

src/position\_service.cpp

```
graph TD; A[src/position_service.cpp] --> B[ros/ros.h]; A --> C[rt2_assignment1/RandomPosition.h];
```

A diagram illustrating the dependencies of the file `src/position_service.cpp`. The file is shown in a grey box at the top. Two blue arrows point from it to two white boxes below: `ros/ros.h` on the left and `rt2_assignment1/RandomPosition.h` on the right.

ros/ros.h

rt2\_assignment1/RandomPosition.h