# Lecture 16 Rayleigh Quotient Iteration

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MATH 562 Numerical Analysis II

#### Outline

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# Solving Eigenvalue Problems

- All eigenvalue solvers must be iterative
- Iterative algorithms have multiple facets:
  - Basic idea behind the algorithms
  - Convergence and techniques to speed-up convergence
  - Efficiency of implementation
  - Termination criteria
- We will focus on first two aspects

# Simplification: Real Symmetric Matrices

- We will consider eigenvalue problems for real symmetric matrices, i.e.,  $\mathbf{A} = \mathbf{A}^T \in \mathbb{R}^{m \times m}$ , and  $\mathbf{A}\mathbf{x} = \lambda \mathbf{x}$  for  $\mathbf{x} \in \mathbb{R}^m$ .
  - Note:  $\mathbf{x}^* = \mathbf{x}^T$ , and  $\|\mathbf{x}\| = \sqrt{\mathbf{x}^T \mathbf{x}}$
- A has real eigenvalues  $\lambda_1, \lambda_2, \dots, \lambda_m$  and orthonormal eigenvectors  $\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_m$ , where  $\|\mathbf{q}_i\| = 1$ .
- Eigenvalues are often also ordered in a particular way (e.g., ordered from large to small in magnitude)
- In addition, we focus on symmetric tridiagonal form
  - Why? Because phase 1 of two-phase algorithm reduces matrix into tridiagonal form

# Rayleigh Quotient

• The Rayleigh quotient of  $\mathbf{x} \in \mathbb{R}^m$  is the scalar

$$r(\mathbf{x}) = \frac{\mathbf{x}^T \mathbf{A} \mathbf{x}}{\mathbf{x}^T \mathbf{x}}$$

- For an eigenvector  $\mathbf{x}$ , its Rayleigh quotient is  $r(\mathbf{x}) = \mathbf{x}^T \lambda \mathbf{x} / \mathbf{x}^T \mathbf{x} = \lambda$  the corresponding eigenvalue of  $\mathbf{x}$
- For general  $\mathbf{x}$ ,  $r(\mathbf{x}) = \alpha$  that minimizes  $\|\mathbf{A}\mathbf{x} \alpha\mathbf{x}\|_2$ .
- $\mathbf{x}$  is eigenvector of  $\mathbf{A} \Leftrightarrow \nabla r(\mathbf{x}) = \frac{2}{\mathbf{x}^T\mathbf{x}}(\mathbf{A}\mathbf{x} r(\mathbf{x})\mathbf{x}) = 0$  with  $\mathbf{x} \neq 0$
- $r(\mathbf{x})$  is smooth and  $\nabla r(\mathbf{q}_j) = 0$  for any j, and therefore is quadratically accurate:

$$r(\mathbf{x}) - r(\mathbf{q}_J) = O(\|\mathbf{x} - \mathbf{q}_J\|^2)$$
 as  $\mathbf{x} \to \mathbf{q}_J$  for some  $J$ 

#### Power Iteration

• Simple power iteration for largest eigenvalue

#### Algorithm: Power Iteration

$$\begin{aligned} \mathbf{v}^{(0)} &= \text{some unit-length vector} \\ \text{for } k = 1, 2, \dots \\ \mathbf{w} &= \mathbf{A} \mathbf{v}^{(k-1)} \\ \mathbf{v}^{(k)} &= \mathbf{w}/\|\mathbf{w}\| \\ \lambda^{(k)} &= r(\mathbf{v}^{(k)}) = (\mathbf{v}^{(k)})^T \mathbf{A} \mathbf{v}^{(k)} \end{aligned}$$

Termination condition is omitted for simplicity

## Convergence of Power Iteration

• Expand initial  $\mathbf{v}^{(0)}$  in orthonormal eigenvectors  $\mathbf{q}_i$ , and apply  $\mathbf{A}^k$ :

$$\mathbf{v}^{(0)} = a_1 \mathbf{q}_1 + a_2 \mathbf{q}_2 + \dots + a_m \mathbf{q}_m$$

$$\mathbf{v}^{(k)} = c_k \mathbf{A}^k \mathbf{v}^{(0)}$$

$$= c_k (a_1 \lambda_1^k \mathbf{q}_1 + a_2 \lambda_2^k \mathbf{q}_2 + \dots + a_m \lambda_m^k \mathbf{q}_m)$$

$$= c_k \lambda_1^k (a_1 \mathbf{q}_1 + a_2 (\lambda_2 / \lambda_1)^k \mathbf{q}_2 + \dots + a_m (\lambda_m / \lambda_1)^k \mathbf{q}_m)$$

• If  $|\lambda_1| > |\lambda_2| \geqslant \cdots \geqslant |\lambda_m| \geqslant 0$  and  $\mathbf{q}_1^T \mathbf{v}^{(0)} \neq 0$ , this gives

$$\|\mathbf{v}^{(k)} - (\pm \mathbf{q}_1)\| = O(|\lambda_2/\lambda_1|^k), \ |\lambda^{(k)} - \lambda_1| = O(|\lambda_2/\lambda_1|^{2k})$$

where  $\pm$  sign is chosen to be sign of  $\mathbf{q}_1^T \mathbf{v}^{(k)}$ 

- It finds the largest eigenvalue (unless eigenvector is orthogonal to  $\mathbf{v}^{(0)}$ )
- Error reduces by only a constant factor ( $\approx |\lambda_2/\lambda_1|$ ) each step, and very slowly especially when  $|\lambda_2| \approx |\lambda_1|$

#### Inverse Iteration

- Apply power iteration on  $(\mathbf{A} \mu \mathbf{I})^{-1}$ , with eigenvalues  $\{(\lambda_i \mu)^{-1}\}$
- If  $\mu \approx \lambda_J$  for some J, then  $(\lambda_J \mu)^{-1}$  may be far larger than  $(\lambda_i - \mu)^{-1}$ ,  $j \neq J$ , so power iteration may converge rapidly

#### Algorithm: Inverse Iteration

$$\begin{aligned} \mathbf{v}^{(0)} &= \text{some unit-length vector} \\ \text{for } k = 1, 2, \dots \\ \text{Solve } (\mathbf{A} - \mu \mathbf{I}) \mathbf{w} &= \mathbf{v}^{(k-1)} \text{ for } \mathbf{w} \\ \mathbf{v}^{(k)} &= \mathbf{w} / \| \mathbf{w} \| \\ \lambda^{(k)} &= r(\mathbf{v}^{(k)}) = (\mathbf{v}^{(k)})^T \mathbf{A} \mathbf{v}^{(k)} \end{aligned}$$

• Converges to eigenvector  $\mathbf{q}_I$  if parameter  $\mu$  is close to  $\lambda_I$ 

$$\|\mathbf{v}^{(k)} - (\pm \mathbf{q}_J)\| = O\left(|\frac{\mu - \lambda_J}{\mu - \lambda_K}|^k\right), \ \|\lambda^{(k)} - \lambda_J\| = O\left(|\frac{\mu - \lambda_J}{\mu - \lambda_K}|^{2k}\right)$$

where  $\lambda_I$  and  $\lambda_K$  are closest and second closest eigenvalues to  $\mu$ 

Standard method for determining eigenvector given eigenvalue

# Rayleigh Quotient Iteration

- Parameter  $\mu$  is constant in inverse iteration, but convergence is better for  $\mu$  close to the eigenvalue
- $\bullet$  Improvement: At each iteration, set  $\mu$  to last computed Rayleigh quotient

## Algorithm: Rayleigh Quotient Iteration

$$\begin{split} \mathbf{v}^{(0)} &= \text{some unit-length vector} \\ \lambda^{(0)} &= r(\mathbf{v}^{(0)}) = (\mathbf{v}^{(0)})^T \mathbf{A} \mathbf{v}^{(0)} \\ \text{for } k = 1, 2, \dots \\ &\quad \text{Solve } (\mathbf{A} - \lambda^{(k-1)} \mathbf{I}) \mathbf{w} = \mathbf{v}^{(k-1)} \text{ for } \mathbf{w} \\ \mathbf{v}^{(k)} &= \mathbf{w} / \| \mathbf{w} \| \\ \lambda^{(k)} &= r(\mathbf{v}^{(k)}) = (\mathbf{v}^{(k)})^T \mathbf{A} \mathbf{v}^{(k)} \end{split}$$

• Cost per iteration is linear for tridiagonal matrix

## Convergence of Rayleigh Quotient Iteration

• Cubic convergence in Rayleigh quotient iteration

$$\|\mathbf{v}^{(k+1)} - (\pm \mathbf{q}_J)\| = O(\|\mathbf{v}^{(k)} - (\pm \mathbf{q}_J)\|^3)$$

and

$$|\lambda^{(k+1)} - \lambda_J| = O(|\lambda^{(k)} - \lambda_J|^3)$$

- In other words, each iteration triples number of digits of accuracy
- Proof idea: If  $\mathbf{v}^{(k)}$  is close to an eigenvector,  $\|\mathbf{v}^{(k)} (\pm \mathbf{q}_J)\| \leqslant \epsilon$ , then accuracy of Rayleigh quotient estimate  $\lambda^{(k)}$  is  $|\lambda^{(k)} \lambda_J| = O(\epsilon^2)$ . One step of inverse iteration then gives

$$\|\mathbf{v}^{(k+1)} - \mathbf{q}_J\| = O(|\lambda^{(k)} - \lambda_J| \|\mathbf{v}^{(k)} - \mathbf{q}_J\|) = O(\epsilon^3)$$

 Rayleigh quotient is great in finding largest (or smallest) eigenvalue and its corresponding eigenvector. What if we want to find all eigenvalues?

## **Operation Counts**

- In Rayleigh quotient iteration,
  - if  $\mathbf{A} \in \mathbb{R}^{m \times m}$  is full matrix, then solving  $(\mathbf{A} \mu \mathbf{I}) = \mathbf{v}^{(k-1)}$  may take  $O(m^3)$  flops per step
  - if  $\mathbf{A} \in \mathbf{R}^{m \times m}$  is upper Hessenberg, then each step takes  $O(m^2)$  flops
  - if  $\mathbf{A} \in \mathbf{R}^{m \times m}$  is tridiagonal, then each step takes O(m) flops