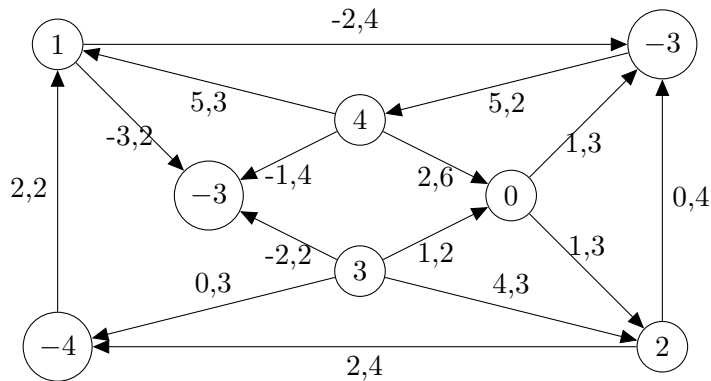
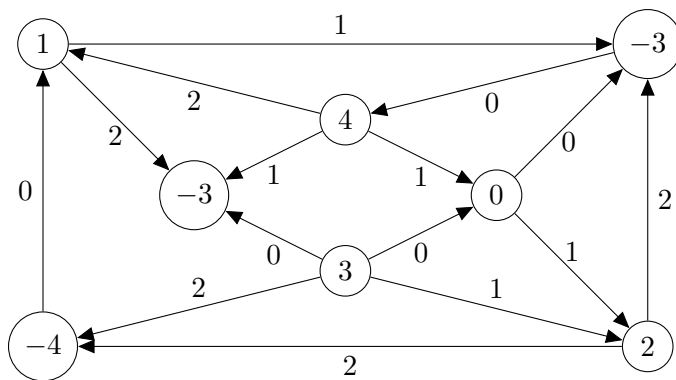


**Caleb Logemann**  
**MATH 566 Discrete Optimization**  
**Homework 8**

Consider the following network  $M$  with costs and capacities depicted on edges and boundary in vertices.



1. Consider the following  $b$ -flow  $f$  in  $M$ .



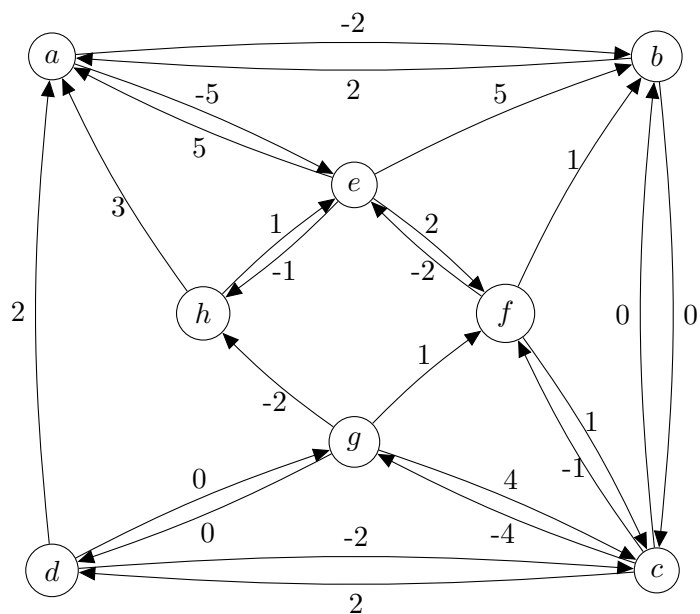
Compute the cost of  $f$ . Start computing the minimum cost  $b$ -flow by finding a sequence of augmenting cycles starting from  $f$ .

First I will compute the cost of the given flow  $f$ .

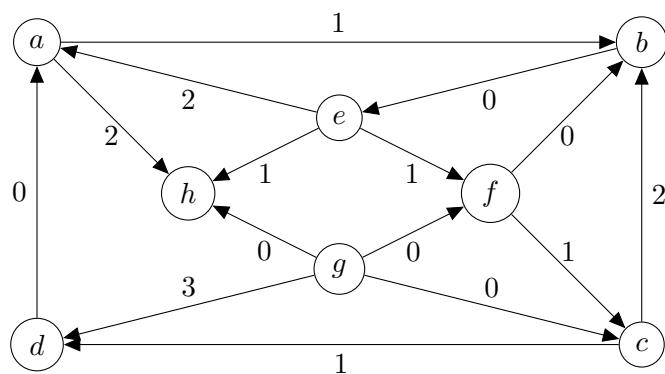
$$1 \times -2 + 2 \times 5 + 2 \times -3 + 1 \times -1 + 1 \times 2 + 1 \times 1 + 1 \times 4 + 2 \times 2 + 2 \times 0 + 2 \times 0 = 12$$

The cost of this flow is 12.

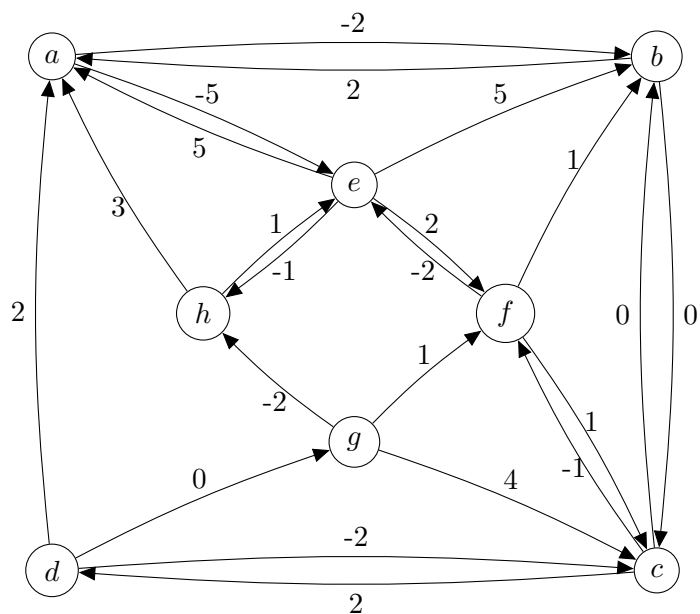
Now I will do 2 augmentations of this flow, first the residual graph must be computed, I relabeled the vertices while doing this. The boundaries at each vertex are not important for this algorithm as the augmentations preserve this property.



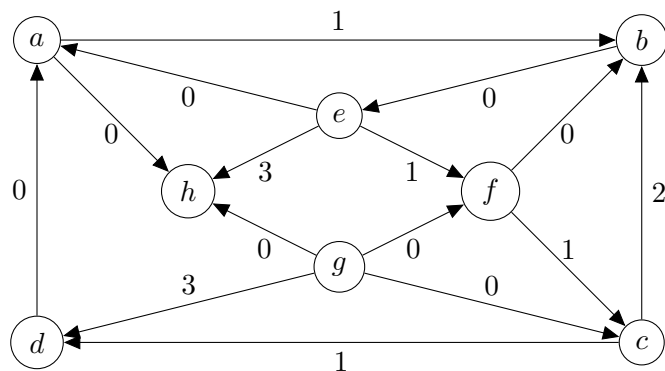
The first negative cycle that I will augment along the cycle  $c \rightarrow d \rightarrow g \rightarrow c$ , the value of this cycle is  $-6$ . The minimum available capacity along this cycle is 1 along the  $g \rightarrow d$  edge. The new flow is shown below, and the value of this new flow is 6.



The new residual graph is shown below.



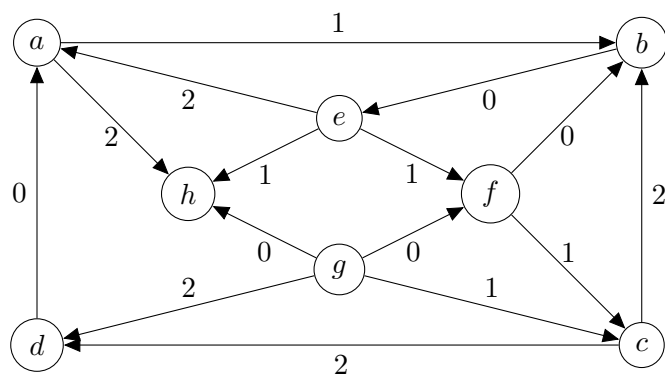
The next cycle I will augment on is  $a \rightarrow e \rightarrow h \rightarrow a$ , which has value  $-3$ . The minimum capacity on this cycle is 2. The new flow will have value 0, and is shown below.



From problem 2 we know that this is the optimal min flow on this network.

2. Solve minimum cost  $b$ -flow for  $M$  using linear programming. That is, formulate the problem using linear programming and solve it using Sage or APMonitor. Then draw the resulting network.

First I will relabel the nodes with letters in order to better describe the flow.



In order to solve the min flow problem we can consider the flow on each edge, which I will denote  $f(e)$  for each edge in  $E(G)$ . Let  $c(e)$  be the cost of edge  $e$ ,  $u(e)$  be the capacity of each edge, and  $b(v)$  be the boundary at vertex  $v$ . Any solution needs to satisfy two types of constraints. First the flow must be greater than zero and less than the capacity, symbolically this can be expressed as

$$0 \leq f(e) \leq u(e)$$

for all  $e \in E(G)$ . Second the difference between the flow out and the flow in of each vertex must be the boundary of each vertex, symbolically this can be expressed as

$$\sum_{(u,v) \in E(G)} f((u,v)) - \sum_{(v,u) \in E(G)} f((v,u)) = b(v)$$

for each vertex  $v$  in  $V(G)$ .

Also the objective function for this linear program is minimizing the flow times the cost of each edge. Therefore the entire linear program is

$$(P) \begin{cases} \text{minimize} & \sum_{e \in E(G)} c(e)f(e) \\ \text{subject to} & f(e) \leq u(e) \quad \forall e \in E(G) \\ & \sum_{e=(u,v) \in E(G)} f(e) - \sum_{e=(v,u) \in E(G)} f(e) = b(v) \quad \forall v \in V(G) \\ & f(e) \geq 0 \quad \forall e \in E(G) \end{cases}$$

This linear program can be solved using the following Sage script.

```
import operator
#
# costs = Matrix([[0, -2, 0, 0, 0, 0, 0, -3], #a
#                 [0, 0, 0, 0, 5, 0, 0, 0], #b
#                 [0, 0, 0, 2, 0, 0, 0, 0], #c
#                 [2, 0, 0, 0, 0, 0, 0, 0], #d
#                 [5, 0, 0, 0, 0, 2, 0, -1], #e
#                 [0, 1, 1, 0, 0, 0, 0, 0], #f
#                 [0, 0, 4, 0, 0, 1, 0, -2], #g
#                 [0, 0, 0, 0, 0, 0, 0, 0]]) #h
#
# capacities = Matrix([[0, 4, 0, 0, 0, 0, 0, 2], #a
#                     [0, 0, 0, 0, 2, 0, 0, 0], #b
#                     [0, 4, 0, 4, 0, 0, 0, 0], #c
#                     [2, 0, 0, 0, 0, 0, 0, 0], #d
#                     [3, 0, 0, 0, 0, 6, 0, 4], #e
#                     [0, 3, 3, 0, 0, 0, 0, 0], #f
#                     [0, 0, 3, 3, 0, 2, 0, 2], #g
#                     [0, 0, 0, 0, 0, 0, 0, 0]]) #h
#
# sources/sinks
b = {'a':1, 'b':-3, 'c':2, 'd':-4, 'e':4, 'f':0, 'g':3, 'h':-3}
G = DiGraph(capacities, weighted=True)

indexToVertex = {0:'a', 1:'b', 2:'c', 3:'d', 4:'e', 5:'f', 6:'g', 7:'h'}
vertexToIndex = {v: k for k, v in indexToVertex.iteritems()}
```

```

G.relabel(indexToVertex)
milp = MixedIntegerLinearProgram(maximization=False)
f = milp.new_variable(nonnegative=True)

milp.set_objective(sum([costs[vertexToIndex[e[0]], vertexToIndex[e[1]]] *
    ↪ f[e[0], e[1]] for e in G.edges()] ))

# Flows less than capacities
for edge in G.edges():
    # edge[2] is weight or label of edge
    milp.add_constraint(f[edge[0], edge[1]] <= edge[2])

# Flows into and out of vertices must be equal to source or sink
for vertex in G.vertices():
    flow_in = sum([f[v, vertex] for v in G.neighbors_in(vertex)])
    flow_out = sum([f[vertex, v] for v in G.neighbors_out(vertex)])
    milp.add_constraint(flow_out - flow_in == b[vertex])

print('Objective Value: {}'.format(milp.solve()))
sol = milp.get_values(f)
sol = sorted(sol.items(), key=operator.itemgetter(0))
for i, v in sol:
    print('f[{}s] = {}s' % (i, v))

```

The output of this script is shown below.

```

Objective Value: 0.0
f[('a', 'b')] = 2.0
f[('a', 'h')] = 0.0
f[('b', 'e')] = 0.0
f[('c', 'b')] = 1.0
f[('c', 'd')] = 1.0
f[('d', 'a')] = 0.0
f[('e', 'a')] = 1.0
f[('e', 'f')] = 0.0
f[('e', 'h')] = 3.0
f[('f', 'b')] = 0.0
f[('f', 'c')] = 0.0
f[('g', 'c')] = 0.0
f[('g', 'd')] = 3.0
f[('g', 'f')] = 0.0
f[('g', 'h')] = 0.0

```

This shows that the minimum cost is 0 and the flow is shown below.

