

Hybridized Discontinuous Galerkin Method

These notes are intended to give background on Hybridized Discontinuous Galerkin methods and then explore how to apply this method to Thin Film Equations

1 Introduction/Main Idea

To start we will consider Poisson's equation with Dirichlet boundary conditions

$$\begin{aligned} -\Delta u &= f & \text{in } \Omega \\ u &= g & \text{on } \partial\Omega \end{aligned}$$

We will consider this in mixed form by introducing the auxiliary variable $\mathbf{q} = -\nabla u$, then the equation becomes

$$\begin{aligned} \mathbf{q} + \nabla u &= 0 & \text{in } \Omega \\ \nabla \cdot \mathbf{q} &= f & \text{in } \Omega \\ u &= g & \text{on } \partial\Omega \end{aligned}$$

This problem has an exact solution that can be found analytically assuming some nice properties.

I will introduce a triangulation of Ω , \mathcal{T}_h , and reformulate the problem on this triangulation that will give the same exact solution.

1.1 Notation

First some notation,

$$\begin{aligned} \partial\mathcal{T}_h &= \{\partial K : K \in \mathcal{T}_h\} \\ F &= \partial K \cap \partial\Omega \text{ for } K \in \mathcal{T}_h \\ F &= \partial K^+ \cap \partial K^- \text{ for } K^+, K^- \in \mathcal{T}_h \end{aligned}$$

Let ε_h be the set of all faces, F , and ε_h^0 be interior faces, and ε_h^∂ be boundary faces.

Let \mathbf{n}^+ and \mathbf{n}^- be the outward unit normals of ∂K^+ and ∂K^- respectively, and (\mathbf{q}^\pm, u^\pm) be the interior values of (\mathbf{q}, u) on F for K^\pm . Define

$$\begin{aligned} \llbracket \mathbf{q} \cdot \mathbf{n} \rrbracket &= \mathbf{q}^+ \cdot \mathbf{n}^+ + \mathbf{q}^- \cdot \mathbf{n}^- \\ \llbracket u \mathbf{n} \rrbracket &= u^+ \mathbf{n}^+ + u^- \mathbf{n}^- \\ \{\mathbf{q}\} &= \frac{\mathbf{q}^+ + \mathbf{q}^-}{2} \\ \{u\} &= \frac{u^+ + u^-}{2} \end{aligned}$$

1.2 Reformulation

Now we can reformulate the original Poisson's problem on \mathcal{T}_h as a local problem for each K

$$\begin{aligned} \mathbf{q} + \nabla u &= 0 \\ \nabla \cdot \mathbf{q} &= f \end{aligned}$$

a transmission condition on each interior face, $F \in \varepsilon_h^0$

$$\begin{aligned} \llbracket u \mathbf{n} \rrbracket &= 0 \\ \llbracket \mathbf{q} \cdot \mathbf{n} \rrbracket &= 0 \end{aligned}$$

and the boundary condition on each boundary face, $F \in \varepsilon_h^\partial$

$$u = g$$

This problem is equivalent to the original problem on Ω . The (\mathbf{q}, u) that satisfies this problem also solve the original problem.

We would like to be able to solve the local problem locally, but this requires boundary conditions on each element K for the local problem to be solved. Therefore consider the local problem

$$\begin{aligned}\mathbf{q} + \nabla u &= 0 & \text{in } K \\ \nabla \cdot \mathbf{q} &= f & \text{in } K \\ u &= \hat{u} & \text{on } \partial K\end{aligned}$$

We have introduced another unknown \hat{u} on each interior face $F \in \varepsilon_h^0$. This unknown automatically makes us satisfy $\llbracket u\mathbf{n} \rrbracket = \mathbf{0}$, so the transmission condition becomes

$$\llbracket \mathbf{q} \cdot \mathbf{n} \rrbracket = 0 \quad \text{on } F \in \varepsilon_h^0$$

and we still have the boundary condition

$$u = g \quad \text{on } F \in \varepsilon_h^\partial$$

Now solving for (\mathbf{q}, u, \hat{u}) will give the same solution as the original problem, however \mathbf{q} and u can be solved locally and only \hat{u} needs to be solved globally.

1.3 General Algorithm

Here is the outline for solving for \mathbf{q} , u , and \hat{u} . First split the local problem in two, so that one part depends on f and the other part depends on \hat{u} , that is let $\mathbf{q} = \mathbf{Q}_f + \mathbf{Q}_{\hat{u}}$ and $u = U_f + U_{\hat{u}}$, where

$$\begin{aligned}\mathbf{Q}_f + \nabla U_f &= 0 & \text{in } K \\ \nabla \cdot \mathbf{Q}_f &= f & \text{in } K \\ U_f &= 0 & \text{on } \partial K\end{aligned}$$

and

$$\begin{aligned}\mathbf{Q}_{\hat{u}} + \nabla U_{\hat{u}} &= 0 & \text{in } K \\ \nabla \cdot \mathbf{Q}_{\hat{u}} &= 0 & \text{in } K \\ U_{\hat{u}} &= \hat{u} & \text{on } \partial K\end{aligned}$$

Now the transmission condition becomes

$$\llbracket \mathbf{Q}_{\hat{u}} \rrbracket = -\llbracket \mathbf{Q}_f \rrbracket$$

First solve for \mathbf{Q}_f exactly, then solve for $\mathbf{Q}_{\hat{u}}$ in terms of \hat{u} . Now the transmission condition gives a global linear algebra problem

$$\llbracket \mathbf{Q}_{\hat{u}} \rrbracket = -\llbracket \mathbf{Q}_f \rrbracket$$

since $\llbracket \mathbf{Q}_{\hat{u}} \rrbracket$ is a linear system in \hat{u} and $-\llbracket \mathbf{Q}_f \rrbracket$ is known.

After this linear algebra problem is solved, the values of $U_{\hat{u}}$ and $\mathbf{Q}_{\hat{u}}$ can be found/reconstructed locally. The full solution is then $\mathbf{q} = \mathbf{Q}_f + \mathbf{Q}_{\hat{u}}$ and $u = U_f + U_{\hat{u}}$.

1.4 1D example

In 1D, the problem becomes

$$\begin{aligned}Q_f + U'_f &= 0 & \text{in } K \\ Q'_f &= f & \text{in } K \\ U_f &= 0 & \text{on } \partial K\end{aligned}$$

and

$$\begin{aligned} Q_{\hat{u}} + U'_{\hat{u}} &= 0 & \text{in } K \\ Q'_{\hat{u}} &= 0 & \text{in } K \\ U_{\hat{u}} &= \hat{u} & \text{on } \partial K \end{aligned}$$

and

$$Q_{\hat{u}}(x_{j+1/2}^-) - Q_{\hat{u}}(x_{j+1/2}^+) = -Q_f(x_{j+1/2}^-) + Q_f(x_{j+1/2}^+)$$

where the uniform mesh is given by x_i at cell centers, $x_{i+1/2}$ at cell interfaces, and spacing h .

Solving the \hat{u} system we see that

$$\begin{aligned} Q'_{\hat{u}} &= 0 \\ Q_{\hat{u}} &= c \end{aligned}$$

and

$$\begin{aligned} Q_{\hat{u}} + U'_{\hat{u}} &= 0 \\ U'_{\hat{u}} &= -c \\ U_{\hat{u}} &= -cx + b \end{aligned}$$

with the boundary conditions, we know $U_{\hat{u}}$ is a line from $\hat{u}_{j-1/2}$ to $\hat{u}_{j+1/2}$, and $Q_{\hat{u}}$ is the opposite of the slope of this line.

$$\begin{aligned} U_{\hat{u}} &= \frac{\hat{u}_{j+1/2} - \hat{u}_{j-1/2}}{h} (x - x_{j-1/2}) - \hat{u}_{j-1/2} \\ Q_{\hat{u}} &= -\frac{\hat{u}_{j+1/2} - \hat{u}_{j-1/2}}{h} \end{aligned}$$

Now we can form the linear system given by the transmission condition

$$\begin{aligned} Q_{\hat{u}}(x_{j+1/2}^-) - Q_{\hat{u}}(x_{j+1/2}^+) &= -Q_f(x_{j+1/2}^-) + Q_f(x_{j+1/2}^+) \\ -\frac{\hat{u}_{j+1/2} - \hat{u}_{j-1/2}}{h} + \frac{\hat{u}_{j+3/2} - \hat{u}_{j+1/2}}{h} &= -Q_f(x_{j+1/2}^-) + Q_f(x_{j+1/2}^+) \\ \frac{\hat{u}_{j-1/2} - 2\hat{u}_{j+1/2} + \hat{u}_{j+3/2}}{h} &= -Q_f(x_{j+1/2}^-) + Q_f(x_{j+1/2}^+) \end{aligned}$$

After solving this linear system we already have expressions for $Q_{\hat{u}}$ and $U_{\hat{u}}$ in terms of \hat{u} .

2 Hybridizable Discontinuous Galerkin Method

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