

Caleb Logemann

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Hyper-Diffusion

Operator

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Introduction to Discontinuous Galerkin Methods

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Goal

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■ Numerically Solve

$$\begin{aligned} u_t + f(u)_x &= 0 \\ x \in \Omega \subset \mathbb{R}^d \quad t \in \mathbb{R}^+ \end{aligned}$$

■ Weak Solution Find u such that for any test function v

$$\int_0^\infty \int_{\mathbb{R}^d} u_t v + f(u)_x v \, dx \, dt = 0$$

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■ Numerically Solve

$$\begin{aligned} u_t + f(u)_x &= 0 \\ x \in [a, b] \quad t \in \mathbb{R}^+ \end{aligned}$$

■ Weak Solution Find u such that for any test function v

$$\int_0^\infty \int_a^b u_t v + f(u)_x v \, dx \, dt = 0$$

Generate Mesh

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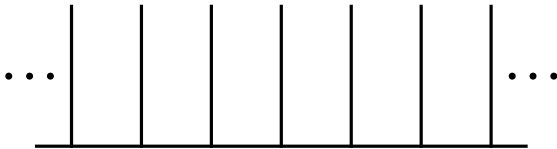
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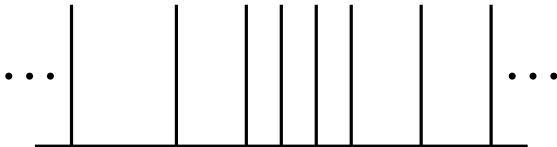
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■ 1D Uniform Grid



■ 1D Variable Grid



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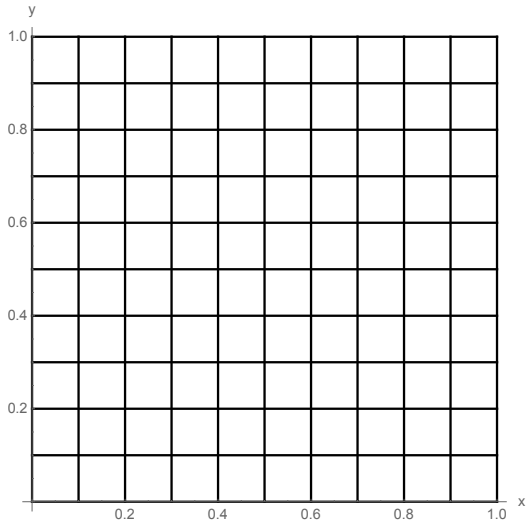
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■ 2D Uniform Grid



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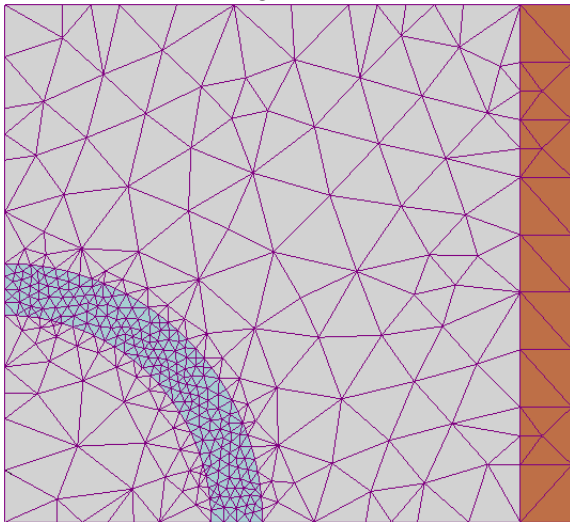
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■ 2D Unstructured Triangulation



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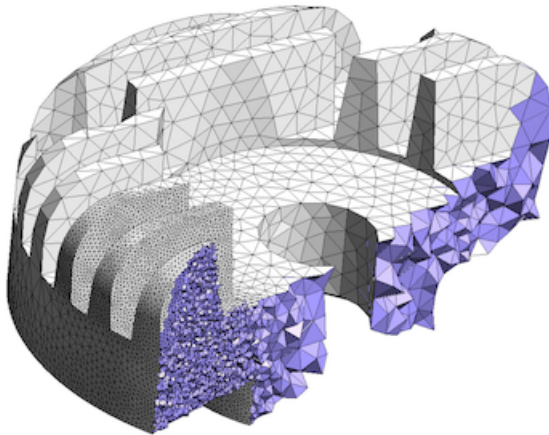
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■ 3D Unstructured Triangulation



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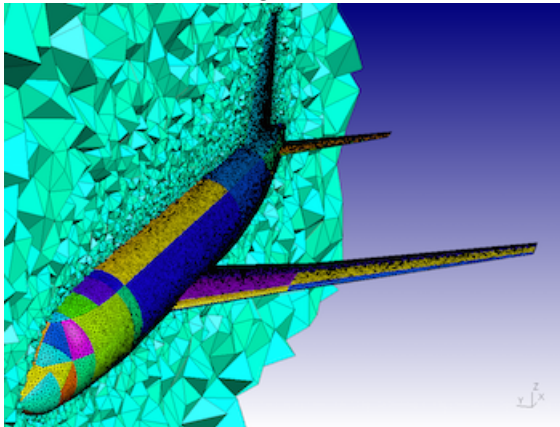
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■ 3D Unstructured Triangulation



Solution Space

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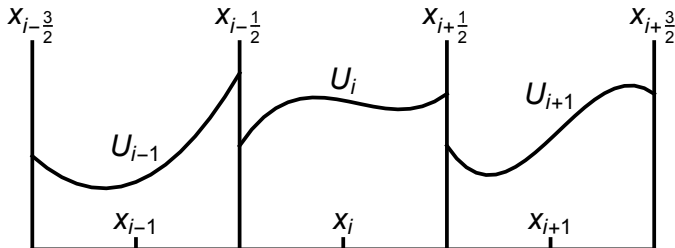
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- Label each element in mesh as I_j , $j = 1, \dots, N$
- Discontinuous Galerkin Finite Element Space

$$V^M = \left\{ u : u|_{I_j} \in P^M(I_j), j = 1, \dots, N \right\}$$



The Method

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- At a given time find $u \in V^M$ such that for all $v \in V^M$ and for all $j = 1, \dots, N$.

$$\int_{I_j} u_t v \, dx + \int_{I_j} f(u)_x v \, dx = 0$$

- Integrate by parts

$$\int_{I_j} u_t v \, dx + \hat{f}_{j+1/2} v_{j+1/2}^- - \hat{f}_{j-1/2} v_{j-1/2}^+ - \int_{I_j} f(u) v_x \, dx = 0$$

- \hat{f} is called the numerical flux
 - Consistent: $\hat{f} u, u$

Numerical Flux

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- Approximating $f(u(x_{j+1/2}, t))$

$$\hat{f}_{j+1/2} = \hat{f}(u_{j+1/2}^-, u_{j+1/2}^+)$$

- Properties

- Consistent: $\hat{f}(u, u) = f(u)$
- Lipschitz Continuous with respect to both arguments
- Monotone: non-decreasing in first argument, non-increasing with second argument

- Examples

- Godunov

$$\hat{f}_{j+1/2} = \begin{cases} \min_{u \in [u^-, u^+]} \{f(u)\} & u^- < u^+ \\ \max_{u \in [u^+, u^-]} \{f(u)\} & u^- \geq u^+ \end{cases}$$

- Rusanov/Local Lax-Friedrichs

$$\hat{f}(u^-, u^+) = \frac{1}{2} (f(u^-) + f(u^+) - \alpha(u^+ - u^-))$$

where $\alpha = \max_u \{|f'(u)|\}$.

Implementation

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- Linear transformation $x \in [x_{j-1/2}, x_{j+1/2}]$ to $\xi \in [-1, 1]$

$$x = \frac{\Delta x}{2} \xi + \frac{x_{j-1/2} + x_{j+1/2}}{2}$$

$$\xi = \frac{2}{\Delta x} \left(x - \frac{x_{j-1/2} + x_{j+1/2}}{2} \right)$$

- Pick a basis for $P^M([-1, 1])$, e.g. Legendre polynomials

$$\frac{1}{2} \int_{-1}^1 \phi^j(\xi) \phi^k(\xi) d\xi = \delta_{jk}$$

$$\phi^1(\xi) = 1 \quad \phi^2(\xi) = \xi \quad \phi^3(\xi) = \sqrt{5}/2(3\xi^2 - 1)$$

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■ Galerkin Expansion

$$u|_{I_j} = \sum_{k=1}^M (U_k \phi^k(\xi))$$

■ Let $v = \phi^j$

$$\begin{aligned} \int_{-1}^1 u_t \phi^j d\xi + \frac{2}{\Delta x} \left(\hat{f}_{j+1/2} \phi^j(1) - \hat{f}_{j-1/2} \phi^j(-1) \right) \\ - \frac{2}{\Delta x} \int_{-1}^1 f(u) \phi_\xi^j d\xi = 0 \end{aligned}$$

■ Using the orthonormality

$$(U_k)_t = \frac{1}{\Delta x} \int_{-1}^1 f(u) \phi_\xi^j d\xi - \frac{1}{\Delta x} \left(\hat{f}_{j+1/2} \phi^j(1) - \hat{f}_{j-1/2} \phi^j(-1) \right)$$

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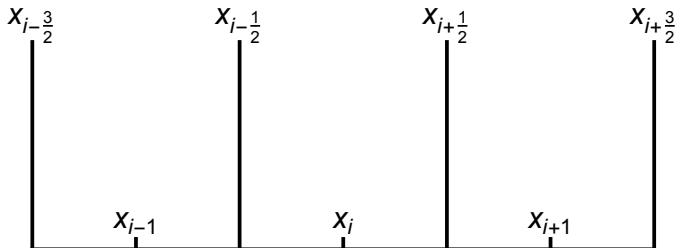
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- Partition the domain, $[a, b]$ as

$$a = x_{1/2} < \cdots < x_{i-1/2} < x_{i+1/2} < \cdots < x_{N+1/2} = b$$

- $V_i = [x_{i-1/2}, x_{i+1/2}]$
- $\Delta x_i = x_{i+1/2} - x_{i-1/2}$
- $x_i = \frac{x_{i+1/2} + x_{i-1/2}}{2}$.



Ongoing Research

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- Create DG methods for certain types of equations
- Strong Stability Preserving (SSP)
- Entropy Solutions
- Positivity Preserving
- Slope/Oscillation Limiting

Motivation

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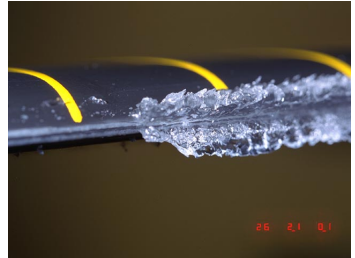
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- Aircraft Icing
- Runback



- Industrial Coating
- Paint Drying

Model Equations

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■ Navier-Stokes Equation

$$\rho_t + (\rho u)_x = 0$$

$$(\rho u)_t + (\rho u^2 + p)_x = \frac{4}{3Re} u_{xx}$$

$$E_t + (u(E + p))_x = \frac{1}{Re} \left(\frac{2}{3} (u^2)_{xx} + \frac{\gamma}{(\gamma - 1)Pr} \left(\frac{p}{\rho} \right)_{xx} \right)$$

■ Asymptotic Limit, $\rho \ll L$

■ Thin-Film Equation - 1D with u as fluid height.

$$u_t + (f(x, t)u^2 - g(x, t)u^3)_x = -(h(x, t)u^3 u_{xxx})_x$$

Current Model

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■ Simplified Expression

$$u_t + (u^2 - u^3)_x = -(u^3 u_{xxx})_x$$

■ Operator Splitting

$$u_t + (u^2 - u^3)_x = 0$$

$$u_t + (u^3 u_{xxx})_x = 0$$

Numerical Solutions

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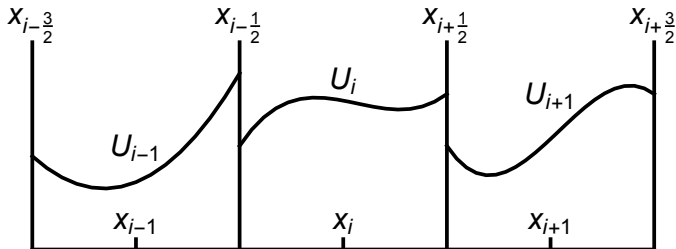
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- Use canonical variable $\xi \in [-1, 1]$
- Let $\{\phi^k(\xi)\}$ be the Legendre polynomials.
- Solution of order M on each cell

$$u|_{x \in V_i} \approx U_i = \sum_{k=1}^M U_i^k \phi^k(\xi)$$



Convection

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■ Convection Equation

$$u_t + \frac{2}{\Delta x} f(u)_\xi = 0$$
$$f(u) = u^2 - u^3$$

■ Weak Form

$$\int_{-1}^1 \left(u_t \phi(\xi) + \frac{2}{\Delta x} f(u)_\xi \phi(\xi) \right) d\xi = 0$$

■ Runge-Kutta Discontinuous Galerkin

$$\dot{U}_i^\ell = \frac{1}{\Delta x} \int_{-1}^1 f(U_i) \phi_\xi^\ell d\xi - \frac{1}{\Delta x} (\mathcal{F}_{i+1/2} - \mathcal{F}_{i-1/2})$$

■ Rusanov Numerical Flux

$$\mathcal{F}_{j+1/2} = \frac{f(U_{i+1}(-1)) + f(U_i(1))}{2} \phi^\ell(1)$$

- Solve this system of ODEs with any Explicit Strong Stability Preserving (SSP) Runge-Kutta Method.

Numerical Example - Square Wave

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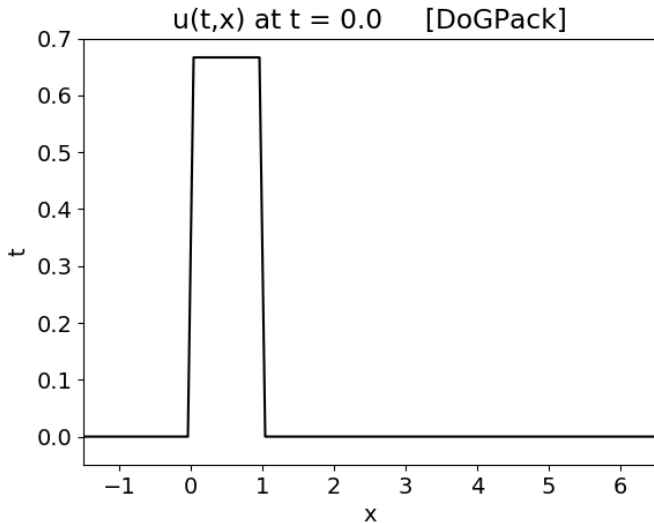
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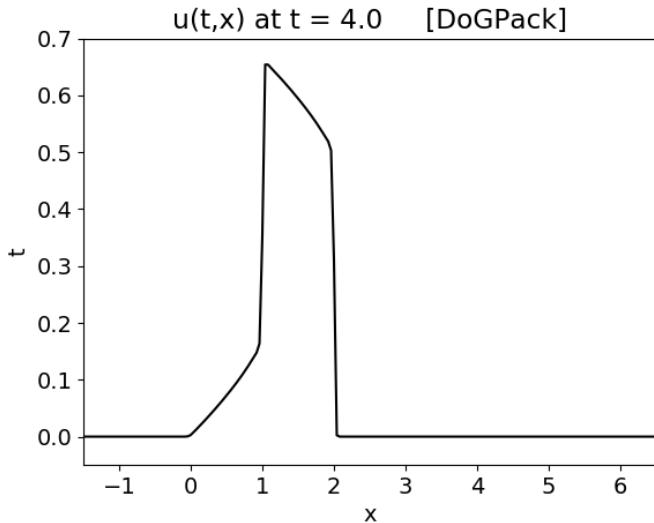
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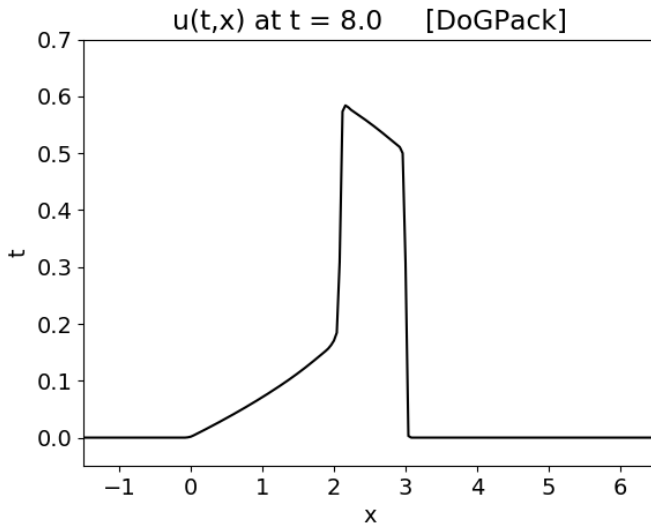
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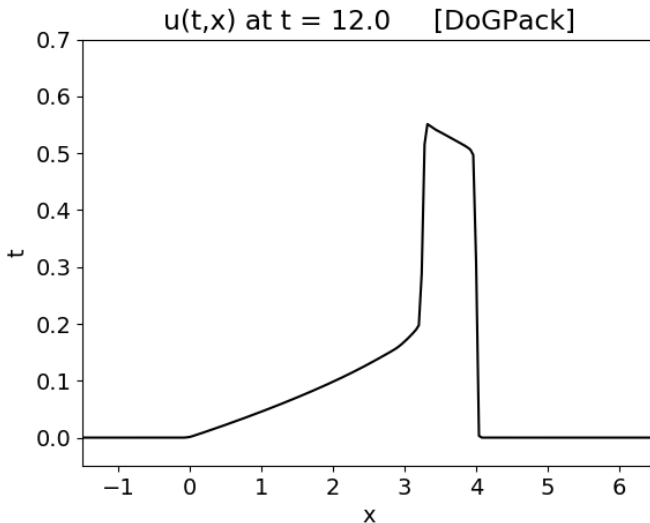
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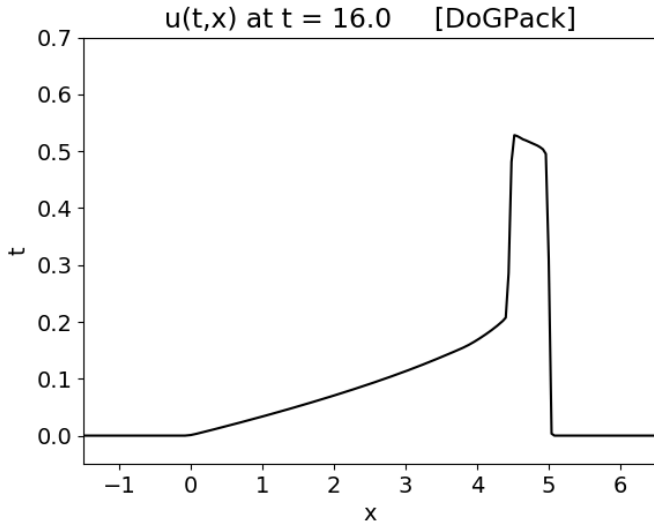
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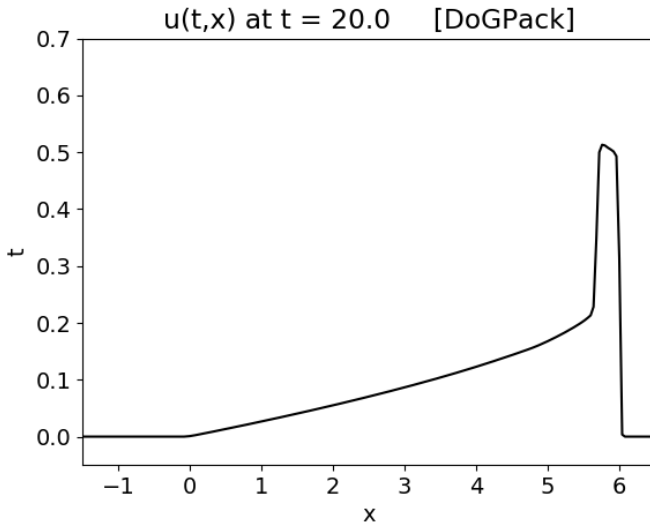
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Hyper-Diffusion

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■ Hyper-Diffusion Equation

$$u_t + \frac{16}{\Delta x^4} (u^3 u_{\xi\xi\xi})_{\xi} = 0$$

■ Local Discontinuous Galerkin (LDG)

$$q = \frac{2}{\Delta x} u_{\xi}$$

$$r = \frac{2}{\Delta x} q_{\xi}$$

$$s = \frac{2}{\Delta x} u^3 r_{\xi}$$

$$u_t = -\frac{2}{\Delta x} s_{\xi}$$

Local Discontinuous Galerkin

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$$\eta(\xi) = (U_i^n)^3$$

$$Q_i^\ell = -\frac{1}{\Delta x} \left(\int_{-1}^1 U_i \phi_\xi^\ell d\xi - \mathcal{F}(U)_{i+1/2}^\ell + \mathcal{F}(U)_{i-1/2}^\ell \right)$$

$$R_i^\ell = -\frac{1}{\Delta x} \left(\int_{-1}^1 Q_i \phi_\xi^\ell d\xi - \mathcal{F}(Q)_{i+1/2}^\ell + \mathcal{F}(Q)_{i-1/2}^\ell \right)$$

$$S_i^\ell = \frac{1}{\Delta x} \left(\int_{-1}^1 (R_i)_\xi \eta(\xi) \phi^\ell d\xi \right) \\ + \frac{1}{\Delta x} \left(\mathcal{F}(\eta)_{i+1/2} \mathcal{F}(R)_{i+1/2}^\ell - \mathcal{F}(\eta)_{i-1/2} \mathcal{F}(R)_{i-1/2}^\ell \right)$$

$$\dot{U}_i^\ell = \frac{1}{\Delta x} \left(\int_{-1}^1 S_i \phi_\xi^\ell d\xi - \mathcal{F}(S)_{i+1/2}^\ell + \mathcal{F}(S)_{i-1/2}^\ell \right)$$

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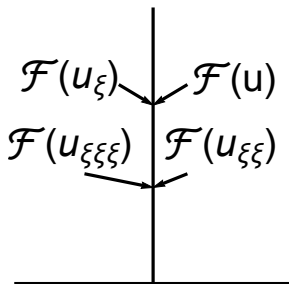
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$$\mathcal{F}(\eta)_{i+1/2} = \frac{1}{2}(\eta_{i+1}(-1) - \eta_i(1))$$

$$\mathcal{F}(\eta)_{i-1/2} = \frac{1}{2}(\eta_{i-1}(1) - \eta_i(-1))$$

$$\mathcal{F}(\ast)_{i+1/2}^\ell = \phi^\ell(1) \ast_{i+1/2}$$



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- Explicit SSP Runge Kutta
 - Severe time step restriction
 - $\Delta t \sim \Delta x^4$
 - $\Delta x = .1 \rightarrow \Delta t \approx 10^{-4}$
 - $\Delta x = .01 \rightarrow \Delta t \approx 10^{-8}$
- Implicit SSP Runge Kutta
 - Linear System Solver
 - Stabilized BiConjugate Gradient
 - MultiGrid Solver

Multigrid Solver

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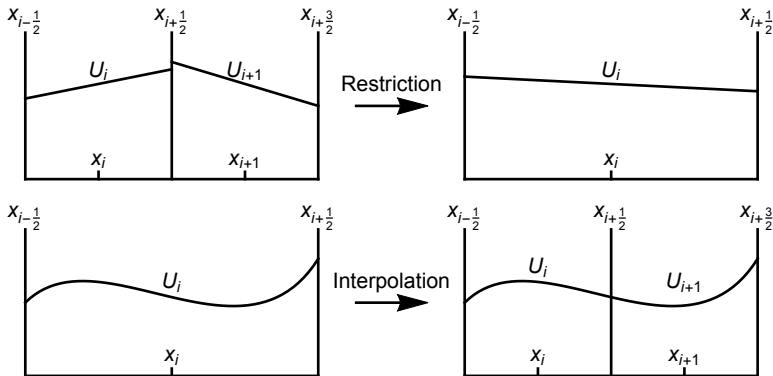
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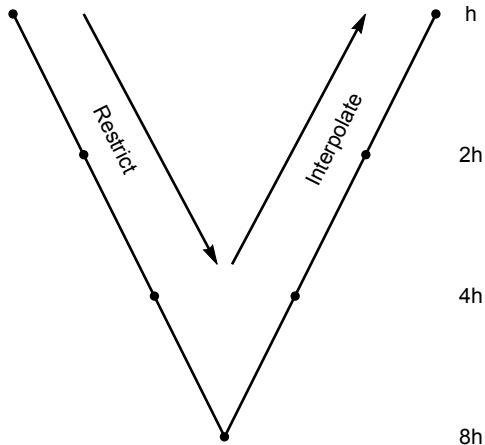
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■ Relaxation e.g. Jacobi Relaxation



Multigrid Solver

V-Cycle



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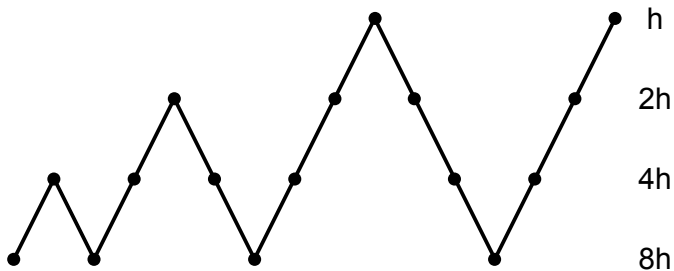
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Operator Splitting

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- Strang Splitting
 - 1 time step
 - $1/2$ time step for convection
 - 1 time step for hyper-diffusion
 - $1/2$ time step for convection
 - Second order splitting

Numerical Results - Riemann Problem

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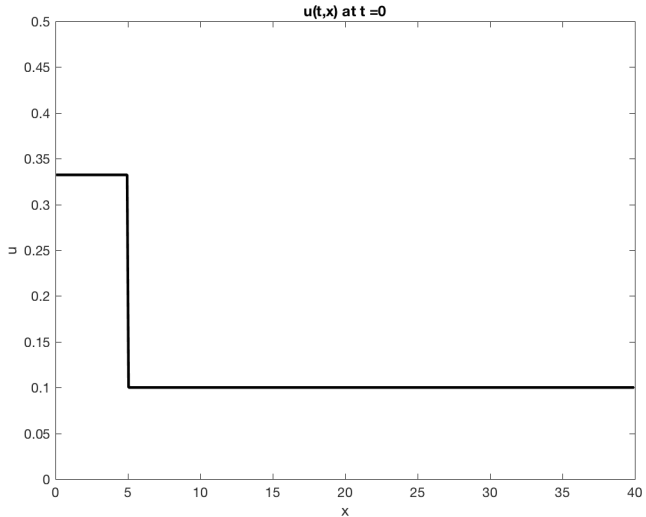
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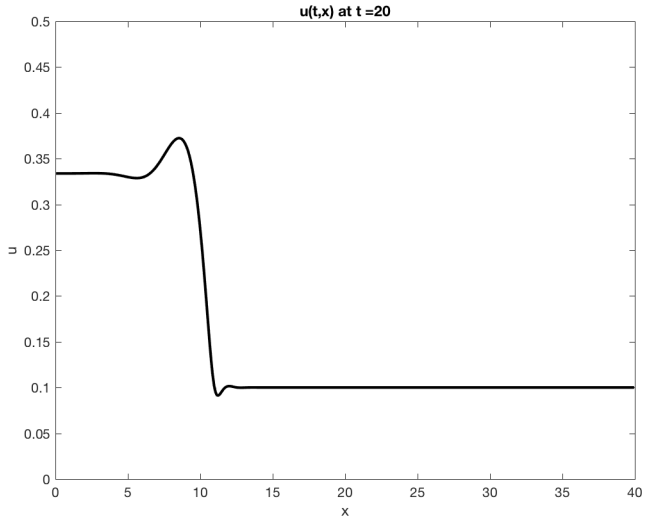
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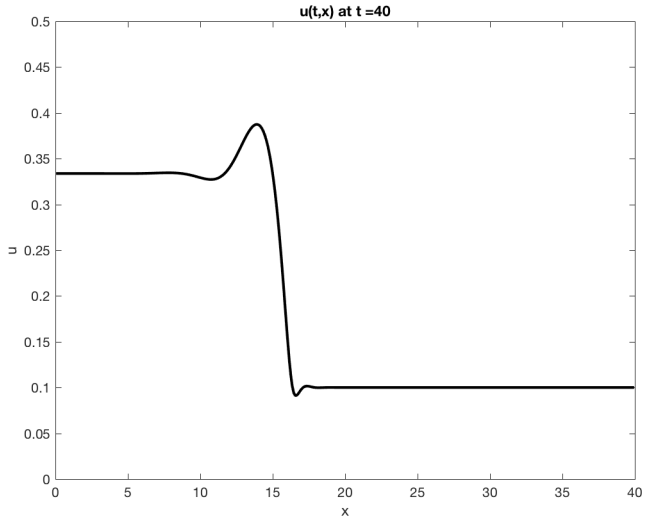
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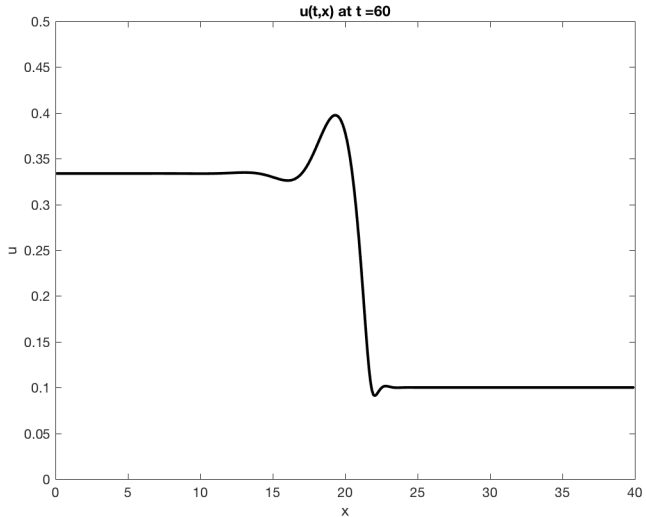
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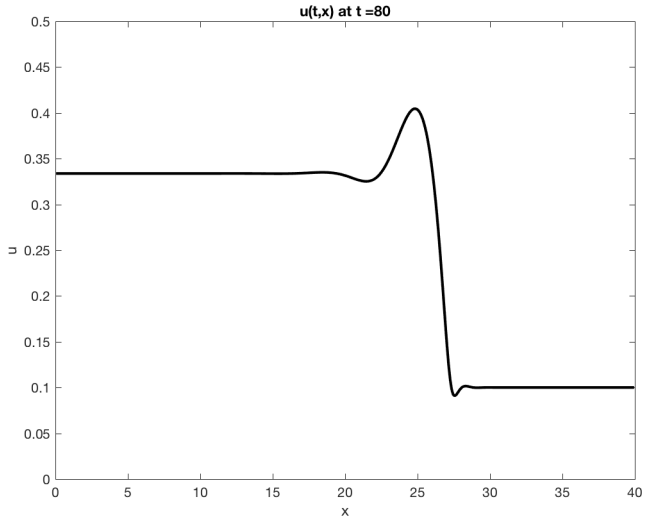
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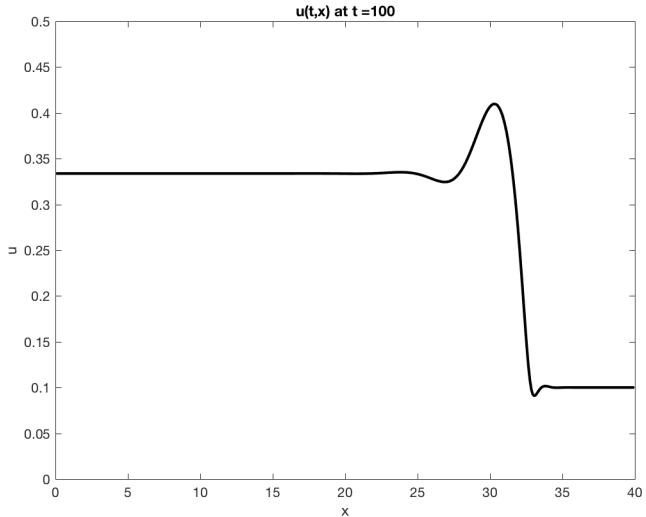
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Future Work

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- Higher dimensions
- Curved surfaces
- Space and time dependent coefficients
- Incorporation with air flow models
- Runge Kutta IMEX

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- Thanks
 - James Rossmannith
 - Alric Rothmayer
- Questions?

Bibliography

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