

1516B Rerun Technical Report

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Abstract

In this technical report, we examine the creation and usage of the program that we have created to run an autonomous program in the 2023-2024 VEX VRC competition. We show the details regarding how the tool was implemented and how the tool executes. Rerun is essentially a function embedded in our greater codebase to provide control for the robot, which repeats a prerecorded path with the same movements, at an accuracy of a couple centimeter inaccuracy. This report will detail the implementation and usage of the program in a programming language-agnostic way, allowing for the tool to be implemented in any other language. The report should be informative and detail everything that the “rerun” prgram aims to do.

Contents

Test	1
test	1

Test

test