## Chapter 6

# Initial Value Problems for ODEs: Multistep Methods

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MATH 561 Numerical Analysis

### Numerical Methods for ODEs

IVP for ODE:

$$\frac{d\mathbf{y}}{dx} = \mathbf{f}(x, \mathbf{y}), \ a \leqslant x \leqslant b; \ \mathbf{y}(a) = \mathbf{y}_0.$$

• Approximation  $\{\mathbf u_n \approx \mathbf y(x_n)\}$  at discrete points  $\{x_n\}$ : grid function  $\{\mathbf u_n\}$  on a grid

$$a = x_0 < x_1 < \dots < x_{N-1} < x_N = b$$

- One-step method: Chap 5.
- Multistep method: in a k-step method,  $\mathbf{u}_{n+k}$  is determined with information from previous k points,  $\mathbf{u}_{n+k-1}, \mathbf{u}_{n+k-2}, \ldots, \mathbf{u}_n$ . k is called the step number (index) of the method.

## Linear Multistep Methods

- Assume uniform grid legnth h.
- Example: start with the ODE, integration from  $x_n$  to  $x_{n+k}$ ,

$$\mathbf{y}(x_{n+k}) - \mathbf{y}(x_n) = \int_{x_n}^{x_{n+k}} \mathbf{f}(x, \mathbf{y}) dx.$$

With appropriate numerical quadrature rules for the integral  $\Rightarrow$  linear multstep methods.

• Examples:  $\mathbf{y}_{n+1} \approx \mathbf{y}_n + \frac{h}{2}(f_{n+1} + f_n)$ .

$$\begin{split} &\mathbf{y}_{n+1} \approx \mathbf{y}_{n-1} + \frac{h}{3} (\mathbf{f}_{n-1} + 4\mathbf{f}_n + \mathbf{f}_{n+1}). \\ &\mathbf{y}_{n+4} \approx \mathbf{y}_{n+3} + \frac{h}{24} \big[ 55\mathbf{f}_{n+3} - 59\mathbf{f}_{n+2} + 37\mathbf{f}_{n+1} - 9\mathbf{f}_n \big]. \\ &\mathbf{y}_{n+4} \approx \mathbf{y}_{n+3} + \frac{h}{24} \big[ 9\mathbf{f}_{n+4} + 19\mathbf{f}_{n+3} - 5\mathbf{f}_{n+2} - 9\mathbf{f}_{n+1} \big]. \end{split}$$

# Linear Multistep Methods

- Assume uniform grid legnth h.
- General k-step method: for  $n = 0, 1, 2, \dots, N k$ ,

$$\mathbf{u}_{n+k} + \alpha_{k-1}\mathbf{u}_{n+k-1} + \dots + \alpha_0\mathbf{u}_n$$
  
=  $h[\beta_k\mathbf{f}_{n+k} + \beta_{k-1}\mathbf{f}_{n+k-1} + \dots + \beta_0\mathbf{f}_n],$ 

with  $\mathbf{u}_0, \mathbf{u}_1, \dots, \mathbf{u}_{k-1}$  provided.

If  $\beta_k = 0$ : explicit methods.

If  $\beta_k \neq 0$ : implicit methods.

ullet For implicit methods:  $oldsymbol{u}_{n+k}$  obtained as solution of nonlinear equation

$$\mathbf{u}_{n+k} = \beta_k \mathbf{f}(x_{n+k}, \mathbf{u}_{n+k}) + \mathbf{g}_n,$$
  
$$\mathbf{g}_n = h \sum_{s=0}^{k-1} \beta_s \mathbf{f}_{n+s} - \sum_{s=0}^{k-1} \alpha_s \mathbf{u}_{n+s}.$$

## Linear Multistep Methods

• Successive iteration (fixed-point iteration) for the nonlinear equation:

$$\mathbf{u}_{n+k}^{[v]} = h\beta_k \mathbf{f}(x_{n+k}, \mathbf{u}_{n+k}^{[v-1]}) + \mathbf{g}_n, \ v = 1, 2, \dots$$

$$\mathbf{u}_{n+k}^{[v]} \to \mathbf{u}_{n+k}, \text{ as } v \to \infty.$$

#### **Theorem**

Assume **f** is Lipschitz continuous for variable **y** with Lipschitz constant L, and  $\lambda \equiv h|\beta_k|L < 1$ , then the above nonlinear equation has a unique solution  $\mathbf{u}_{n+k} = \lim_{v \to \infty} \mathbf{u}_{n+k}^{[v]}$ , and

$$\|\mathbf{u}_{n+k}^{[v]} - \mathbf{u}_{n+k}\| \leqslant \frac{\lambda^v}{1-\lambda} \|\mathbf{u}_{n+k}^{[1]} - \mathbf{u}_{n+k}^{[0]}\|, \ v = 1, 2, \dots$$

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## Truncation Error; Consistency

Residual Operator:

$$\begin{split} &(R\mathbf{y})(x) \equiv \mathbf{y}'(x) - \mathbf{f}(x,\mathbf{y}), \ \mathbf{y} \in C^1[a,b] \\ &(R_h\mathbf{u})_n \equiv \frac{1}{h} \sum_{s=0}^k \alpha_s \mathbf{u}_{n+s} - \sum_{s=0}^k \beta_s \mathbf{f}(x_{n+s},\mathbf{u}_{n+s}), \ \mathbf{u} = \{\mathbf{u}_n\} \in \Gamma_h[a,b], \end{split}$$

- Truncation error:  $(\mathbf{T}_h)_n = (R_n \mathbf{y})_n, \ n = 0, 1, \dots, N.$
- Consistency:  $\|\mathbf{T}_h\|_{\infty} \to \mathbf{0}$ , as  $h \to 0$ .
- Order  $p: \|\mathbf{T}_h\|_{\infty} = O(h^p)$ , as  $h \to 0$ .
- Principal error function  $\tau$ :  $(\mathbf{T}_h)_n = \tau(x_n)h^p + O(h^{p+1})$ , as  $h \to 0$ .

### Truncation Error

Truncation error:

$$(\mathbf{T}_h)_n = \frac{1}{h} \sum_{s=0}^k \alpha_s \mathbf{y}_{n+s} - \sum_{s=0}^k \beta_s \mathbf{y}'_{n+s}, \ n = 0, 1, \dots, N$$

With Taylor series expansion:

$$\mathbf{y}(x_{n+s}) = \mathbf{y}(x_n) + sh\mathbf{y}'(x_n) + \frac{1}{2}(sh)^2\mathbf{y}''(x_n) + \cdots$$

$$\mathbf{y}'(x_{n+s}) = \mathbf{y}(x_n) + sh\mathbf{y}''(x_n) + \frac{1}{2}(sh)^2\mathbf{y}'''(x_n) + \cdots$$

Then we have

$$(\mathbf{T}_h)_n = \frac{1}{h} (\sum_{s=0}^k \alpha_s) \mathbf{y}(x_n) + (\sum_{s=0}^k (s\alpha_s - \beta_s)) \mathbf{y}'(x_n) + O(h)$$

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# Truncation Error; Consistency; Characteristic Polynomials

• Consistency  $(\mathbf{T}_h)_n \to 0$  as  $h \to 0$  implies consistency conditions

$$\sum_{s=0}^{k} \alpha_s = 0, \quad \sum_{s=0}^{k} s \alpha_s = \sum_{s=0}^{k} \beta_s.$$

Introduce characteristic polynomials

$$\alpha(t) = \sum_{s=0}^{k} \alpha_s t^s, \quad \beta(t) = \sum_{s=0}^{k} \beta_s t^s.$$

Consistency conditions ⇒

$$\alpha(1) = 0, \quad \alpha'(1) = \beta(1).$$

• MORE Results using characteristic polynomials (later).

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## Local Description; $\Omega$ -degree

From local truncation error:

$$\sum_{s=0}^k \alpha_s \mathbf{y}(x_{n+s}) - h \sum_{s=0}^k \beta_s \mathbf{y}'(x_{n+s}) = h(\mathbf{T}_h)_n.$$

• Define linear operator  $L_h:C^1[\mathbf{R}]\to C^1[\mathbf{R}]$ ,

$$(L_h z)(x) = \sum_{s=0}^k \alpha_s z(x+sh) - h \sum_{s=0}^k \beta_s z'(x+sh), \ z \in C^1[\mathbf{R}].$$

- Given a set of linearly independent "gauge functions"  $\{\omega_r(x)\}_{r=0}^\infty$ , and define  $\Omega_p=\mathrm{Span}\{\omega_0,\omega_1,\ldots,\omega_p\}$
- $\Omega$ -degree p of the method:

$$L_h\omega = 0, \ \forall \omega \in \Omega_p, \forall h > 0.$$

## Local Description

- $\Omega_p$  closed under translation if  $\omega(x) \in \Omega_p$  implies  $\omega(x+c) \in \Omega_p$
- $\Omega_p$  closed under scaling if  $\omega(x) \in \Omega_p$  implies  $\omega(cx) \in \Omega_p$

#### **Theorem**

• If  $\Omega_p$  closed under translation, then the method has  $\Omega$ -degree p iff

$$(L_h\omega)(0) = 0, \ \forall \omega \in \Omega_p, \forall h > 0.$$

• if  $\Omega_p$  closed under translation and scaling, then the method has  $\Omega$ -degree p iff

$$(L_1\omega)(0) = 0, \ \forall \omega \in \Omega_p.$$

## Local Description

• Linear functional  $L: C^1[\mathbf{R}] \to \mathbf{R}$ :

$$Lu = \sum_{s=0}^{k} [\alpha_s u(s) - \beta_s u'(s)], \ u \in C^1[\mathbf{R}].$$

- For  $\Omega_m = \mathbf{P}_m$ ,  $\Omega$ -degree referred as algebraic (or polynomial) degree.
- The method has algebraic degree p if  $Lu=0, \ \forall u \in \mathbf{P}_p$ , equivalently,

$$Lt^r = 0, \ r = 0, 1, \dots, p.$$

• Examples: Explicit two-step methods: what  $\alpha$ 's,  $\beta$ 's? what polynomial degree p?  $\mathbf{u}_{n+2} + \alpha_1 \mathbf{u}_{n+1} + \alpha_0 \mathbf{u}_n = h(\beta_1 \mathbf{f}_{n+1} + \beta_0 \mathbf{f}_n)$ .

## Peano Kernel of Linear Functionals

• Denote local solution  $\mathbf{v}(t) \equiv \mathbf{y}(x_n + th), \ 0 \leqslant t \leqslant k$ , then

$$L\mathbf{v} = \sum_{s=0}^{k} [\alpha_s \mathbf{v}(s) - \beta_s \mathbf{v}'(s)] = h(\mathbf{T}_h)_n.$$

For the linear functional L, Define p-th Peano kernel

$$\lambda_p(\sigma) = L_{(t)}(t - \sigma)_+^p = \sum_{s=0}^k \left[ \alpha_s (s - \sigma)_+^p - \beta_s p(s - \sigma)_+^{p-1} \right], \ p \geqslant 1,$$

Peano representation of the function L,

$$L\mathbf{v} = \frac{1}{p!} \int_0^k \lambda_p(\sigma) \mathbf{v}^{(p+1)}(\sigma) d\sigma.$$

• L is definite of order p if  $\lambda_p$  is of the same sign.

## Peano Kernel of Linear Functionals

• L is definite of order p, then

$$L\mathbf{v} = l_{p+1}\mathbf{v}^{(p+1)}(\bar{\sigma}), \ 0 < \bar{\sigma} < k; \ l_{p+1} = L\frac{t^{p+1}}{(p+1)!}$$

### Theorem

A multistep method of polynomial degree p has order p whenever the exact solution  $\mathbf{y}(x)$  is in the smoothness class  $C^{p+1}[a,b]$ . If the associated functional L is definite, then

$$(\mathbf{T}_h)_n = l_{p+1} \mathbf{y}^{(p+1)}(\bar{x}_n) h^p, \ x_n < \bar{x}_n < x_{n+k}.$$

Moreover, for the principal error function au of the method, whenever definite or not, we have if  $\mathbf{y} \in C^{p+2}[a,b]$ ,

$$\boldsymbol{\tau}(x) = l_{p+1} \mathbf{y}^{(p+1)}(x).$$

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