## Caleb Logemann MATH 565 Continuous Optimization Homework 3

## 1. Page 100: Problem 4.9.

Derive the solution of the two-dimensional subspace minimization problem in the case where B is positive definite.

*Proof.* The two-dimensional subspace minimization problem can be stated as

$$\min_{p} \{m(p)\} = \min_{p} \left\{ f + g^T p + \frac{1}{2} p^T B p \right\} \qquad s.t. \|p\| < \Delta, p \in \operatorname{span}\left(g, B^{-1} g\right)$$

## 2. Page 100: Problem 4.10.

Show that if B is any symmetric matrix, then there exists  $\lambda \geq 0$  such that  $B + \lambda I$  is positive definite.

Proof. Let B be a symmetric matrix. Since B is symmetric all of the eigenvalues of B are real. If all of the eigenvalues of B are positive, then B is already positive definite. In this case, B = B + 0I is positive definite. Therefore consider when B has some negative eigenvalues. Let  $\mu_1$  be the most negative eigenvalue, that is  $\mu_1 \leq \mu_i$  for any eigenvalue,  $\mu_i$ , of B. I will let  $\lambda = -\mu_1 + 1$ . I now claim that  $B + \lambda I$  is positive definite. To see this note that the eigenvectors of B can form an orthonormal basis of  $\mathbb{R}^N$ , when  $B \in \mathbb{R}^{N \times N}$ . Let  $\{v_i\}$  denote this basis and consider that any  $x \in \mathbb{R}^N$  can be expressed as  $x = \sum_{i=1}^N (a_i v_i)$ . Now consider  $x^T(B + \lambda I)x$ .

$$x^{T}(B + \lambda I)x = \sum_{i=1}^{N} \left(a_{i}v_{i}^{T}\right)(B + \lambda I) \sum_{j=1}^{N} \left(a_{j}v_{j}\right)$$

$$= \sum_{i=1}^{N} \left(\sum_{j=1}^{N} \left(a_{i}a_{j}v_{i}^{T}(B + \lambda I)v_{j}\right)\right)$$

$$= \sum_{i=1}^{N} \left(\sum_{j=1}^{N} \left(a_{i}a_{j}\left(v_{i}^{T}Bv_{j} + \lambda v_{i}^{T}v_{j}\right)\right)\right)$$

$$= \sum_{i=1}^{N} \left(\sum_{j=1}^{N} \left(a_{i}a_{j}\left(\mu_{j}v_{i}^{T}v_{j} + \lambda v_{i}^{T}v_{j}\right)\right)\right)$$

Since  $v_i^T v_j = 0$  for all  $i \neq j$ 

$$= \sum_{i=1}^{N} \left( a_i^2 \left( \mu_j v_i^T v_i + \lambda v_i^T v_i \right) \right)$$

$$= \sum_{i=1}^{N} \left( a_i^2 \left( \mu_i ||v_i||^2 + \lambda ||v_i||^2 \right) \right)$$

$$= \sum_{i=1}^{N} \left( a_i^2 (\mu_i + \lambda) \right)$$

Note that  $\mu_i + \lambda > 0$  for any eigenvalue  $\mu_i$  as  $\lambda + \mu_1 = 1$  and  $\mu_1 \leq \mu_i$  for all eigenvalues, therefore

$$x^T(B + \lambda I)x > 0$$

This shows that  $B + \lambda I$  is positive definite.

3. Implement the linear conjugate gradient method in Matlab or Python.

The following function implements the linear conjugate gradient method in Python.

```
import numpy as np
def linearConjugateGradient(A, b, x, MaxIter, TOL):
   r = np.dot(A, x) - b
   delta = np.dot(r, r)
   p = -r
    k = 0
    mstop = 1
    while k < MaxIter and mstop:</pre>
       k+=1
        w = np.dot(A, p)
        alpha = delta/np.dot(p, w)
        x = x + alpha*p
        r = r + alpha*w
        deltaOld = delta
        delta = np.dot(r, r)
        if np.sqrt(delta) < TOL:</pre>
            mstop = 0
        else:
            beta = delta/deltaOld
            p = -r + beta*p
    return (x, k)
```

4. Page 133: Problem 5.1. (Use your method from the previous problem).

Implement Algorithm 5.2 and use it to solve linear systems in which A is the Hilbert matrix, whose elements  $A_{i,j} = 1/(i+j-1)$ . Set the right-hand-side to  $b = (1,1,\ldots,1)^T$  and the initial point to  $x_0 = 0$ . Try dimensions n = 5, 8, 12, 20 and report the number of iterations required to reduce the residual below  $10^{-6}$ .

The following script uses the linear conjugate gradient method to solve the given linear system.

```
import numpy as np
from scipy.linalg import hilbert
execfile('linearConjugateGradient.py')

TOL = 1e-6
MaxIter = 100
for n in [5, 8, 12, 20]:
    A = hilbert(n)
    b = np.ones(n)
    x = np.zeros(n)
    (x, k) = linearConjugateGradient(A, b, x, MaxIter, TOL)
    print(k)
```

The required number of iterations to achieve error less than  $10^{-6}$  is shown in the table below for different size matrices.

n	Number of Iterations
5	
8	
12	
20	

## 5. Page 133: Problem 5.2.

Show that if the nonzero vectors  $p_0, p_1, \ldots, p_l$  satisfy (5.5), where A is symmetric and positive definite, then these vectors are linearly independent. (This result implies that A has a most n conjugate directions.)

*Proof.* Let A be symmetric and positive definite and let  $p_0, p_1, \ldots, p_l$  be A-conjugate, that is

$$p_i^T A p_i = 0 \qquad \forall i \neq j.$$

Consider a set of constants  $c_0, c_1, \ldots, c_l$ , such that

$$\sum_{i=0}^{l} (c_i p_i) = 0$$

The set of vectors  $\{p_i\}$  are linearly independent if  $c_i = 0$  for all i. Consider the following

$$0 = \sum_{i=0}^{l} \left( c_i p_i^T \right) A \sum_{j=0}^{l} \left( c_j p_j \right)$$

$$0 = \sum_{i=0}^{l} \left( \sum_{j=0}^{l} \left( c_i c_j p_i^T A p_j \right) \right)$$

Since these vectors are A-conjugate

$$0 = \sum_{i=0}^{l} \left( c_i^2 p_i^T A p_i \right).$$

Note that since A is positive definite  $p_i^T A p_i > 0$  for all i, and since  $c_i^2 \ge 0$  this implies that

$$0 = c_i$$

This shows that  $p_0, p_1, \ldots, p_l$  are linearly independent. Therefore any set of A-conjugate vectors must also be linearly independent. Since a set of linearly independent vectors can be at most of size n, this implies that a set of A-conjugate vectors can be at most of size n.

6. Let  $n = N^2$ . Download the MATLAB file CreateA.m from the course website. The correct syntax for calling this code is

$$A = CreateA(N);$$

This creates a matrix of size  $N^2 \times N^2$ .

Apply your conjugate gradient method to this problem for various N. Make a table that records the number of iterations required to achieve a reasonable tolerance for N=10,20,40,80,160,320. You should use the same tolerance in each case. How does the number of iterations scale with N? What does this tell you about the condition number of A as N varies?

```
from scipy.sparse import spdiags
from scipy.sparse import lil_matrix
from scipy.sparse import identity

execfile('linearConjugateGradient.py')
import ipdb

def CreateA(n1):
```

```
e1= np.ones(n1)
    e2= np.zeros(n1)
   T = spdiags([e1, -4*e1, e1], [-1, 0, 1], n1, n1)
    I = identity(n1)
    A = lil\_matrix((n1*n1,n1*n1))
    for i in range(n1):
       ma = i*n1
       mb = (i+1)*n1
       A[ma:mb, ma:mb] = T
    for i in range(n1-1):
       ma = i*n1
       mb = (i+1)*n1
       mc = (i+1)*n1
       md = (i+2)*n1
       A[ma:mb,mc:md] = I
       A[mc:md, ma:mb] = I
   A = -A
    return(A)
TOL = 1e-6
MaxIter = 500
for n in [10, 20, 40, 80]:
   x0 = np.zeros(n*n)
   b = np.ones(n*n)
   A = CreateA(n).toarray()
    (x, k) = linearConjugateGradient(A, b, x0, MaxIter, TOL)
   print(k)
   ek = TOL
   e0 = np.linalg.norm(x - x0)
    e = (ek/(2*e0))**(1.0/k)
    cond = ((e + 1)/(1 - e)) **2
    print (cond)
```

For this problem, I used  $b = [1, 1, ..., 1]^T$  and  $x_0 = 0$ . The error tolerance was  $10^{-6}$ .

N	number of iterations
10	15
20	35
40	73
80	149
160	302
320	

This sho