Caleb Logemann MATH667 Hyperbolic Partial Differential Equations Final Project

1. Write out the Jacobian matrix and derive the eigenvalues and eigenvectors for the Euler equations. We have the following vector flux function written in terms of the conserved variables.

$$\mathbf{f}(\mathbf{w}) = \begin{bmatrix} m \\ \frac{m^2}{\rho} + P \\ \frac{m}{\rho} (E + P) \end{bmatrix}$$

where

$$P = (\gamma - 1) \left(E - \frac{m^2}{2\rho} \right)$$

or

$$E = \frac{P}{\gamma - 1} + \frac{\rho u^2}{2}$$

In order to compute the Jacobian of f I will first compute the partial derivatives of P.

$$P_{\rho} = (\gamma - 1) \frac{m^2}{2\rho^2}$$

$$P_m = -(\gamma - 1) \frac{m}{\rho}$$

$$P_E = \gamma - 1$$

Now the Jacobian of f can expressed as

$$\mathbf{f}'(\mathbf{w}) = \begin{bmatrix} 0 & 1 & 0 \\ -\frac{m^2}{\rho^2} + P_{\rho} & 2\frac{m}{\rho} + P_{m} & P_{E} \\ P_{\rho}\frac{m}{\rho} - (E+P)\frac{m}{\rho^2} & P_{m}\frac{m}{\rho} + (E+P)\frac{1}{\rho} & \frac{m}{p}(1+P_{E}) \end{bmatrix}$$

Simplifying this results in

$$\mathbf{f}'(\mathbf{w}) = \begin{bmatrix} 0 & 1 & 0\\ (\gamma - 3)\frac{m^2}{2\rho^2} & (3 - \gamma)\frac{m}{\rho} & \gamma - 1\\ (\gamma - 1)\frac{m^3}{2\rho^3} - m\frac{E + P}{\rho^2} & \frac{E + P}{\rho} - (\gamma - 1)\frac{m^2}{\rho^2} & \gamma\frac{m}{\rho} \end{bmatrix}$$

This can also be changed into primitive variables.

$$\mathbf{f}'(\mathbf{w}) = \begin{bmatrix} 0 & 1 & 0\\ (\gamma - 3)\frac{u^2}{2} & (3 - \gamma)u & \gamma - 1\\ \frac{1}{2}(\gamma - 2)u^3 - \frac{\gamma}{\gamma - 1}\frac{uP}{\rho} & \frac{\gamma}{\gamma - 1}\frac{P}{\rho} + \left(\frac{3}{2} - \gamma\right)u^2 & \gamma u \end{bmatrix}$$

Now in order to find the eigenvalues and eigenvectors of this matrix we start by subtracting λI and solving $\det(\mathbf{f}'(\mathbf{w}) - \lambda I) = 0$.

$$\det(\mathbf{f}'(\mathbf{w}) - \lambda I) = \begin{vmatrix} -\lambda & 1 & 0\\ (\gamma - 3)\frac{u^2}{2} & (3 - \gamma)u - \lambda & \gamma - 1\\ \frac{1}{2}(\gamma - 2)u^3 - \frac{\gamma}{\gamma - 1}\frac{uP}{\rho} & \frac{\gamma}{\gamma - 1}\frac{P}{\rho} + \left(\frac{3}{2} - \gamma\right)u^2 & \gamma u - \lambda \end{vmatrix}$$
$$= -\lambda((3 - \gamma)u - \lambda)(\gamma u - \lambda) + (\gamma - 1)\left(\frac{1}{2}(\gamma - 2)u^3 - \frac{\gamma}{\gamma - 1}\frac{uP}{\rho}\right)$$
$$+\lambda(\gamma - 1)\left(\frac{\gamma}{\gamma - 1}\frac{P}{\rho} + \left(\frac{3}{2} - \gamma\right)u^2\right) - (\gamma - 3)\frac{u^2}{2}(\gamma u - \lambda)$$

I will separate out each of these terms as

$$a_1 = -\lambda((3-\gamma)u - \lambda)(\gamma u - \lambda)$$

$$a_2 = (\gamma - 1)\left(\frac{1}{2}(\gamma - 2)u^3 - \frac{\gamma}{\gamma - 1}\frac{uP}{\rho}\right)$$

$$a_3 = \lambda(\gamma - 1)\left(\frac{\gamma}{\gamma - 1}\frac{P}{\rho} + \left(\frac{3}{2} - \gamma\right)u^2\right)$$

$$a_4 = -(\gamma - 3)\frac{u^2}{2}(\gamma u - \lambda)$$

so the determinant is $a_1 + a_2 + a_3 + a_4$. Now I will simplify each of these terms

$$a_1 = -\lambda((3 - \gamma)u - \lambda)(\gamma u - \lambda)$$

$$= ((\gamma - 3)u\lambda + \lambda^2)(\gamma u - \lambda)$$

$$= (\gamma - 3)\gamma u^2\lambda - (\gamma - 3)u\lambda^2 + \gamma u\lambda^2 - \lambda^3$$

$$= (\gamma - 3)\gamma u^2\lambda + 3u\lambda^2 - \lambda^3$$

$$a_2 = (\gamma - 1) \left(\frac{1}{2} (\gamma - 2) u^3 - \frac{\gamma}{\gamma - 1} \frac{uP}{\rho} \right)$$
$$= \frac{1}{2} (\gamma - 1) (\gamma - 2) u^3 - \gamma \frac{uP}{\rho}$$

$$a_3 = \lambda(\gamma - 1) \left(\frac{\gamma}{\gamma - 1} \frac{P}{\rho} + \left(\frac{3}{2} - \gamma \right) u^2 \right)$$
$$= \lambda \left(\gamma \frac{P}{\rho} + (\gamma - 1) \left(\frac{3}{2} - \gamma \right) u^2 \right)$$

$$a_4 = -(\gamma - 3)\frac{u^2}{2}(\gamma u - \lambda)$$
$$= \lambda(\gamma - 3)\frac{u^2}{2} - \gamma(\gamma - 3)\frac{u^3}{2}$$

Adding these all back together gives

$$a_1 + a_2 + a_3 + a_4 = -\lambda^3 + 3u\lambda^2 + \left(\gamma \frac{P}{\rho} + (\gamma - 1)\left(\frac{3}{2} - \gamma\right)u^2 + (\gamma - 3)\left(\gamma + \frac{1}{2}\right)u^2\right)\lambda - \gamma(\gamma - 3)\frac{u^3}{2} + \frac{1}{2}(\gamma - 1)(\gamma - 2)u^3 - \gamma\frac{uP}{\rho}$$

Now I will simplify each of the coefficients of λ .

$$\begin{split} &\gamma\frac{P}{\rho}+(\gamma-1)\Big(\frac{3}{2}-\gamma\Big)u^2+(\gamma-3)\Big(\gamma+\frac{1}{2}\Big)u^2\\ &=\gamma\frac{P}{\rho}+\Big((\gamma-1)\Big(\frac{3}{2}-\gamma\Big)+(\gamma-3)\Big(\gamma+\frac{1}{2}\Big)\Big)u^2\\ &=\gamma\frac{P}{\rho}+\Big(-\gamma^2+\frac{5}{2}\gamma-\frac{3}{2}+\gamma^2-\frac{5}{2}\gamma-\frac{3}{2}\Big)u^2\\ &=\gamma\frac{P}{\rho}+-3u^2 \end{split}$$

$$-\gamma(\gamma - 3)\frac{u^{3}}{2} + \frac{1}{2}(\gamma - 1)(\gamma - 2)u^{3} - \gamma \frac{uP}{\rho}$$

$$= (-\gamma(\gamma - 3) + (\gamma - 1)(\gamma - 2))\frac{u^{3}}{2} - \gamma \frac{uP}{\rho}$$

$$= (-\gamma^{2} + 3\gamma + \gamma^{2} - 3\gamma + 2)\frac{u^{3}}{2} - \gamma \frac{uP}{\rho}$$

$$= u^{3} - \gamma \frac{uP}{\rho}$$

So now simplifying these terms by factoring into a difference cubed

$$a_1 + a_2 + a_3 + a_4 = -\lambda^3 + 3u\lambda^2 + \left(\gamma \frac{P}{\rho} + -3u^2\right)\lambda + u^3 - \gamma \frac{uP}{\rho}$$
$$= -\lambda^3 + 3u\lambda^2 - 3u^2\lambda + u^3 + \gamma\lambda \frac{P}{\rho} - \gamma \frac{uP}{\rho}$$
$$= (u - \lambda)^3 - (u - \lambda)\frac{\gamma P}{\rho}$$

Thus we have shown that

$$\det(\mathbf{f}'(\mathbf{w}) - \lambda I) = (u - \lambda)^3 - (u - \lambda)\frac{\gamma P}{\rho}$$

Setting this equal to zero and solving for λ gives.

$$(u - \lambda)^3 - (u - \lambda)\frac{\gamma P}{\rho} = 0$$

$$(u - \lambda)\left((u - \lambda)^2 - \frac{\gamma P}{\rho}\right) = 0$$

$$\lambda = u$$

$$(u - \lambda)^2 - \frac{\gamma P}{\rho} = 0$$

$$(u - \lambda)^2 = \frac{\gamma P}{\rho}$$

$$(u - \lambda) = \pm \sqrt{\frac{\gamma P}{\rho}}$$

$$\lambda = u \pm \sqrt{\frac{\gamma P}{\rho}}$$

So the three eigenvalues of this system are

$$\lambda_1 = u, \quad \lambda_2 = u + \sqrt{\frac{\gamma P}{\rho}}, \quad \lambda_3 = u - \sqrt{\frac{\gamma P}{\rho}}$$

Now I will just check that we have the correct eigenvectors. The eigenvectors are

$$\mathbf{w}_1 = \begin{bmatrix} 1 \\ u \\ \frac{1}{2}u^2 \end{bmatrix}, \quad \mathbf{w}_2 = \begin{bmatrix} 1 \\ u + \sqrt{\frac{\gamma P}{\rho}} \\ \frac{\gamma}{\gamma - 1} \frac{P}{\rho} + \frac{u^2}{2} + u\sqrt{\frac{\gamma P}{\rho}} \end{bmatrix}, \quad \mathbf{w}_3 = \begin{bmatrix} 1 \\ u - \sqrt{\frac{\gamma P}{\rho}} \\ \frac{\gamma}{\gamma - 1} \frac{P}{\rho} + \frac{u^2}{2} - u\sqrt{\frac{\gamma P}{\rho}} \end{bmatrix}$$

To check

$$\mathbf{f}'\mathbf{w}_{1} = \begin{bmatrix} 0 & 1 & 0 \\ (\gamma - 3)\frac{u^{2}}{2} & (3 - \gamma)u & \gamma - 1 \\ \frac{1}{2}(\gamma - 2)u^{3} - \frac{\gamma}{\gamma - 1}\frac{uP}{\rho} & \frac{\gamma}{\gamma - 1}\frac{P}{\rho} + \left(\frac{3}{2} - \gamma\right)u^{2} & \gamma u \end{bmatrix} \begin{bmatrix} 1 \\ u \\ \frac{1}{2}u^{2} \end{bmatrix}$$

$$= \begin{bmatrix} u \\ (\gamma - 3)\frac{u^{2}}{2} - (\gamma - 3)u^{2} + (\gamma - 1)\frac{u^{2}}{2} \\ \frac{1}{2}(\gamma - 2)u^{3} - \frac{\gamma}{\gamma - 1}\frac{uP}{\rho} + \frac{\gamma}{\gamma - 1}\frac{uP}{\rho} + \left(\frac{3}{2} - \gamma\right)u^{3} + \gamma\frac{u^{3}}{2} \end{bmatrix}$$

$$= \begin{bmatrix} u \\ u^{2} \\ \frac{1}{2}u^{3} \end{bmatrix}$$

$$= u \begin{bmatrix} 1 \\ u \\ \frac{1}{2}u^{2} \end{bmatrix}$$

Let
$$c = \sqrt{\frac{\gamma P}{\rho}}$$

$$\mathbf{f}'\mathbf{w}_{2} = \begin{bmatrix} 0 & 1 & 0 \\ (\gamma - 3)\frac{u^{2}}{2} & (3 - \gamma)u & \gamma - 1 \\ \frac{1}{2}(\gamma - 2)u^{3} - \frac{\gamma}{\gamma - 1}\frac{uP}{\rho} & \frac{\gamma}{\gamma - 1}\frac{P}{\rho} + \left(\frac{3}{2} - \gamma\right)u^{2} & \gamma u \end{bmatrix} \begin{bmatrix} 1 \\ u + c \\ \frac{1}{\gamma - 1}c^{2} + \frac{u^{2}}{2} + uc \end{bmatrix}$$

$$= \begin{bmatrix} (\gamma - 3)\frac{u^{2}}{2} + (3 - \gamma)u(u + c) + (\gamma - 1)\left(\frac{1}{\gamma - 1}c^{2} + \frac{u^{2}}{2} + uc\right) \\ \frac{1}{2}(\gamma - 2)u^{3} - \frac{\gamma}{\gamma - 1}\frac{uP}{\rho} + \left(\frac{\gamma}{\gamma - 1}\frac{P}{\rho} + \left(\frac{3}{2} - \gamma\right)u^{2}\right)(u + c) + \gamma u\left(\frac{1}{\gamma - 1}c^{2} + \frac{u^{2}}{2} + uc\right) \end{bmatrix}$$

$$= \begin{bmatrix} (\gamma - 3)\frac{u^{2}}{2} + (3 - \gamma)u^{2} + (3 - \gamma)uc + c^{2} + (\gamma - 1)\frac{u^{2}}{2} + (\gamma - 1)uc \\ \frac{1}{2}(\gamma - 2)u^{3} + uc^{2} + \frac{1}{\gamma - 1}c^{2}(u + c) + \left(\frac{3}{2} - \gamma\right)u^{3} + \left(\frac{3}{2} - \gamma\right)u^{2}c + \gamma\frac{u^{3}}{2} + \gamma u^{2}c \end{bmatrix}$$

$$= \begin{bmatrix} u + c \\ u^{2} + 2uc + c^{2} \\ \frac{1}{2}u^{3} + \frac{1}{\gamma - 1}c^{2}(u + c) + \frac{3}{2}u^{2}c + uc^{2} \end{bmatrix}$$

$$= \begin{bmatrix} u + c \\ (u + c)^{2} \\ \left(\frac{u^{2}}{2} + uc\right)(u + c) + \frac{1}{\gamma - 1}c^{2}(u + c) \end{bmatrix}$$

$$= (u + c) \begin{bmatrix} 1 \\ u + c \\ \frac{1}{\gamma - 1}c^{2} + \frac{u^{2}}{2} + uc \end{bmatrix}$$

$$\begin{aligned} \mathbf{f}'\mathbf{w}_{3} &= \begin{bmatrix} 0 & 1 & 0 \\ (\gamma - 3)\frac{u^{2}}{2} & (3 - \gamma)u & \gamma - 1 \\ \frac{1}{2}(\gamma - 2)u^{3} - \frac{\gamma}{\gamma - 1}\frac{uP}{\rho} & \frac{\gamma}{\gamma - 1}\frac{P}{\rho} + \left(\frac{3}{2} - \gamma\right)u^{2} & \gamma u \end{bmatrix} \begin{bmatrix} 1 \\ u - c \\ \frac{1}{\gamma - 1}c^{2} + \frac{u^{2}}{2} - uc \end{bmatrix} \\ &= \begin{bmatrix} u - c \\ (\gamma - 3)\frac{u^{2}}{2} + (3 - \gamma)u(u - c) + (\gamma - 1)\left(\frac{1}{\gamma - 1}c^{2} + \frac{u^{2}}{2} - uc\right) \\ \frac{1}{2}(\gamma - 2)u^{3} - \frac{\gamma}{\gamma - 1}\frac{uP}{\rho} + \left(\frac{\gamma}{\gamma - 1}\frac{P}{\rho} + \left(\frac{3}{2} - \gamma\right)u^{2}\right)(u - c) + \gamma u\left(\frac{1}{\gamma - 1}c^{2} + \frac{u^{2}}{2} - uc\right) \end{bmatrix} \\ &= \begin{bmatrix} u - c \\ (\gamma - 3)\frac{u^{2}}{2} + (3 - \gamma)u^{2} - (3 - \gamma)uc + c^{2} + (\gamma - 1)\frac{u^{2}}{2} - (\gamma - 1)uc \\ \frac{1}{2}(\gamma - 2)u^{3} + uc^{2} + \frac{1}{\gamma - 1}c^{2}(u - c) + \left(\frac{3}{2} - \gamma\right)u^{3} - \left(\frac{3}{2} - \gamma\right)u^{2}c + \gamma\frac{u^{3}}{2} - \gamma u^{2}c \end{bmatrix} \\ &= \begin{bmatrix} u - c \\ u^{2} - 2uc + c^{2} \\ \frac{1}{2}u^{3} + \frac{1}{\gamma - 1}c^{2}(u - c) - \frac{3}{2}u^{2}c + uc^{2} \end{bmatrix} \\ &= \begin{bmatrix} u - c \\ (u - c)^{2} \\ \left(\frac{u^{2}}{2} - uc\right)(u - c) + \frac{1}{\gamma - 1}c^{2}(u - c) \end{bmatrix} \\ &= (u - c) \begin{bmatrix} 1 \\ u - c \\ \frac{1}{\gamma - 1}c^{2} + \frac{u^{2}}{2} - uc \end{bmatrix} \end{aligned}$$

2. The following is my function for 3rd order MUSCL scheme on a system of equations.

```
function [L] = muscl3System(w, f, deltaX, deltaT, RFunc, LambdaFunc)
    [n, nGridCells] = size(w);
   L = zeros(n, nGridCells);
   nu = 1/deltaX;
    %a = deltaX/(2*deltaT);
   boundaryConditions = 'zeroFlux';
   % flux array, F(:, i) is flux at i + 1/2 interface
   F = zeros(n, nGridCells);
    % compute fluxes at boundaries
    for j = 1:nGridCells
       % boundary conditions
       jm1 = j-1;
       if (j == 1)
           if (strcmp(boundaryConditions, 'periodic'))
               jm1 = nGridCells;
            elseif (strcmp(boundaryConditions,'zeroFlux'))
                jm1 = 1;
            end
       end
       jp1 = j+1;
       jp2 = j+2;
       if (j == nGridCells)
            if (strcmp(boundaryConditions, 'periodic'))
                jp1 = 1;
                jp2 = 2;
```

```
elseif (strcmp(boundaryConditions,'zeroFlux'))
            jp1 = nGridCells;
            jp2 = nGridCells;
        end
    elseif (j == nGridCells - 1)
        if (strcmp(boundaryConditions, 'periodic'))
            jp2 = 1;
        elseif (strcmp(boundaryConditions,'zeroFlux'))
            jp2 = nGridCells;
        end
    end
    wjm1 = w(:, jm1);
    wj = w(:,j);
    wjp1 = w(:, jp1);
    wjp2 = w(:, jp2);
    % Component wise
    wminus = -(1/6) *wjm1 + (5/6) *wj + (1/3) *wjp1;
    wplus = (1/3) *wj + (5/6) *wjp1 - (1/6) *wjp2;
    %wtilde = wminus - wj;
    %wdoubletilde = wplus + wjp1;
    %wtildemod = minmod3System(wtilde, wjp1 - wj, wj - wjm1);
    %wdoubletildemod = minmod3System(wdoubletilde, wjp2 - wjp1, wjp1 - wj);
    %wminusmod = wj + wtildemod;
    %wplusmod = wjp1 - wdoubletildemod;
    %F(:,j) = a*(wminusmod - wplusmod) + 0.5*(f(wminusmod) + f(wplusmod));
    % Characteristic Wise
    % reference solution
    wtilde = 0.5*(wj + wjp1);
    R = RFunc(wtilde);
    Lambda = LambdaFunc(wtilde);
    a = max(max(abs(Lambda)));
    vjm1 = R \setminus wjm1;
    vj = R \setminus wj;
    vjp1 = R \setminus wjp1;
    vjp2 = R \setminus wjp2;
    vminus = -(1/6) * vjm1 + (5/6) * vj + (1/3) * vjp1;
    vplus = (1/3) * vj + (5/6) * vjp1 - (1/6) * vjp2;
    vtilde = vminus - vj;
    vdoubletilde = vplus + vjp1;
    vtildemod = minmod3System(vtilde, vjp1 - vj, vj - vjm1);
    vdoubletildemod = minmod3System(vdoubletilde, vjp2 - vjp1, vjp1 - vj);
    vminusmod = vj + vtildemod;
    vplusmod = vjp1 - vdoubletildemod;
    wminus = R*vminusmod;
    wplus = R*vplusmod;
    %w1 = wminus - wj;
    %w2 = wplus - wj;
    %F(:,j) = f(wj + minmodSystem(w1,w2));
    F(:,j) = a*(wminus - wplus) + 0.5*(f(wminus) + f(wplus));
end
```

I use the following RK3 method.

```
function [sol] = rungeKutta3(L, t, w0)
            [nEqns, nCells] = size(w0);
           nTimeSteps = length(t)-1;
           deltaT = diff(t);
           k = zeros(nEqns, nCells, 3);
           sol = zeros(nEqns, nCells, nTimeSteps+1);
           sol(:,:,1) = w0;
           alpha = [1/6, 2/3, 1/6];
           lambda = [0, 0, 0; 1/2, 0, 0; -1, 2, 0];
           for n = 1:nTimeSteps
                       k(:,:,1) = L(t(n), sol(:, :, n));
                       k(:,:,2) = L(t(n) + sum(lambda(2,:))*deltaT(n), sol(:,:,n) + deltaT(n)*lambda
                                 \hookrightarrow (2,1) *k(:,:,1));
                       k(:,:,3) = L(t(n) + sum(lambda(3,:))*deltaT(n), sol(:,:,n) + deltaT(n)*(lambda(3,:))*deltaT(n), sol(:,:,n) + deltaT(n)*(lambda(3,:))*deltaT(n), sol(:,:,n) + deltaT(n)*(lambda(3,:))*deltaT(n), sol(:,:,n) + deltaT(n)*(lambda(3,:))*deltaT(n), sol(:,:,n) + deltaT(n)*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(lambda(3,:))*(la
                                  \hookrightarrow (3,1)*k(:,:,1) + lambda(3,2)*k(:,:,2)));
                       sol(:,:,n+1) = sol(:,:,n) + deltaT(n) * (alpha(1) * k(:,:,1) + alpha(2) * k(:,:,2) +
                                  \hookrightarrow alpha(3) *k(:,:,3));
                       disp(n/nTimeSteps);
           end
                 alpha = [1, 0, 0; 3/4, 1/4, 0; 1/3, 0, 2/3];
                beta = [1, 0, 0; 0, 1/4, 0; 0, 0, 2/3];
                 for n = 1:nTimeSteps
                            k(:,:,1) = sol(:,:,n) + beta(1,1)*deltaT(n)*L(t(n), sol(:,:,n));
                            k(:,:,2) = alpha(2,1)*sol(:,:,n) + alpha(2,2)*k(:,:,1) + beta(2,2)*deltaT(n)*
          \hookrightarrow L(t(n),k(:,:,1));
응
                            k(:,:,3) = alpha(3,1)*sol(:,:,n) + alpha(3,3)*k(:,:,2) + beta(3,3)*deltaT(n)*
           \hookrightarrow L(t(n),k(:,:,2));
응
                             sol(:,:,n+1) = k(:,:,3);
응
                            disp(n/nTimeSteps);
                 end
end
```

This script now uses the previous methods to solve the given problem.

```
 g = 1.4; \\ energyFuncPrimitive = @(rho, u, P) P/(g - 1) + 0.5*rho*u^2; \\ energyFunc = @(rho, m, P) P/(g - 1) + 0.5*m^2/rho; \\ pressureFuncPrimitive = @(rho, u, E) (g - 1)*(E - 0.5*rho*u^2); \\ pressureFunc = @(rho, m, E) (g - 1)*(E - 0.5*m^2/rho);
```

```
rhoL = 1;
uL = 0;
mL = rhoL*uL;
PL = 1;
EL = energyFuncPrimitive(rhoL, uL, PL);
rhoR = 0.125;
uR = 0;
mR = rhoR*uR;
PR = 0.1;
ER = energyFuncPrimitive(rhoR, uR, PR);
w0func = @(x) [rhoL, mL, EL]'*(x \le 0) + [rhoR, mR, ER]'*(x > 0);
a = -5;
b = 5;
fConservative = @(rho, m, E) [m; m^2/rho + pressureFunc(rho, m, E); m/rho*(E +
   \hookrightarrow pressureFunc(rho, m, E))];
fPrimitive = @(rho, u, P) [rho*u; rho*u^2 + P; u*(energyFuncPrimitive(rho, u, P) + P)];
f = Q(w) fConservative(w(1), w(2), w(3));
N = 1000;
tFinal = 2.0;
deltaX = (b - a)/N;
x = linspace(a+0.5*deltaX, b-0.5*deltaX, N);
w0 = w0func(x);
RPrimitive = @(\text{rho}, u, P) [1, 1, 1; u - \text{sqrt}(g*P/\text{rho}), u, u + \text{sqrt}(g*P/\text{rho}); g/(g - 1)*
   \hookrightarrow P/rho + u^2/2 - u*sqrt(g*P/rho), 0.5*u^2, g/(g - 1)*P/rho + u^2/2 - u*sqrt(g*P/
   \hookrightarrow rho)];
RConservative = @(rho, m, E) RPrimitive(rho, m/rho, pressureFunc(rho, m, E));
RFunc = @(w) RConservative(w(1), w(2), w(3));
multByR = @(w) RFunc(w) *w;
%multByRInverse = @(w) RFunc(w)\w;
LambdaConservative = @(rho, m, E) LambdaPrimitive(rho, m/rho, pressureFunc(rho, m, E));
LambdaFunc = @(w) LambdaConservative(w(1), w(2), w(3));
multByLambda = @(w) LambdaFunc(w) *w;
cfl = 0.1;
deltaT = cfl*deltaX;
nTimeSteps = ceil(tFinal/deltaT);
deltaT = tFinal/nTimeSteps;
t = 0:deltaT:tFinal;
%v0 = multByRInverse(w0);
L = @(t, u) muscl3System(u, f, deltaX, deltaT, RFunc, LambdaFunc);
%rk3 = NumericalAnalysis.ODES.standardRK3Method;
%sol = rk3.solveSystem(L, t, w0);
sol = rungeKutta3(L, t, w0);
rho = sol(1,:,end);
u = sol(2, :, end)./sol(1, :, end);
p = (g - 1) * (sol(3,:,end) - 0.5*rho.*u.^2);
subplot(3, 1, 1);
plot(x, rho, 'LineWidth', 2);
xlabel('x');
ylabel('rho');
title('Density');
subplot(3, 1, 2);
```

```
plot(x, u, 'LineWidth', 2);
xlabel('x');
ylabel('u');
title('Velocity');
subplot(3, 1, 3);
plot(x, p, 'LineWidth', 2);
xlabel('x');
ylabel('P');
title('Pressure');
saveas(gcf, 'Figures/finalProject.png', 'png');
figure;
plot(x, sol(:, :,end), 'k--', 'LineWidth', 2);
xlabel('x');
ylabel('w');
title(strcat('Euler equations at t = ', num2str(tFinal)));
saveas(gcf, 'Figures/finalProject_2.png', 'png');
```

The following image is output.

