Caleb Logemann MATH 562 Numerical Analysis II Final Exam

1. Let $A \in \mathbb{R}^{m \times m}$ be written in the form A = L + D + U, where L is strictly lower triangular, D is the diagonal of A, and U is the strictly upper triangular part of A. Assuming D is invertible, $A\mathbf{x} = \mathbf{b}$ is equivalent to $\mathbf{x} = -D^{-1}(L+U)\mathbf{x} + D^{-1}\mathbf{b}$. The Jacobi iteration method for solving $A\mathbf{x} = \mathbf{b}$ is defined by

$$\mathbf{x}^{n+1} = -D^{-1}(L+U)\mathbf{x}^n + D^{-1}\mathbf{b}$$

Show that if A is nonsingular and strictly row diagonally dominant:

$$0 < \sum_{j \neq i} (|a_{ij}|) < |a_{ii}|$$

then the Jacobi iteration converges to $\mathbf{x}_* = A^{-1}\mathbf{b}$ for each fixed $\mathbf{b} \in \mathbb{R}^m$.

Proof.

2. Let $A \in \mathbb{R}^{m \times m}$ be symmetric positive definite (SPD), $\mathbf{b} \in \mathbb{R}^m$ and define $\phi : \mathbb{R}^m \to \mathbb{R}$ by

$$\phi(\mathbf{x}) = \frac{1}{2}\mathbf{x}^T A \mathbf{x} - \mathbf{x}^T \mathbf{b}$$

Suppose K is a subspace of \mathbb{R}^m . Show that $\hat{\mathbf{x}} \in K$ minimizes $\phi(\mathbf{x})$ over K if and only if $\nabla \phi(\hat{\mathbf{x}}) \perp K$.

Proof.

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- 4.
- 5.
- 6.
- 7.
- 8.
- 9.
- 10.