System Calls

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1

What is a System Call?

- · A way for unprivileged space (user space) to access kernel services.
- Examples:
 - exit
 - open
 - close
 - read
 - write

2

How System Calls Work

- · Typically an assembly instruction causes the CPU to immediately jump to a certain kernel function.
- RISC-V: ecall (environment call)
- · ARM: svc (supervisor call)
- x86_64: syscall (system call)

3

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Trapping

- · The ecall instruction causes the CPU to
 - · Finish currently executing instruction
 - · Halt execution
 - · Switch to higher privilege level
 - · Jump to trap vector
 - This is the memory address where the handler's code can be found.
 - It is responsibility of the OS to resume normal operations (in RISC-V, this is done by mret instruction).

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System Calls in Linux #define NR read 0 #define NR vrite 1 #define NR open 2 #define NR open 2 #define NR close 3 #define NR stat 4 #define NR stat 4 #define NR stat 5 #define NR stat 6 #define NR lose 8 #define NR lose 8 #define NR morbect 10 #define NR morbect 10 #define NR myrotect 10 #define NR myrotect 10 #define NR myrotect 10 #define NR write 11 #define NR rt signrocmask 14 #define NR read 19 #define NR pwrite64 18 #d

5

CPU Vectoring System 3.1.12 Machine Trap-Vector Base-Address Register (atvec) The atvec register is an XLEN-bit read/write register that holds trap vector configuration, consisting of a vector base address (BASE) and a vector mode (MODE). XLEN-1 BASE(XIEN-12 (WARL) 2 1 MODE (WARE) XLEN-2 1 MACHINE 1 1 MODE (WARE) XLEN-2 2 Figure 3.8: Machine trap-vector base-address register (atvec). The atvec register must always be implemented, but can contain a hardwired read-only value. If atvec is writable, these 4 of values the register may hold can vary by implementation. The value in the BASE field must always be adjuncted on a 4-byte boundary, and the MODE setting may impose address in writable, the set of values the register may hold can vary by implementation. The value in the BASE field must always be adjuncted on a 4-byte boundary, and the MODE setting may impose address that the set of values the register may hold can vary by implementations adjuncted constraints on the value in the BASE field. We also for considerable flexibility in emplementation of the ray vector have address. On the one hand, we do not wish to handen love and upon the part of the ray vector have address. On the one hand, we do not wish to handen love and upon the part of the ray vector have address. On the one hand, we do not wish to handen love and upon the part of the ray vector have address. On the one hand, we do not wish to handen love and upon the part of the ray vector have address. On the one hand, we do not wish to handen love and upon the part of the ray vector have address. On the one hand, we do not wish to handen love and upon the part of the ray vector have address. Value 2 vector 4 vector 4 vector mode for the ray vector and the part of the ray vector has a distract of the ray vector has a distract of the ray vector and the ray vector and read vector and read vector and read vector and read vector mode and read vecto

6

COSC 361 2

1 1 1 1 1 1 1 1 1 1 1 1 1 0 0	0 1 2 3 4 5 6 6 7 7 8 9 10 11 ≥12 0	User software interrupt Reserved Machine software interrupt User timer interrupt User timer interrupt Supervisor timer interrupt Reserved Machine timer interrupt User external interrupt User external interrupt Machine external interrupt Reserved Instruction address misaligned Instruction access fault
1 1 1 1 1 1 1 1 0 0	2 3 4 5 6 7 8 9 10 11 ≥12 0	Reserved Machine software interrupt User timer interrupt Supervisor timer interrupt Reserved Machine timer interrupt User external interrupt Supervisor external interrupt Reserved Machine external interrupt Reserved Instruction address misaligned
1 1 1 1 1 1 1 1 0 0	3 4 5 6 7 8 9 10 11 ≥12 0	Machine software interrupt User timer interrupt Supervisor timer interrupt Reserved Machine timer interrupt User external interrupt Supervisor external interrupt Reserved Machine external interrupt Reserved Instruction address misaligned
1 1 1 1 1 1 1 1 0 0	4 5 6 7 8 9 10 11 ≥12 0	User timer interrupt Supervisor timer interrupt Reserved Machine timer interrupt User external interrupt Supervisor external interrupt Reserved Machine external interrupt Reserved Instruction address misaligned
1 1 1 1 1 1 1 1 0 0	5 6 7 8 9 10 11 ≥12 0	Supervisor timer Interrupt Reserved Machine timer interrupt User external interrupt Supervisor external interrupt Reserved Machine external interrupt Reserved Instruction address misaligned
0 0	6 7 8 9 10 11 ≥12 0	Reserved Machine timer interrupt User external interrupt Supervisor external interrupt Reserved Machine external interrupt Reserved Instruction address misaligned
0 0	7 8 9 10 11 ≥12 0	Machine timer interrupt User external interrupt Supervisor external interrupt Reserved Machine external interrupt Reserved Instruction address misaligned
0 0	8 9 10 11 ≥12 0 1	User external interrupt Supervisor external interrupt Reserved Machine external interrupt Reserved Instruction address misaligned
0 0	9 10 11 ≥12 0 1	Supervisor external interrupt Reserved Machine external interrupt Reserved Instruction address misaligned
0 0	10 11 ≥12 0 1	Reserved Machine external interrupt Reserved Instruction address misaligned
0 0	11 ≥12 0 1	Machine external interrupt Reserved Instruction address misaligned
0 0	≥12 0 1	Reserved Instruction address misaligned
0 0	0	Instruction address misaligned
0	1	
0		Instruction access fault
	2	Illegal instruction
0	3	Breakpoint
0	4	Load address misaligned
0	5	Load access fault
0	6	Store/AMO address misaligned
0		
		Environment call from U-mode
		Environment call from S-mode
		Reserved
		Environment call from M-mode
		Instruction page fault
		Load page fault
		Reserved
		Store/AMO page fault
0	≥16	Reserved
	0 0 0 0 0 0 0 0	0 6 7 7 0 8 8 0 9 0 10 11 0 12 0 13 0 14 4 0 15

7

Linux System Call ABI

- Syscall number goes into register a0
- · Parameters
 - a1
 - a2
 - a3a4
 - a5
 - a6
- · Only 6 parameters are possible

8 25-Jan-19 COSC 361 TENNESSEE 1

8

Linux System Call ABI

X86-64

- Syscall number goes into register rcx
- Parameters
 - rdi
 - rsi
 - rdx
 - r10
 - r8
 - r9
- Only 6 parameters are possible

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9

COSC 361 3



10

COSC 361 4