

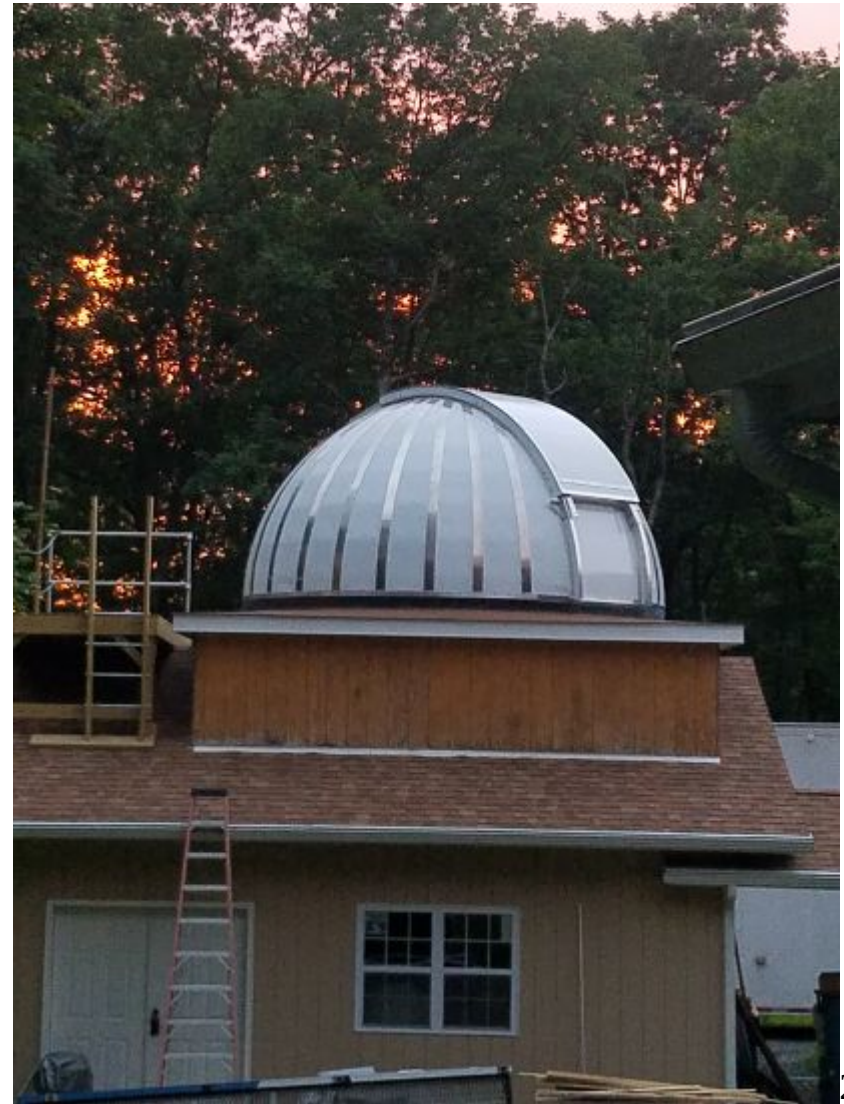
Polar Alignment using Plate Solving

Novel way of doing Polar Alignment

Mark Sproul
Springfield Telescope Makers
Oct 2021

My Observatory

- 15 foot diameter home built dome
- Pike County Pennsylvania



My Scope

3 Main Scopes

16 inch Newtonian (F4.15)

4 inch refractor (WO102)

3 inch refractor (WO71)

Finder scope

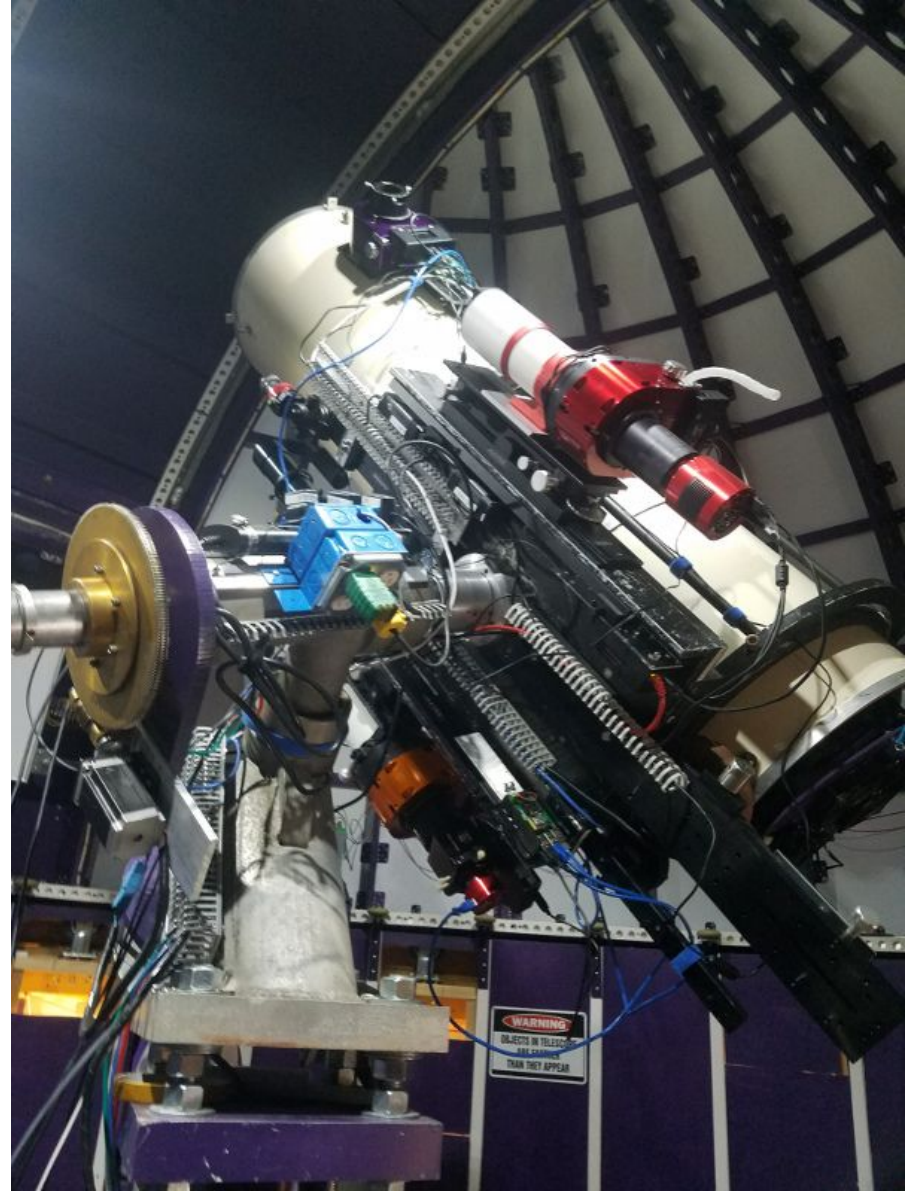
Guide Scope

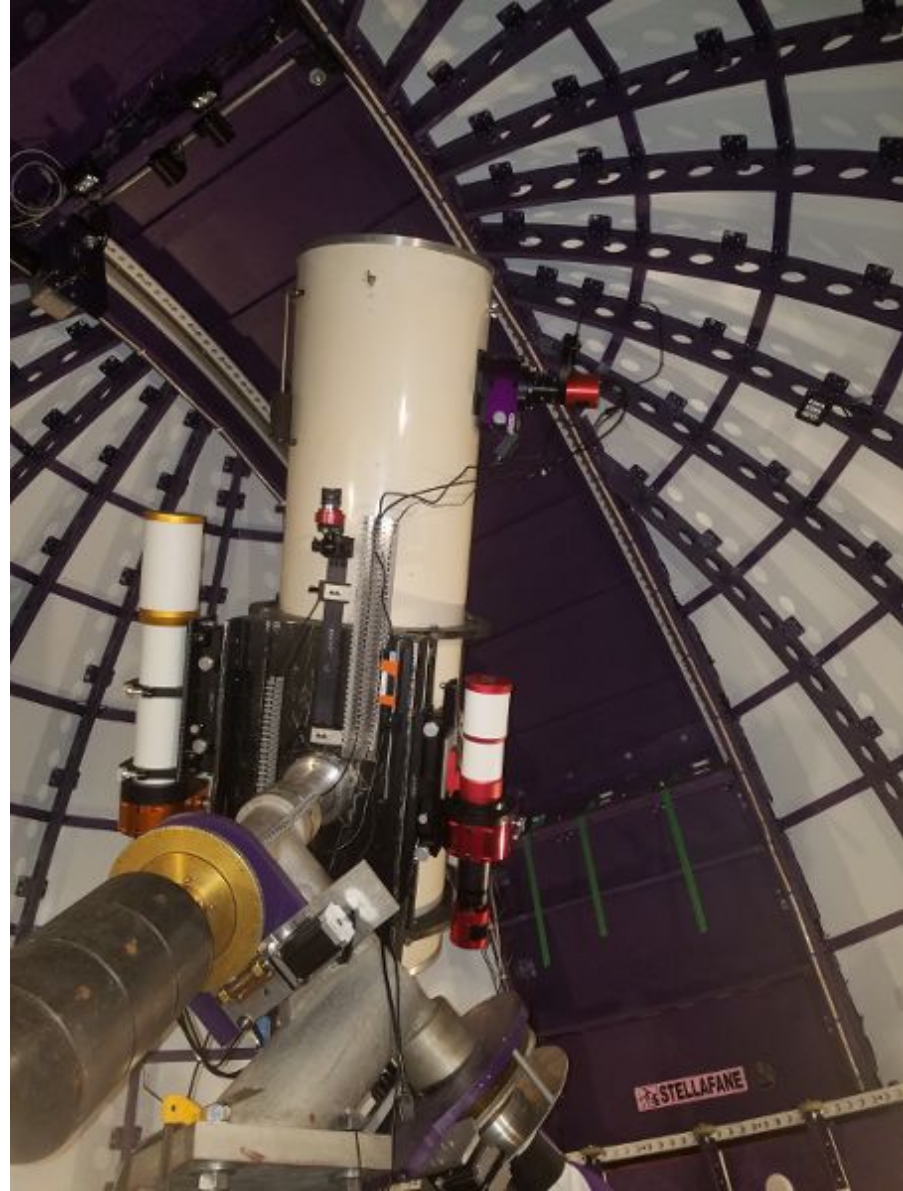
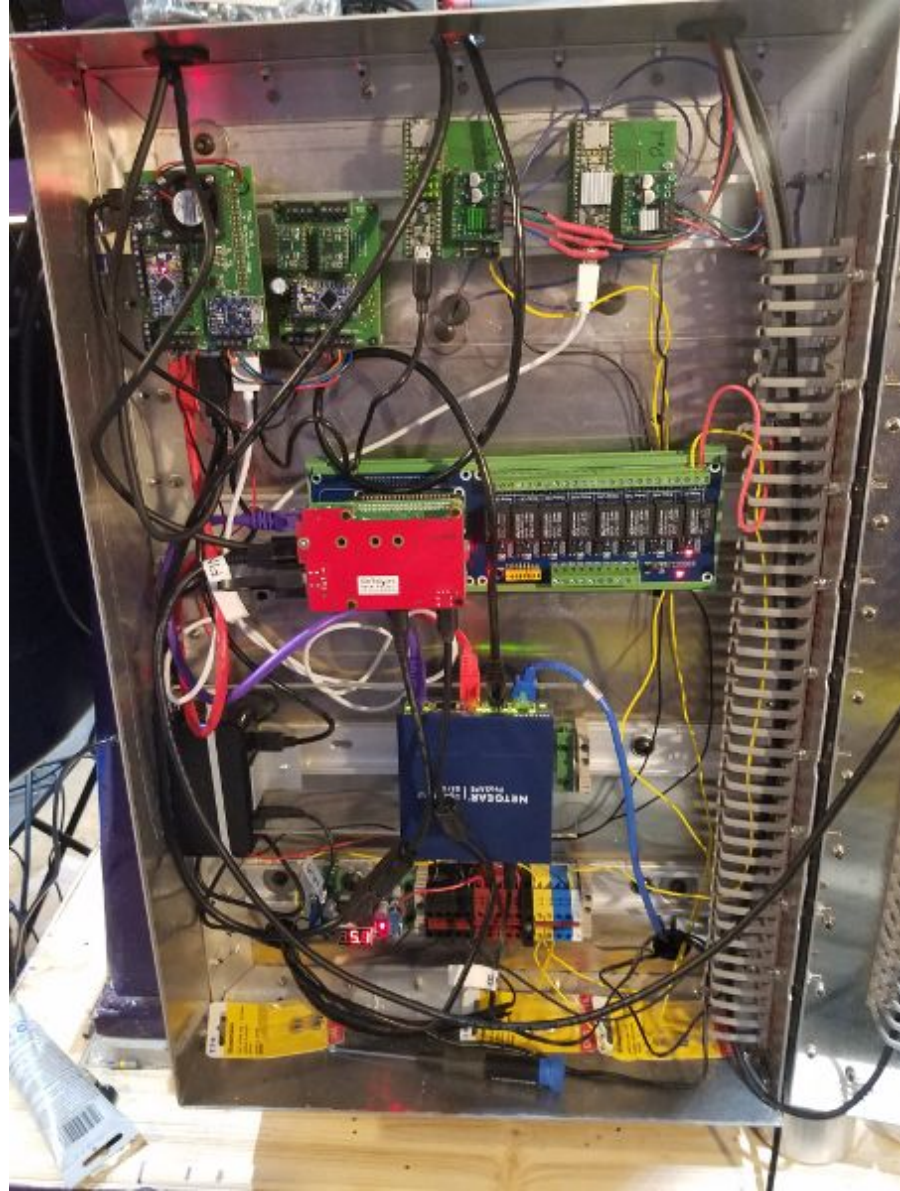
6 Raspberry Pi's

170 lbs counter weight

Total moving mass ~400 pounds

German Equatorial Mount with
2.5" shafts







<----

Adjustment Nuts
on 1 inch
diameter rods

---->

Adjustment
Tools



Many ways, tried and true

- Built in polar scope
- Drift method
- QHY Polemaster
- Software
 - K-Stars
 - Lots of others

What DIDN'T work (for me)

- Drift method
 - 8 months working at it, just made it worse
- QHY Polemaster
 - Bought one used, no way to accurately mount it

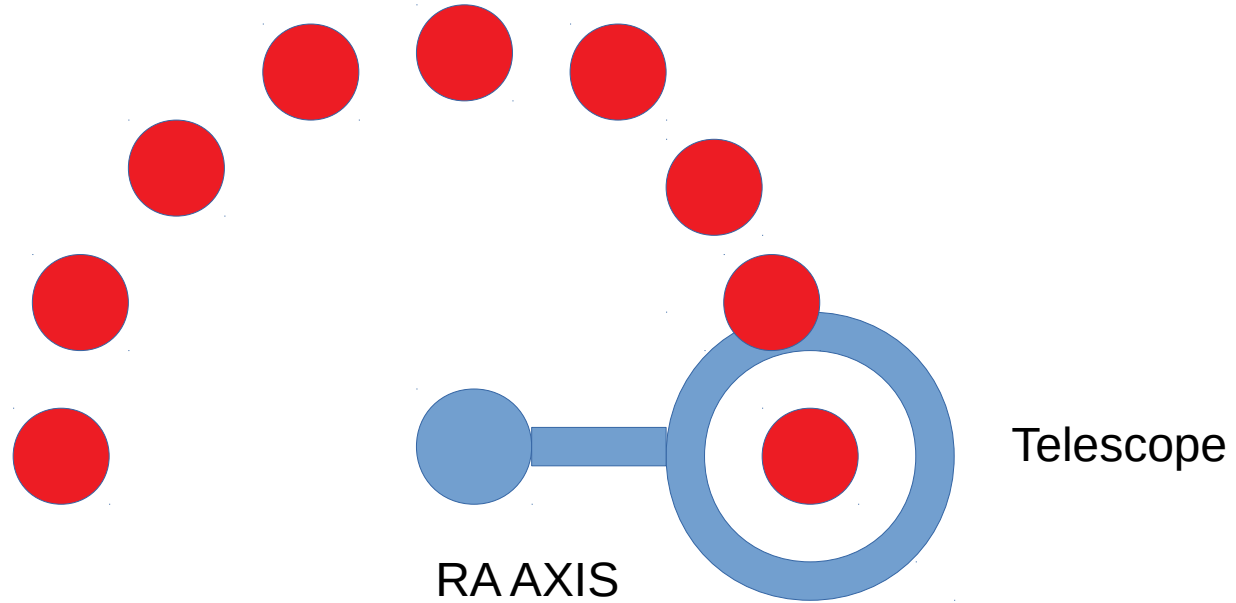
What to do NEXT???

- Figure out WHERE I am pointing????

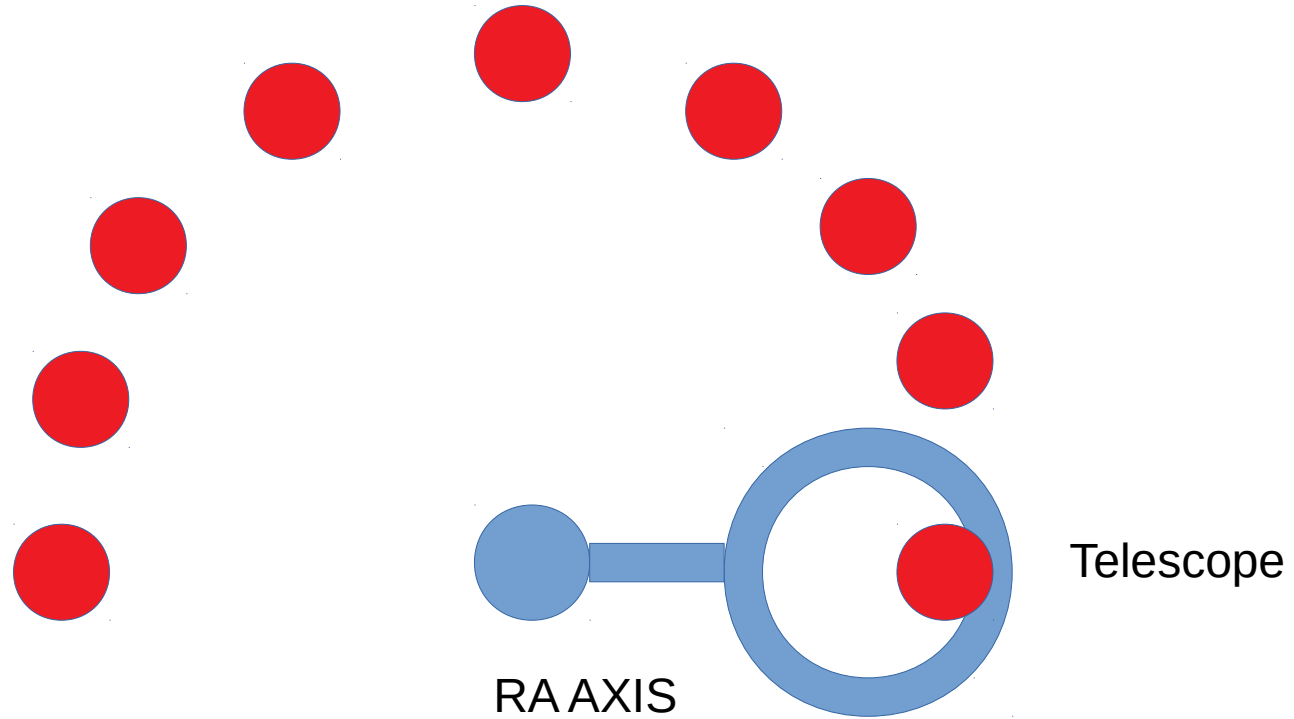
Theory

- Take a series of pictures while rotating around the RA axis WITHOUT tracking turned on and WITHOUT changing DEC.
- Plot the center points of each picture, this should generate an arc
- The center of the arc is where RA is pointed

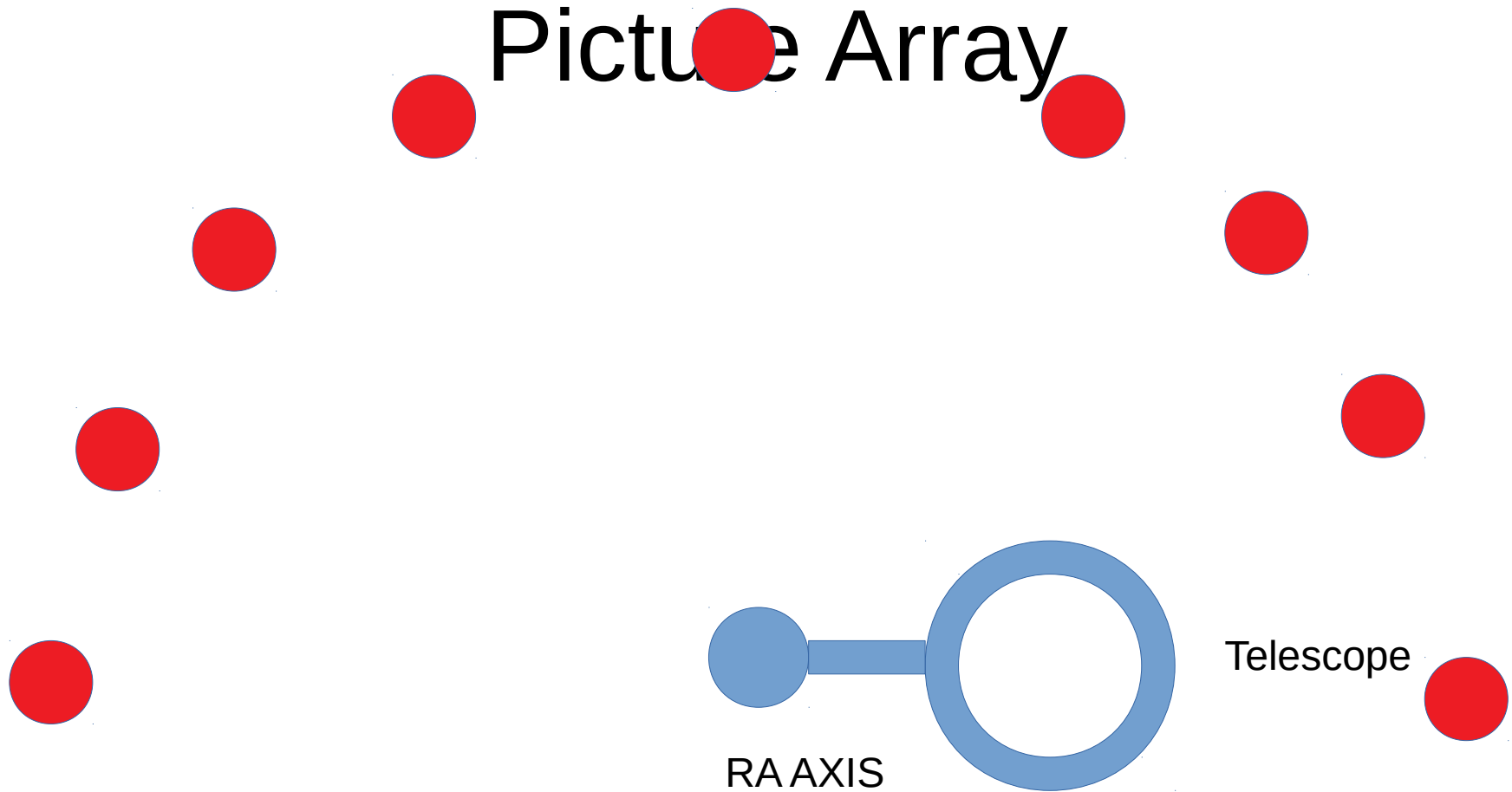
Picture Array



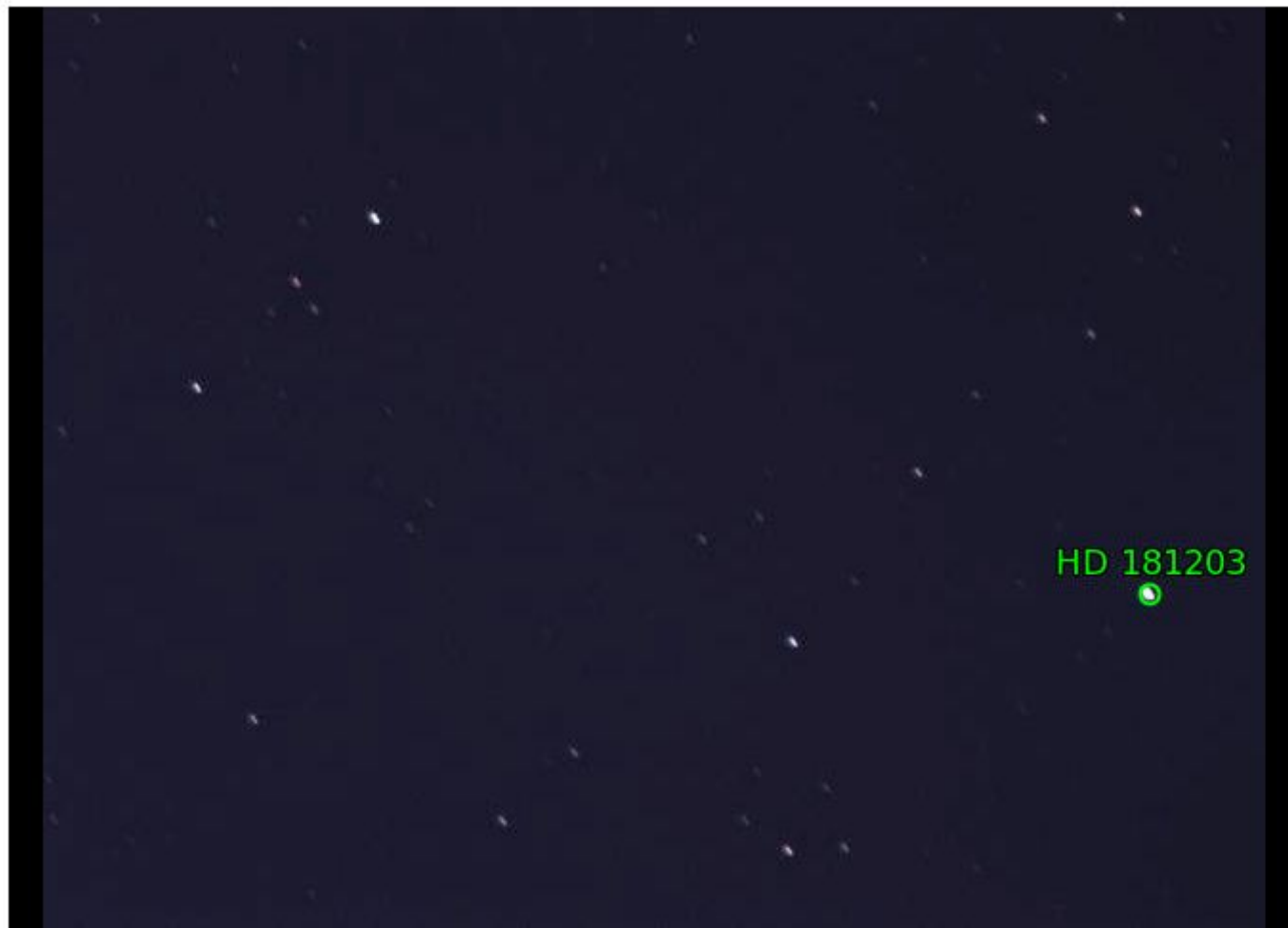
Picture Array



Picture Array



Astrometry.net



on 2021-08-26T00:35:33Z
as "E-17-2021-08-25T01_49...16.jpg"
(Submission 4925429)
under Attribution-NonCommercial 3.0
Unported

publicly visible: **yes** | **no**

Job Status

Job 5629977:
Success

Calibration

Center (RA, Dec): (282.251, 87.149)
Center (RA, hms): 18^h 49^m 00.350^s
Center (Dec, dms): +87° 08' 57.559"
Size: 31.9 x 24.1 arcmin
Radius: 0.333 deg
Pixel scale: 0.411 arcsec/pixel
Orientation: Up is 305 degrees E
of N
WCS file: [wcs.fits](#)
New FITS image: [new-image.fits](#)
Reference stars
nearby (RA,Dec
table): [rdls.fits](#)
Stars detected in
your images (x y): [avv.fits](#)

Special Objects

- # July 4th, 2021

- C-09 10 7 13.666 89 10 20.873
- C-10 10 26 7.848 89 16 08.653
- C-11 10 3 0.336 89 20 06.477
- C-12 10 17 34.816 89 28 16.307
- C-01 10 3 42.384 89 33 24.364
- C-01a 9 22 32.986 89 38 53.870
- C-01b 8 26 3.155 89 41 17.671
- C-01c 6 11 38.237 89 40 05.569
- C-02 4 58 16.122 89 31 48.547
- C-02a 4 48 50.126 89 23 09.162
- C-02b 5 23 40.917 89 09 39.456
- C-03 5 33 22.312 88 54 41.756

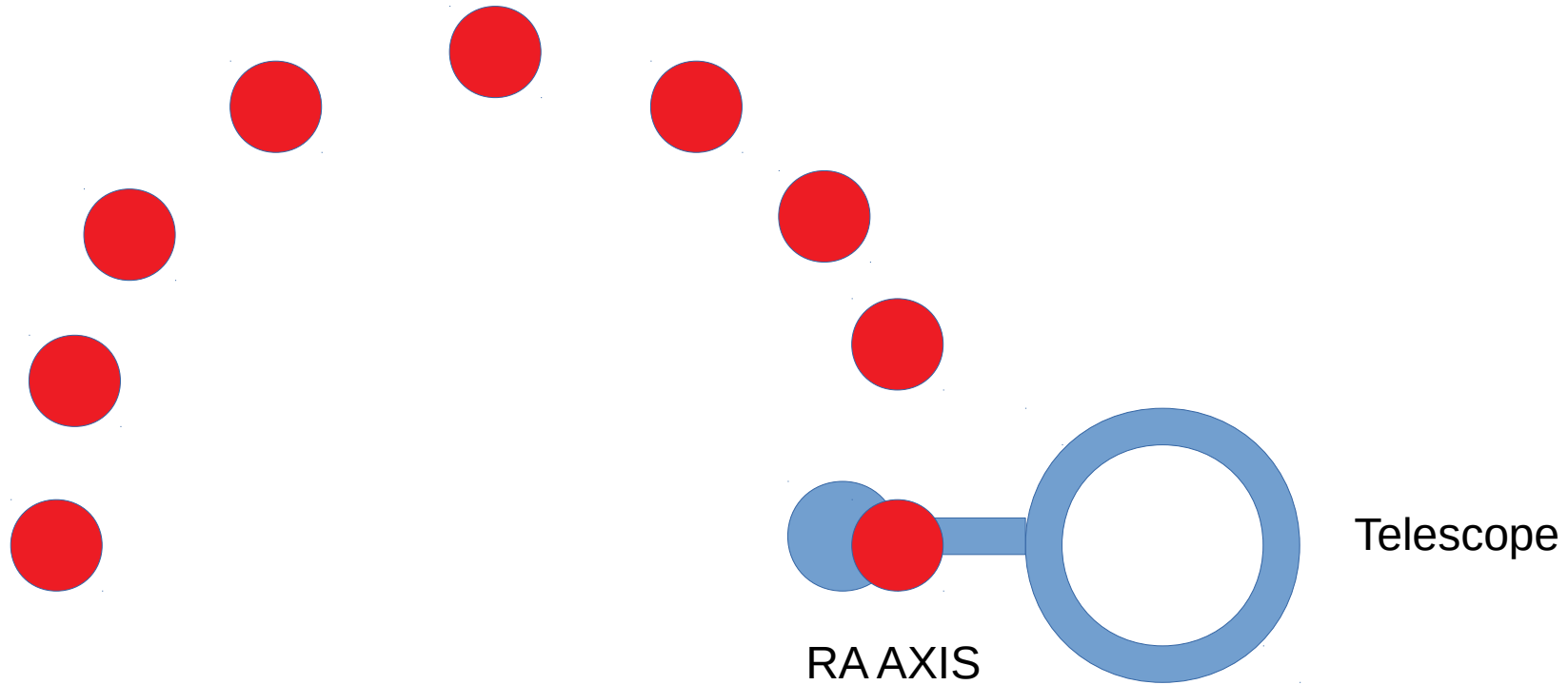
- # Aug 12, 2021

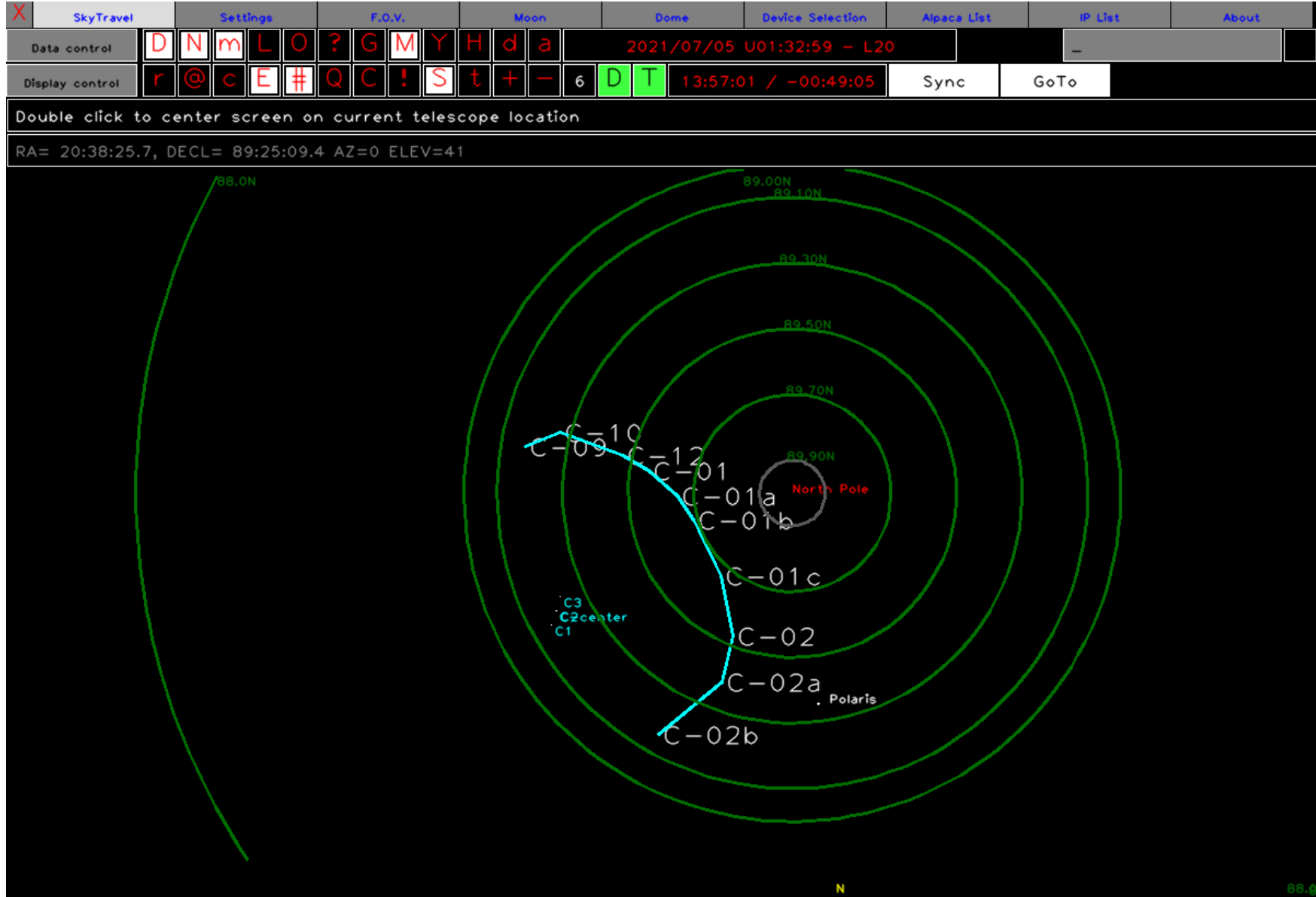
- D-01 3 59 58.709 89 21 45.927
- D-02 4 03 56.111 89 21 53.330
- D-03 3 44 35.271 89 22 32.839
- D-04 3 19 11.633 89 23 22.069
- D-05 2 55 55.243 89 24 09.338
- D-06 2 31 23.711 89 27 50.02
- D-07 1 45 48.602 89 29 16.603
- D-08 0 48 47.696 89 29 3.645
- D-09 23 51 21.394 89 26 54.663
- D-10 23 2 57.408 89 28 25.010
- D-11 21 55 3.401 89 29 2.260
- D-12 21 6 34.346 89 29 7.683
- D-13 20 26 23.988 89 28 37.730
- D-14 19 14 55.178 89 27 32.860
- D-15 17 56 58.162 89 25 39.815
- D-16 17 31 13.109 89 23 20.973

- #Aug 24, 2021

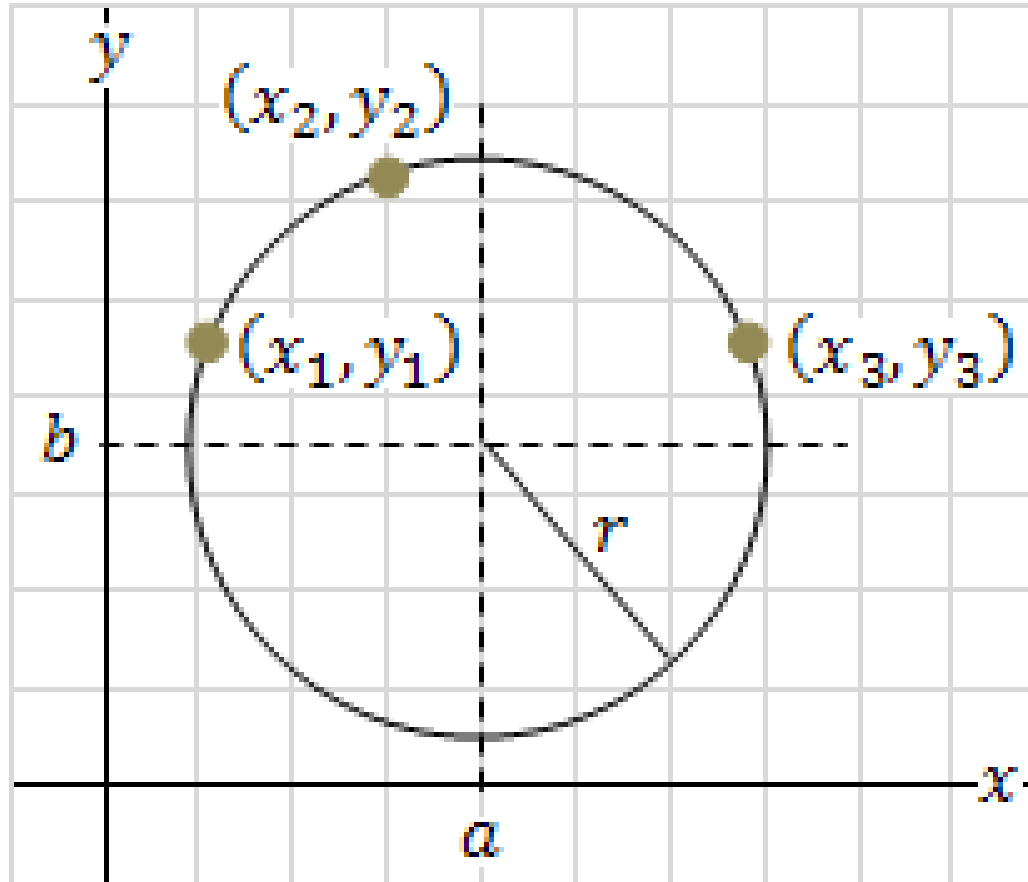
- E-01 4 44 59.254 87 07 3.997
- E-02 4 17 26.036 87 07 48.038
- E-03 3 50 22.011 87 08 39.364
- E-04 3 26 55.760 87 11 49.242
- E-05 2 59 29.684 87 13 19.530
- E-06 2 27 23.428 87 14 7.700
- E-07 1 47 25.186 87 14 59.649
- E-08 1 0 19.140 87 16 9.261
- E-09 0 13 59.637 87 16 46.602
- E-10 23 35 16.183 87 13 50.746
- E-11 22 58 44.322 87 14 2.168
- E-12 22 14 17.611 87 14 18.613
- E-13 21 28 32.173 87 14 42.577
- E-14 20 47 45.622 87 13 50.575
- E-15 20 2 54.672 87 12 45.113
- E-16 19 21 5.467 87 11 30.324
- E-17 18 49 0.350 87 08 57.559

Picture Array

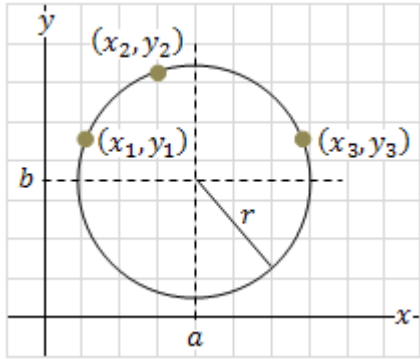




3 Points Make a circle



3 Points Make a circle



The equation of the circle is described by the equation:

$$Ax^2 + Ay^2 + Bx + Cy + D = 0$$

After substituting the three given points which lies on the circle we get the set of equations that can be described by the determinant:

$$\begin{vmatrix} x^2 + y^2 & x & y & 1 \\ x_1^2 + y_1^2 & x_1 & y_1 & 1 \\ x_2^2 + y_2^2 & x_2 & y_2 & 1 \\ x_3^2 + y_3^2 & x_3 & y_3 & 1 \end{vmatrix} = 0$$

- <http://ambrsoft.com/TrigoCalc/Circle3D.htm>

3 Points Make a circle

$$A = \begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{vmatrix} \quad B = - \begin{vmatrix} x_1^2 + y_1^2 & y_1 & 1 \\ x_2^2 + y_2^2 & y_2 & 1 \\ x_3^2 + y_3^2 & y_3 & 1 \end{vmatrix} \quad C = \begin{vmatrix} x_1^2 + y_1^2 & x_1 & 1 \\ x_2^2 + y_2^2 & x_2 & 1 \\ x_3^2 + y_3^2 & x_3 & 1 \end{vmatrix} \quad D = - \begin{vmatrix} x_1^2 + y_1^2 & x_1 & y_1 \\ x_2^2 + y_2^2 & x_2 & y_2 \\ x_3^2 + y_3^2 & x_3 & y_3 \end{vmatrix}$$

$$A = x_1(y_2 - y_3) - y_1(x_2 - x_3) + x_2y_3 - x_3y_2$$

$$B = (x_1^2 + y_1^2)(y_3 - y_2) + (x_2^2 + y_2^2)(y_1 - y_3) + (x_3^2 + y_3^2)(y_2 - y_1)$$

$$C = (x_1^2 + y_1^2)(x_2 - x_3) + (x_2^2 + y_2^2)(x_3 - x_1) + (x_3^2 + y_3^2)(x_1 - x_2)$$

$$D = (x_1^2 + y_1^2)(x_3y_2 - x_2y_3) + (x_2^2 + y_2^2)(x_1y_3 - x_3y_1) + (x_3^2 + y_3^2)(x_2y_1 - x_1y_2)$$

$$x = \frac{(x_1^2 + y_1^2)(y_2 - y_3) + (x_2^2 + y_2^2)(y_3 - y_1) + (x_3^2 + y_3^2)(y_1 - y_2)}{2(x_1(y_2 - y_3) - y_1(x_2 - x_3) + x_2y_3 - x_3y_2)} = -\frac{B}{2A}$$

$$y = \frac{(x_1^2 + y_1^2)(x_3 - x_2) + (x_2^2 + y_2^2)(x_1 - x_3) + (x_3^2 + y_3^2)(x_2 - x_1)}{2(x_1(y_2 - y_3) - y_1(x_2 - x_3) + x_2y_3 - x_3y_2)} = -\frac{C}{2A}$$

$$r = \sqrt{(x - x_1)^2 + (y - y_1)^2} = \sqrt{\frac{B^2 + C^2 - 4AD}{4A^2}}$$

3 Points Make a circle

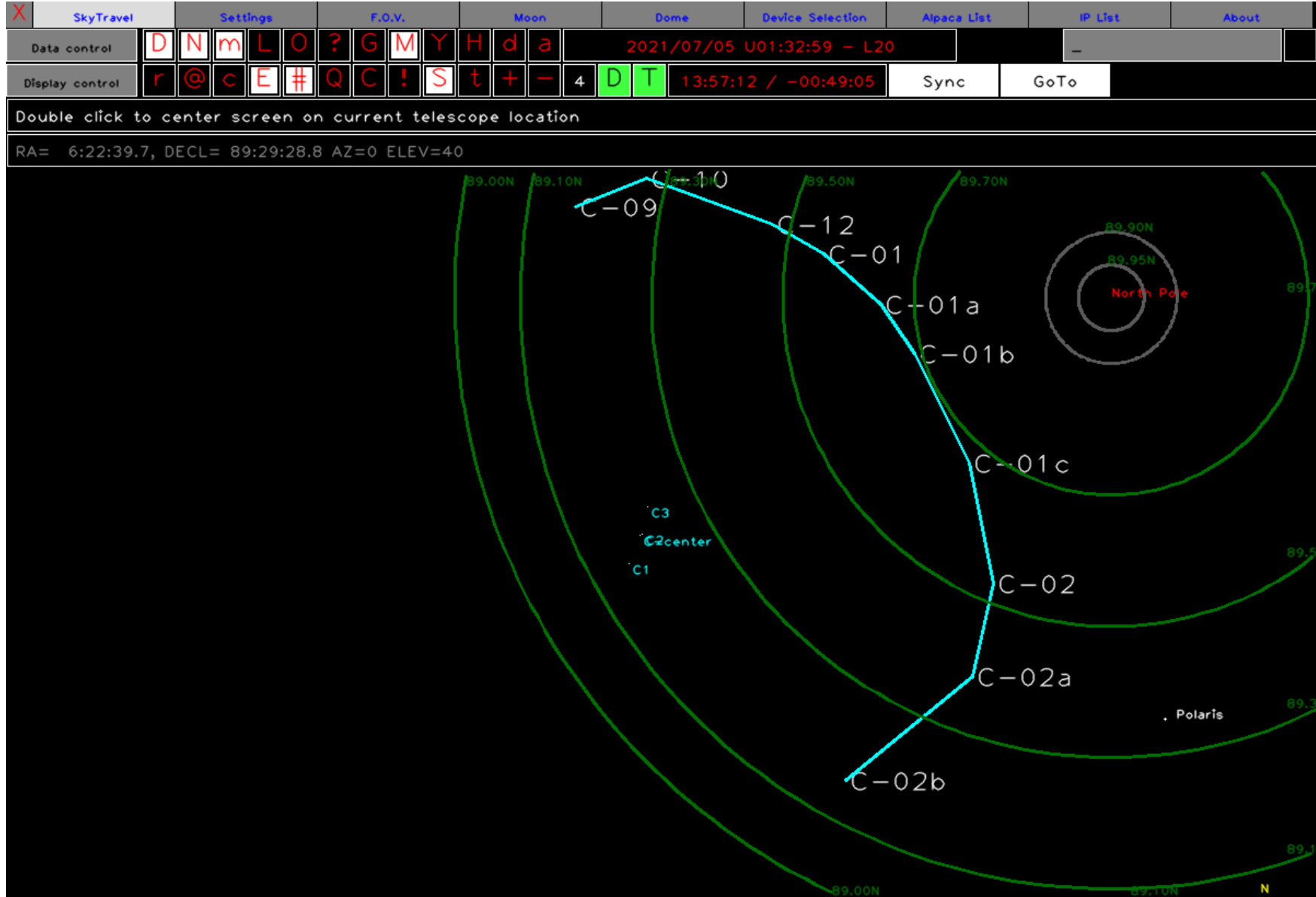
- BUT.....

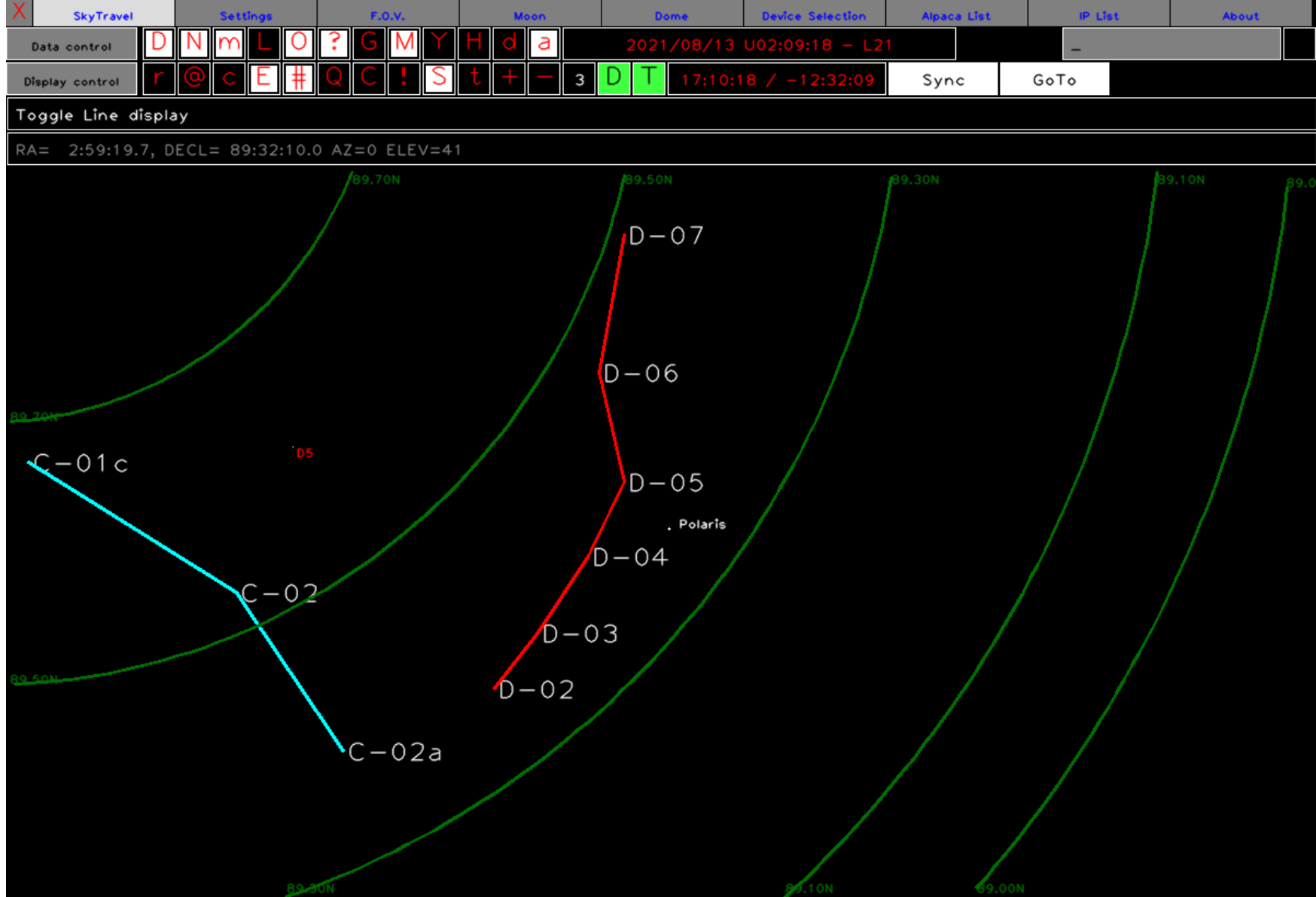
All of this is in Cartesian coordinates.

And, we have polar coordinates with the “center” at the equator.....

3 Points Make a circle

- So...
- $R = 90.0 - \text{DEC}$ - makes coordinates relative to the north pole
- $\text{Theta} = \text{RA}$ (converted from Hours to Degrees/Radians)
- Convert to Cartesian ($x = R \cos(\text{theta})$ $y = R \sin(\text{theta})$)
- Do the 3 point math
- Find the Average (in Cartesian coordinates)
- Convert all back to Polar
 - remember to adjust back for equator relative
- Plot on the sky

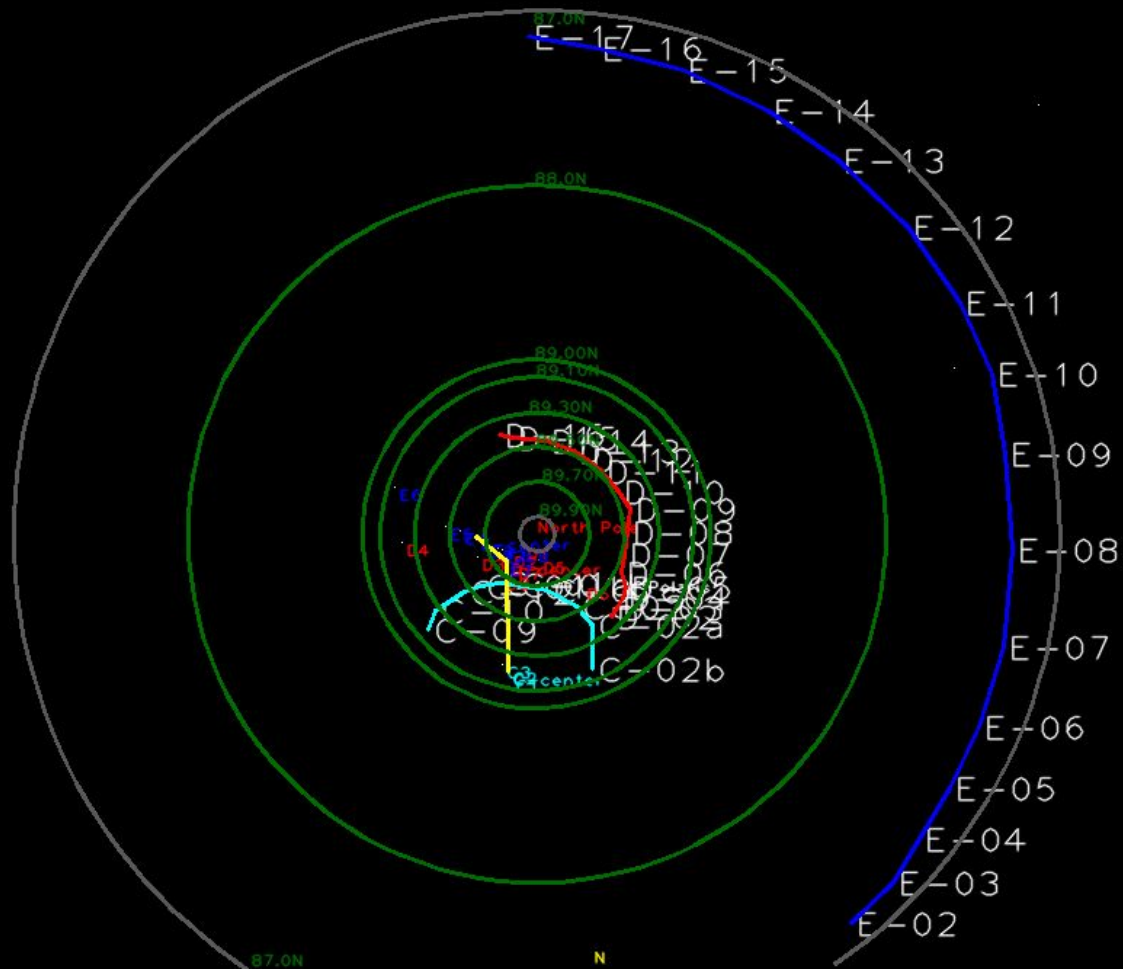


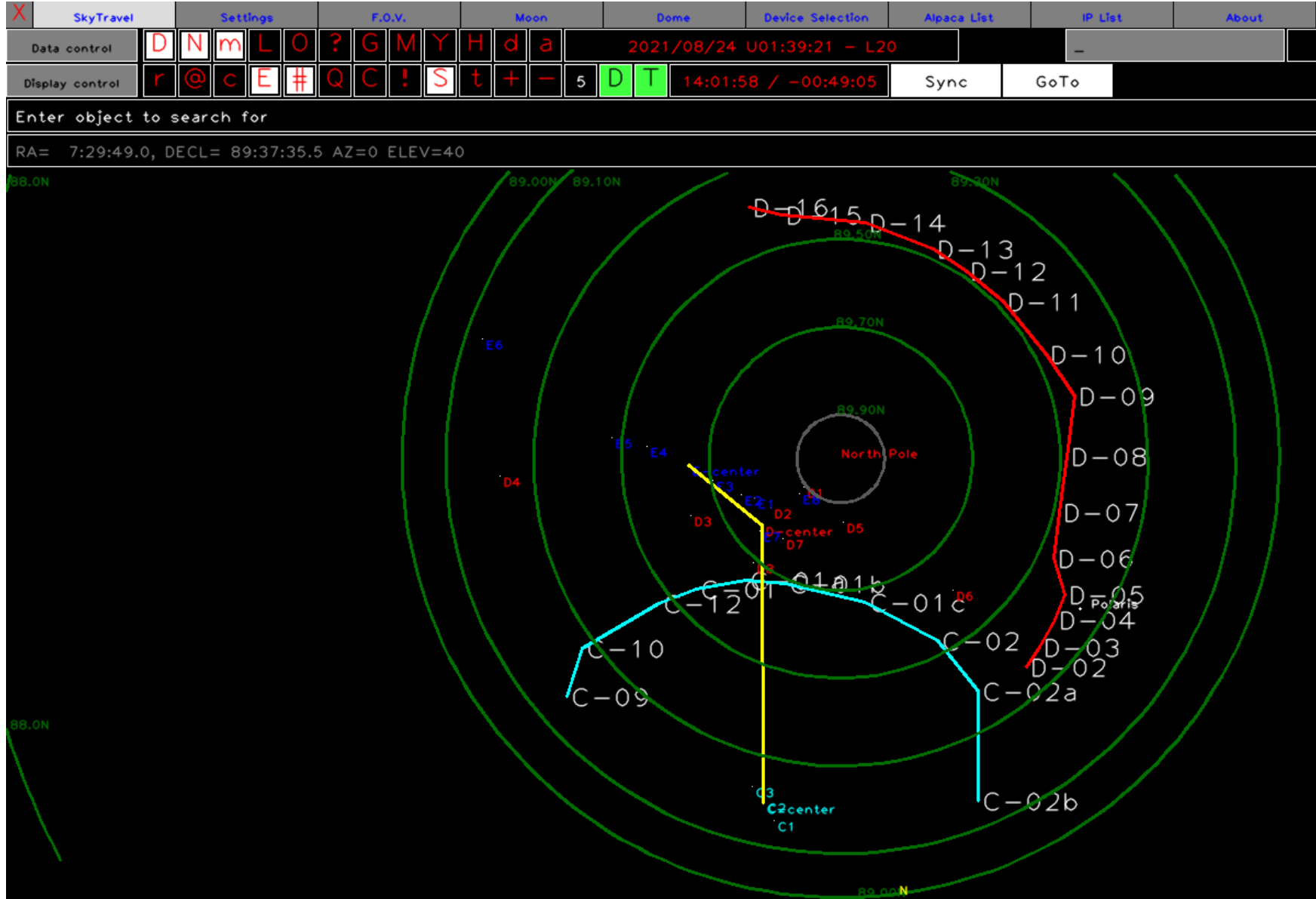


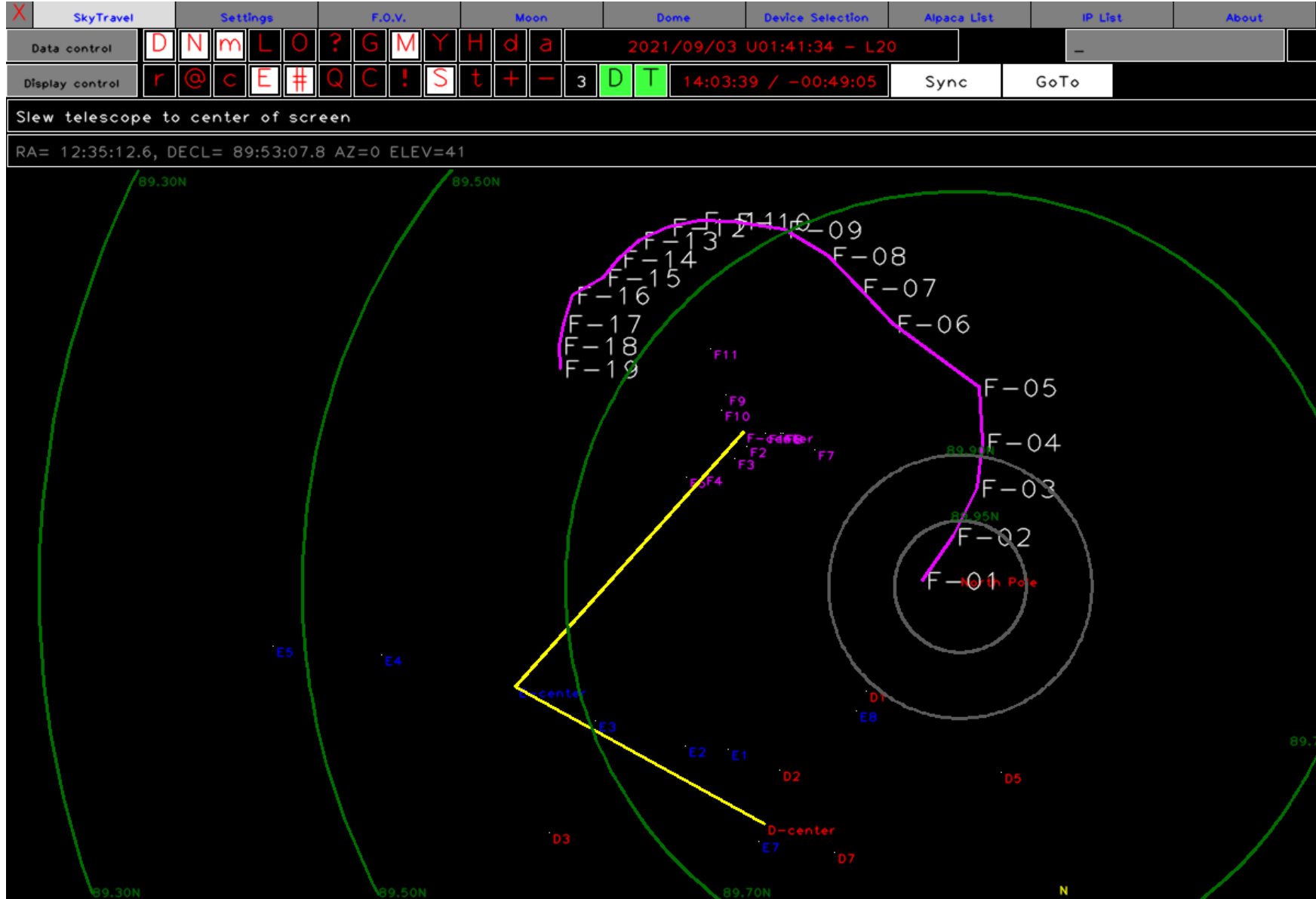
D05 plate solved w/ Polaris visible

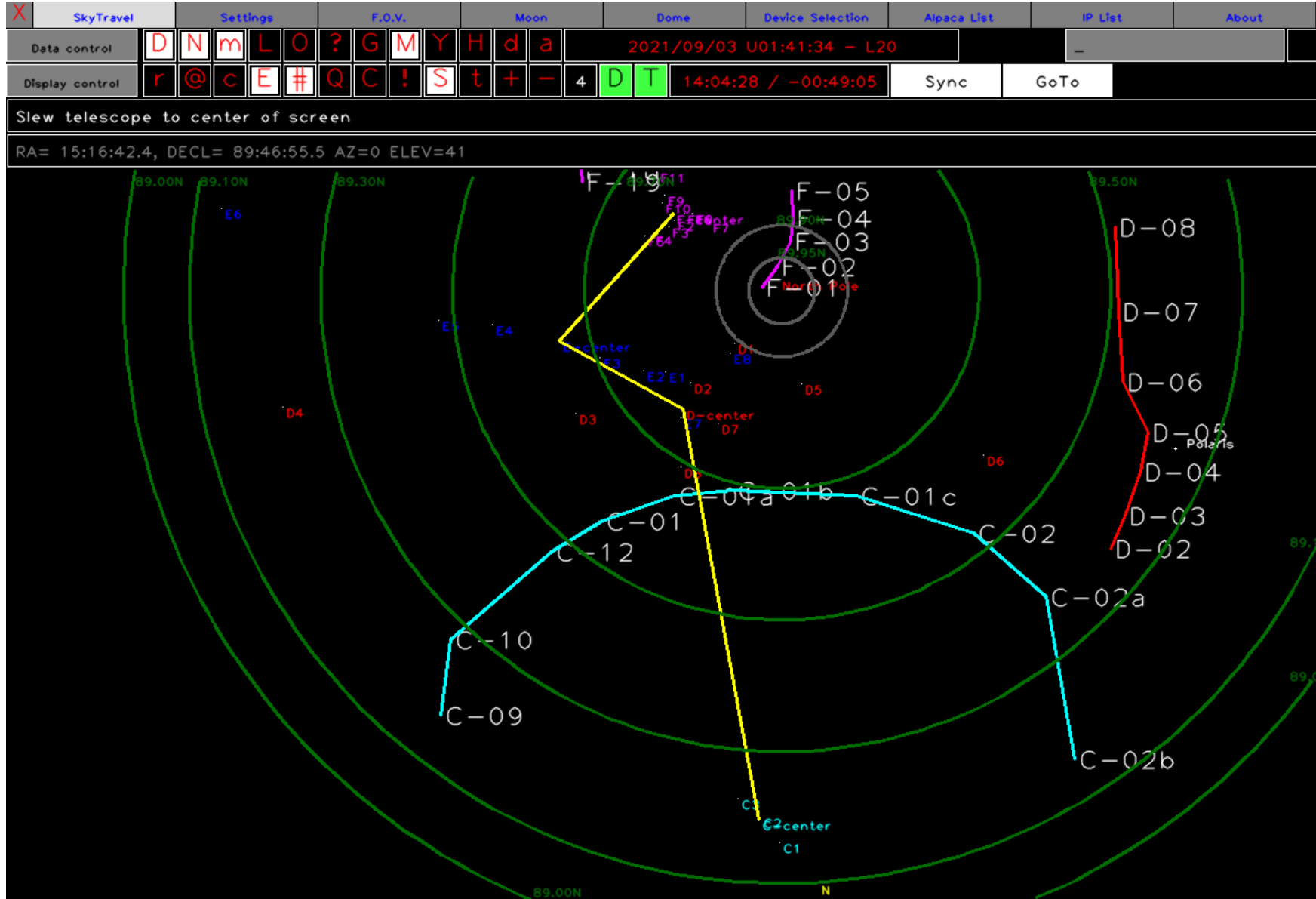


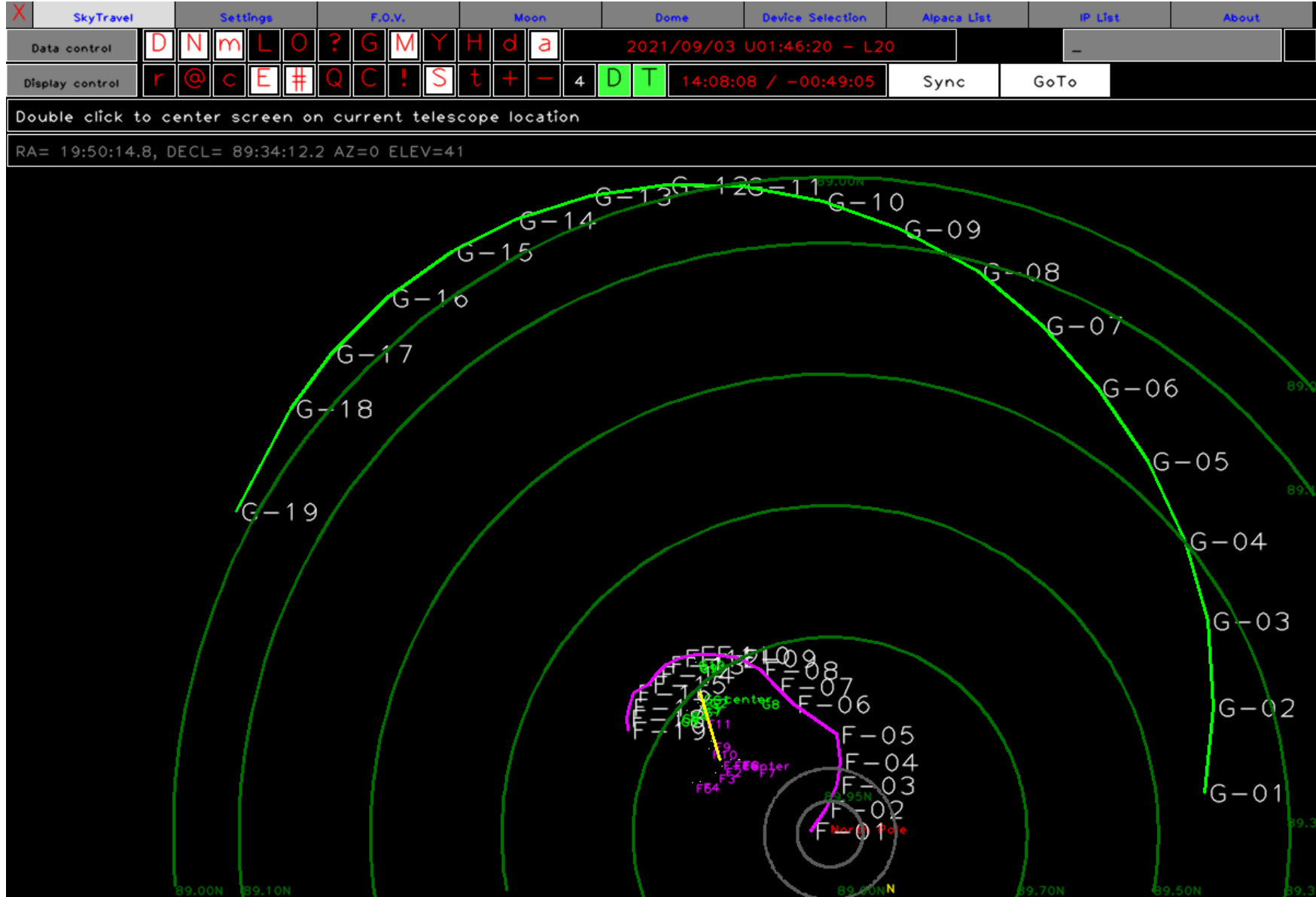
X	SkyTravel	Settings	F.O.V.	Moon	Dome	Device Selection	Alpaca List	IP List	About									
Data control	D	N	m	L	O	?	G	M	Y	H	d	a	2021/08/24 U01:39:21 - L20					
Display control	r	@	c	E	#	Q	C	!	S	t	+	-	12	D	T	14:01:38 / -00:49:05	Sync	GoTo
Enter object to search for																		
RA= 22:00:24.4, DECL= 88:09:49.7 AZ=1 ELEV=42																		

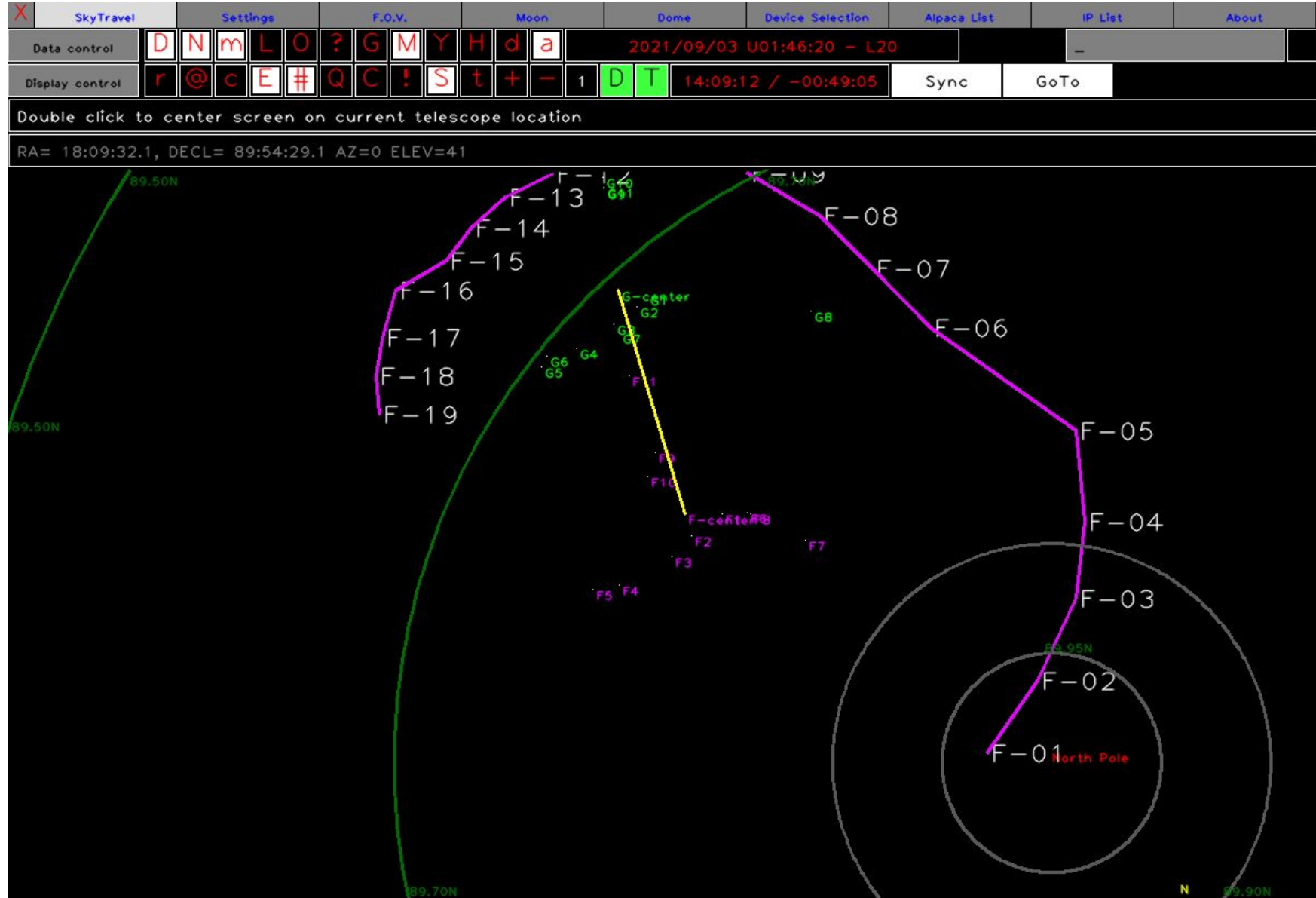


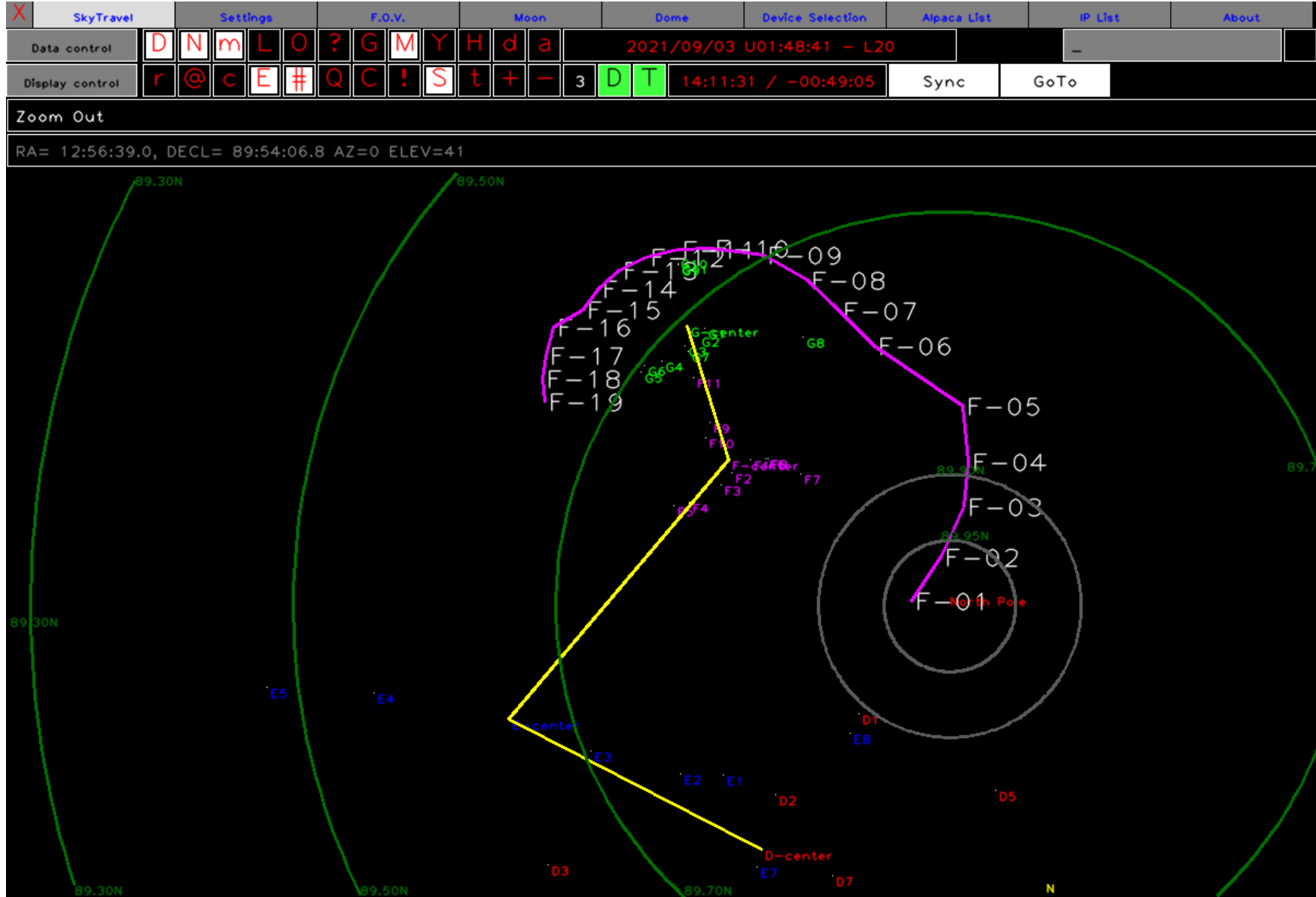












TO-DO List

- Obviously I have a few more adjustments to make
- Add plate solving to my software
- Add some automation to the process

How To

- With the exception of the plate solving, this could be done on manual charts.
- Plate solving
 - <https://nova.astrometry.net/>
- My software
 - <https://github.com/msproul/AlpacaPi>

Intermission / Questions

Part 2

AlpacaPi software, what is it and how does it fit in today's computer controlled environment

What is AlpacaPi?

- Suite of software I wrote in C++
- Targeted to run on Raspberry-Pi's
 - Will run on most any Linux
- 131,000 lines of code
- Planetarium code adapted from code Clif Ashcraft wrote for the Commodore 64 in the early 80s (SkyTravel - 7000, lines of code)

What is AlpacaPi?

- All open source
- Utilizes **Alpaca** protocol to implement a distributed observatory control system.

What is Alpaca?



History

- ASCOM developed by Bob Denny 20 years ago.
- Group in UK now controls the published standard
- Most hardware vendors support ASCOM
- Lots of commercial and free software support for ASCOM
- ASCOM only runs on Windows!!!
- April 2019, ASCOM group announced **Alpaca**

What is Alpaca?

- Networked version of ASCOM for ALL platforms
- Client / server model that uses:
 - HTTP – Hyper Text Transport Protocol
 - Used by web browsers to talk to web servers
 - Can be use for other purposes
 - JSON Java Script Object Notation
 - Plain text format for keyword / value pairs. Much simpler than XML

What is *Alpaca*?

- Data and Commands are *identical* to ASCOM
- Transport method changed to HTTP and JSON (ASCOM uses COM on Windows)
- ASCOM limited to single computer
- Alpaca fully network based allowing for fully distributed system
- Backwards compatible with ASCOM via software bridge on Windows

What is **Alpaca**?

- WINDOWS IS NOT REQUIRED!!!!!!!!!!

HTTP

- HTTP to web server
 - GET /index.html
 - GET /subdirectory/index.php
 - GET /imagedirectory/image.jpg
- Alpaca HTTP
 - GET /api/v1/camera/0/camerastate
 - GET /api/v1/camera/0/pixelsize
 - PUT /api/v1/camera/0/startexposure
 - PUT /api/v1/dome/0/closes shutter

JSON

```
{  
  "Device":"WO102-ZWO ASI1600MM Pro",  
  "Command":"pixelsize",  
  "Value":3.800000,  
  "ClientTransactionID":4,  
  "ServerTransactionID":15074,  
  "ErrorNumber":0,  
  "ErrorMessage":""  
}
```

Command Line

Alpaca commands can be sent from a unix command line, no programming required. This allows very easy automation.

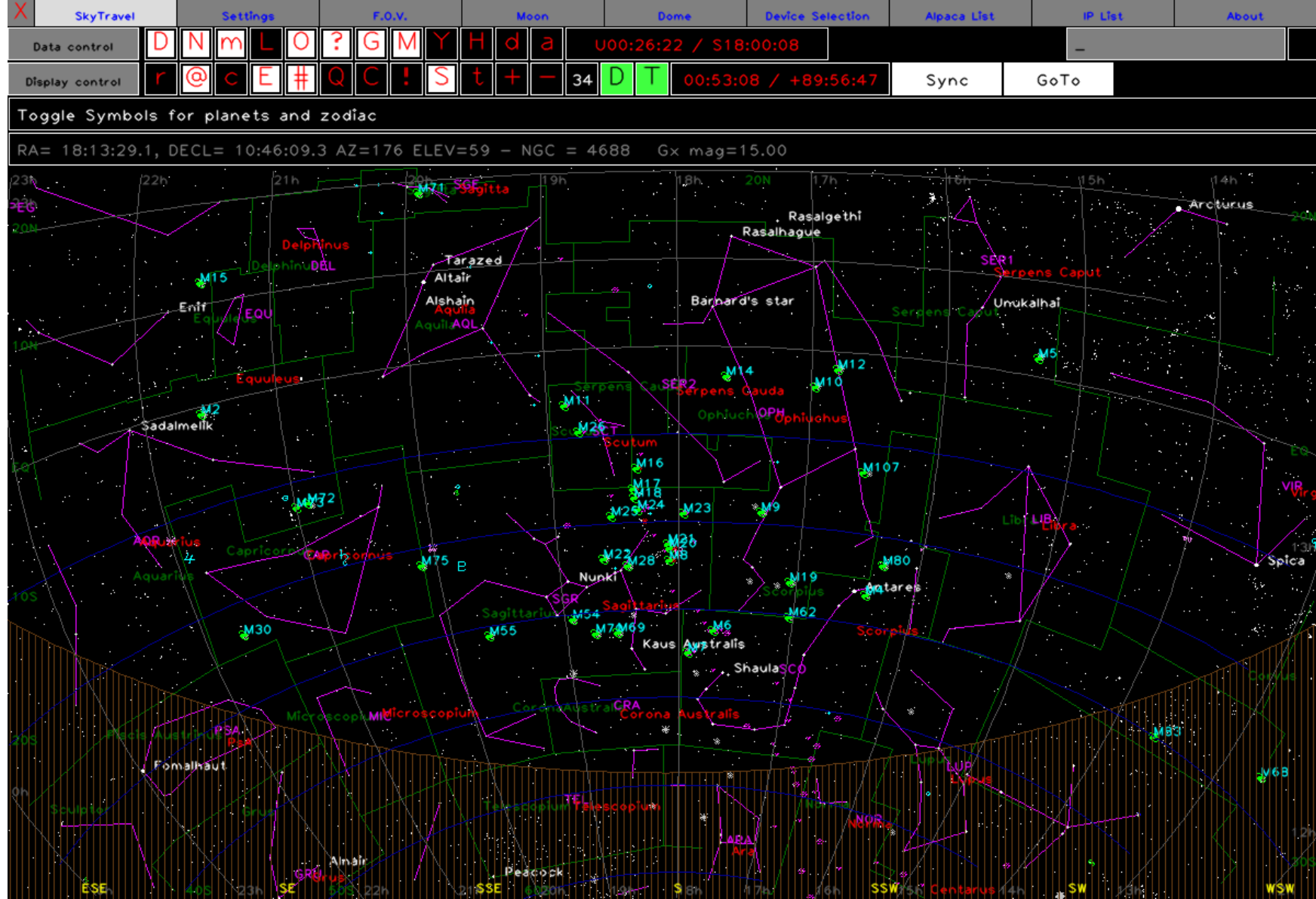
```
curl -X PUT "http://192.168.1.22:6800/api/v1/dome/0/closes shutter"
```

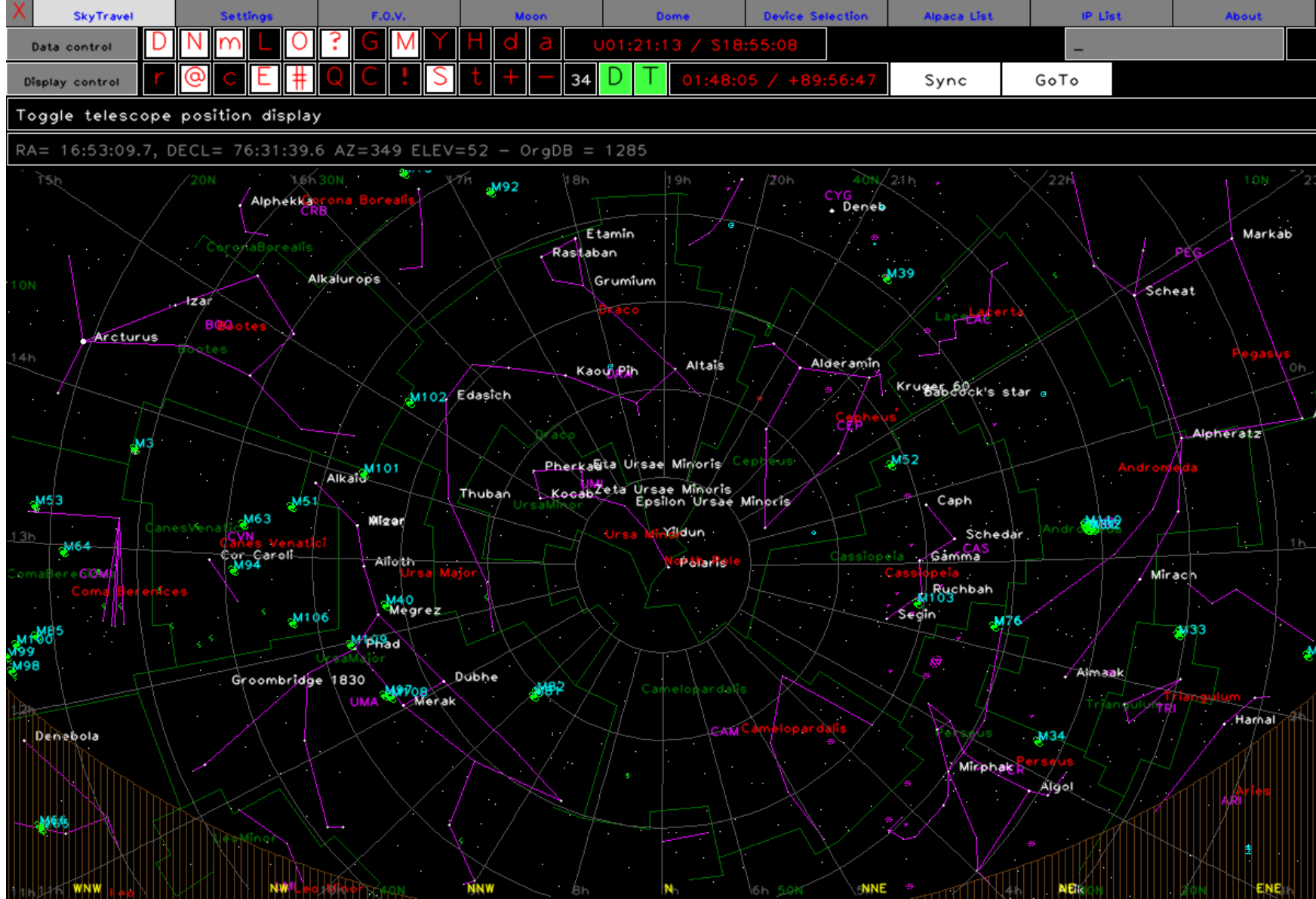
Back to AlpacaPi

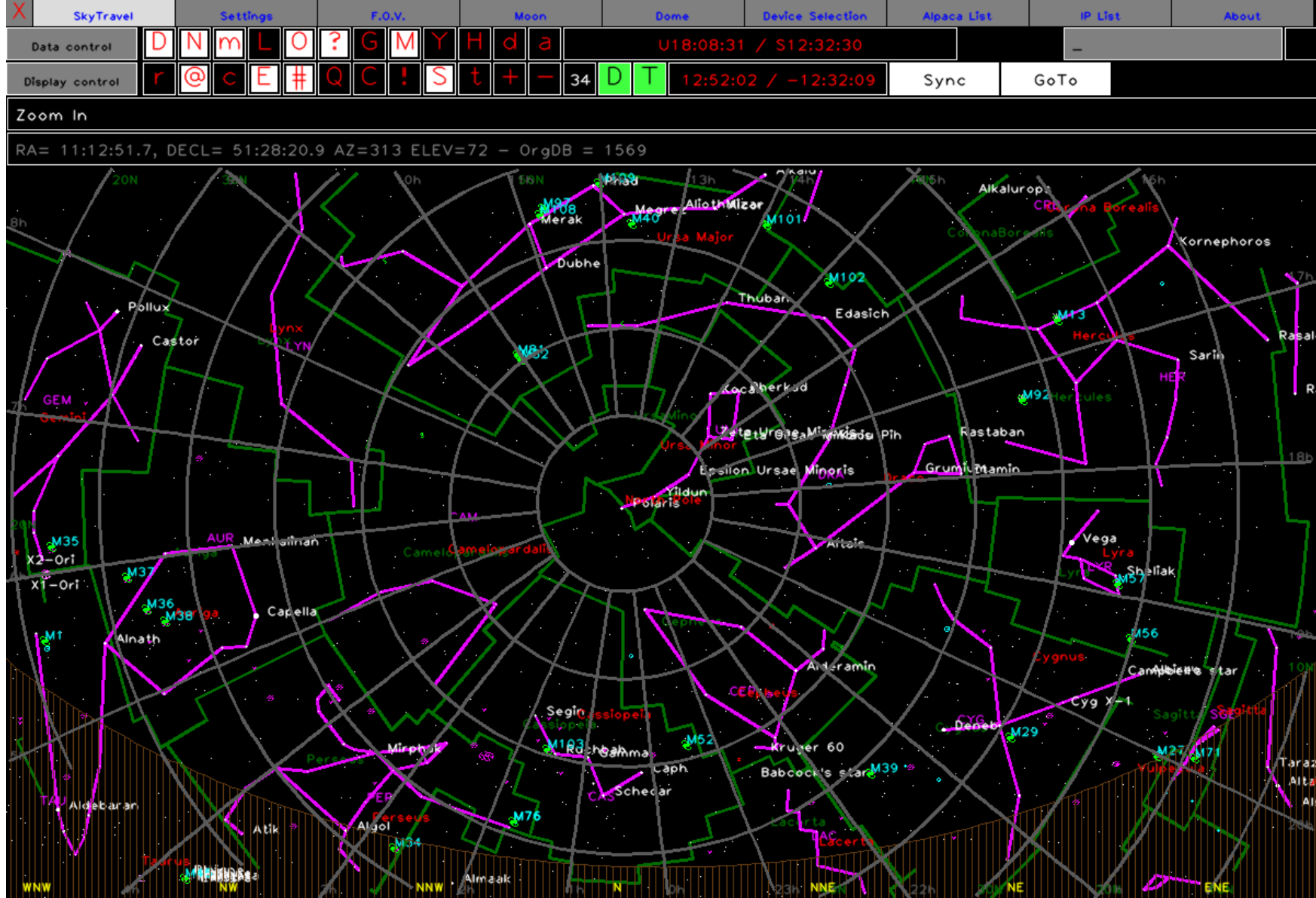
- AlpacaPi is a collection of drivers and clients that implements Alpaca on Linux.
- **IMPORTANT NOTE:** You can use your existing ASCOM client on Windows to talk to any of my Linux Alpaca drivers.

AlpacaPi software suite

- Drivers
 - Camera
 - Focuser
 - Rotator
 - Filterwheel
 - Dome
 - Calibration
 - Switch
- Clients
 - Controllers for all the drivers
 - Planetarium with full integration to all of the drivers.







ip-address : port	/etc/hosts	type	name
192.168.1.177:6800	calib	Camera	calib-ZWO ASI034MC
192.168.1.146:6800	door	Camera	Door-ZWO ASI034MC
192.168.1.165:6800	finder	Camera	FINDER-ZWO ASI120MC
192.168.1.165:6800	finder	Camera	FINDER-ZWO ASI120MC-S
192.168.1.164:6800	newt16	Camera	NEWT16-ZWO ASI1600MC Pro
192.168.1.173:6800	wo102	Camera	W0102-ZWO ASI1600MM Pro
192.168.1.173:6800	wo102	Camera	W0102-ZWO ASI290MM
192.168.1.161:6800	wo71	Camera	W071-ZWO ASI120MC-S
192.168.1.177:6800	calib	CoverCalibrator	CoverCalibration-Raspberry-Pi
192.168.1.223:6800	dome	Dome	AlpacaPi-Dome
192.168.1.164:6800	newt16	Filterwheel	ZWO EFW-5
192.168.1.173:6800	wo102	Filterwheel	ZWO EFW-8
192.168.1.166:6800	gyro	Focuser	Moonlite
192.168.1.161:6800	wo71	Focuser	NiteCrawler Focuser
192.168.1.164:6800	newt16	Focuser	NiteCrawler Focuser
192.168.1.173:6800	wo102	Focuser	NiteCrawler Focuser
192.168.1.165:6800	finder	Multicam	MultiCam
192.168.1.161:6800	wo71	Rotator	NiteCrawler Rotator
192.168.1.164:6800	newt16	Rotator	NiteCrawler Rotator
192.168.1.173:6800	wo102	Rotator	NiteCrawler Rotator
192.168.1.146:6800	door	Shutter	Arduino-shutter
192.168.1.164:6800	newt16	SlitTracker	SlitTracker
192.168.1.146:6800	door	Switch	Switch-Raspberry-Pi
192.168.1.165:6800	finder	Switch	Switch-Raspberry-Pi
192.168.1.153:6800		Telescope	Telescope-LX200

X
SkyTravel
Settings
F.O.V.
Moon
Dome
Device Selection
Alpaca List
IP List
About

c
AlpacaPi Dome

Position	Park						
Azimuth	170.0						
Altitude	0.0 %						
Shutter	Closed						
Slaved	No						
Go Home	Go Park						
-20	-10	-5	-1	+1	+5	+10	+20
Go Left	STOP				Go Right		
Slow Left					Slow Right		
Bump Left					Bump Right		
Enable Slave mode							
Open Shutter				Close Shutter			
STOP Shutter							

AlpacaPi - V0.4.1-beta build #118

R
192.168.1.223:6800/0

Telescope Control

X

Telescope

Capabilities

Driver Info

About

C

AlpacaPi project

Up

East

STOP

West

Down

Tracking On

Tracking Off

Tracking is Off

Slew Rate

☐ Fast

☒ Medium

☐ Slow

☐ Very Slow

Slewing is Off

RA

10:00:11

DEC

-12:32:09


Tracking Rate

☒ Sidereal

☐ Lunar

☐ Solar

☐ King



AlpacaPi - V0.4.1-beta build #118

R

192.168.1.153:6800/0

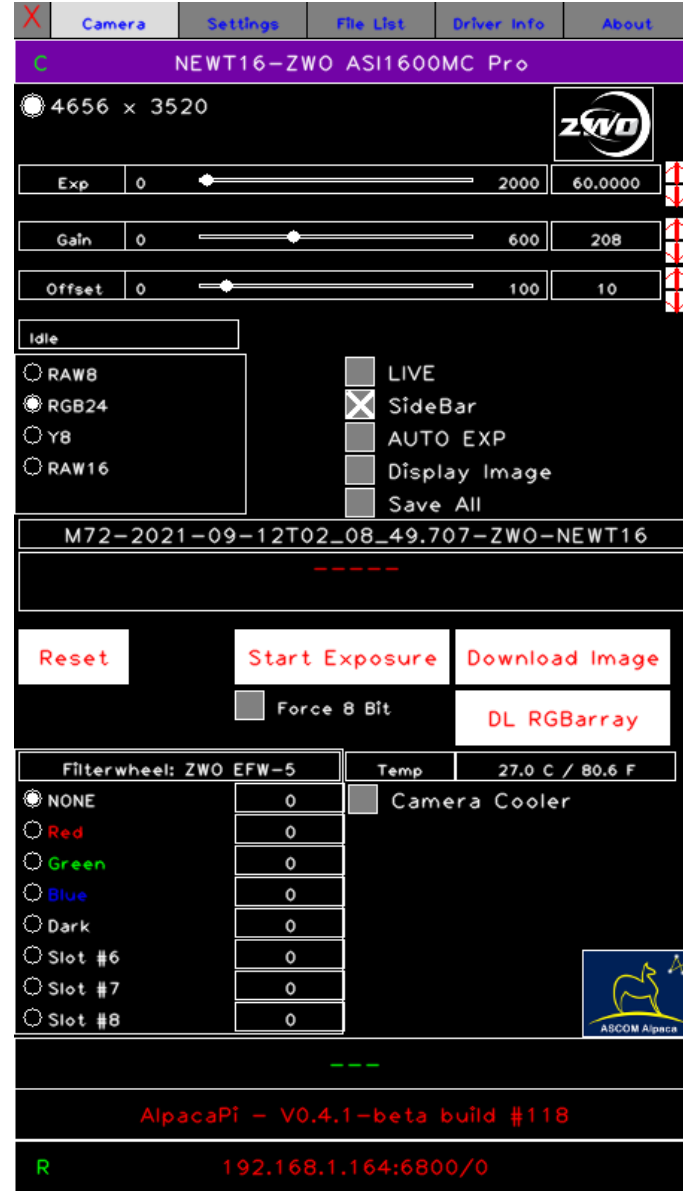
4



← Focuser Control

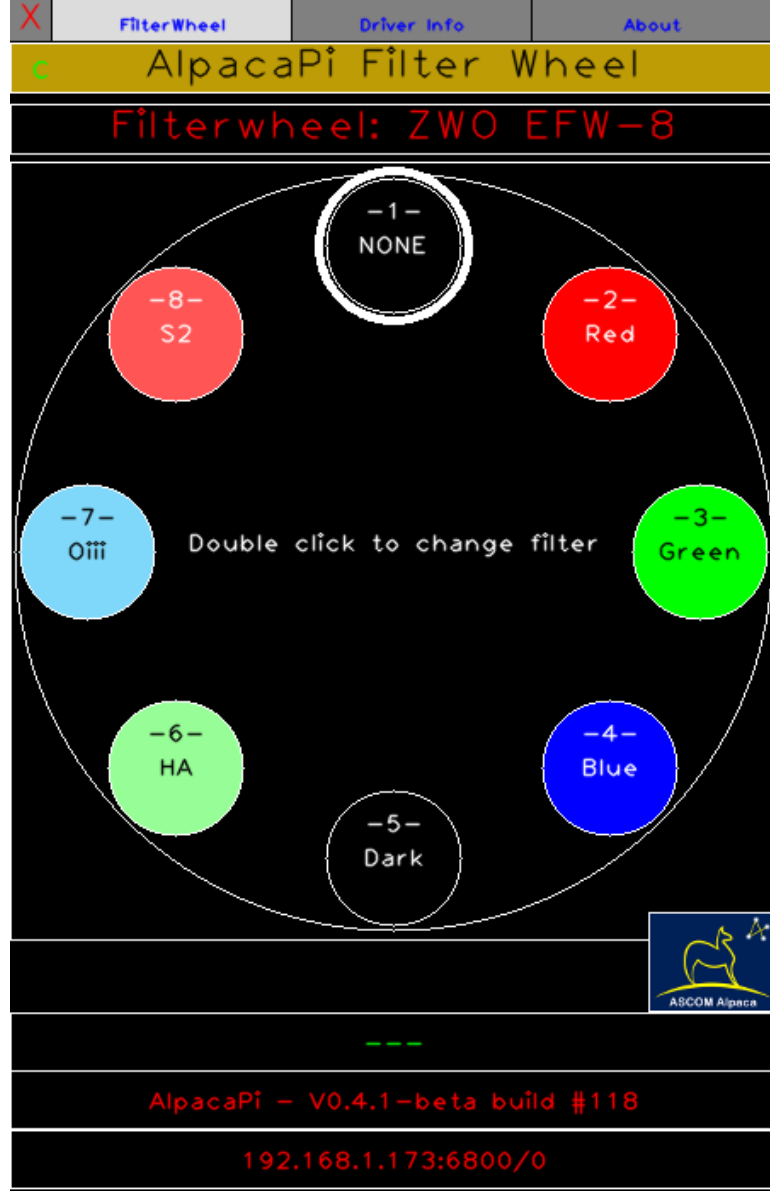
Camera Control →

Filter wheel info is included ->



Filter Wheel Control

Double click on any filter to move to that position.



Switch Control

1	RED	Led Strip-red
2	GRN	Led Strip-green
3	BLU	Led Strip-blue
4	Lights	Lower flood lights
5	Lights	Upper flood lights

X

Switch

Driver Info

About

AlpacaPi Switches

1	RED	Led Strip-red	--	OFF
2	GRN	Led Strip-green	--	OFF
3	BLU	Led Strip-blue	--	OFF
4	Lights	Lower flood lights	--	OFF
5	Lights	Upper flood lights	--	OFF
6	Switch#5	Not defined	--	OFF
7	Switch#6	Not defined	--	OFF
8	Switch#7	Not defined	--	OFF

ALL OFF



AlpacaPi - V0.4.1-beta build #118

R192.168.1.146:6800/0

Clicking the RED LED switch turns on some lights.



AlpacaPi supported hardware

- Cameras
 - ZWO
 - ATIK
 - SVBONY
 - QHY
 - Touptech
 - FLIR
 - SONY
- Focusers
 - Moonlite Nitecrawler
 - Moonlite HiRes
- Filterwheel
 - ZWO
 - ATIK
- Rotator
 - Moonlite Nitecrawler

AlpacaPi supported hardware

- Dome
 - Raspberry-Pi using motor control boards for Dome
 - Raspberry-Pi using relay board for Roll Off Roof
- Switch
 - Raspberry-Pi using relay board
- Calibration
 - Raspberry-Pi using motor control board to adjust brightness of flat panel

AAVSO

AAVSO - American Association of Variable Star Observers puts out observations alerts on a regular basis.

You can sign up to receive this via email OR

Go online and find them

<https://filtergraph.com/aavso/api/index#>

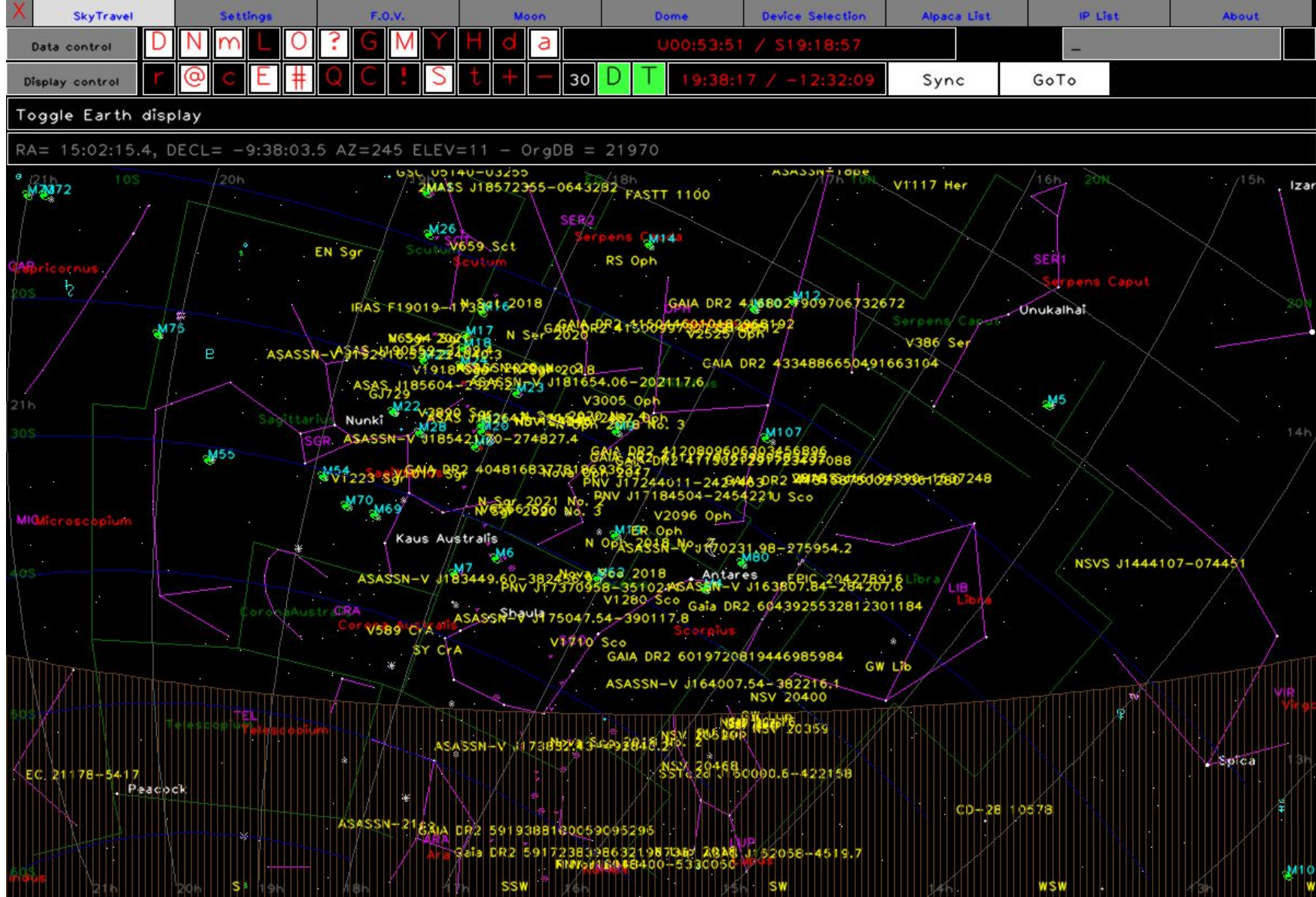
Supports full API for access

AAVSO List

AlertID	Star Name	Right Ascension	Declination	Org RA/DEC
754	1SWASP J022916.91-395901.4	2:30:08.9	-39:53:16.2	2:29:16.9/-39:59:01.6
754	KR Aur	6:17:06.4	28:34:37.5	6:15:43.9/ 28:35:08.6
754	V442 Oph	17:33:30.3	-16:16:13.5	17:32:15.1/-16:15:22.1
754	GS Pav	-3:49:39.1	-69:45:06.3	20:08:07.6/-69:48:58.8
754	V794 Aql	-3:41:17.8	-3:35:44.4	20:17:33.9/ -3:39:51.0
754	VY Scl	0:29:50.6	-29:39:34.9	23:29:00.5/-29:46:46.0
754	1RXS J233801.0+430852	0:20:56.6	43:16:04.0	23:37:59.2/ 43:08:51.0
754	V704 And	0:13:57.5	43:38:36.4	23:44:57.5/ 43:31:22.3
754	HS 0220+0603	2:24:10.3	6:22:41.9	2:23:01.7/ 6:16:49.6
754	WX Ari	2:48:46.6	10:41:00.7	2:47:36.2/ 10:35:37.7
754	V1024 Cep	5:11:57.2	83:20:58.6	5:06:48.3/ 83:19:23.3
754	LN UMa	10:06:13.3	66:22:53.2	10:04:34.7/ 66:29:14.9
754	V380 Oph	17:51:17.3	6:05:11.8	17:50:13.6/ 6:05:29.3
754	V425 Cas	0:55:16.0	53:24:17.0	23:03:46.7/ 53:17:14.9
753	DO Dra	11:44:51.2	71:34:06.6	11:43:38.5/ 71:41:20.5
753	DW Cnc	8:00:07.2	16:13:08.8	7:58:53.1/ 16:16:45.4
753	V515 And	0:56:33.9	46:19:59.0	0:55:19.9/ 46:12:57.0
753	V1223 Sgr	-5:03:33.9	-31:08:04.9	18:55:02.3/-31:09:49.6
753	V1025 Cen	12:39:27.0	-38:49:54.5	12:38:16.3/-38:42:45.8
753	A0 Psc	-1:03:34.8	-3:03:41.9	22:55:18.0/ -3:10:40.0
753	1RXS J213344.1+510725	-2:25:31.1	51:13:14.5	21:33:43.6/ 51:07:24.7
752	RS Oph	17:51:23.3	-6:42:46.0	17:50:13.2/ -6:42:28.6
751	RU Lup	15:58:08.4	-37:52:57.2	15:56:42.3/-37:49:15.5
751	BP Tau	4:20:37.2	29:09:30.7	4:19:15.8/ 29:06:26.8
750	T CrB	16:00:24.7	25:51:35.1	15:59:30.2/ 25:55:12.6
749	N Vul 2021	-3:37:58.8	29:18:21.0	20:21:07.7/ 29:14:09.1
748	SSTc2d J160000.6-422158	16:01:30.3	-42:25:33.0	16:00:00.6/-42:21:56.8
748	NSV 20468	16:02:00.3	-41:47:12.4	16:00:31.0/-41:43:37.0
747	V627 Peg	-2:20:55.0	26:25:50.8	21:38:06.6/ 26:19:56.0
746	rho Cas	0:04:31.2	57:37:12.6	23:54:23.0/ 57:29:57.8
745	N Her 2021	-5:01:30.8	16:55:28.5	18:57:31.0/ 16:53:39.6
744	V1117 Her	16:40:08.5	9:45:25.9	16:39:06.4/ 9:47:55.3
743	V603 Aql	-5:09:58.9	0:36:36.1	18:48:54.6/ 0:35:02.9
742	N Cas 2021	0:34:13.5	61:18:24.8	23:24:47.7/ 61:11:14.8

Total stars =294

[Export to CSV](#)



X
SkyTravel
Settings
F.O.V.
Moon
Dome
Device Selection
Alpaca List
IP List
About

Data control

D N m L O ? G M Y H d a

U12:37:39 / S07:16:30

-

Display control

r @ c E # Q C ! S t + - 12 D T

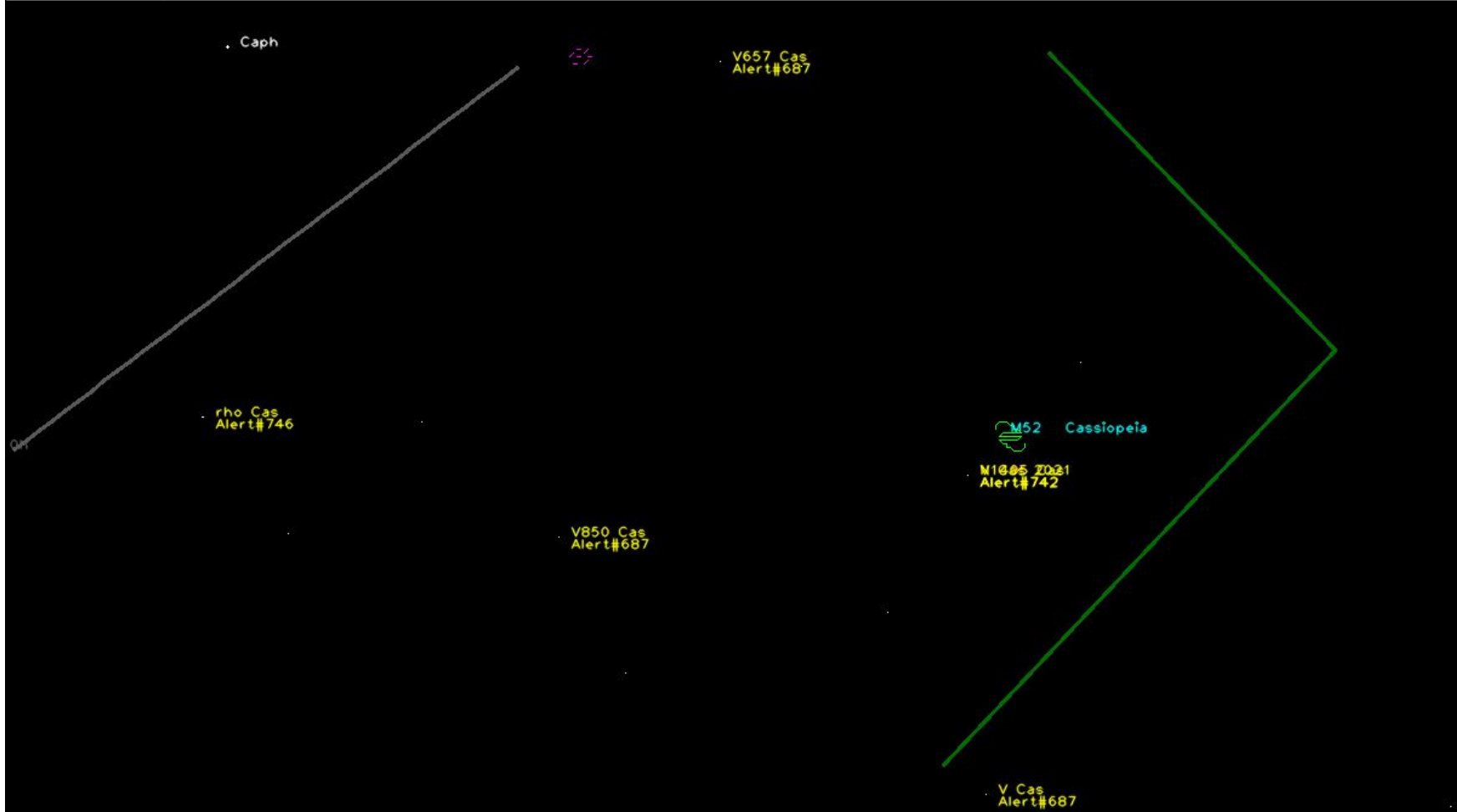
07:33:27 / -12:32:09

Sync

GoTo

Toggle Name display

RA= 23:33:17.3, DECL= 60:30:08.9 AZ=332 ELEV=24



Future

- One major hardware vendor already building Alpaca into the device itself.
- At least one major planetarium program is working on Alpaca support
- I predict that ASCOM will be barely breathing in 5 years, replaced entirely by Alpaca

Future

- Imagine, NO USB cables, only Power Over Ethernet
- Gigabit speeds
- No cable length restrictions like USB3
- Completely Operating System independent. Mix and match any way you like.
- Remote operation very easy to implement.

Questions

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