

# Derivation of Shallow Water Equations

We begin by considering the Navier-Stokes equations,

$$\nabla \cdot \mathbf{u} = 0 \quad (1)$$

$$\mathbf{u}_t + \nabla * \mathbf{u}\mathbf{u} = -\frac{1}{\rho}\nabla p + \frac{1}{\rho}\nabla \sigma + \mathbf{g}, \quad (2)$$

where  $\mathbf{u} = [u, v, w]^T$  is the vector of velocities,  $p$  is the pressure,  $\rho$  is the constant density,  $\sigma$  is the deviatoric stress tensor, and  $\mathbf{g}$  is the gravitational force vector. We also have two boundaries, the bottom topography  $h_b(t, x, y)$ , and the free surface  $h_s(t, x, y)$ . At both of these boundaries the kinematic boundary conditions are in effect and can be expressed as

$$(h_s)_t + [u(t, x, y, h_s), v(t, x, y, h_s)]^T \cdot \nabla h_s = w(t, x, y, h_s) \quad (3)$$

$$(h_b)_t + [u(t, x, y, h_b), v(t, x, y, h_b)]^T \cdot \nabla h_b = w(t, x, y, h_b). \quad (4)$$

In practice the bottom topography is unchanging in time, but we express  $h_b$  with time dependence to allow for a symmetric representation of the boundary conditions.

## 1 Dimensional Analysis

Now we consider the characteristic scales of the problem. Let  $L$  be the characteristic horizontal length scale, and let  $H$  be the characteristic vertical length scale. For this problem we assume that  $H \ll L$  and we denote the ratio of these lengths as  $\varepsilon = H/L$ . With these characteristic lengths we can scale the length variables to a nondimensional form

$$x = L\hat{x}, \quad y = L\hat{y}, \quad z = H\hat{z}. \quad (5)$$

Now let  $U$  be the characteristic horizontal velocity, then because of the shallowness the characteristic vertical velocity will be  $\varepsilon U$ . Therefore the velocity variables can be scaled as follows,

$$u = U\hat{u}, \quad v = U\hat{v}, \quad w = \varepsilon U\hat{w}. \quad (6)$$

Now with the characteristic length and velocity, the time scaling can be described as

$$t = \frac{L}{U}\hat{t} \quad (7)$$

The pressure will be scaled by the characteristic height,  $H$ , and the stresses will be scaled by a characteristic stress,  $S$ . It is assumed that the basal shear stresses,  $\sigma_{xz}$  and  $\sigma_{yz}$  are of larger order than the lateral shear stress,  $\sigma_{xy}$ , and the normal stresses,  $\sigma_{xx}$ ,  $\sigma_{yy}$ , and  $\sigma_{zz}$ , so that

$$p = \rho g H \hat{p}, \quad \sigma_{xz/yz} = S \hat{\sigma}_{xz/yz}, \quad \sigma_{xx/xy/yy/zz} = \varepsilon S \hat{\sigma}_{xx/xy/yy/zz}. \quad (8)$$

$$\begin{aligned} \nabla \cdot \mathbf{u} &= 0 \\ \mathbf{u}_t + \nabla * \mathbf{u}\mathbf{u} &= -\frac{1}{\rho}\nabla p + \frac{1}{\rho}\nabla \sigma + \mathbf{g}, u_x + v_y + w_z = 0 \\ u_t + (u^2)_x + (uv)_y + (uw)_z &= -\frac{1}{\rho}p_x + \frac{1}{\rho}\left((\sigma_{xx})_x + (\sigma_{xy})_y + (\sigma_{xz})_z\right) + ge_x \\ v_t + (uv)_x + (v^2)_y + (vw)_z &= -\frac{1}{\rho}p_y + \frac{1}{\rho}\left((\sigma_{xy})_x + (\sigma_{yy})_y + (\sigma_{yz})_z\right) + ge_y \\ w_t + (uw)_x + (vw)_y + (w^2)_z &= -\frac{1}{\rho}p_z + \frac{1}{\rho}\left((\sigma_{xz})_x + (\sigma_{yz})_y + (\sigma_{zz})_z\right) + ge_z \end{aligned}$$

$$\begin{aligned}
u_x &= (U\hat{u})_x = (U\hat{u})_{\hat{x}}\hat{x}_x = \frac{U}{L}\hat{u}_{\hat{x}} \\
v_y &= (U\hat{v})_{\hat{y}}\hat{y}_y = \frac{U}{L}\hat{v}_{\hat{y}} \\
w_z &= (\varepsilon U\hat{w})_{\hat{z}}\hat{z}_z = \frac{\varepsilon U}{H}\hat{w}_{\hat{z}} = \frac{U}{L}\hat{w}_{\hat{z}} \\
u_x + v_y + w_z &= \frac{U}{L}\hat{u}_{\hat{x}} + \frac{U}{L}\hat{v}_{\hat{y}} + \frac{U}{L}\hat{w}_{\hat{z}} = 0 \\
\hat{u}_{\hat{x}} + \hat{v}_{\hat{y}} + \hat{w}_{\hat{z}} &= 0 \\
u_t &= (U\hat{u})_{\hat{t}}\hat{t}_t = \frac{U^2}{L}\hat{u}_{\hat{t}} \\
v_t &= (U\hat{v})_{\hat{t}}\hat{t}_t = \frac{U^2}{L}\hat{v}_{\hat{t}} \\
w_t &= (\varepsilon U\hat{w})_{\hat{t}}\hat{t}_t = \varepsilon \frac{U^2}{L}\hat{w}_{\hat{t}} \\
(u^2)_x &= (U^2\hat{u}^2)_{\hat{x}}\hat{x}_x = \frac{U^2}{L}(\hat{u}^2)_{\hat{x}} \\
(uv)_y &= (U^2\hat{u}\hat{v})_{\hat{y}}\hat{y}_y = \frac{U^2}{L}(\hat{u}\hat{v})_{\hat{y}} \\
(uw)_z &= (\varepsilon U^2\hat{u}\hat{w})_{\hat{z}}\hat{z}_z = \frac{U^2}{L}(\hat{u}\hat{w})_{\hat{z}} \\
(uv)_x &= (U^2\hat{u}\hat{v})_{\hat{x}}\hat{x}_x = \frac{U^2}{L}(\hat{u}\hat{v})_{\hat{x}} \\
(v^2)_y &= (U^2\hat{v}^2)_{\hat{y}}\hat{y}_y = \frac{U^2}{L}(\hat{v}^2)_{\hat{y}} \\
(vw)_z &= (\varepsilon U^2\hat{v}\hat{w})_{\hat{z}}\hat{z}_z = \frac{U^2}{L}(\hat{v}\hat{w})_{\hat{z}} \\
(uw)_x &= (\varepsilon U^2\hat{u}\hat{w})_{\hat{x}}\hat{x}_x = \varepsilon \frac{U^2}{L}(\hat{u}\hat{w})_{\hat{x}} \\
(vw)_y &= (\varepsilon U^2\hat{v}\hat{w})_{\hat{y}}\hat{y}_y = \varepsilon \frac{U^2}{L}(\hat{v}\hat{w})_{\hat{y}} \\
(w^2)_z &= (\varepsilon^2 U^2\hat{w}^2)_{\hat{z}}\hat{z}_z = \varepsilon \frac{U^2}{L}(\hat{w}^2)_{\hat{z}}
\end{aligned}$$

$$\begin{aligned}
\frac{1}{\rho}p_x &= \frac{1}{\rho}(\rho g H \hat{p})_{\hat{x}} \hat{x}_x = \frac{\varepsilon g L}{L} \hat{p}_{\hat{x}} = \varepsilon g \hat{p}_{\hat{x}} \\
\frac{1}{\rho}p_y &= \frac{1}{\rho}(\rho g H \hat{p})_{\hat{y}} \hat{y}_y = \frac{\varepsilon g L}{L} \hat{p}_{\hat{y}} = \varepsilon g \hat{p}_{\hat{y}} \\
\frac{1}{\rho}p_z &= \frac{1}{\rho}(\rho g H \hat{p})_{\hat{z}} \hat{z}_z = \frac{\varepsilon g L}{\varepsilon L} \hat{p}_{\hat{z}} = g \hat{p}_{\hat{z}} \\
\frac{1}{\rho}(\sigma_{xx})_x &= \frac{1}{\rho}(\varepsilon S \hat{\sigma}_{xx})_{\hat{x}} \hat{x}_x = \varepsilon \frac{S}{\rho L} (\hat{\sigma}_{xx})_{\hat{x}} \\
\frac{1}{\rho}(\sigma_{xy})_y &= \frac{1}{\rho}(\varepsilon S \hat{\sigma}_{xy})_{\hat{y}} \hat{y}_y = \varepsilon \frac{S}{\rho L} (\hat{\sigma}_{xy})_{\hat{y}} \\
\frac{1}{\rho}(\sigma_{xz})_z &= \frac{1}{\rho}(S \hat{\sigma}_{xz})_{\hat{z}} \hat{z}_z = \frac{S}{\rho H} (\hat{\sigma}_{xz})_{\hat{z}} \\
\frac{1}{\rho}(\sigma_{xy})_x &= \frac{1}{\rho}(\varepsilon S \hat{\sigma}_{xy})_{\hat{x}} \hat{x}_x = \varepsilon \frac{S}{\rho L} (\hat{\sigma}_{xy})_{\hat{x}} \\
\frac{1}{\rho}(\sigma_{yy})_y &= \frac{1}{\rho}(\varepsilon S \hat{\sigma}_{yy})_{\hat{y}} \hat{y}_y = \varepsilon \frac{S}{\rho L} (\hat{\sigma}_{yy})_{\hat{y}} \\
\frac{1}{\rho}(\sigma_{yz})_z &= \frac{1}{\rho}(S \hat{\sigma}_{yz})_{\hat{z}} \hat{z}_z = \frac{S}{\rho H} (\hat{\sigma}_{yz})_{\hat{z}} \\
\frac{1}{\rho}(\sigma_{xz})_x &= \frac{1}{\rho}(S \hat{\sigma}_{xz})_{\hat{x}} \hat{x}_x = \frac{S}{\rho L} (\hat{\sigma}_{xz})_{\hat{x}} \\
\frac{1}{\rho}(\sigma_{yz})_y &= \frac{1}{\rho}(S \hat{\sigma}_{yz})_{\hat{y}} \hat{y}_y = \frac{S}{\rho L} (\hat{\sigma}_{yz})_{\hat{y}} \\
\frac{1}{\rho}(\sigma_{zz})_z &= \frac{1}{\rho}(\varepsilon S \hat{\sigma}_{zz})_{\hat{z}} \hat{z}_z = \varepsilon \frac{S}{\rho H} (\hat{\sigma}_{zz})_{\hat{z}} \frac{U^2}{L} \hat{u}_{\hat{t}} + \frac{U^2}{L} (\hat{u}^2)_{\hat{x}} + \frac{U^2}{L} (\hat{u} \hat{v})_{\hat{y}} + \frac{U^2}{L} (\hat{u} \hat{w})_{\hat{z}} = -\varepsilon g \hat{p}_{\hat{x}} \\
\frac{U^2}{L} \hat{v}_{\hat{t}} + \frac{U^2}{L} (\hat{u} \hat{v})_{\hat{x}} + \frac{U^2}{L} (\hat{v}^2)_{\hat{y}} + \frac{U^2}{L} (\hat{v} \hat{w})_{\hat{z}} &= -\varepsilon g \hat{p}_{\hat{y}} + \varepsilon \frac{S}{\rho L} (\hat{\sigma}_{xy})_{\hat{x}} + \varepsilon \frac{S}{\rho L} (\hat{\sigma}_{yy})_{\hat{y}} + \frac{S}{\rho H} (\hat{\sigma}_{yz})_{\hat{z}} + g e_y \\
\varepsilon \frac{U^2}{L} \hat{w}_{\hat{t}} + \varepsilon \frac{U^2}{L} (\hat{u} \hat{w})_{\hat{x}} + \varepsilon \frac{U^2}{L} (\hat{v} \hat{w})_{\hat{y}} + \varepsilon \frac{U^2}{L} (\hat{w}^2)_{\hat{z}} &= -g \hat{p}_{\hat{z}} + \frac{S}{\rho L} (\hat{\sigma}_{xz})_{\hat{x}} \left( (\sigma_{xz})_x + (\sigma_{yz})_y + (\sigma_{zz})_z \right) + g e_z
\end{aligned}$$

Substituting all of these scaled variables into the Navier-Stokes system gives,

$$\begin{aligned}
\hat{u}_{\hat{x}} + \hat{v}_{\hat{y}} + \hat{w}_{\hat{z}} &= 0 \\
\frac{U^2}{gL} \left( \hat{u}_{\hat{t}} + (\hat{u}^2)_{\hat{x}} + (\hat{u} \hat{v})_{\hat{y}} + (\hat{u} \hat{w})_{\hat{z}} \right) &= -\varepsilon \hat{p}_{\hat{x}} + \frac{S}{\rho g L} \left( \varepsilon (\hat{\sigma}_{xx})_{\hat{x}} + \varepsilon (\hat{\sigma}_{xy})_{\hat{y}} + (\hat{\sigma}_{xz})_{\hat{z}} \right) + e_x \\
\frac{U^2}{gL} \left( \hat{v}_{\hat{t}} + (\hat{u} \hat{v})_{\hat{x}} + (\hat{v}^2)_{\hat{y}} + (\hat{v} \hat{w})_{\hat{z}} \right) &= -\varepsilon \hat{p}_{\hat{y}} + \frac{S}{\rho g L} \left( \varepsilon (\hat{\sigma}_{xy})_{\hat{x}} + \varepsilon (\hat{\sigma}_{yy})_{\hat{y}} + (\hat{\sigma}_{yz})_{\hat{z}} \right) + e_y
\end{aligned}$$

$$\begin{aligned}
u_x + v_y + w_z &= 0 \\
u_t + (u^2)_x + (uv)_y + (uw)_z &= -\frac{1}{\rho} p_x + \frac{1}{\rho} (\sigma_{xz})_z + g e_x \\
v_t + (uv)_x + (v^2)_y + (vw)_z &= -\frac{1}{\rho} p_y + \frac{1}{\rho} (\sigma_{yz})_z + g e_y
\end{aligned}$$

## 2 Mapping

In order to make this system more accessible we will map the vertical variable  $z$  to the normalized variable  $\zeta$ , through the transformation

$$\zeta(t, x, y, z) = \frac{z - h_b(t, x, y)}{h(t, x, y)},$$

or equivalently

$$z(t, x, y, \zeta) = h(t, x, y)\zeta + h_b(t, x, y)$$

where  $h(t, x, y) = h_s(t, x, y) - h_b(t, x, y)$ . This transformation maps the vertical variable onto a scale from 0 to 1 everywhere.

Consider a function  $\Psi(t, x, y, z)$ , then its mapped counterpart  $\tilde{\Psi}(t, x, y, \zeta)$  can be described as

$$\tilde{\Psi}(t, x, y, \zeta) = \Psi(t, x, y, z(t, x, y, \zeta)) = \Psi(t, x, y, h(t, x, y)\zeta + h_b(t, x, y)),$$

or equivalently

$$\Psi(t, x, y, z) = \tilde{\Psi}(t, x, y, \zeta(t, x, y, z)) = \tilde{\Psi}\left(t, x, y, \frac{z - h_b(t, x, y)}{h(t, x, y)}\right).$$

We also need to be able to map derivatives of functions in order to be able to map the differential equations. This can be described

$$\begin{aligned}\Psi_z(t, x, y, z) &= \left(\tilde{\Psi}(t, x, y, \zeta(t, x, y, z))\right)_z \\ \Psi_z(t, x, y, z) &= \tilde{\Psi}_\zeta(t, x, y, \zeta(t, x, y, z))\zeta_z(t, x, y, z) \\ \Psi_z(t, x, y, z) &= \tilde{\Psi}_\zeta(t, x, y, \zeta(t, x, y, z))\frac{1}{h(t, x, y)} \\ h(t, x, y)\Psi_z(t, x, y, z) &= \tilde{\Psi}_\zeta(t, x, y, \zeta(t, x, y, z)) \\ h\Psi_z &= \tilde{\Psi}_\zeta\end{aligned}$$

$$\begin{aligned}\Psi_t(t, x, y, z) &= \left(\tilde{\Psi}(t, x, y, \zeta(t, x, y, z))\right)_t \\ \Psi_t(t, x, y, z) &= \tilde{\Psi}_t(t, x, y, \zeta(t, x, y, z)) + \tilde{\Psi}_\zeta(t, x, y, \zeta(t, x, y, z))\zeta_t(t, x, y, z)\end{aligned}$$