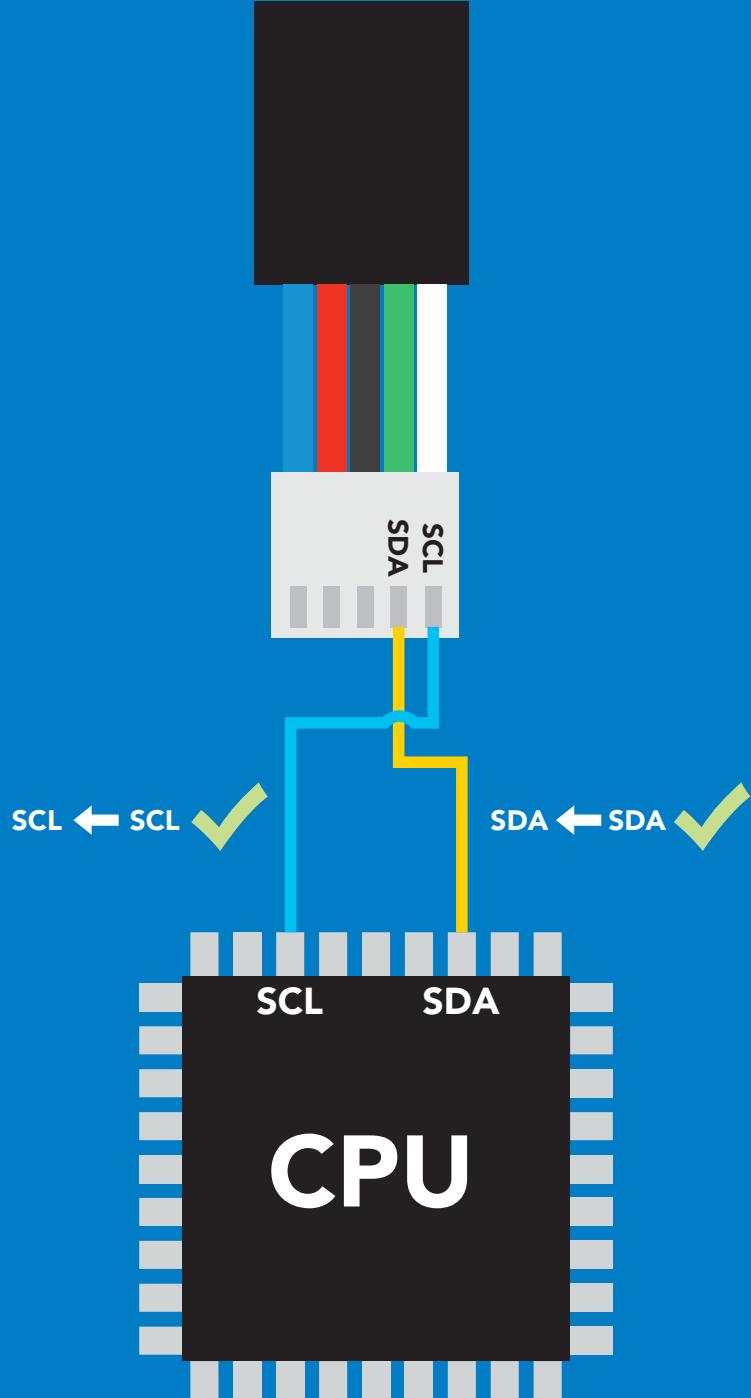
SDA



SCL



0V VCC



## Data format

Output pressure

Units PSI default  
(ATM, kPa, bar,  
inch's of water  
cm of water)

Encoding ASCII

Format string

Data type floating point

Decimal places 3

Smallest string 3 characters

Largest string 39 characters

# Sending commands to device

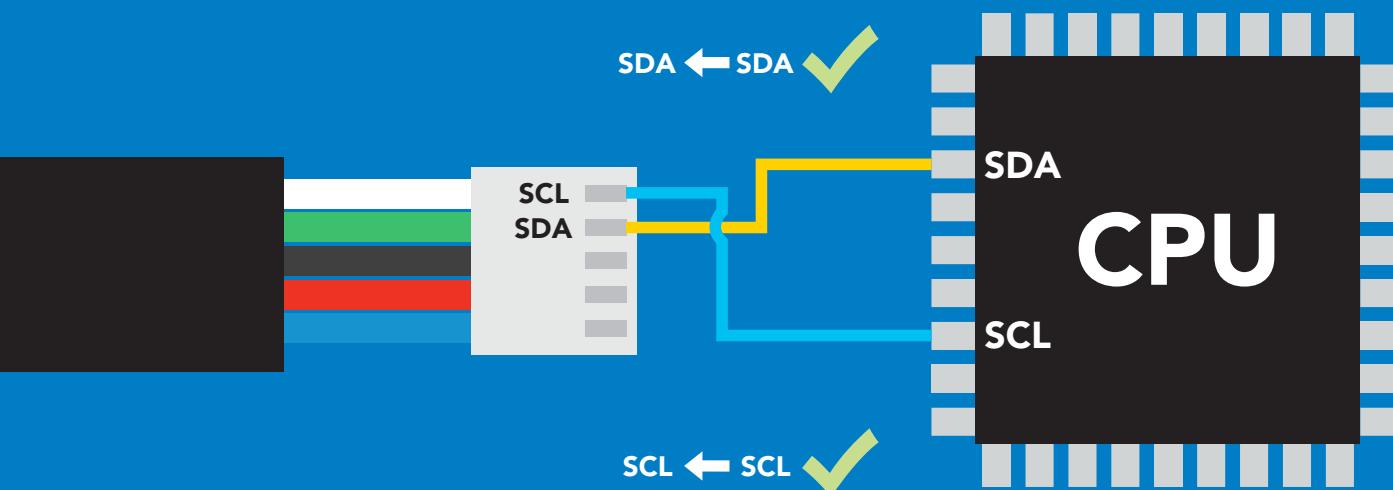
5 parts



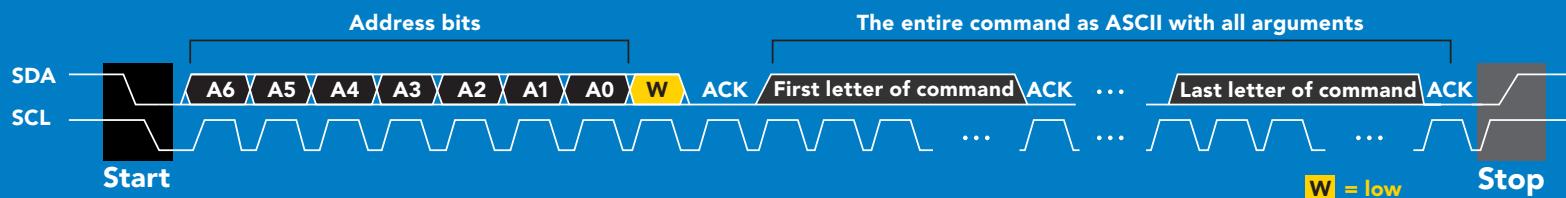
## Example

**Start**    **106 (0x6A)**    **Write**    **Sleep**    **Stop**

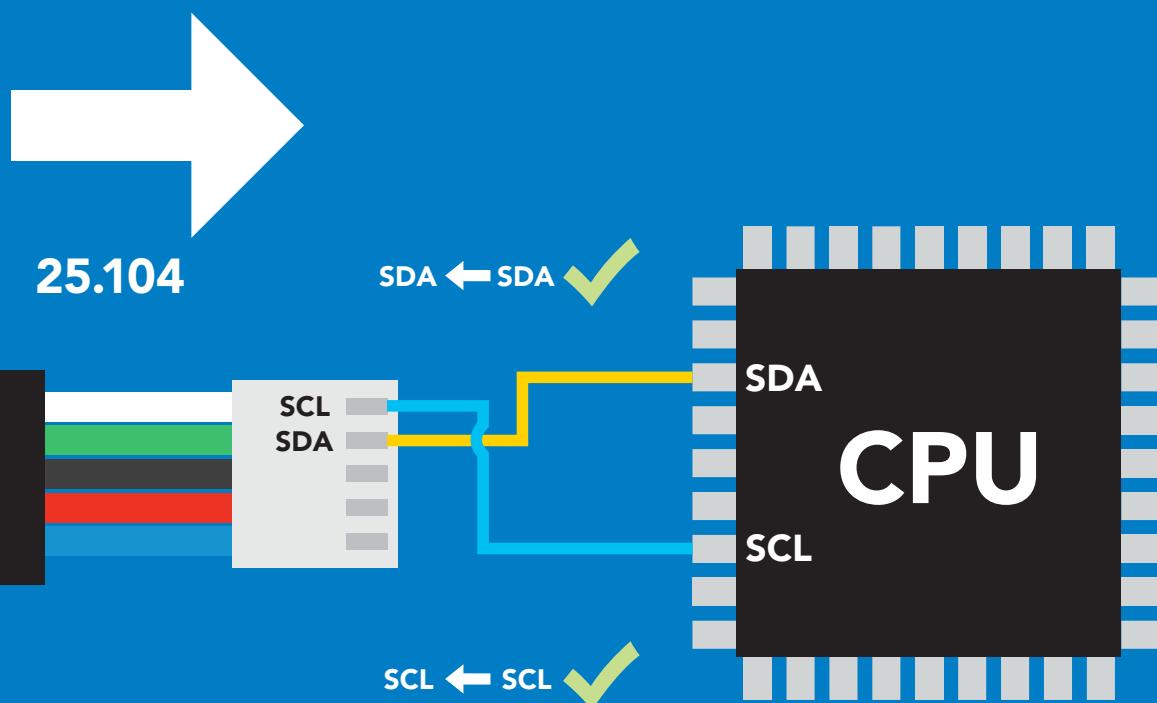
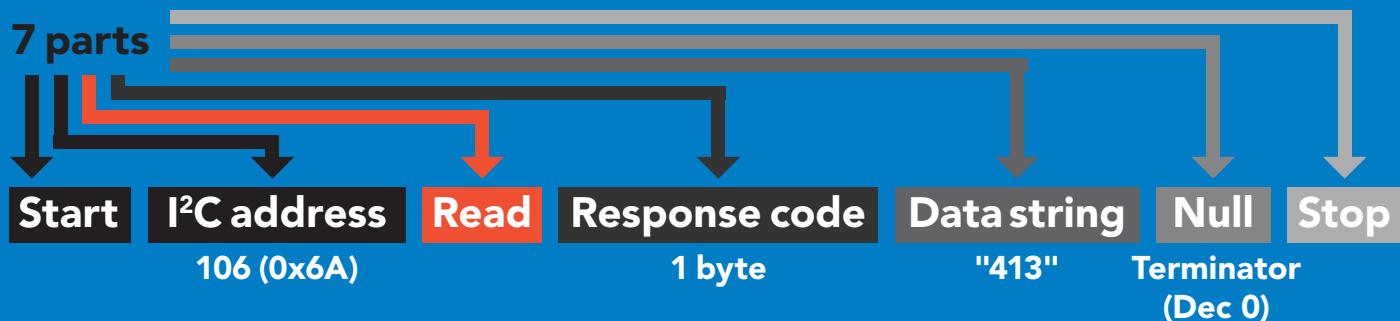
I<sup>2</sup>C address                      Command



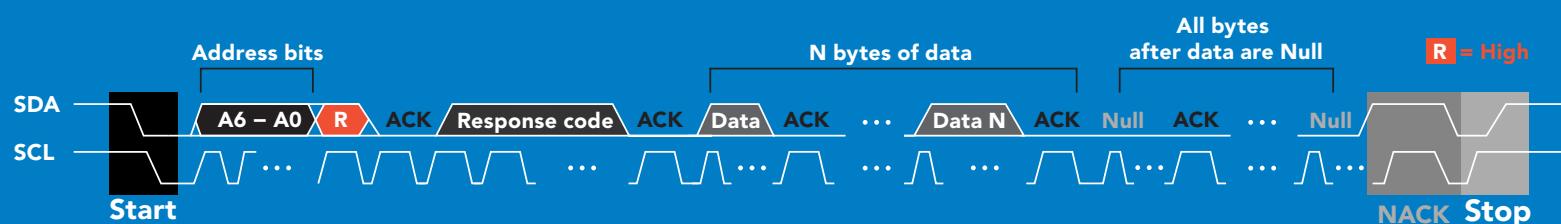
## Advanced



# Requesting data from device



## Advanced

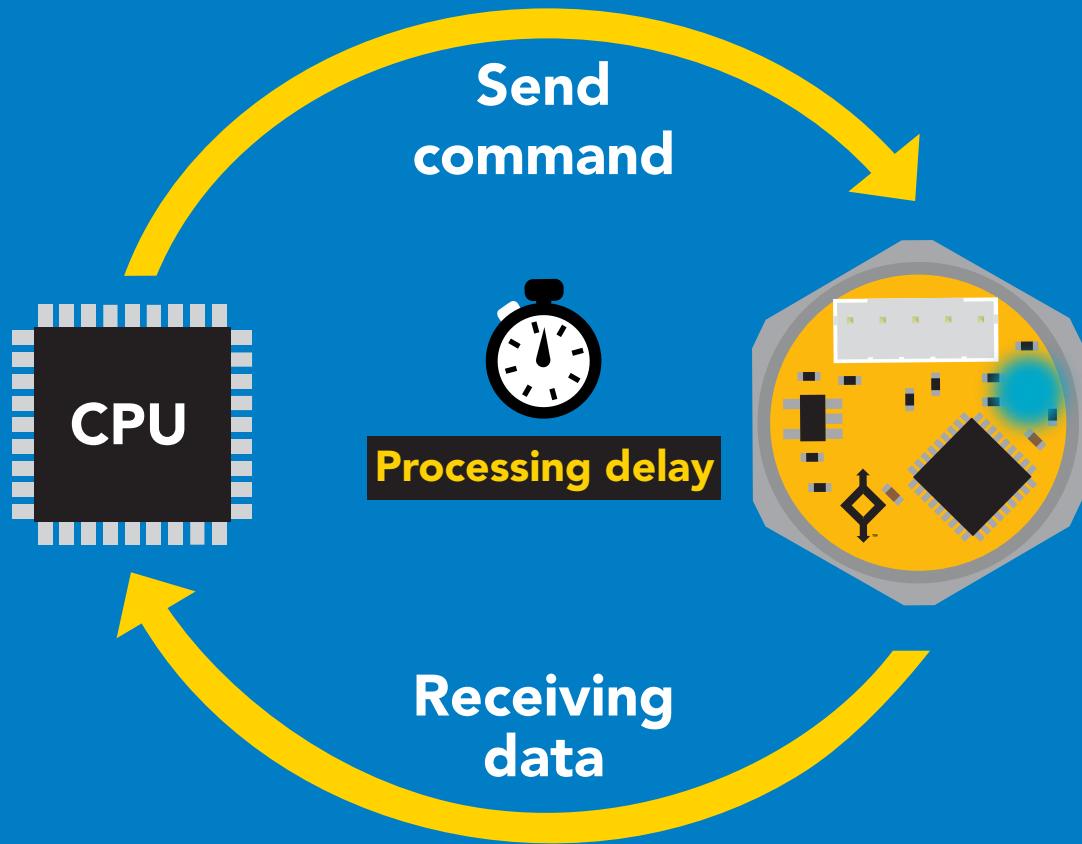


1 50 53 46 49 48 52 0 = 25.104  
Dec      Dec  
ASCII

# Response codes

After a command has been issued, a 1 byte response code can be read in order to confirm that the command was processed successfully.

*Reading back the response code is completely optional, and is not required for normal operation.*



## Example

```
I2C_start;  
I2C_address;  
I2C_write(EZO_command);  
I2C_stop;
```

```
delay(300); →  Processing delay
```

```
I2C_start;  
I2C_address;  
Char[ ] = I2C_read;  
I2C_stop;
```

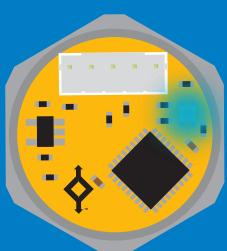
If there is no processing delay or the processing delay is too short, the response code will always be 254.

### Response codes

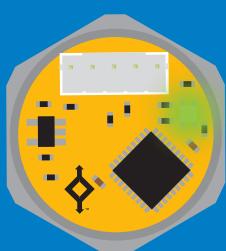
Single byte, not string

255	no data to send
254	still processing, not ready
2	syntax error
1	successful request

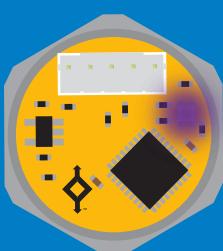
# LED color definition



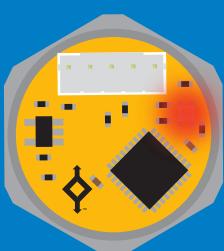
**Blue**  
I<sup>2</sup>C standby



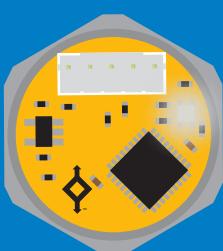
**Green**  
Taking reading



**Purple**  
Changing  
I<sup>2</sup>C address



**Red**  
Command  
not understood



**White**  
Find

<b>5V</b>	LED ON <b>+.25 mA</b>
<b>3.3V</b>	<b>+.26 mA</b>

# I<sup>2</sup>C mode

## command quick reference

All commands are ASCII strings or single ASCII characters.

Command	Function	
Alarm	enable/disable alarm	pg. 45
Baud	switch back to UART mode	pg. 56
Cal	performs custom calibration	pg. 46
Dec	add/remove decimal places	pg. 47
Factory	enable factory reset	pg. 55
Find	finds device with blinking white LED	pg. 43
i	device information	pg. 50
I2C	change I <sup>2</sup> C address	pg. 54
L	enable/disable LED	pg. 42
Name	set/show name of device	pg. 49
Plock	enable/disable protocol lock	pg. 53
R	returns a single reading	pg. 44
Sleep	enter sleep mode/low power	pg. 52
Status	retrieve status information	pg. 51
U	pressure units	pg. 48

# LED control

## Command syntax

300ms  processing delay

L,1 LED on **default**

L,0 LED off

L,? LED state on/off?

## Example

L,1

  
Wait 300ms

**1**  
Dec  
0  
Null

L,0

  
Wait 300ms

**1**  
Dec  
0  
Null

L,?

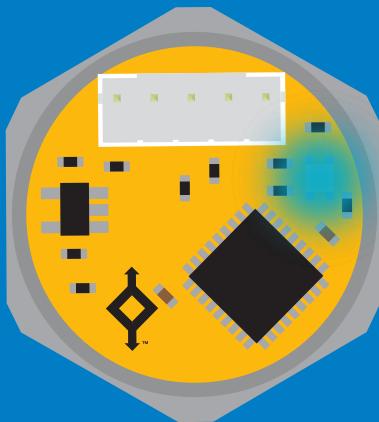
  
Wait 300ms

**1**  
Dec  
?L,1  
ASCII  
0  
Null

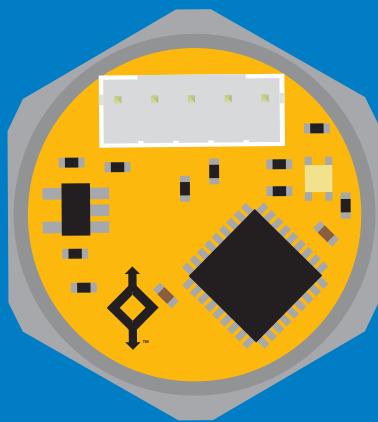
or

  
Wait 300ms

**1**  
Dec  
?L,0  
ASCII  
0  
Null



L,1



L,0

# Find

300ms  processing delay

## Command syntax

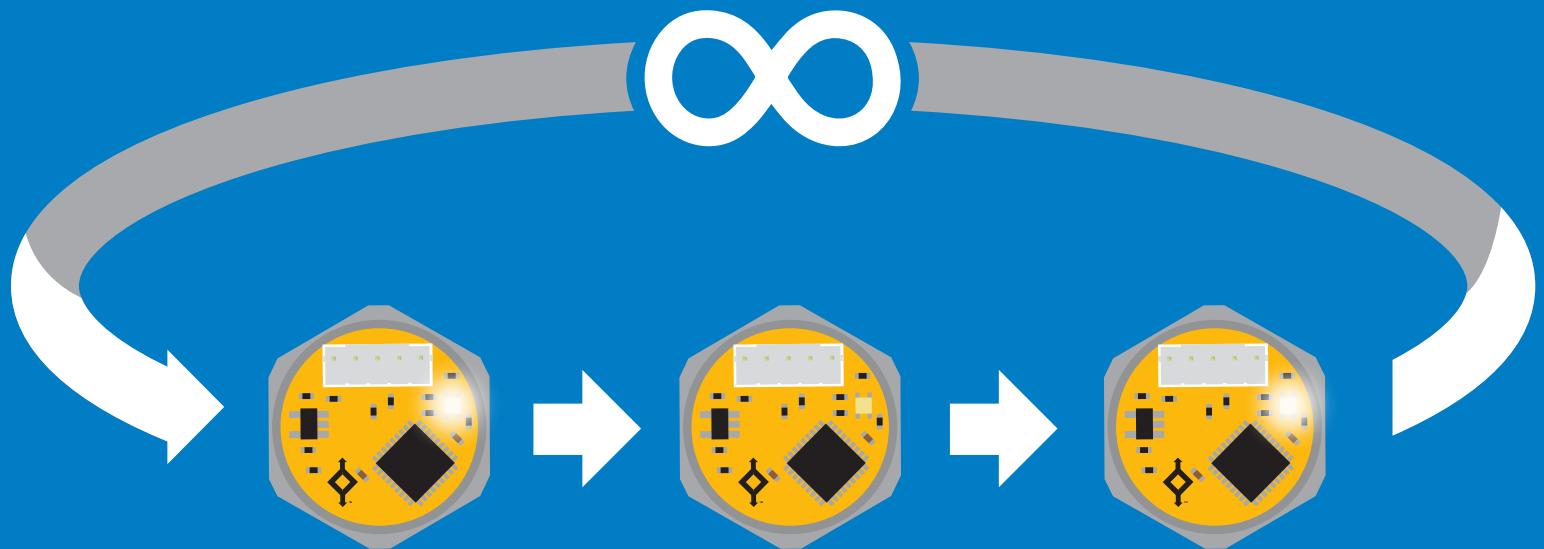
This command will disable continuous mode.  
Send any character or command to terminate find.

Find LED rapidly blinks white, used to help find device

## Example Response

Find

 1 0  
Wait 300ms Dec Null



# Taking reading

Command syntax

900ms  processing delay

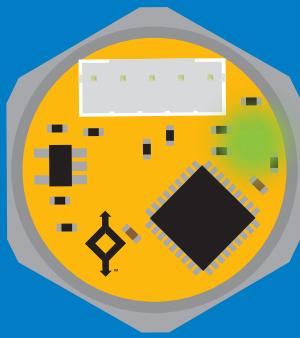
R return 1 reading

Example

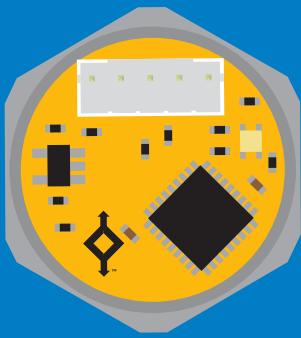
Response

R

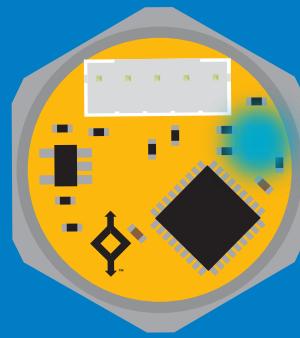
 1 38.462 0  
Wait 900ms Dec ASCII Null



Green  
Taking reading



Transmitting



Cyan  
Standby

# Alarm

300ms  processing delay

## Command syntax

**Alarm,en,[1,0]** enable / disable alarm

**Alarm,n** sets alarm

**Alarm,tol,n** sets alarm tolerance

**Alarm,?** alarm set?

The alarm pin will = 1 when pressure levels are > alarm set point. Alarm tolerance sets how far below the set point pressure levels need to drop before the pin will = 0 again.

## Example

## Response

**Alarm,en,1**

 Wait 300ms    1 Dec 0 Null

Enable alarm

**Alarm,35**

 Wait 300ms    1 Dec 0 Null

**Alarm,tol,10**

 Wait 300ms    1 Dec 0 Null

Pressure level must fall 10 units below set point for alarm to reset.

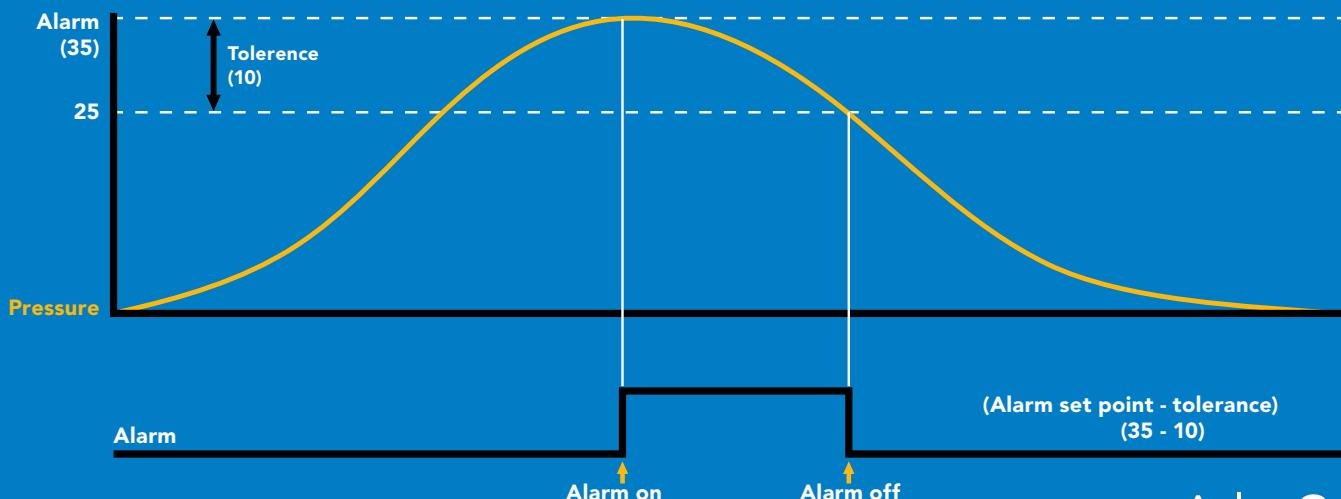
**Alarm,?**

 Wait 300ms    1 Dec 0 Null

? ,alarm,35,10,1

0

if all are enabled



# Custom calibration

900ms  processing delay

## Command syntax

Although calibration is not required, it may be necessary to adjust your 0 point or perform a custom calibration.

Cal,n

calibrates the high point

Cal,0

calibrates the zero point

Cal,clear

restores calibration to factory settings

Cal,?

device calibrated?

## Example

## Response

Cal,50



1 Dec 0 Null

high point calibration in psi

Cal,0



1 Dec 0 Null

low point calibration in psi

Cal,clear



1 Dec 0 Null

Cal,?



1 Dec ?Cal,0 0 Null

or 1 Dec ?Cal,1 0 Null

only zero point calibration

or 1 Dec ?Cal,2 0 Null

only high point calibration

or 1 Dec ?Cal,3 0 Null

zero and high point calibration

Calibration should be done using the pressure scale you have set the sensor to.

### Example

Readings are set to bar.

High point calibration = 3.44  
(3.44 bar = 50 psi)

# Add/remove decimal places

900ms  processing delay

## Command syntax

Change how many decimal points the reading outputs.

Dec,n    n = number of decimal points between 0 and 3

Dec,?    number of decimal points the output is set to

## Example

## Response

R

 Wait 900ms  
1 Dec    38.462 ASCII    0 Null

Dec,1

 Wait 900ms  
1 Dec    0 Null

R

 Wait 900ms  
1 Dec    38.4 ASCII    0 Null

Dec,?

 Wait 900ms  
1 Dec    ?Dec,1 ASCII    0 Null

# Pressure units

(psi, atm, bar, kPa, inch's of water, cm of water)

## Command syntax

U,[1/0]	1 will add a unit identifier to the output	
U,psi	output will be in psi	
U,atm	output will be in atm	
U,bar	output will be in bar	
U,kPa	output will be in kPa	
U,inh2o	output will be in inches of water	(Resolution: 0.027")
U,cmh2o	output will be in cm of water	(Resolution: 0.7mm)
U,?	pressure units?	

## Example

## Response

U,bar

 Wait 300ms  
1 Dec 0 Null

U,1

 Wait 300ms  
1 Dec 0 Null

 Wait 300ms  
1 Dec 1.228,bar 0 ASCII Null

U,?

 Wait 300ms  
1 Dec ?U,bar 0 Null

# Naming device

300ms  processing delay

## Command syntax

Do not use spaces in the name

Name,n    set name

n =

— 1 2 3 4 5 6 7 8 9 — 10 11 12 13 14 15 16 —

Name,    clears name

Up to 16 ASCII characters

Name,?    show name

## Example

## Response

Name,



1 Dec 0 Null

name has been cleared

Name,zzt



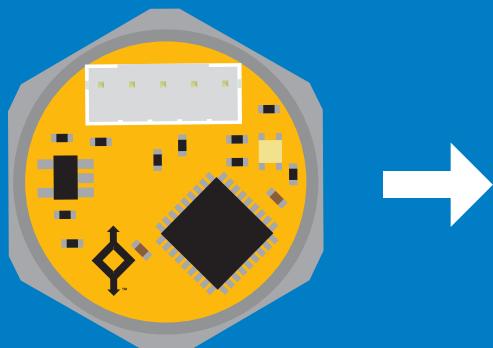
1 Dec 0 Null

Name,?



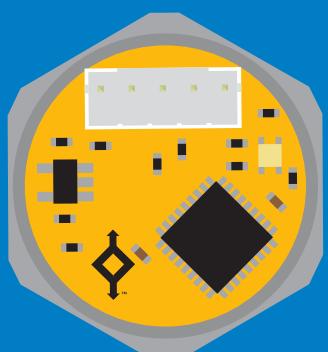
1 Dec ?Name,zzt 0 Null

Name,zzt



1 0

Name,?



1 ?Name,zzt 0

# Device information

## Command syntax

300ms  processing delay

i device information

Example Response

i



Wait 300ms

1  
Dec

?i,PRS, 1.0  
ASCII

0  
Null

## Response breakdown

?i, PRS, 1.0  
↑      ↑  
Device Firmware

# Reading device status

## Command syntax

300ms  processing delay

Status voltage at Vcc pin and reason for last restart

## Example Response

Status



Wait 300ms

1

?Status,P,5.038

Dec

ASCII

0

Null

## Response breakdown

?Status, P,  
Reason for restart      5.038  
                            Voltage at Vcc

### Restart codes

P	powered off
S	software reset
B	brown out
W	watchdog
U	unknown

# Sleep mode/low power

## Command syntax

**Sleep** enter sleep mode/low power

Send any character or command to awaken device.

### Example

### Response

**Sleep**

**no response**

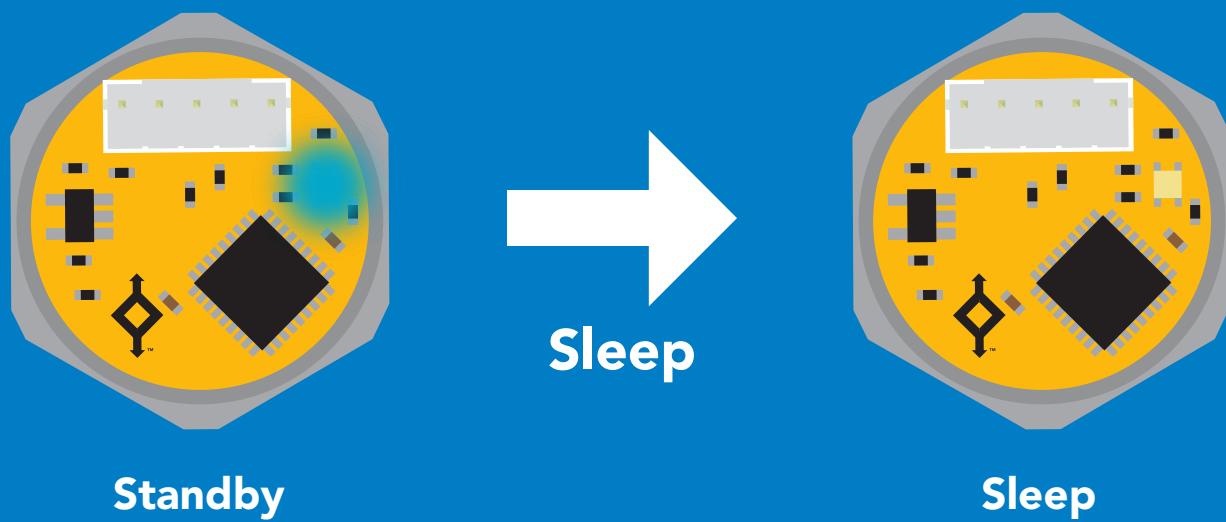
Do not read status byte after issuing sleep command.

**Any command**

**wakes up device**

	STANDBY	SLEEP
<b>5V</b>	<b>13.4 mA</b>	<b>0.415 mA</b>

<b>3.3V</b>	<b>12.4 mA</b>	<b>0.13 mA</b>
-------------	----------------	----------------



# Protocol lock

## Command syntax

300ms  processing delay

Plock,1 enable Plock

Locks device to I<sup>2</sup>C mode.

Plock,0 disable Plock **default**

Plock,? Plock on/off?

## Example

Plock,1

 Wait 300ms

**1** Dec **0** Null

Plock,0

 Wait 300ms

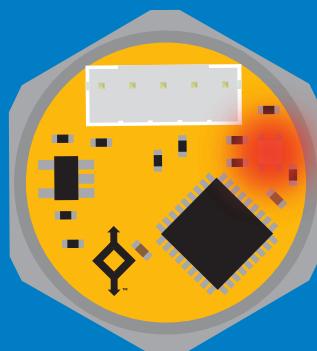
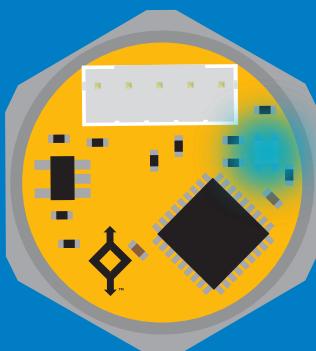
**1** Dec **0** Null

Plock,?

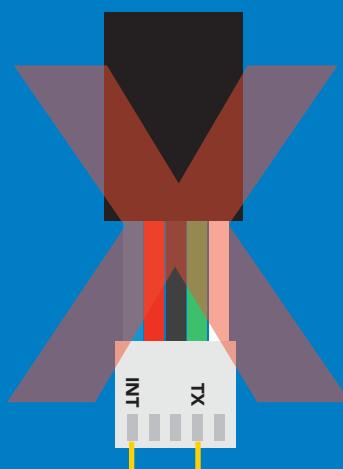
 Wait 300ms

**1** Dec **?Plock,1** ASCII **0** Null

Baud, 9600



cannot change to UART



cannot change to UART

# I<sup>2</sup>C address change

## Command syntax

300ms  processing delay

I2C,n sets I<sup>2</sup>C address and reboots into I<sup>2</sup>C mode

## Example Response

I2C,101

device reboot

(no response given)

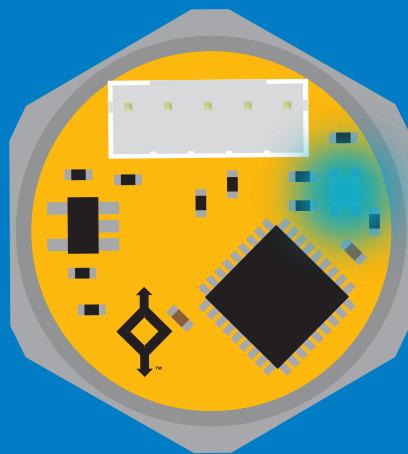
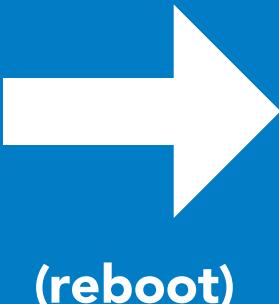
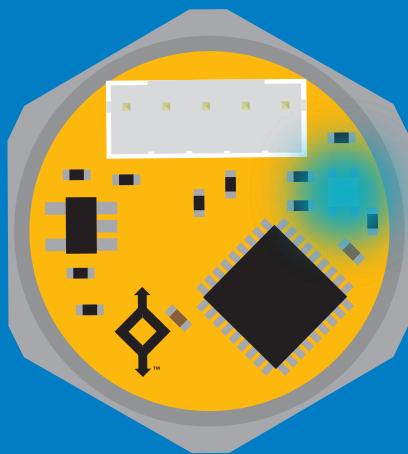
## Warning!

Changing the I<sup>2</sup>C address will prevent communication between the device and the CPU until the CPU is updated with the new I<sup>2</sup>C address.

Default I<sup>2</sup>C address is 106 (0x6A).

n = any number 1 – 127

I2C,101



# Factory reset

## Command syntax

Factory reset will not take the device out of I<sup>2</sup>C mode.

Factory enable factory reset

I<sup>2</sup>C address will not change

## Example Response

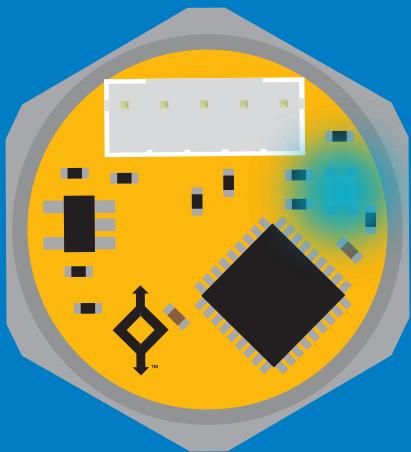
Factory

device reboot

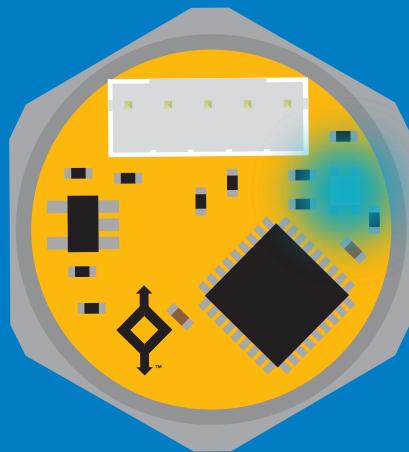
(no response given)

Clears calibration  
LED on  
Response codes enabled

Factory



(reboot)



# Change to UART mode

## Command syntax

Baud,n switch from I<sup>2</sup>C to UART

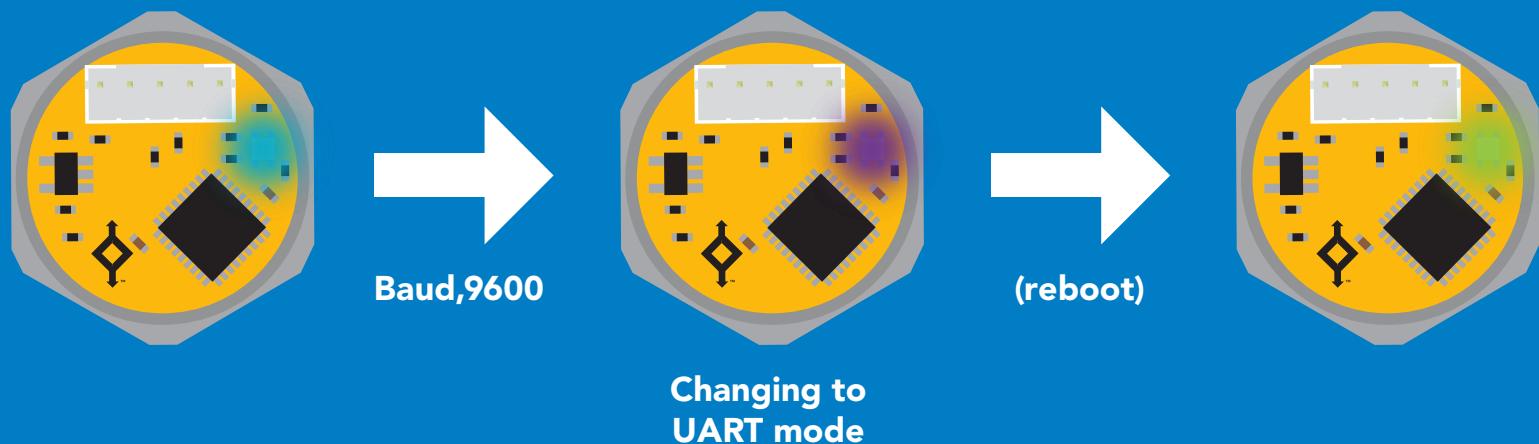
### Example      Response

Baud,9600

reboot in UART mode

(no response given)

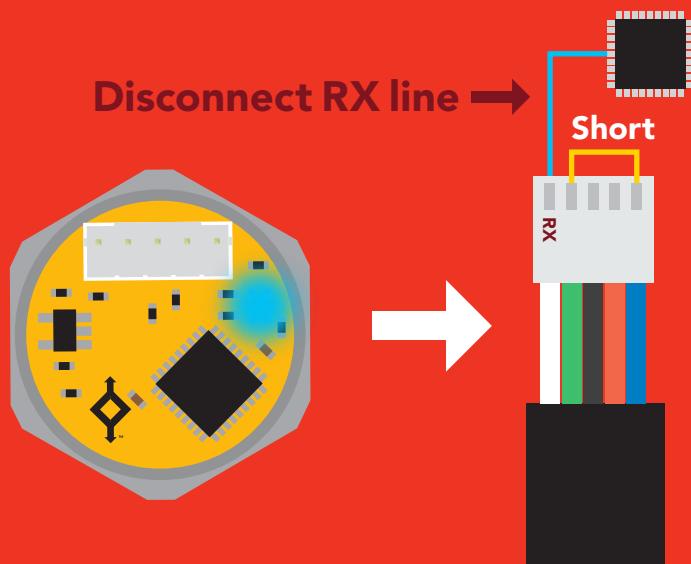
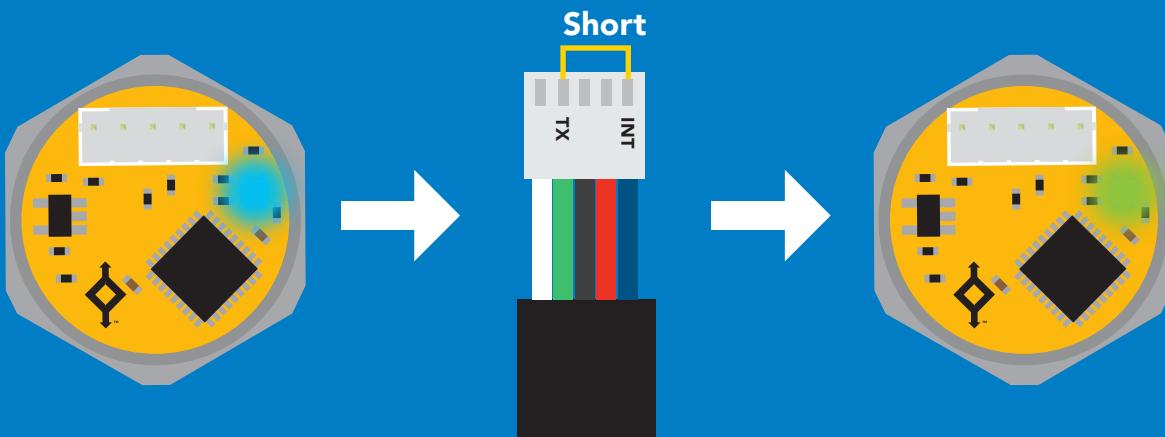
$$n = \left[ \begin{array}{l} 300 \\ 1200 \\ 2400 \\ 9600 \\ 19200 \\ 38400 \\ 57600 \\ 115200 \end{array} \right]$$



# Manual switching to UART

- Disconnect ground (power off)
- Disconnect TX and RX
- Connect TX to INT
- Confirm RX is disconnected
- Connect ground (power on)
- Wait for LED to change from **Blue** to **Green**
- Disconnect ground (power off)
- Reconnect all data and power

## Example



# Datasheet change log

## **Datasheet V 2.2**

Revised artwork of sensor throughout datasheet.

## **Datasheet V 2.1**

Revised artwork on page 8.

## **Datasheet V 2.0**

Revised design of EZO-PRS throughout document.

## **Datasheet V 1.6**

Revised naming device info on pages 25 & 49.

## **Datasheet V 1.5**

Added the custom calibartion pages on pages 22 & 46.

## **Datasheet V 1.4**

Revised accuracy value on cover page.

## **Datasheet V 1.3**

Revised pressure output in PSI to 50.000 on cover pg.  
added inches of water & cm of water resolution info on pages 23 and 46.

## **Datasheet V 1.2**

Updated firmware info on pg 55.

## **Datasheet V 1.1**

Moved Default state to pg 9.

## **Datasheet V 1.0**

Initial release - New datasheet

# Firmware updates

V1.0 – Initial release (Aug, 7 2019)

V1.01 – (Nov, 5 2019)

- Fixed glitch where the alarm was not initially set correctly.

V1.02 – (April, 9 2021)

- Added custom calibration

# Warranty

Atlas Scientific™ Warranties the EZO-PRS™ Embedded Pressure Sensor to be free of defect during the debugging phase of device implementation, or 30 days after receiving the EZO-PRS™ Embedded Pressure Sensor (which ever comes first).

## The debugging phase

The debugging phase as defined by Atlas Scientific™ is the time period when the EZO-PRS™ Embedded Pressure Sensor is inserted into a bread board, or shield. If the EZO-PRS™ is being debugged in a bread board, the bread board must be devoid of other components. If the EZO-PRS™ Embedded Pressure Sensor is being connected to a microcontroller, the microcontroller must be running code that has been designed to drive the EZO-PRS™ Embedded Pressure Sensor exclusively and output the EZO-PRS™ data as a serial string.

**It is important for the embedded systems engineer to keep in mind that the following activities will void the EZO-PRS™ Embedded Pressure Sensor warranty:**

- **Soldering any part of the EZO-PRS™ Embedded Pressure Sensor.**
- **Running any code, that does not exclusively drive the EZO-PRS™ Embedded Dosing Pump and output its data in a serial string.**
- **Embedding the EZO-PRS™ Embedded Pressure Sensor into a custom made device.**
- **Removing any potting compound.**

# Reasoning behind this warranty

Because Atlas Scientific™ does not sell consumer electronics; once the device has been embedded into a custom made system, Atlas Scientific™ cannot possibly warranty the EZO-PRS™ Embedded Pressure Sensor, against the thousands of possible variables that may cause the EZO-PRS™ Embedded Pressure Sensor to no longer function properly.

## Please keep this in mind:

- 1. All Atlas Scientific™ devices have been designed to be embedded into a custom made system by you, the embedded systems engineer.**
- 2. All Atlas Scientific™ devices have been designed to run indefinitely without failure in the field.**
- 3. All Atlas Scientific™ devices can be soldered into place, however you do so at your own risk.**

Atlas Scientific™ is simply stating that once the device is being used in your application, Atlas Scientific can no longer take responsibility for the EZO-PRS™ Embedded Pressure Sensors continued operation. This is because that would be equivalent to Atlas Scientific™ taking responsibility over the correct operation of your entire device.