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**Кафедра 806 «Вычислительная математика и программирование»**

**Лабораторные работы по курсу «Численные методы»**

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## 4.1 Методы Эйлера, Рунге-Кутты и Адамса

### 1 Постановка задачи

Реализовать методы Эйлера, Рунге-Кутты и Адамса 4-го порядка в виде программ, задавая в качестве входных данных шаг сетки. С использованием разработанного программного обеспечения решить задачу Коши для ОДУ 2-го порядка на указанном отрезке. Оценить погрешность численного решения с использованием метода Рунге – Ромберга и путем сравнения с точным решением.

**Вариант: 26**

26	$x^4 y'' + 2x^3 y' + y = 0,$ $y(1) = 1,$ $y'(1) = 1,$ $x \in [1, 2], h = 0.1$	$y = (\sin 1 + \cos 1) \cos \frac{1}{x} + (\sin 1 - \cos 1) \sin \frac{1}{x}$
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Рис. 1: Входные данные

### 2 Результаты работы

```
X: 1 1.1 1.2 1.3 1.4 1.5 1.6 1.7 1.8 1.9 2
Y: 1 1.08665 1.15204 1.20222 1.2413 1.27215 1.29678 1.31664 1.33281 1.34606 1.35701

Euler method: 1 1.1 1.17 1.21976 1.25558 1.28163 1.30068 1.31466 1.32491 1.33238 1.33775
Runge-Kutte method: 1 1.08876 1.15497 1.20522 1.24394 1.27416 1.29802 1.31705 1.33236 1.34476 1.35488
Adams method: 1 1.08876 1.15497 1.20522 1.24806 1.28173 1.3084 1.32985 1.34717 1.36131 1.37291

With Runge-Romberg-Richardson method

Euler method: 1 1.09 1.15656 1.20662 1.24482 1.27434 1.29741 1.3156 1.33006 1.34163 1.35094
Runge-Kutte method: 1 1.08723 1.15281 1.20297 1.2419 1.27253 1.29689 1.31647 1.33235 1.34532 1.35599
Adams method: 1 1.08876 1.15497 1.20522 1.24806 1.28173 1.3084 1.32985 1.34717 1.36131 1.37291

Delta of exact value

Euler method: 0 0.00334546 0.00452163 0.0044013 0.00351564 0.00219133 0.000630817 0.00103998 0.00274286 0.00442975 0.006
07174
Runge-Kutte method: 0 0.000570788 0.000770289 0.000749147 0.000598656 0.00037461 0.00011136 0.000169869 0.000455984 0.00
0738994 0.00101413
Adams method: 0 0.00210235 0.00293314 0.0030072 0.00675603 0.00958042 0.0116214 0.0132061 0.0143666 0.0152505 0.0158987
```

Рис. 2: Вывод программы в консоли

### 3 Исходный код

```
1 | #include <iostream>
2 | #include <vector>
3 | #include <cmath>
4 | #include <fstream>
5 |
6 | using namespace std;
7 |
8 | double f(double x, double y, double z) {
9 |     return -2 * z / x - y / pow(x, 4);
10 | }
11 |
12 | double exact_solution(double x) {
13 |     return (sin(1) + cos(1)) * cos(1 / x) + (sin(1) - cos(1)) * sin(1 / x);
14 | }
15 |
16 | vector<double> Euler_method(double a, double b, double h) {
17 |     int s = (b - a) / h + 1;
18 |     vector<double> x(s);
19 |     vector<double> y(s, 1.0);
20 |     vector<double> z(s, 1.0);
21 |     x[0] = a;
22 |     for (int i = 1; i < s; ++i) {
23 |         x[i] = x[i - 1] + h;
24 |         z[i] = z[i - 1] + h * f(x[i - 1], y[i - 1], z[i - 1]);
25 |         y[i] = y[i - 1] + h * z[i - 1];
26 |     }
27 |     return y;
28 | }
29 |
30 | vector<vector<double>> RK_method(double a, double b, double h) {
31 |     int s = (b - a) / h + 1;
32 |     vector<double> x(s);
33 |     vector<double> y(s, 1);
34 |     vector<double> z(s, 1);
35 |     vector<double> K(4, 0.0);
36 |     vector<double> L(4, 0.0);
37 |     x[0] = a;
38 |     for (int i = 1; i < s; ++i) {
39 |         x[i] = x[i - 1] + h;
40 |         for (int j = 1; j < K.size(); ++j) {
41 |             K[0] = h * z[i - 1];
42 |             L[0] = h * f(x[i - 1], y[i - 1], z[i - 1]);
43 |             K[j] = h * (z[i - 1] + L[j - 1] / 2);
44 |             L[j] = h * f(x[i - 1] + h / 2, y[i - 1] + K[j - 1] / 2, z[i - 1] + L[j - 1] / 2);
45 |         }
46 |         double deltax = (K[0] + 2 * K[1] + 2 * K[2] + K[3]) / 6;
```

```

47     double deltax = (L[0] + 2 * L[1] + 2 * L[2] + L[3]) / 6;
48     y[i] = y[i - 1] + deltax;
49     z[i] = z[i - 1] + deltaz;
50 }
51 return { y, z };
52 }
53
54
55 vector<double> Adams_method(double a, double b, double h) {
56     int s = (b - a) / h + 1;
57     vector<double> x;
58     vector<double> y(s, 0);
59     vector<double> z(s, 0);
60     for (double i = a; i < b + h; i += h) {
61         x.push_back(i);
62     }
63     vector<double> y_start = RK_method(a, a + 3 * h, h)[0];
64     vector<double> z_start = RK_method(a, a + 3 * h, h)[1];
65     for (int i = 0; i < y_start.size(); ++i) {
66         y[i] = y_start[i];
67         z[i] = z_start[i];
68     }
69     for (int i = 4; i < s; ++i) {
70         z[i] = (z[i - 1] + h * (
71             55 * f(x[i - 1], y[i - 1], z[i - 1]) - 59 * f(x[i - 2], y[i - 2], z[i - 2])
72             + 37 * f(x[i - 3], y[i - 3], z[i - 3]) - 9 * f(x[i - 4], y[i - 4], z[i -
73                 4])) / 24);
74         y[i] = y[i - 1] + h * z[i - 1];
75     }
76     return y;
77 }
78
79 vector<vector<double>> RRR_method(double a, double b, double h) {
80     vector<double> Euler1, RK1, Adams1;
81     vector<double> Euler_norm = Euler_method(a, b, h);
82     vector<double> Euler_half = Euler_method(a, b, h / 2);
83     vector<double> RK_norm = RK_method(a, b, h)[0];
84     vector<double> RK_half = RK_method(a, b, h / 2)[0];
85     vector<double> Adams_norm = Adams_method(a, b, h);
86     vector<double> Adams_half = Adams_method(a, b, h / 2);
87     int s = (b - a) / h + 1;
88     Euler1.resize(s);
89     RK1.resize(s);
90     Adams1.resize(s);
91     for (int i = 0; i < s; ++i) {
92         Euler1[i] = Euler_norm[i] + (Euler_half[i * 2] - Euler_norm[i]) / (1 - 0.5 *
93             0.5);
94         RK1[i] = RK_norm[i] + (RK_half[i * 2] - RK_norm[i]) / (1 - 0.5 * 0.5);
95         Adams1[i] = Adams_norm[i] + (Adams_half[i * 2] - Adams_norm[i]) / (1 - 0.5 * 0.5);

```

```

94     }
95     return { Euler1, RK1, Adams1 };
96 }
97
98
99 int main() {
100     double h = 0.1;
101     double a = 1;
102     double b = 2;
103     vector<double> x, y;
104     for (double i = a; i < b + h; i += h) {
105         x.push_back(i);
106         y.push_back(exact_solution(i));
107     }
108     std::cout << "X: ";
109     for (int i = 0; i < x.size(); ++i) {
110         std::cout << x[i] << " ";
111     }
112     std::cout << std::endl;
113     std::cout << "Y: ";
114     for (int i = 0; i < y.size(); ++i) {
115         std::cout << y[i] << " ";
116     }
117     std::cout << endl << std::endl;
118     std::cout << "Euler method: ";
119     for (int i = 0; i < Euler_method(a, b, h).size(); ++i) {
120         std::cout << Euler_method(a, b, h)[i] << " ";
121     }
122     std::cout << std::endl;
123     std::cout << "Runge-Kutte method: ";
124     for (int i = 0; i < RK_method(a, b, h)[0].size(); ++i) {
125         std::cout << RK_method(a, b, h)[0][i] << " ";
126     }
127     std::cout << std::endl;
128     std::cout << "Adams method: ";
129     vector <double> res_adams = Adams_method(a, b, h);
130     for (int i = 0; i < res_adams.size(); ++i) {
131         std::cout << res_adams[i] << " ";
132     }
133     std::cout << endl << std::endl;
134     std::cout << "With Runge-Romberg-Richardson method \n" << std::endl;
135     vector<vector<double>> result = RRR_method(a, b, h);
136     std::cout << "Euler method: ";
137     for (int i = 0; i < result[0].size(); ++i) {
138         std::cout << result[0][i] << " ";
139     }
140     std::cout << std::endl;
141     std::cout << "Runge-Kutte method: ";
142     for (int i = 0; i < result[1].size(); ++i) {

```

```

143     std::cout << result[1][i] << " ";
144 }
145 std::cout << std::endl;
146 std::cout << "Adams method: ";
147 for (int i = 0; i < result[2].size(); ++i) {
148     std::cout << result[2][i] << " ";
149 }
150 std::cout << endl << std::endl;
151 std::cout << "Delta of exact value \n" << std::endl;
152 std::cout << "Euler method: ";
153 for (int i = 0; i < result[0].size(); ++i) {
154     std::cout << abs(result[0][i] - y[i]) << " ";
155 }
156 std::cout << std::endl;
157 std::cout << "Runge-Kutte method: ";
158 for (int i = 0; i < result[1].size(); ++i) {
159     std::cout << abs(result[1][i] - y[i]) << " ";
160 }
161 std::cout << std::endl;
162 std::cout << "Adams method: ";
163 for (int i = 0; i < result[2].size(); ++i) {
164     std::cout << abs(result[2][i] - y[i]) << " ";
165 }
166 std::cout << std::endl;
167 return 0;
168 }

```

## 4.2 Метод стрельбы и конечно-разностный метод

### 4 Постановка задачи

Реализовать метод стрельбы и конечно-разностный метод решения краевой задачи для ОДУ в виде программ. С использованием разработанного программного обеспечения решить краевую задачу для обыкновенного дифференциального уравнения 2-го порядка на указанном отрезке. Оценить погрешность численного решения с использованием метода Рунге – Ромберга и путем сравнения с точным решением.

Вариант: 26

26	$x(x+1)y''+(x+2)y'-y=x+\frac{1}{x},$ $y'(1)=\frac{3}{2},$ $4y'(2)+y(2)=13+4\ln 2$	$y(x)=x+\frac{7}{2}+\frac{1}{x}+\left(\frac{x}{2}+1\right)\ln x $
----	---	---

Рис. 3: Входные данные

### 5 Результаты работы

```
Real: 5 Shooting: 7.14538 Difference: 5
Real: 5.15682 Shooting: 7.2548 Difference: 5.28814
Real: 5.32505 Shooting: 7.37993 Difference: 5.44703
Real: 5.50213 Shooting: 7.51713 Difference: 5.61313
Real: 5.68629 Shooting: 7.66382 Difference: 5.78511
Real: 5.87623 Shooting: 7.81811 Difference: 5.96203
Real: 6.07101 Shooting: 7.97856 Difference: 6.14313
Real: 6.2699 Shooting: 8.14409 Difference: 6.32785
Real: 6.47235 Shooting: 8.31386 Difference: 6.51576
Real: 6.67793 Shooting: 8.48719 Difference: 6.70649
Real: 6.88629 Shooting: 8.66356 Difference: 6.88629
Error shooting: 2.14538Runge shooting: 8.64075e-06Error difference: 0Runge difference : 0
Error shooting: 2.09798Runge shooting: -6.69623e-06Error difference: 0.131316Runge difference : -0.0326808
Error shooting: 2.05488Runge shooting: -1.10775e-05Error difference: 0.121982Runge difference : -0.0277617
Error shooting: 2.015Runge shooting: -1.22756e-05Error difference: 0.110994Runge difference : -0.0229065
Error shooting: 1.97753Runge shooting: -1.24455e-05Error difference: 0.0988256Runge difference : -0.0182013
```

Рис. 4: Вывод программы в консоли

## 6 Исходный код

```
1 | #include <iostream>
2 | #include <cmath>
3 | #include <vector>
4 |
5 | const double e = 0.00001;
6 |
7 | double func(double x) {
8 |     return x + 7 / 2 + 1 / x + (x / 2 + 1) * log(abs(x));
9 | }
10 |
11 | double dfunc(double x, double y, double z) {
12 |     return -(x + 2) * z + y / (x * (x + 1));
13 | }
14 |
15 | double g(double y, double z) {
16 |     return 4 * z + y - 13 - 4 * log(2);
17 | }
18 |
19 | double p(double x) {
20 |     return (x + 2) / (x * (x + 1));
21 | }
22 |
23 | double q(double x) {
24 |     return -1 / (x * (x + 1));
25 | }
26 |
27 | double f(double x) {
28 |     return (x + 1 / x) / (x * (x + 1));
29 | }
30 |
31 | double K(double x, double y, double z, double h, int i);
32 |
33 | double L(double x, double y, double z, double h, int i) {
34 |     if (i == 0) {
35 |         return h * z;
36 |     }
37 |     else if (i == 3) {
38 |         return h * (z + K(x, y, z, h, i - 1));
39 |     }
40 |     else {
41 |         return h * (z + K(x, y, z, h, i - 1) / 2);
42 |     }
43 | }
44 |
45 | double K(double x, double y, double z, double h, int i) {
46 |     if (i == 0) {
47 |         return h * dfunc(x, y, z);
```



```

48     }
49     else if (i == 3) {
50         return h * dfunc(x + h, y + L(x, y, z, h, i - 1), z + K(x, y, z, h, i - 1));
51     }
52     else {
53         return h * dfunc(x + h / 2, y + L(x, y, z, h, i - 1) / 2, z + K(x, y, z, h, i -
54             1) / 2);
55     }
56 }
57 double delta_z(double x, double y, double z, double h) {
58     double d = 0;
59     for (int i = 0; i < 4; ++i) {
60         if (i == 0 || i == 3) {
61             d += K(x, y, z, h, i);
62         }
63         else {
64             d += 2 * K(x, y, z, h, i);
65         }
66     }
67     return d / 6;
68 }
69
70 double delta_y(double x, double y, double z, double h) {
71     double d = 0;
72     for (int i = 0; i < 4; ++i) {
73         if (i == 0 || i == 3) {
74             d += L(x, y, z, h, i);
75         }
76         else {
77             d += 2 * L(x, y, z, h, i);
78         }
79     }
80     return d / 6;
81 }
82
83
84 std::vector<std::vector<double>> Runge_method(double l, double r, double h, double y0,
85     double z0) {
86     double x = l;
87     int n = (int)((r - l) / h);
88     double z = z0;
89     double y = y0;
90     std::vector<double> res(n + 1);
91     std::vector<double> res_z(n + 1);
92     res[0] = y0;
93     res_z[0] = z0;
94     for (int i = 1; i <= n; ++i) {
95         double z1 = z + delta_z(x, y, z, h);

```

```

95     y = y + delta_y(x, y, z, h);
96     res[i] = y;
97     res_z[i] = z1;
98     z = z1;
99     x += h;
100 }
101 return { res, res_z };
102 }
103
104 std::vector<double> Shooting(double l, double r, double h, double z0) {
105     double n1 = 1, n2 = 0.8, n3;
106     double g1, g2, g3;
107
108     std::vector<std::vector<double>> res1 = Runge_method(l, r, h, n1, z0);
109     double res1y = res1[0][res1[0].size() - 1];
110     double res1z = res1[1][res1[1].size() - 1];
111     std::vector<std::vector<double>> res2 = Runge_method(l, r, h, n2, z0);
112     double res2y = res2[0][res2[0].size() - 1];
113     double res2z = res2[1][res2[1].size() - 1];
114     g1 = g(res1y, res1z);
115     g2 = g(res2y, res2z);
116     std::vector<std::vector<double>> res;
117     while (std::abs(g2) > e) {
118         n3 = n2 - (n2 - n1) / (g2 - g1) * g2;
119         res = Runge_method(l, r, h, n3, z0);
120         double resy = res[0][res[0].size() - 1];
121         double res_z = res[1][res[1].size() - 1];
122         g3 = g(resy, res_z);
123         n1 = n2;
124         n2 = n3;
125         g1 = g2;
126         g2 = g3;
127     }
128     return res[0];
129 }
130
131 std::vector<double> Difference(double l, double r, double h, double y0, double y1) {
132     int n = (int)((r - l) / h);
133
134     std::vector<std::vector<double>> A(n, std::vector<double>(n));
135     std::vector<double> d(n);
136     double x = l + h;
137
138     for (int i = 0; i < n; ++i) {
139         A[i][i] = -2 + h * h * q(x);
140         if (i > 0) A[i][i - 1] = 1 - p(x) * h / 2;
141         if (i < n - 1) A[i][i + 1] = (1 + p(x) * h / 2);
142         x += h;
143     }

```

```

144
145     d[0] = h * h * f(l + h) - (1 - p(l + h) * h / 2) * y0;
146     d[n - 1] = h * h * f(r - h) - (1 + p(r - h) * h / 2) * y1;
147     x = l + 2 * h;
148     for (int i = 1; i < n - 1; ++i) {
149         d[i] = h * h * f(x);
150         x += h;
151     }
152
153     std::vector<double> P(n);
154     std::vector<double> Q(n);
155
156     for (int i = 0; i < n; ++i) {
157         if (i == 0) {
158             P[i] = -A[i][i + 1] / A[i][i];
159             Q[i] = d[i] / A[i][i];
160         }
161         else if (i == n - 1) {
162             P[i] = 0;
163             Q[i] = (d[i] - A[i][i - 1] * Q[i - 1]) / (A[i][i] + A[i][i - 1] * P[i - 1])
164                 ;
165         }
166         else {
167             P[i] = -A[i][i + 1] / (A[i][i] + A[i][i - 1] * P[i - 1]);
168             Q[i] = (d[i] - A[i][i - 1] * Q[i - 1]) / (A[i][i] + A[i][i - 1] * P[i - 1])
169                 ;
170         }
171     }
172
173     std::vector<double> y(n + 1);
174
175     for (int i = n - 1; i >= 0; --i) {
176         if (i == n - 1) y[i] = Q[i];
177         else {
178             y[i] = P[i] * y[i + 1] + Q[i];
179         }
180     }
181     y[0] = y0;
182     y[n] = y1;
183
184     return y;
185 }
186
187
188
189 std::vector<double> RR_method(std::vector<double> Y1, std::vector<double> Y2, int n,
    int p) {

```

```

190     std::vector<double> R(n);
191     for (int i = 0; i < n; ++i) {
192         R[i] = (Y1[i * 2] - Y2[i]) / (std::pow(2, p) - 1);
193     }
194     return R;
195 }
196
197 std::vector<double> Error(std::vector<double> Yt, std::vector<double> Y, int n) {
198     std::vector<double> eps(n);
199     for (int i = 0; i < n; ++i) {
200         eps[i] = std::abs(Yt[i] - Y[i]);
201     }
202     return eps;
203 }
204
205 int main() {
206     double l = 1, r = 2;
207     double z0 = 3 / 2;
208     double h = 0.1;
209     double y0 = func(l);
210     double y1 = func(r);
211
212     std::vector<double> shooting = Shooting(l, r, h, z0);
213     std::vector<double> difference = Difference(l, r, h, y0, y1);
214
215     std::vector<double> real(shooting.size());
216     double x = l;
217     for (int i = 0; i < real.size(); i++) {
218         real[i] = func(x);
219         x += h;
220
221         std::cout << "Real: " << real[i] << " Shooting: " << shooting[i] << "
222             Difference: " << difference[i] << std::endl;
223     }
224
225     std::vector<double> shooting2 = Shooting(l, r, h * 2, z0);
226     std::vector<double> difference2 = Difference(l, r, h * 2, y0, y1);
227
228     std::vector<double> RShooting = RR_method(shooting, shooting2, real.size() / 2, 2);
229     std::vector<double> RDifference = RR_method(difference, difference2, real.size() /
230         2, 2);
231
232     std::vector<double> EShooting = Error(shooting, real, real.size() / 2);
233     std::vector<double> EDifference = Error(difference, real, real.size() / 2);
234
235     for (int i = 0; i < real.size() / 2; i++) {
236         std::cout << "Error shooting: " << EShooting[i] << "Runge shooting: " <<
237             RShooting[i] << "Error difference: " << EDifference[i] << "Runge difference
238             : " << RDifference[i] << std::endl;

```

235 || }  
236 || }