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MATH 520 Methods of Applied Math II
Homework 12

Section 16.8

#20 Show that the Fréchet derivative, if it exists, must be unique.

Proof. Let X, Y be Banach spaces and let $F : D(F) \subset X \rightarrow Y$. Now suppose that $A_1, A_2 \in B(X, Y)$ exist such that $A_1 \neq A_2$ and they both are the Fréchet derivative of F at some $x_0 \in D(F)$. This means that

$$\lim_{x \rightarrow x_0} \frac{\|F(x) - F(x_0) - A_1(x - x_0)\|}{\|x - x_0\|} = 0$$

and

$$\lim_{x \rightarrow x_0} \frac{\|F(x) - F(x_0) - A_2(x - x_0)\|}{\|x - x_0\|} = 0$$

□

#21 If $F : \mathbb{R}^2 \rightarrow \mathbb{R}$ is defined by

$$F(x, y) = \begin{cases} \frac{xy^2}{x^2+y^4} & (x, y) \neq (0, 0) \\ 0 & (x, y) = (0, 0) \end{cases}$$

show that F is Gâteaux differentiable but not Fréchet differentiable at the origin.

The Gâteaux derivative of F at the origin can be computed as follows.

$$\begin{aligned} DF(0, 0)(u, v) &= \left. \frac{d}{dt} (F(0 + tu, 0 + tv)) \right|_{t=0} \\ &= \left. \frac{d}{dt} \left(\frac{tu(tv)^2}{(tu)^2 + (tv)^4} \right) \right|_{t=0} \\ &= \left. \frac{d}{dt} \left(\frac{tuv^2}{u^2 + t^2v^4} \right) \right|_{t=0} \\ &= \left. \frac{(u^2 + t^2v^4)uv^2 + tuv^2(2v^4t)}{(u^2 + t^2v^4)^2} \right|_{t=0} \\ &= \frac{u^3v^2}{u^4} \\ &= \frac{v^2}{u} \end{aligned}$$

This shows that the Gâteaux derivative of F is $A(u, v) = \frac{v^2}{u}$

Now we will consider the Fréchet derivative of F at $(0, 0)$. If the Fréchet derivative exists, then $A \in B(X, Y)$ will exist such that

$$\lim_{x \rightarrow x_0} \frac{\|F(x) - F(x_0) - A(x - x_0)\|}{\|x - x_0\|} = 0.$$

This can be simplified by noting that $x_0 = (0, 0)$ and using the definition of F .

$$\lim_{(u,v) \rightarrow (0,0)} \frac{\left| \frac{uv^2}{u^2+v^4} - A(u, v) \right|}{\sqrt{u^2 + v^2}} = 0.$$

#27 Let X, Y be Banach spaces, $F : D(F) \subset X \rightarrow Y$, and let $x, x_0 \in D(F)$ be such that $tx + (1-t)x_0 \in D(F)$ for $t \in [0, 1]$. If

$$M := \sup_{0 \leq t \leq 1} \|DF(tx + (1-t)x_0)\|$$

show that

$$\|F(x) - F(x_0)\| \leq M\|x - x_0\|$$

(Suggestion: justify and use a suitable version of the fundamental theorem of calculus.)

Section 17.5

#2 Let λ_1 be the smallest Dirichlet eigenvalue for $-\Delta$ in Ω , assume that $c \in C(\overline{\Omega})$ and $c(x) > -\lambda_1$ in $\overline{\Omega}$. If $f \in L^2(\Omega)$ prove the existence of a solution of

$$-\Delta u + c(x)u = f \quad x \in \Omega \quad u = 0 \quad \forall x \in \partial\Omega$$

Proof.

□

#3 Let $\lambda > 0$ and define

$$A[u, v] = \int_{\Omega} a_{jk}(x) u_{x_k}(x) v_{x_j}(x) \, dx + \lambda \int_{\Omega} uv \, dx$$

for all $u, v \in H^1(\Omega)$. Assume the ellipticity property (17.1.3) and that $a_{jk} \in L^{\infty}(\Omega)$. If $f \in L^2(\Omega)$ show that there exists a unique solution of

$$u \in H^1(\Omega) \quad A[u, v] = \int_{\Omega} f v \, dx \quad \forall v \in H^1(\Omega).$$

Justify that u may be regarded as the weak solution of

$$-(a_{jk} u_{x_k})_{x_j} + \lambda u = f(x) \quad x \in \Omega \quad a_{jk} u_{x_k} n_j = 0 \quad x \in \partial\Omega$$

The above boundary condition is said to be of conormal type.

Proof. Lax-Milgram's Theorem can be used to show that there exists a unique solution to

$$u \in H^1(\Omega) \quad A[u, v] = \int_{\Omega} f v \, dx \quad \forall v \in H^1(\Omega).$$

First I will show that A is bilinear.

$$\begin{aligned} A[u_1 + u_2, v] &= \int_{\Omega} a_{jk}(x) (u_1 + u_2)_{x_k}(x) v_{x_j}(x) \, dx + \lambda \int_{\Omega} (u_1 + u_2) v \, dx \\ &= \int_{\Omega} a_{jk}(x) (u_1)_{x_k}(x) v_{x_j}(x) \, dx + \int_{\Omega} a_{jk}(x) (u_2)_{x_k}(x) v_{x_j}(x) \, dx + \lambda \int_{\Omega} u_1 v + u_2 v \, dx \\ &= \int_{\Omega} a_{jk}(x) (u_1)_{x_k}(x) v_{x_j}(x) \, dx + \int_{\Omega} a_{jk}(x) (u_2)_{x_k}(x) v_{x_j}(x) \, dx + \lambda \int_{\Omega} u_1 v \, dx + \lambda \int_{\Omega} u_2 v \, dx \\ &= A[u_1, v] + A[u_2, v] \\ A[u, v_1 + v_2] &= \int_{\Omega} a_{jk}(x) u_{x_k}(x) (v_1 + v_2)_{x_j}(x) \, dx + \lambda \int_{\Omega} u (v_1 + v_2) \, dx \\ &= \int_{\Omega} a_{jk}(x) u_{x_k}(x) (v_1)_{x_j}(x) \, dx + \int_{\Omega} a_{jk}(x) u_{x_k}(x) (v_2)_{x_j}(x) \, dx + \lambda \int_{\Omega} u v_1 + u v_2 \, dx \\ &= \int_{\Omega} a_{jk}(x) u_{x_k}(x) (v_1)_{x_j}(x) \, dx + \int_{\Omega} a_{jk}(x) u_{x_k}(x) (v_2)_{x_j}(x) \, dx + \lambda \int_{\Omega} u v_1 \, dx + \lambda \int_{\Omega} u v_2 \, dx \\ &= A[u, v_1] + A[u, v_2] \end{aligned}$$

□

#6 Let f and g be in $L^2(0, 1)$. Use the Lax-Milgram Theorem to prove there is a unique weak solution $\{u, v\} \in H_0^1(0, 1)$ to

$$\begin{aligned} -u'' + u + v' &= f \\ -v'' + v + u' &= g, \end{aligned}$$

where $u(0) = v(0) = 0$ and $u(1) = v(1) = 0$. (Hint: Start by defining the bilinear form

$$A[(u, v), (\phi, \psi)] = \int_0^1 u' \phi' + u \phi + v' \phi + v' \psi' + v \psi + u' \psi \, dx$$

on $H_0^1(0, 1) \times H_0^1(0, 1)$.

Proof. First I will rewrite this system of PDEs in weak form.

$$\int_0^1 -u'' \phi + u \phi + v' \phi - v'' \psi + v \psi + u' \psi \, dx = \int_0^1 f \phi + g \psi \, dx$$

for all $\phi, \psi \in H_0^1(0, 1)$. Integrating by parts where necessary gives

$$\int_0^1 u' \phi' + u \phi + v' \phi + v' \psi' + v \psi + u' \psi \, dx = \int_0^1 f \phi + g \psi \, dx.$$

Now I will define the following bilinear function

$$A[(u, v), (\phi, \psi)] = \int_0^1 u' \phi' + u \phi + v' \phi + v' \psi' + v \psi + u' \psi \, dx.$$

This function is bilinear because differentiation and integration are both linear operations. To verify this note that

$$\begin{aligned} A[(u_1 + u_2, v_1 + v_2), (\phi, \psi)] &= \int_0^1 (u_1 + u_2)' \phi' + (u_1 + u_2) \phi + (v_1 + v_2)' \phi + (v_1 + v_2)' \psi' + (v_1 + v_2) \psi + (u_1 + u_2)' \psi \, dx \\ &= \int_0^1 u_1' \phi' + u_2' \phi' + u_1 \phi + u_2 \phi + v_1' \phi + v_2' \phi + v_1' \psi' + v_2' \psi' + v_1 \psi + v_2 \psi + u_1' \psi + u_2' \psi \, dx \\ &= \int_0^1 u_1' \phi' + u_1 \phi + v_1' \phi + v_1' \psi' + v_1 \psi + u_1' \psi \, dx + \int_0^1 u_2' \phi' + u_2 \phi + v_2' \phi + v_2' \psi' + v_2 \psi + u_2' \psi \, dx \\ &= A[(u_1, v_1), (\phi, \psi)] + A[(u_2, v_2), (\phi, \psi)] \end{aligned}$$

and the same can be shown for the second argument.

Next I will show that A is bounded.

$$A[(u, v), (\phi, \psi)]$$

Lastly I will show that A is coercive. Let $u, v \in H_0^1(0, 1)$, then

$$\begin{aligned} A[(u, v), (u, v)] &= \int_0^1 (u')^2 + u^2 + uv' + (v')^2 + v^2 + u'v \, dx \\ &= \int_0^1 (u')^2 \, dx + \int_0^1 u^2 \, dx + \int_0^1 uv' \, dx + \int_0^1 (v')^2 \, dx + \int_0^1 v^2 \, dx + \int_0^1 u'v \, dx \end{aligned}$$

Integrating by parts

$$\begin{aligned} &= \int_0^1 (u')^2 \, dx + \int_0^1 u^2 \, dx - \int_0^1 u'v \, dx + \int_0^1 (v')^2 \, dx + \int_0^1 v^2 \, dx + \int_0^1 u'v \, dx \\ &= \int_0^1 (u')^2 \, dx + \int_0^1 u^2 \, dx + \int_0^1 (v')^2 \, dx + \int_0^1 v^2 \, dx \\ &= \|u\|_{H_0^1}^2 + \|u\|_{L^2}^2 + \|v\|_{H_0^1}^2 + \|v\|_{L^2}^2 \end{aligned}$$

□